

Lecture 8

Introduction to hierarchical models

WILD6900 (Spring 2020)

Readings

Kéry & Schaub 73-82

What are random effects?

What are random effects?

- Fixed effects are constant across observational units, random effects vary across units
- Fixed effects are used when you are interested in the specific factor levels, random effects are used when you are interested in the underlying population
- When factors levels are exhaustive, they are fixed. When they are a sample of the possible levels, they are random
- Random effects are the realized values of a random variable
- Fixed effects are estimated by maximum likelihood, random effects are estimated with shrinkage

$$y_{ij} = eta_{[j]} + \epsilon_i \ \epsilon_i \sim normal(0, au)$$

```
  If β<sub>[1]</sub> = β<sub>[2]</sub> = β<sub>[3]</sub> = ... = β<sub>[J]</sub>
  model {
      # Priors
      beta0 ~ dnorm(0, 0.33)
      tau ~ dgamma(0.25, 0.25)

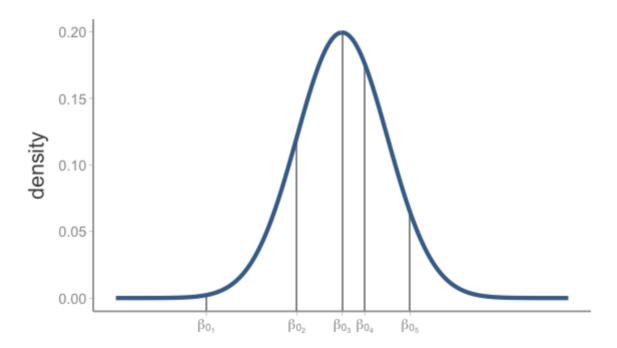
      # Likelihood
      for (i in 1:N){
      y[i] ~ dnorm(mu[i], tau)
      mu[i] <- beta0
      } #i
      }</li>
```

```
y_{ij} = eta_{[j]} + \epsilon_i \ \epsilon_i \sim normal(0,	au)
```

```
• If \beta_{[1]} \perp \beta_{[2]} \perp \beta_{[3]} \perp \ldots \perp \beta_{[J]}
model {
# Priors
for(j in 1:J){
beta0[j] \sim dnorm(0, 0.33)
}
tau \sim dgamma(0.25, 0.25)
# Likelihood
for (i in 1:N){
y[i] ~ dnorm(mu[i], tau)
mu[i] <- beta0[group[j]]</pre>
} #i
```

$$y_{ij} = eta_{[j]} + \epsilon_i \ \epsilon_i \sim normal(0, au)$$

ullet If $eta_{[j]} \sim normal(\mu_{eta 0}, au_{eta 0})$



$$y_{ij} = eta_{[j]} + \epsilon_i \ \epsilon_i \sim normal(0, au)$$

• If $eta_{[j]} \sim normal(\mu_{eta 0}, au_{eta 0})$ model { # Priors for(j in 1:J){ beta0[j] ~ dnorm(mu.beta, tau.beta) } $mu.beta \sim dnorm(0, 0.33)$ tau.beta \sim dgamma(0.25, 0.25) $tau \sim dgamma(0.25, 0.25)$ # Likelihood for (i in 1:N){ y[i] ~ dnorm(mu[i], tau) mu[i] <- beta0[group[j]]</pre> } #i

Random effects

- Only apply to factors
- Imply grouped effects
- Can include intercept, slope, and variance parameters
- Assume exchangeability
- Represent a compromise between total pooling $(\beta_{0[1]} = \beta_{0[2]} = \ldots = \beta_{0[J]})$ and no pooling $(\beta_{[1]} \perp \beta_{[2]} \perp \ldots \perp \beta_{[J]})$
- Typically require > 5 10 factor levels

Random effects = hierarchical model

$$[eta_{0[j]},\mu_{eta 0}, au_{eta 0}, au_{|y_{ij}}]=[y_{ij}|eta_{0[j]}, au][eta_{0[j]}|\mu_{eta 0}, au_{eta 0}][au][\mu_{eta 0}][au_{eta 0}]$$

- Can include multiple random effects
- Can include fixed and random effects (mixed-models)
- Can include multiple levels of hierarchy

- 1) Scope of inference
 - learn about $eta_{0[j]}$ and μ_{beta_0} , au_{beta_0}
 - prediction to unsampled groups (in space or time)

- 1) Scope of inference
- 2) Partitioning of variance
 - Account for variability among groups vs. among observational units

- 1) Scope of inference
- 2) Partitioning of variance
- 3) Accounting for uncertainty
 - modeling τ_{beta_0} recognizes uncertainty from sampling groups

- 1) Scope of inference
- 2) Partitioning of variance
- 3) Accounting for uncertainty
- 4) Avoiding psuedo-replication
 - Account for non-independence within groups

- 1) Scope of inference
- 2) Partitioning of variance
- 3) Accounting for uncertainty
- 4) Avoiding psuedo-replication
- 5) Borrowing strength
 - $\beta_{0[j]}$ estimating from group j observations + all other groups
 - "shrinkage"" towards mean
 - degree of shrinkage inversely proportional to precision

Always use random effects (Gelman & Hill 2007)

but...

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but...

- Assumption of exchangeability
- Requires 5-10 levels
- Computationally intensive
- Harder to interpret