RĪGAS TEHNISKĀ UNIVERSITĀTE ELEKTRONIKAS UN TELEKOMUNIKĀCIJU FAKULTĀTE



Datu pārraide bezvadu sensoru tīklos

Laboratorijas darbs Nr.5

I REGV0

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Darba uzdevums:

Laboratorijas darbā tiek modificēts kods lai iekļautu: ierīču adreses (un kādai ierīcei ziņas tiek adresētas), ziņu pāradresāciju, ziņu pārsūtījuma skaitu (Network lalyer). Kopumā tas veido "Flooding" datu maršrutēšanas algoritmu.

Izmantotā aparatūra: DISCO-L072CZ-LRWAN1 izstrādes platforma.

```
Izstrādātais c++ kods:
// UID of used kits are: 3145789, 3342368
#define MY_MAC_ADDRESS myUidValue
#define OTHER_MAC_ADDRESS 3342368
#include "mbed.h"
#include "PinMap.h"
#include "GenericPingPong.h"
#include "sx1276-mbed-hal.h"
#include "main.h"
#ifdef FEATURE_LORA
/* Set this flag to '1' to display debug messages on the console */
#define DEBUG_MESSAGE 1
/* Set this flag to '1' to use the LoRa modulation or to '0' to use FSK modulation */
#define USE_MODEM_LORA 0
#define USE_MODEM_FSK !USE_MODEM_LORA
#define RF_FREQUENCY
                           868300000 // Hz
#define TX_OUTPUT_POWER
                              14
                                        // 14 dBm
#if USE_MODEM_LORA == 1
#define LORA_BANDWIDTH
                              125000 // LoRa default, details in SX1276::BandwidthMap
#define LORA_SPREADING_FACTOR LORA_SF7
                              LORA_ERROR_CODING_RATE_4_5
#define LORA_CODINGRATE
#define LORA_PREAMBLE_LENGTH 8
                                     // Same for Tx and Rx
#define LORA_SYMBOL_TIMEOUT 5
                                     // Symbols
#define LORA_FIX_LENGTH_PAYLOAD_ON false
#define LORA_FHSS_ENABLED
                               false
                               4
#define LORA_NB_SYMB_HOP
#define LORA_IQ_INVERSION_ON false
#define LORA_CRC_ENABLED
#elif USE_MODEM_FSK == 1
#define FSK_FDEV
                        25000 // Hz
                                              H=1
#define FSK_DATARATE
                           50000 // bps
#define FSK_BANDWIDTH
                            100000 // Hz
                                                      TX_BW
#define FSK_AFC_BANDWIDTH
                               103473 // Hz
                                                      RX_BW
                                     // Same for Tx and Rx
#define FSK_PREAMBLE_LENGTH 5
#define FSK_FIX_LENGTH_PAYLOAD_ON false
#define FSK_CRC_ENABLED
                             true
```

```
#error "Please define a modem in the compiler options."
#endif
#define RX_TIMEOUT_VALUE 0 // in ms
#define MAX_RX_LENGTH
                                          64
                                          3
#define MAX_HOP_COUNT
#define LENGTH_OFFSET
                            11
* Global variables declarations
*/
typedef enum
  IDLE,
  RX_COMPLETE,
  RX_TIMEOUT,
  RX_ERROR,
  TX_START,
  TX_WAITING_COMPLETE,
  TX_COMPLETE,
  TX_TIMEOUT,
} AppStates_t;
volatile AppStates_t State = IDLE;
/*!
* Radio events function pointer
static RadioEvents_t RadioEvents;
* Global variables declarations
SX1276Generic *Radio;
typedef __packed struct {
        uint8_t length;
        uint8_t hopCounter;
        uint32_t destinationAddress;
        uint32_t sourceAddress;
        uint8_t payload[54];
} myPacket_t;
myPacket_t myRxPacket, myTxPacket;
```

#else

```
volatile uint8_t lastRxLength;
uint32_t buttonPressCounter;
InterruptIn mybutton(USER_BUTTON);
void myButtonInterruptFunction(){
        if(State == IDLE){
                State = TX_START;
                buttonPressCounter++;
        }
}
int SX1276PingPong()
        uint32_t * addressUID = (uint32_t *)(0x1FF80050 + 0x14);
        uint32_t myUidValue = *addressUID;
        dprintf("myUidValue = %u", myUidValue);
        srand(myUidValue);
        dprintf("sizeof(myRxPacket) = %u", sizeof(myRxPacket));
        dprintf("MY_MAC_ADDRESS = 0x%08X", MY_MAC_ADDRESS);
        mybutton.fall(&myButtonInterruptFunction);
  Radio = new SX1276Generic(NULL, MURATA_SX1276,
                LORA_SPI_MOSI, LORA_SPI_MISO, LORA_SPI_SCLK, LORA_CS, LORA_RESET,
        LORA_DIO0, LORA_DIO1, LORA_DIO2, LORA_DIO3, LORA_DIO4, LORA_DIO5,
        LORA_ANT_RX, LORA_ANT_TX, LORA_ANT_BOOST, LORA_TCXO);
  uint8_t i;
  dprintf("SX1276 Ping Pong Demo Application" );
  dprintf("Frequency: %.6f", (double)RF_FREQUENCY/1000000.0);
  dprintf("TXPower: %d dBm", TX_OUTPUT_POWER);
#if USE_MODEM_LORA == 1
  dprintf("Bandwidth: %d Hz", LORA_BANDWIDTH);
  dprintf("Spreading factor: SF%d", LORA_SPREADING_FACTOR);
#elif USE_MODEM_FSK == 1
  dprintf("Bandwidth: %d kHz", FSK_BANDWIDTH);
  dprintf("Baudrate: %d", FSK_DATARATE);
#endif
 // Initialize Radio driver
  RadioEvents.TxDone = OnTxDone;
  RadioEvents.RxDone = OnRxDone;
  RadioEvents.RxError = OnRxError;
  RadioEvents.TxTimeout = OnTxTimeout;
  RadioEvents.RxTimeout = OnRxTimeout;
```

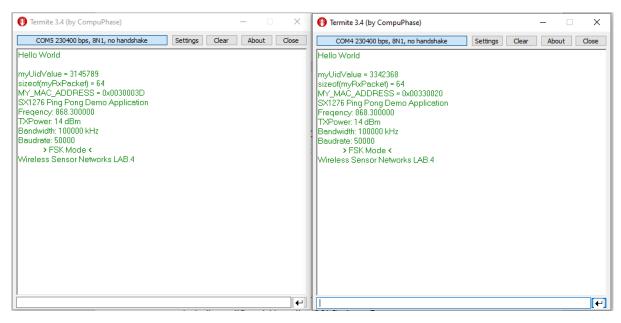
```
if (Radio->Init( &RadioEvents ) == false) {
   while(1) {
       dprintf("Radio could not be detected!");
       wait( 1 );
   }
 Radio->SetChannel(RF_FREQUENCY );
#if USE_MODEM_LORA == 1
 if (LORA_FHSS_ENABLED)
   dprintf("
                > LORA FHSS Mode <");
 if (!LORA_FHSS_ENABLED)
                > LORA Mode <");
   dprintf("
 Radio->SetTxConfig( MODEM_LORA, TX_OUTPUT_POWER, 0, LORA_BANDWIDTH,
           LORA_SPREADING_FACTOR, LORA_CODINGRATE,
           LORA\_PREAMBLE\_LENGTH, LORA\_FIX\_LENGTH\_PAYLOAD\_ON,
           LORA_CRC_ENABLED, LORA_FHSS_ENABLED, LORA_NB_SYMB_HOP,
           LORA_IQ_INVERSION_ON, 2000);
 Radio->SetRxConfig(MODEM_LORA, LORA_BANDWIDTH, LORA_SPREADING_FACTOR,
           LORA_CODINGRATE, 0, LORA_PREAMBLE_LENGTH,
           LORA_SYMBOL_TIMEOUT, LORA_FIX_LENGTH_PAYLOAD_ON, 0,
           LORA_CRC_ENABLED, LORA_FHSS_ENABLED, LORA_NB_SYMB_HOP,
           LORA_IQ_INVERSION_ON, true );
#elif USE_MODEM_FSK == 1
               > FSK Mode <");
 dprintf("
 Radio->SetTxConfig( MODEM_FSK, TX_OUTPUT_POWER, FSK_FDEV, 0,
           FSK_DATARATE, 0,
           FSK_PREAMBLE_LENGTH, FSK_FIX_LENGTH_PAYLOAD_ON,
           FSK_CRC_ENABLED, 0, 0, 0, 2000);
 Radio->SetRxConfig( MODEM_FSK, FSK_BANDWIDTH, FSK_DATARATE,
           0, FSK_AFC_BANDWIDTH, FSK_PREAMBLE_LENGTH,
           0, FSK_FIX_LENGTH_PAYLOAD_ON, 0, FSK_CRC_ENABLED,
           0, 0, false, true);
#else
#error "Please define a modem in the compiler options."
#endif
   dprintf("Wireless Sensor Networks LAB.4");
 Radio->Rx( RX_TIMEOUT_VALUE );
 while(1)
```

```
{
#ifdef TARGET_STM32L4
    WatchDogUpdate();
#endif
    switch(State)
    case IDLE:
         // Do nothing - wait for button interrupt
         sleep();
         break;
    case RX_COMPLETE:
         if (myRxPacket.length == lastRxLength){
                  dprintf("Rx complete!");
                  dprintf("myRxPacket.length = %u",myRxPacket.length);
                  dprintf("myRxPacket.hopCounter = \%u", myRxPacket.hopCounter);\\
                  dprintf("myRxPacket.sourceAddress = 0x%08X",myRxPacket.sourceAddress);
                  dprintf("myRxPacket.destinationAddress" = 0x\%08X", myRxPacket.destinationAddress");\\
                  if(myRxPacket.destinationAddress == MY_MAC_ADDRESS){
                           dprintf("This packet is for us!");
                           myRxPacket.payload[myRxPacket.length-LENGTH_OFFSET]=0; // Add Null at the end of text
manually
                           dprintf("Payload is %s\n",myRxPacket.payload);
                      }
                      else{
                           dprintf("Packet was not for us (different destinationAddress)");
                           if (myRxPacket.sourceAddress == MY\_MAC\_ADDRESS){
                                    dprintf("This packet was sent for us, so we do not forward it again");
                           }
                           else{
                                    if (myRxPacket.hopCounter >0){
                                             dprintf("Hop counter > 0, forwarding packet");
                                             myRxPacket.hopCounter--;
                                             uint16_t random_wait_ms = rand() % 1000;
                                             dprintf("Waiting %d ms before forwarding", random_wait_ms);
                                             wait(random_wait_ms * 0.001);
                                             Radio->Send( &myRxPacket, myRxPacket.length );
                                             State = TX_WAITING_COMPLETE;
                                             break;
                                    }
                           }
                      }
         }
         else{
```

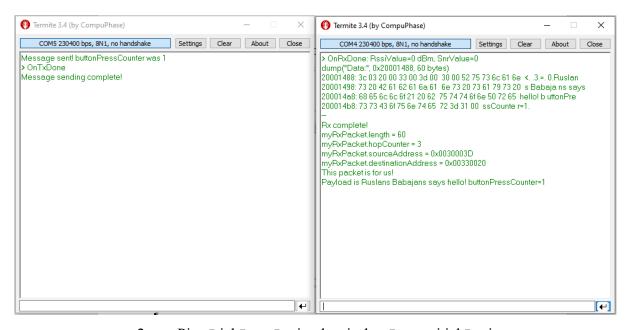
```
dprintf("Packet length error!");
                     }
                     Radio->Rx( RX_TIMEOUT_VALUE ); // Put transceiver back to Rx
                State = IDLE;
                break;
          case RX_TIMEOUT:
                     Radio->Rx( RX_TIMEOUT_VALUE ); // Put transceiver back to Rx
                     dprintf("Rx Timeout happened\n");
                     State = IDLE;
                     break;
          case RX_ERROR:
                     Radio->Rx( RX_TIMEOUT_VALUE ); // Put transceiver back to Rx
                     dprintf("Rx CRC Error happened\n");
                     State = IDLE;
                     break;
          case TX START:
                     myTxPacket.hopCounter = MAX_HOP_COUNT;
                     myTxPacket.sourceAddress = MY_MAC_ADDRESS;
                     myTxPacket.destinationAddress = OTHER_MAC_ADDRESS;
                     myTxPacket.length = sprintf((char*)myTxPacket.payload, "Ruslans \ Babajans \ says \ hello! \ buttonPressCounter=\% \ d", \ and the sum of the 
buttonPressCounter);
                     myTxPacket.length += LENGTH_OFFSET; // Add null terminated character and header length
                     Radio->Sleep(); // First we need to put chip from Rx to Sleep state
                     Radio->Send( &myTxPacket, myTxPacket.length );
                     dprintf("Message sent! buttonPressCounter was %d", buttonPressCounter);
                     State = TX_WAITING_COMPLETE;
                     break;
          case TX_WAITING_COMPLETE:
                                                                sleep();
                break;
          case TX_COMPLETE:
                     dprintf("Message sending complete!");
                     Radio->Rx( RX_TIMEOUT_VALUE ); // Put transceiver back to Rx
                     State = IDLE:
                     break;
          case TX_TIMEOUT:
                dprintf("TX_TIMEOUT happened!");
                     Radio->Rx( RX_TIMEOUT_VALUE ); // Put transceiver back to Rx
                     State = IDLE;
                     break;
           default:
                State = IDLE;
                break;
```

```
}
void OnTxDone(void *radio, void *userThisPtr, void *userData)
  Radio->Sleep();
  State = TX_COMPLETE;
  if (DEBUG_MESSAGE)
    dprintf(">OnTxDone");
}
void OnRxDone(void *radio, void *userThisPtr, void *userData, uint8_t *payload, uint16_t size, int16_t rssi, int8_t snr)
  Radio->Sleep();
  lastRxLength = size;
  if (size > MAX_RX_LENGTH){
        lastRxLength = 64;
  }
  memcpy( &myRxPacket, payload, size );
  State = RX_COMPLETE;
  if (DEBUG_MESSAGE)
    dprintf("> OnRxDone: RssiValue=%d dBm, SnrValue=%d", rssi, snr);
  dump("Data:", payload, size);
void OnTxTimeout(void *radio, void *userThisPtr, void *userData)
  Radio->Sleep();
  State = TX_TIMEOUT;
  if(DEBUG_MESSAGE)
    dprintf("> OnTxTimeout");
}
void OnRxTimeout(void *radio, void *userThisPtr, void *userData)
{
  Radio->Sleep();
  State = RX_TIMEOUT;
  if (DEBUG_MESSAGE)
    dprintf("> OnRxTimeout");
}
void OnRxError(void *radio, void *userThisPtr, void *userData)
  Radio->Sleep();
  State = RX_ERROR;
  if (DEBUG_MESSAGE)
    dprintf("> OnRxError");
}
#endif
```

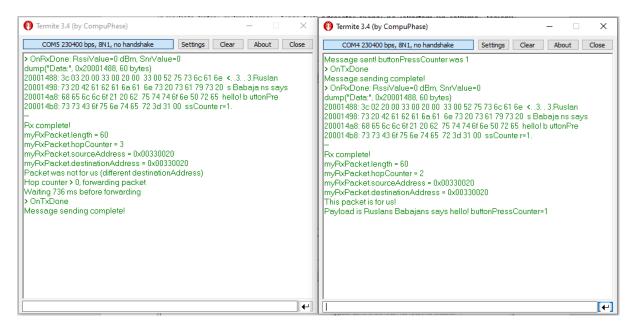
Katrai iekārtai tika pievienota MAC adrese vienāda ar mikrokontrolera UID adresi, kas ir unikāla katrai mikroshēmai. Ziņas tiek adresētas vienai no iekārtām un sākumā "lēcienu skaitītājam" maksimāla vērtība ir 3.



1. att. Divu iekāru parametri

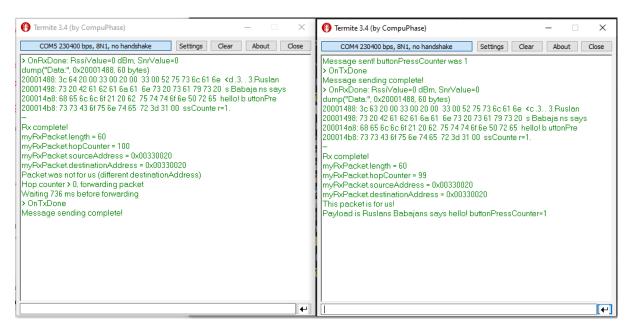


2. att. Pirmā iekārta sūt ziņu kas ir domāta otrai iekārtai



3. att. Otrā iekārta sūt ziņu kas ir domāta otrai iekārtai

2. att. var redzēt ka pirmā iekārta sūt ziņu, otrā saņem, un ziņu pāradresācija nenotiek. Bet kad otrā iekārta izsūt ziņu kas ir domāta viņai pašai, pirmā iekārta to uztver, samazina lēcienu skaitu uz 1, un pārsūt, jo ziņai nav domāta viņai. Viss strādā perfekti. Tālāk "lēcienu skaitītājam" ir uzstādīta maksimālā vērtība 100, un tiek pamēģināts 3. att. gadījums.



4. att. Otrā iekārta sūt ziņu kas ir domāta otrai iekārtai

4. att. var redzēt ka no šīm izmainām sistēmas darbība nemainījās - lēcienu skaits tika samazināts uz 1, un ziņa tika pārsūtīta. Pēdējā solī tika izrēķināts maksimālais ziņu ilgums. MATLAB kods aprēķiniem:

```
%% Clear variables and close figures
format long, clear variables, close all
%============
%% FSK calculations
DEVIATION=25e3; % Hz
H=1; % modulation index
F0=868300000; % Hz central frequency
PPM=2; % ppm
DATA RATE=(2*DEVIATION)/(H); % bps
TX BW=2*DEVIATION+DATA RATE; % Hz
RX BW=TX BW+F0*2*(PPM/\overline{1}e6); % Hz
%% LAB. 5
bit time=1/DATA RATE; % DATA RATE = 50000 bps
Max packet length = 512; % bits or 64B
CRC 16= 16; % bits
Preamble = 20; % bits
Sync word = 16; % bits
Total max length = Max packet length+CRC 16+Preamble+Sync word;
t_max=Total_max_length*bit_time; % 11.28 ms
```

Aprēķinu rezultātā maksimālais ziņu ilgums ir vienāds ar 11.28 ms. Internetā neatradu ar ko salīdzināt (ieexplore un researchgate tas arī nav atrodams).

Secinājumi:

Šajā darbā tika izveidots kods kas iekļauj "Flooding" datu maršrutēšanas algoritmu. Algoritmam ir priekšrocība ka nav jāveido speciālas maršrutēšanas tabulas, bet ziņa netiek pārsūtīta pa visefektīvāko ceļu. "Flooding" algoritma realizācijai ir jāpievērš uzmanība, jo pastāv risks ka ziņa mūžīgi ceļos pa tīklu ja "lēcienu skaitītājs" un saistītas darbības ir realizētas nepareizi.