Scheduling - Stanford CS 221 Fall 2017-2018

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0 Problem 0: Warmup

a Let's create a CSP. Suppose you have n light bulbs, where each light bulb $i=1,\ldots,n$ is initially off. You also have m buttons which control the lights. For each button $j=1,\ldots,m$, we know the subset $T_j\subseteq 1,\ldots,n$ of light bulbs that it controls. When button j is pressed, it toggles the state of each light bulb in T_j (For example, if $3\in T_j$ and light bulb 3 is off, then after the button is pressed, light bulb 3 will be on, and vice versa).

Your goal is to turn on all the light bulbs by pressing a subset of the buttons. Construct a CSP to solve this problem. Your CSP should have m variables and n constraints. For this problem only, you can use n-ary constraints. Describe your CSP precisely and concisely. You need to specify the variables with their domain, and the constraints with their scope and expression. Make sure to include T_i in your answer.

A light bulb can be either off (0) or on (1). So if we have 2 bulbs the possible states are (0,0),(0,1),(1,0),(1,1).

Variables: We define the variable X_i to be one of m switches. The values of X_j $(j = 1, \dots, m)$ are a tuple of size n where each column is a 1 if that switch toggles the bulb and 0 otherwise. Formally

```
X_j = (x_1, x_2, \dots, x_n) where x_i = \begin{cases} 1 \text{ if } x_i \subseteq T_j \\ 0 \text{ otherwise} \end{cases}
```

Constraints: We have n constraint where constraint(i) implies that the sum of column i for all our variables X_j should be odd (i.e. the sum of columns mod 2 = 1). We will have n constraints since our tuple is size n.

b Let's consider a simple CSP with 3 variables and 2 binary factors:

```
where X_1, X_2, X_3 \in \{0, 1\} and t_1, t_2 are XOR functions (that is t_1(X) = x_1 \oplus x_2 and t_2(X) = x_2 \oplus x_3).
```

b.i How many consistent assignments are there for this CSP?

There are 2 consistent assignments. See table below.

X_1	X_2	X_3	t_1	t_2	Consistent
0	0	0	0	0	No
0	0	1	0	1	No
0	1	0	1	1	Yes
0	1	1	1	0	No
1	0	0	1	0	No
1	0	1	1	1	Yes
1	1	0	0	1	No
1	1	1	0	0	No

b.ii To see why variable ordering is important, let's use backtracking search to solve the CSP without using any heuristics (MCV, LCV, AC-3) or lookahead. How many times will backtrack() be called to get all consistent assignments if we use the fixed ordering X_1, X_3, X_2 ? Draw the call stack for backtrack(). (You should use the Backtrack algorithm from the slides. The initial arguments are $\mathbf{x} = \emptyset$, w = 1, and the original Domain.)

In the code, this will be BacktrackingSearch.numOperations.

Backtrack will be called 9 times (including the initial call). We will initially call backtrack on \emptyset with w=1. The call stack is as follows

```
\texttt{Backtrack}(\left\{\emptyset\right\},1,\left\{0,1\right\})
       X_1 = 0
       Backtrack(\{X_1 = 0\}, 1, \{0, 1\})
               X_3 = 0
               \delta = 1
               Backtrack(\{X_1 = 0, X_3 = 0\}, 1, \{0, 1\})
                       X_2 = 0
                       \delta = 0
                       continue
                       X_2 = 1
                       Backtrack(\{X_1 = 0, X_3 = 0, X_2 = 1\}, 1, \{0, 1\})
                               COMPLETE ASSIGNMENT. Update best and return
               X_3 = 1
               \delta = 1
               Backtrack(\{X_1 = 0, X_3 = 1\}, 1, \{0, 1\})
                       X_2 = 0
                       \delta = 0
                       continue
                       X_2 = 1
                       \delta = 0
                       continue
       X_1 = 1
```

```
\delta = 1
Backtrack(\{X_1 = 1\}, 1, \{0, 1\})
       X_3 = 0
       \delta = 1
       Backtrack(\{X_1 = 1, X_3 = 0\}, 1, \{0, 1\})
              X_2 = 0
              \delta = 0
              continue
              X_2 = 1
              \delta = 0
              continue
       X_3 = 1
       \delta = 1
       Backtrack(\{X_1 = 1, X_3 = 1\}, 1, \{0, 1\})
              X_2 = 0
              \delta = 0
              Backtrack(\{X_1 = 1, X_3 = 1, X_2 = 0\}, 1, \{0, 1\})
                      COMPLETE ASSIGNMENT. Update best and return
              X_2 = 1
              \delta = 0
              continue
```

b.iii To see why lookahead can be useful, let's do it again with the ordering X_1, X_3, X_2 and AC-3. How many times will Backtrack be called to get all consistent assignments? Draw the call stack for backtrack()

Backtrack will be called 7 times including the initial call. The call stack is as follows

```
\begin{aligned} & \text{Backtrack}(\{\emptyset\},1,\{0,1\}) \\ & X_1=0 \\ & \delta=1 \\ & \text{Backtrack}(\{X_1=0\},1,\{0,1\}) \\ & \text{Enforce arc consistency on neighbors} \\ & \text{Add } X_1=0 \text{ to set} \\ & \text{While Set is nonempty} \\ & \text{Remove } X_1=0 \text{ from set} \\ & \text{Enforce arc consistency on } X_2. \text{ Domain of } X_2=\{1\} \\ & \text{Domain changed so add } X_2=1 \text{ to set} \\ & \text{Remove } X2=1 \text{ from set.} \\ & \text{Enforce arc consistency on } X_3. \text{ Domain of } X_3=\{0\} \\ & \text{Domain changed so add } X_3=0 \text{ to set} \\ & \text{Remove } X_3=0 \text{ from set.} \\ & \text{Set is empty so return} \end{aligned}
```

```
X_3 = 0
      \delta = 1
      Backtrack(\{X_1 = 0, X_3 = 0\}, 1, \{0, 1\})
             X_2 = 1
             \delta = 1
             Backtrack(\{X_1 = 0, X_3 = 0, X_2 = 1\}, 1, \{0, 1\})
                    COMPLETE ASSIGNMENT. Update best and return
X_1 = 1
\delta = 1
Backtrack(\{X_1 = 1\}, 1, \{0, 1\})
Enforce arc consistency on neighbors
      \operatorname{Add}\ X_1=1\ \operatorname{to}\ \operatorname{set}
      While Set is nonempty
             Remove X_1=1 from set
             Enforce arc consistency on X_2. Domain of X_2=\{0\}
             Domain changed so add X_2=0 to set
             Remove X2 = 0 from set.
             Enforce arc consistency on X_3. Domain of X_3 = \{1\}
             Domain changed so add X_3 = 1 to set
             Remove X_3 = 1 from set.
             Set is empty so return
      X_3 = 1
      \delta = 1
      Backtrack(\{X_1 = 1, X_3 = 1\}, 1, \{0, 1\})
             X_2 = 0
             \delta = 0
             Backtrack(\{X_1 = 1, X_3 = 1, X_2 = 0\}, 1, \{0, 1\})
                    COMPLETE ASSIGNMENT. Update best and return
```

1 Problem 1: CSP Solving

2 Problem 2: Handling *n*-ary factors

So far, our CSP solver only handles unary and binary factors, but for course scheduling (and really any non-trivial application), we would like to define factors that involve more than two variables. It would be nice if we could have a general way of reducing n-ary constraint to unary and binary constraints. In this problem, we will do exactly that for two types of n-ary constraints. Suppose we have boolean variables X_1, X_2, X_3 , where X_i represents whether the i-th course is taken. Suppose we want to enforce the constraint that $Y = X_1 \vee X_2 \vee X_3$, that is, Y is a boolean representing whether at least one course has been taken. For reference, in util.py, the function get_or_variable() does such a reduction. It takes in a list of variables and a target value, and re-

turns a boolean variable with domain [True, False] whose value is constrained to the condition of having at least one of the variables assigned to the target value. For example, we would call get_or_variable() with arguments $(X_1, X_2, X_3, True)$, which would return a new (auxiliary) variable X_4 , and then add another constraint $[X_4 = True]$. The second type of n-ary factors is constraints on the sum over n variables. You are going to implement reduction of this type but let's first look at a simpler problem to get started:

a Suppose we have a CSP with three variables X_1, X_2, X_3 with the same domain $\{0, 1, 2\}$ and a ternary constraint $[X_1 + X_2 + X_3 \le K]$. How can we reduce this CSP to one with only unary and/or binary constraints? Explain what auxiliary variables we need to introduce, what their domains are, what unary/binary factors you'll add, and why your scheme works. Add a graph if you think that'll better explain your scheme.

Hint: draw inspiration from the example of enforcing $[X_i = 1$ for exactly one i] which is in the first CSP lecture.

We know that X_i has domain $\{0,1,2\}$. Let us define a new variable A_i as follows

Factors

Initialization: $A_0 = 0$ Processing: $A_i = A_{i-1} + X_i$ Final output: $A_4 \leq K$

We now need to pack A_{i-1} and A_i into one variable B_i where B_i represents the

tuple (A_{i-1}, A_i) .

Factors

Initialization: $B_1[1] = 0$ Processing: $B_i[2] = B_i[1] + X_i$ Final output: $B_4[2] \le K$ Consistency: $B_{i-1}[2] = B_i[1]$

3 Problem 3: Course Scheduling

- a see submission.py
- b see submission.py

request CS227B request CS1U

c Now try to use the course scheduler for the winter and spring (and next year if applicable). Create your own profile.txt and then run the course scheduler: python run_p3.py profile.txt You might want to turn on the appropriate heuristic flags to speed up the computation. Does it produce a reasonable course schedule? Please include your profile.txt and the best schedule in your writeup; we're curious how it worked out for you!

I ran mine on a simple premise - I am an SCPD student and havent done a college course since I graduated in 2001. I wasnted to see if I could take a 6 month sabbatical, how many courses I could take in as a part time student at Stanford. This is my profile file

```
# Unit limit per quarter.
minUnits 6
maxUnits 12
# These are the quarters that I need to fill. It is assumed that
# the quarters are sorted in chronological order.
register Win2017
register Spr2018
# Courses I've already taken
taken CS221
taken MATH51
taken CS106B
taken CS124
taken CS107
taken CS103
# Courses that I'm requesting
request CS223A
request CS347
request CS341
request CS110
request CS802
request CS801
```

request CS1C

request CS248 in Win2017

This is the schedule I get. Its reasonable.

WARNING: missing prerequisite of CS248 -- CS148: Introduction to Computer

Graphics and Imaging; you should add it as 'taken' or 'request'

Found 1696 optimal assignments with weight 1.000000 in 124295 operations

First assignment took 4719 operations

Here's the best schedule:

Quarter Units Course
Win2017 5 CS110
Win2017 4 CS248

Spr2018 3 CS341 Spr2018 3 CS227B