

Eighth Edition

GATE

ELECTRONICS & COMMUNICATION

Electromagnetics

Vol 10 of 10

RK Kanodia
Ashish Murolia

NODIA & COMPANY

GATE Electronics & Communication Vol 10, 8e
Electromagnetics
RK Kanodia & Ashish Murolia

Copyright © By NODIA & COMPANY

Information contained in this book has been obtained by author, from sources believes to be reliable. However, neither NODIA & COMPANY nor its author guarantee the accuracy or completeness of any information herein, and NODIA & COMPANY nor its author shall be responsible for any error, omissions, or damages arising out of use of this information. This book is published with the understanding that NODIA & COMPANY and its author are supplying information but are not attempting to render engineering or other professional services.

MRP 590.00

NODIA & COMPANY

B – 8, Dhanshree Ist, Central Spine, Vidyadhar Nagar, Jaipur – 302039

Ph : +91 – 141 – 2101150,

www.nodia.co.in

email : enquiry@nodia.co.in

To Our Parents

Preface to the Series

For almost a decade, we have been receiving tremendous responses from GATE aspirants for our earlier books: GATE Multiple Choice Questions, GATE Guide, and the GATE Cloud series. Our first book, GATE Multiple Choice Questions (MCQ), was a compilation of objective questions and solutions for all subjects of GATE Electronics & Communication Engineering in one book. The idea behind the book was that Gate aspirants who had just completed or about to finish their last semester to achieve his or her B.E/B.Tech need only to practice answering questions to crack GATE. The solutions in the book were presented in such a manner that a student needs to know fundamental concepts to understand them. We assumed that students have learned enough of the fundamentals by his or her graduation. The book was a great success, but still there were a large ratio of aspirants who needed more preparatory materials beyond just problems and solutions. This large ratio mainly included average students.

Later, we perceived that many aspirants couldn't develop a good problem solving approach in their B.E/B.Tech. Some of them lacked the fundamentals of a subject and had difficulty understanding simple solutions. Now, we have an idea to enhance our content and present two separate books for each subject: one for theory, which contains brief theory, problem solving methods, fundamental concepts, and points-to-remember. The second book is about problems, including a vast collection of problems with descriptive and step-by-step solutions that can be understood by an average student. This was the origin of *GATE Guide* (the theory book) and *GATE Cloud* (the problem bank) series: two books for each subject. *GATE Guide* and *GATE Cloud* were published in three subjects only.

Thereafter we received an immense number of emails from our readers looking for a complete study package for all subjects and a book that combines both *GATE Guide* and *GATE Cloud*. This encouraged us to present GATE Study Package (a set of 10 books: one for each subject) for GATE Electronic and Communication Engineering. Each book in this package is adequate for the purpose of qualifying GATE for an average student. Each book contains brief theory, fundamental concepts, problem solving methodology, summary of formulae, and a solved question bank. The question bank has three exercises for each chapter: 1) Theoretical MCQs, 2) Numerical MCQs, and 3) Numerical Type Questions (based on the new GATE pattern). Solutions are presented in a descriptive and step-by-step manner, which are easy to understand for all aspirants.

We believe that each book of GATE Study Package helps a student learn fundamental concepts and develop problem solving skills for a subject, which are key essentials to crack GATE. Although we have put a vigorous effort in preparing this book, some errors may have crept in. We shall appreciate and greatly acknowledge all constructive comments, criticisms, and suggestions from the users of this book. You may write to us at rajkumar.kanodia@gmail.com and ashish.murolia@gmail.com.

Acknowledgements

We would like to express our sincere thanks to all the co-authors, editors, and reviewers for their efforts in making this project successful. We would also like to thank Team NODIA for providing professional support for this project through all phases of its development. At last, we express our gratitude to God and our Family for providing moral support and motivation.

We wish you good luck !

R. K. Kanodia

Ashish Murolia

SYLLABUS

GATE Electronics & Communications:

Electromagnetics :

Elements of vector calculus: divergence and curl; Gauss' and Stokes' theorems, Maxwell's equations: differential and integral forms. Wave equation, Poynting vector. Plane waves: propagation through various media; reflection and refraction; phase and group velocity; skin depth. Transmission lines: characteristic impedance; impedance transformation; Smith chart; impedance matching; S parameters, pulse excitation. Waveguides: modes in rectangular waveguides; boundary conditions; cut-off frequencies; dispersion relations. Basics of propagation in dielectric waveguide and optical fibers. Basics of Antennas: Dipole antennas; radiation pattern; antenna gain.

IES Electronics & Telecommunication

Electromagnetic Theory

Analysis of electrostatic and magnetostatic fields; Laplace's and Poisson's equations; Boundary value problems and their solutions; Maxwell's equations; application to wave propagation in bounded and unbounded media; Transmission lines : basic theory, standing waves, matching applications, microstrip lines; Basics of wave guides and resonators; Elements of antenna theory.

IES Electrical

EM Theory

Electric and magnetic fields. Gauss's Law and Amperes Law. Fields in dielectrics, conductors and magnetic materials. Maxwell's equations. Time varying fields. Plane-Wave propagating in dielectric and conducting media. Transmission lines.

CHAPTER 1 VECTOR ANALYSIS

1.1	INTRODUCTION	1
1.2	VECTOR QUANTITY	1
1.2.1	Representation of a Vector	1
1.2.2	Unit Vector	1
1.3	BASIC VECTOR OPERATIONS	1
1.3.1	Scaling of a Vector	2
1.3.2	Addition of Vectors	2
1.3.3	Position Vector	2
1.3.4	Distance Vector	3
1.4	MULTIPLICATION OF VECTORS	3
1.4.1	Scalar Product	3
1.4.2	Vector or Cross Product	4
1.4.3	Triple Product	5
1.4.4	Application of Vector Multiplication	6
1.5	COORDINATE SYSTEMS	7
1.5.1	Rectangular Coordinate System	7
1.5.2	Cylindrical Coordinate System	8
1.5.3	Spherical Coordinate System	9
1.6	RELATIONSHIP BETWEEN DIFFERENT COORDINATE SYSTEMS	11
1.6.1	Coordinate Conversion	11
1.6.2	Relationship between Unit Vectors of Different Coordinate Systems	11
1.6.3	Transformation of a Vector	12
1.7	DIFFERENTIAL ELEMENTS IN COORDINATE SYSTEMS	13
1.7.1	Differential Elements in Rectangular Coordinate System	13
1.7.2	Differential Elements in Cylindrical Coordinate System	13
1.7.3	Differential Elements in Spherical Coordinate System	13
1.8	INTEGRAL CALCULUS	13
1.9	DIFFERENTIAL CALCULUS	14
1.9.1	Gradient of a Scalar	14
1.9.2	Divergence of a Vector	15
1.9.3	Curl of a Vector	15
1.9.4	Laplacian Operator	16

1.10	INTEGRAL THEOREMS	17
1.10.1	Divergence theorem	17
1.10.2	Stoke's Theorem	17
1.10.3	Helmholtz's Theorem	17
EXERCISE 1.1		18
EXERCISE 1.2		25
EXERCISE 1.3		29
EXERCISE 1.4		31
SOLUTIONS 1.1		35
SOLUTIONS 1.2		50
SOLUTIONS 1.3		61
SOLUTIONS 1.4		63

CHAPTER 2 ELECTROSTATIC FIELDS

2.1	INTRODUCTION	67
2.2	ELECTRIC CHARGE	67
2.2.1	Point Charge	67
2.2.2	Line Charge	67
2.2.3	Surface Charge	67
2.2.4	Volume Charge	68
2.3	COULOMB'S LAW	68
2.3.1	Vector Form of Coulomb's Law	68
2.3.2	Principle of Superposition	69
2.4	ELECTRIC FIELD INTENSITY	69
2.4.1	Electric Field Intensity due to a Point Charge	69
2.4.2	Electric Field Intensity due to a Line Charge Distribution	70
2.4.3	Electric Field Intensity due to Surface Charge Distribution	71
2.5	ELECTRIC FLUX DENSITY	71
2.6	GAUSS'S LAW	72
2.6.1	Gaussian Surface	72
2.7	ELECTRIC POTENTIAL	73
2.7.1	Potential Difference	73
2.7.2	Potential Gradient	73
2.7.3	Equipotential Surfaces	73
2.8	ENERGY STORED IN ELECTROSTATIC FIELD	74
2.8.1	Energy Stored in a Region with Discrete Charges	74
2.8.2	Energy Stored in a Region with Continuous Charge Distribution	74
2.8.3	Electrostatic Energy in terms of Electric Field Intensity	74
2.9	ELECTRIC DIPOLE	75

2.9.1	Electric Dipole Moment	75
2.9.2	Electric Potential due to a Dipole	75
2.9.3	Electric Field Intensity due to a Dipole	75
EXERCISE 2.1		76
EXERCISE 2.2		84
EXERCISE 2.3		89
EXERCISE 2.4		91
SOLUTIONS 2.1		99
SOLUTIONS 2.2		114
SOLUTIONS 2.3		127
SOLUTIONS 2.4		129

CHAPTER 3 ELECTRIC FIELD IN MATTER

3.1	INTRODUCTION	141
3.2	ELECTRIC CURRENT DENSITY	141
3.3	CONTINUITY EQUATION	142
3.4	ELECTRIC FIELD IN A DIELECTRIC MATERIAL	142
3.4.1	Electric Susceptibility	142
3.4.2	Dielectric Constant	142
3.4.3	Relation between Dielectric Constant and Electric Susceptibility	142
3.5	ELECTRIC BOUNDARY CONDITIONS	143
3.5.1	Dielectric–Dielectric Boundary Conditions	143
3.5.2	Conductor–Dielectric Boundary Conditions	144
3.5.3	Conductor–Free Space Boundary Conditions	144
3.6	CAPACITOR	144
3.6.1	Capacitance	145
3.6.2	Energy Stored in a Capacitor	145
3.7	POISSON’S AND LAPLACE’S EQUATION	145
3.7.1	Uniqueness Theorem	145
EXERCISE 3.1		147
EXERCISE 3.2		156
EXERCISE 3.3		161
EXERCISE 3.4		163
SOLUTIONS 3.1		172
SOLUTIONS 3.2		186
SOLUTIONS 3.3		200
SOLUTIONS 3.4		201

CHAPTER 4 MAGNETOSTATIC FIELDS

4.1	INTRODUCTION	213	
4.2	MAGNETIC FIELD CONCEPT	213	
4.2.1	Magnetic Flux	213	
4.2.2	Magnetic Flux Density	214	
4.2.3	Magnetic Field Intensity	214	
4.2.4	Relation between Magnetic Field Intensity (H) and Magnetic Flux Density (B)		214
4.3	BIOT-SAVART'S LAW	214	
4.3.1	Direction of Magnetic Field Intensity	215	
4.3.2	Conventional Representation of (H) or Current (I)	215	
4.4	AMPERE'S CIRCUITAL LAW	216	
4.5	MAGNETIC FIELD INTENSITY DUE TO VARIOUS CURRENT DISTRIBUTIONS		216
4.5.1	Magnetic Field Intensity due to a Straight Line Current	217	
4.5.2	Magnetic Field Intensity due to an Infinite Line Current	217	
4.5.3	Magnetic Field Intensity due to a Square Current Carrying Loop		217
4.5.4	Magnetic Field Intensity due to a Solenoid	218	
4.5.5	Magnetic Field Intensity due to an Infinite Sheet of Current		218
4.6	MAGNETIC POTENTIAL	218	
4.6.1	Magnetic Scalar Potential	219	
4.6.2	Magnetic Vector Potential	219	
EXERCISE 4.1		220	
EXERCISE 4.2		226	
EXERCISE 4.3		232	
EXERCISE 4.4		235	
SOLUTIONS 4.1		240	
SOLUTIONS 4.2		254	
SOLUTIONS 4.3		272	
SOLUTIONS 4.4		274	

CHAPTER 5 MAGNETIC FIELDS IN MATTER

5.1	INTRODUCTION	281	
5.2	MAGNETIC FORCES	281	
5.2.1	Force on a Moving Point Charge in Magnetic Field	281	
5.2.2	Force on a Differential Current Element in Magnetic Field	282	
5.2.3	Force on a Straight Current Carrying Conductor in Magnetic Field		282
5.2.4	Magnetic Force Between Two Current Elements	282	
5.2.5	Magnetic Force Between Two Current Carrying Wires	282	
5.3	MAGNETIC DIPOLE	283	

5.4	MAGNETIC TORQUE	284
5.4.1	Torque in Terms of Magnetic Dipole Moment	284
5.5	MAGNETIZATION IN MATERIALS	284
5.5.1	Magnetic Susceptibility	284
5.5.2	Relation between Magnetic Field Intensity and Magnetic Flux Density	284
5.5.3	Classification of Magnetic Materials	285
5.6	MAGNETOSTATIC BOUNDARY CONDITIONS	285
5.6.1	Boundary condition for the normal components	285
5.6.2	Boundary Condition for the Tangential Components	287
5.6.3	Law of Refraction for Magnetic Field	287
5.7	MAGNETIC ENERGY	287
5.7.1	Energy Stored in a Coil	287
5.7.2	Energy Density in a Magnetic Field	287
5.8	MAGNETIC CIRCUIT	287
EXERCISE 5.1		289
EXERCISE 5.2		300
EXERCISE 5.3		306
EXERCISE 5.4		308
SOLUTIONS 5.1		313
SOLUTIONS 5.2		331
SOLUTIONS 5.3		347
SOLUTIONS 5.4		349

CHAPTER 6 TIME VARYING FIELDS AND MAXWELL EQUATIONS

6.1	INTRODUCTION	355
6.2	FARADAY'S LAW OF ELECTROMAGNETIC INDUCTION	355
6.2.1	Integral Form of Faraday's Law	355
6.2.2	Differential Form of Faraday's Law	356
6.3	LENZ'S LAW	356
6.4	MOTIONAL AND TRANSFORMER EMFS	357
6.4.1	Stationary Loop in a Time Varying Magnetic Field	357
6.4.2	Moving Loop in Static Magnetic Field	357
6.4.3	Moving Loop in Time Varying Magnetic Field	357
6.5	INDUCTANCE	357
6.5.1	Self Inductance	357
6.5.2	Mutual Inductance	358
6.6	MAXWELL'S EQUATIONS	359
6.6.1	Maxwell's Equations for Time Varying Fields	359
6.6.2	Maxwell's Equations for Static Fields	360

6.6.3	Maxwell's Equations in Phasor Form	361
6.7	MAXWELL'S EQUATIONS IN FREE SPACE	363
6.7.1	Maxwell's Equations for Time Varying Fields in Free Space	363
6.7.2	Maxwell's Equations for Static Fields in Free Space	363
6.7.3	Maxwell's Equations for Time Harmonic Fields in Free Space	364
EXERCISE 6.1		365
EXERCISE 6.2		374
EXERCISE 6.3		378
EXERCISE 6.4		381
SOLUTIONS 6.1		390
SOLUTIONS 6.2		404
SOLUTIONS 6.3		413
SOLUTIONS 6.4		416

CHAPTER 7 ELECTROMAGNETIC WAVES

7.1	INTRODUCTION	425
7.2	ELECTROMAGNETIC WAVES	425
7.2.1	General Wave Equation for Electromagnetic Waves	425
7.2.2	Wave Equation for Perfect Dielectric Medium	425
7.2.3	Wave Equation for Free Space	426
7.2.4	Wave Equation for Time-Harmonic Fields	426
7.3	UNIFORM PLANE WAVES	426
7.4	WAVE PROPAGATION IN LOSSY DIELECTRICS	428
7.4.1	Propagation Constant in Lossy Dielectrics	428
7.4.2	Solution of Uniform Plane Wave Equations in Lossy Dielectrics	428
7.4.3	Velocity of Wave Propagation in Lossy Dielectrics	429
7.4.4	Wavelength of Propagating Wave	429
7.4.5	Intrinsic Impedance	429
7.4.6	Loss Tangent	429
7.5	WAVE PROPAGATION IN LOSSLESS DIELECTRICS	430
7.5.1	Attenuation Constant	430
7.5.2	Phase Constant	430
7.5.3	Propagation Constant	430
7.5.4	Velocity of Wave Propagation	431
7.5.5	Intrinsic Impedance	431
7.5.6	Field Components of Uniform Plane Wave in Lossless Dielectric	431
7.6	WAVE PROPAGATION IN PERFECT CONDUCTORS	431
7.6.1	Attenuation Constant	431
7.6.2	Phase Constant	432

7.6.3	Propagation Constant	432	
7.6.4	Velocity of Wave Propagation		432
7.6.5	Intrinsic Impedance	432	
7.6.6	Skin Effect	432	
7.7	WAVE PROPAGATION IN FREE SPACE	433	
7.7.1	Attenuation Constant	433	
7.7.2	Phase Constant	433	
7.7.3	Propagation Constant	433	
7.7.4	Velocity of Wave Propagation		434
7.7.5	Intrinsic Impedance	434	
7.7.6	Field Components of Uniform Plane Wave in Free Space		434
7.8	POWER CONSIDERATION IN ELECTROMAGNETIC WAVES	434	
7.8.1	Poynting's Theorem	434	
7.8.2	Average Power Flow in Uniform Plane Waves	435	
7.9	WAVE POLARIZATION	436	
7.9.1	Linear Polarization	436	
7.9.2	Elliptical Polarization	436	
7.9.3	Circular Polarization	436	
7.10	REFLECTION & REFRACTION OF UNIFORM PLANE WAVES		438
7.11	NORMAL INCIDENCE OF UNIFORM PLANE WAVE AT THE INTERFACE BETWEEN TWO DIELECTRICS	438	
7.11.1	Reflection and Transmission Coefficients		439
7.11.2	Standing Wave Ratio	439	
7.12	NORMAL INCIDENCE OF UNIFORM PLANE WAVE ON A PERFECT CONDUCTOR	439	
7.12.1	Reflection and Transmission Coefficients		440
7.12.2	Standing Wave Ratio	440	
7.13	OBLIQUE INCIDENCE OF UNIFORM PLANE WAVE AT THE INTERFACE BETWEEN TWO DIELECTRICS	440	
7.13.1	Parallel Polarization	440	
7.13.2	Perpendicular Polarization	441	
7.14	OBLIQUE INCIDENCE OF UNIFORM PLANE WAVE ON A PERFECT CONDUCTOR		442
7.14.1	Parallel Polarisation	442	
7.14.2	Perpendicular Polarisation	442	
EXERCISE 7.1		444	
EXERCISE 7.2		451	
EXERCISE 7.3		454	
EXERCISE 7.4		459	
SOLUTIONS 7.1		474	
SOLUTIONS 7.2		489	
SOLUTIONS 7.3		498	

CHAPTER 8 TRANSMISSION LINES

8.1	INTRODUCTION	525	
8.2	TRANSMISSION LINE PARAMETERS	525	
8.2.1	Primary Constants	525	
8.2.2	Secondary Constants	526	
8.3	TRANSMISSION LINE EQUATIONS	527	
8.3.1	Input Impedance of Transmission Line	528	
8.3.2	Reflection Coefficient	529	
8.4	LOSSLESS TRANSMISSION LINE	529	
8.4.1	Primary Constants of a Lossless Line	529	
8.4.2	Secondary Constants of a Lossless Line	529	
8.4.3	Velocity of Wave Propagation in a Lossless Line	529	
8.4.4	Input Impedance of a Lossless Line	529	
8.5	DISTORTIONLESS TRANSMISSION LINE	530	
8.5.1	Primary Constants of a Distortionless Line	530	
8.5.2	Secondary Constants of a Distortionless Line	530	
8.5.3	Velocity of Wave Propagation in a distortionless Line	530	
8.6	STANDING WAVES IN TRANSMISSION LINE	531	
8.7	SMITH CHART	532	
8.7.1	Constant Resistance Circles	532	
8.7.2	Constant Reactance Circles	533	
8.7.3	Application of Smith Chart	533	
8.8	TRANSIENTS ON TRANSMISSION LINE	534	
8.8.1	Instantaneous Voltage and Current on Transmission Line	535	
8.8.2	Bounce Diagram	535	
EXERCISE 8.1		537	
EXERCISE 8.2		545	
EXERCISE 8.3		549	
EXERCISE 8.4		551	
SOLUTIONS 8.1		567	
SOLUTIONS 8.2		586	
SOLUTIONS 8.3		597	
SOLUTIONS 8.4		599	

CHAPTER 9 WAVEGUIDES

9.1	INTRODUCTION	623
-----	--------------	-----

9.2	MODES OF WAVE PROPAGATION	623
9.3	PARALLEL PLATE WAVEGUIDE	624
9.3.1	TE Mode	624
9.3.2	TM Mode	625
9.3.3	TEM Mode	625
9.4	RECTANGULAR WAVEGUIDE	626
9.4.1	TM Modes	626
9.4.2	TE Modes	628
9.4.3	Wave Propagation in Rectangular Waveguide	629
9.5	CIRCULAR WAVEGUIDE	630
9.5.1	TM Modes	631
9.5.2	TE Modes	632
9.6	WAVEGUIDE RESONATOR	632
9.6.1	TM Mode	633
9.6.2	TE Mode	633
9.6.3	Quality Factor	634
EXERCISE 9.1		635
EXERCISE 9.2		640
EXERCISE 9.3		644
EXERCISE 9.4		646
SOLUTIONS 9.1		656
SOLUTIONS 9.2		664
SOLUTIONS 9.3		675
SOLUTIONS 9.4		677

CHAPTER 10 ANTENNA AND RADIATING SYSTEMS

10.1	INTRODUCTION	687
10.2	ANTENNA BASICS	687
10.2.1	Types of Antenna	687
10.2.2	Basic Antenna Elements	689
10.2.3	Antenna Parameters	689
10.3	RADIATION FUNDAMENTALS	691
10.3.1	Concept of Radiation	691
10.3.2	Retarded Potentials	692
10.4	RADIATION FROM A HERTZIAN DIPOLE	693
10.4.1	Field Components at Near Zone	693
10.4.2	Field Components at Far Zone	693
10.4.3	Power Flow from Hertzian Dipole	694
10.4.4	Radiation Resistance of Hertzian Dipole	694

10.5	DIFFERENT CURRENT DISTRIBUTIONS IN LINEAR ANTENNAS	694
10.5.1	Constant Current along its Length	694
10.5.2	Triangular Current Distribution	695
10.5.3	Sinusoidal Current Distribution	695
10.6	RADIATION FROM SHORT DIPOLE ($d < \lambda/4$)	696
10.7	RADIATION FROM SHORT MONOPOLE ($d < \lambda/8$)	696
10.8	RADIATION FROM HALF WAVE DIPOLE ANTENNA	696
10.8.1	Power Flow from Half Wave Dipole Antenna	696
10.8.2	Radiation Resistance of Half Wave Dipole Antenna	697
10.9	RADIATION FROM QUARTER WAVE MONOPOLE ANTENNA	697
10.9.1	Power Flow from Quarter Wave Monopole Antenna	698
10.9.2	Radiation Resistance of Quarter Wave Monopole Antenna	698
10.10	ANTENNA ARRAY	698
10.10.1	Two-elements Arrays	698
10.10.2	Uniform Linear Arrays	699
10.11	FRIIS EQUATION	700
EXERCISE 10.1		701
EXERCISE 10.2		707
EXERCISE 10.3		710
EXERCISE 10.4		711
SOLUTIONS 10.1		719
SOLUTIONS 10.2		731
SOLUTIONS 10.3		740
SOLUTIONS 10.4		741

CHAPTER 6

TIME VARYING FIELDS AND MAXWELL EQUATIONS

6.1 INTRODUCTION

Maxwell's equations are very popular and they are known as Electromagnetic Field Equations. The main aim of this chapter is to provide sufficient background and concepts on Maxwell's equations. They include:

- Faraday's law of electromagnetic induction for three different cases: time-varying magnetic field, moving conductor with static magnetic field, and the general case of moving conductor with time-varying magnetic field.
- Lenz's law which gives direction of the induced current in the loop associated with magnetic flux change.
- Concept of self and mutual inductance
- Maxwell's equations for static and time varying fields in free space and conductive media in differential and integral form

6.2 FARADAY'S LAW OF ELECTROMAGNETIC INDUCTION

According to Faraday's law of electromagnetic induction, emf induced in a conductor is equal to the rate of change of flux linkage in it. Here, we will denote the induced emf by V_{emf} . Mathematically, the induced emf in a closed loop is given as

$$V_{\text{emf}} = \frac{-d\Phi}{dt} = -\frac{d}{dt} \int_S \mathbf{B} \cdot d\mathbf{S} \quad \dots(6.1)$$

where Φ is the total magnetic flux through the closed loop, \mathbf{B} is the magnetic flux density through the loop and S is the surface area of the loop. If the closed path is taken by an N -turn filamentary conductor, the induced emf becomes

$$V_{\text{emf}} = -N \frac{d\Phi}{dt}$$

6.2.1 Integral Form of Faraday's Law

We know that the induced emf in the closed loop can be written in terms of electric field as

$$V_{\text{emf}} = \oint_L \mathbf{E} \cdot d\mathbf{L} \quad \dots(6.2)$$

From equations (6.1) and (6.2), we get

$$\oint_L \mathbf{E} \cdot d\mathbf{L} = -\frac{d}{dt} \int_S \mathbf{B} \cdot d\mathbf{S} \quad \dots(6.3)$$

This equation is termed as the integral form of Faraday's law.

6.2.2 Differential Form of Faraday's Law

Applying Stoke's theorem to equation (6.3), we obtain

$$\int_S (\nabla \times \mathbf{E}) \cdot d\mathbf{S} = -\frac{d}{dt} \int_S \mathbf{B} \cdot d\mathbf{S}$$

Thus, equating the integrands in above equation, we get

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

This is the differential form of Faraday's law.

6.3 LENZ'S LAW

The negative sign in Faraday equation is due to Lenz's law which states that the direction of emf induced opposes the cause producing it. To understand the Lenz's law, consider the two conducting loops placed in magnetic fields with increasing and decreasing flux densities respectively as shown in Figure 6.1.

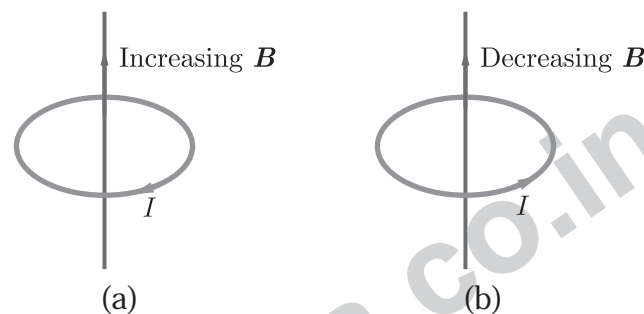


Figure 6.1: Determination of Direction of Induced Current in a Loop according to Lenz's Law
(a) \mathbf{B} in Upward Direction Increasing with Time (b) \mathbf{B} in Upward Direction Decreasing with Time

METHODOLOGY: TO DETERMINE THE POLARITY OF INDUCED EMF

To determine the polarity of induced emf (direction of induced current), we may follow the steps given below.

Step 1: Obtain the direction of magnetic flux density through the loop. In both the Figures 6.1(a),(b) the magnetic field is directed upward.

Step 2: Deduce whether the field is increasing or decreasing with time along its direction. In Figure 6.1(a), the magnetic field directed upward is increasing, whereas in Figure 6.1(b), the magnetic field directed upward is decreasing with time.

Step 3: For increasing field assign the direction of induced current in the loop such that it produces the field opposite to the given magnetic field direction. Whereas for decreasing field assign the direction of induced current in the loop such that it produces the field in the same direction that of the given magnetic field. In Figure 6.1(a), using right hand rule we conclude that any current flowing in clockwise direction in the loop will cause a magnetic field directed downward and hence, opposes the increase in flux (i.e. opposes the field that causes it). Similarly in Figure 6.1(b), using right hand rule, we conclude that any current flowing in anti-clockwise direction in the loop will cause a magnetic field directed upward and hence, opposes the decrease in flux (i.e. opposes the field that causes it).

Step 4: Assign the polarity of induced emf in the loop corresponding to the obtained direction of induced current.

6.4 MOTIONAL AND TRANSFORMER EMFS

According to Faraday's law, for a flux variation through a loop, there will be induced emf in the loop. The variation of flux with time may be caused in following three ways:

6.4.1 Stationary Loop in a Time Varying Magnetic Field

For a stationary loop located in a time varying magnetic field, the induced emf in the loop is given by

$$V_{\text{emf}} = \oint_L \mathbf{E} \cdot d\mathbf{L} = - \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S}$$

This emf is induced by the time-varying current (producing time-varying magnetic field) in a stationary loop is called *transformer emf*.

6.4.2 Moving Loop in Static Magnetic Field

When a conducting loop is moving in a static field, an emf is induced in the loop. This induced emf is called *motional emf* and given by

$$V_{\text{emf}} = \oint_L \mathbf{E}_m \cdot d\mathbf{L} = \oint_L (\mathbf{u} \times \mathbf{B}) \cdot d\mathbf{L}$$

where \mathbf{u} is the velocity of loop in magnetic field. Using Stoke's theorem in above equation, we get

$$\nabla \times \mathbf{E}_m = \nabla \times (\mathbf{u} \times \mathbf{B})$$

6.4.3 Moving Loop in Time Varying Magnetic Field

This is the general case of induced emf when a conducting loop is moving in time varying magnetic field. Combining the above two results, total emf induced is

$$V_{\text{emf}} = \oint_L \mathbf{E} \cdot d\mathbf{L} = - \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S} + \oint_L (\mathbf{u} \times \mathbf{B}) \cdot d\mathbf{L}$$

or,

$$V_{\text{emf}} = \underbrace{- \int_S \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S}}_{\text{transformer emf}} + \underbrace{\oint_L (\mathbf{u} \times \mathbf{B}) \cdot d\mathbf{L}}_{\text{motional emf}}$$

Using Stoke's theorem, we can write the above equation in differential form as

$$\nabla \times \mathbf{E} = - \frac{\partial \mathbf{B}}{\partial t} + \nabla \times (\mathbf{u} \times \mathbf{B})$$

6.5 INDUCTANCE

An inductance is the inertial property of a circuit caused by an induced reverse voltage that opposes the flow of current when a voltage is applied. A circuit or a part of circuit that has inductance is called an inductor. A device can have either self inductance or mutual inductance.

6.5.1 Self Inductance

Consider a circuit carrying a varying current which produces varying magnetic field which in turn produces induced emf in the circuit to oppose the change in flux. The emf induced is called emf of self-induction because

the change in flux is produced by the circuit itself. This phenomena is called self-induction and the property of the circuit to produce self-induction is known as *self inductance*.

Self Inductance of a Coil

Suppose a coil with N number of turns carrying current I . Let the current induces the total magnetic flux Φ passing through the loop of the coil. Thus, we have

$$N\Phi \propto I$$

$$\text{or } N\Phi = LI$$

$$\text{or } L = \frac{N\Phi}{I}$$

where L is a constant of proportionality known as self inductance.

Expression for Induced EMF in terms of Self Inductance

If a variable current i is introduced in the circuit, then magnetic flux linked with the circuit also varies depending on the current. So, the self-inductance of the circuit can be written as

$$L = \frac{d\Phi}{di} \quad \dots (6.4)$$

Since, the change in flux through the coil induces an emf in the coil given by

$$V_{\text{emf}} = -\frac{d\Phi}{dt} \quad \dots (6.5)$$

So, from equations (6.4) and (6.5), we get

$$V_{\text{emf}} = -L \frac{di}{dt}$$

6.5.2 Mutual Inductance

Mutual inductance is the ability of one inductor to induce an emf across another inductor placed very close to it. Consider two coils carrying current I_1 and I_2 as shown in Figure 6.2. Let \mathbf{B}_2 be the magnetic flux density produced due to the current I_2 and S_1 be the cross sectional area of coil 1. So, the magnetic flux due to \mathbf{B}_2 will link with the coil 1, that is, it will pass through the surface S_1 . Total magnetic flux produced by coil 2 that passes through coil 1 is called mutual flux and given as

$$\Phi_{12} = \int_{S_1} \mathbf{B}_2 \cdot d\mathbf{S}$$

We define the mutual inductance M_{12} as the ratio of the flux linkage on coil 1 to current I_2 , i.e.

$$M_{12} = \frac{N_1 \Phi_{12}}{I_2}$$

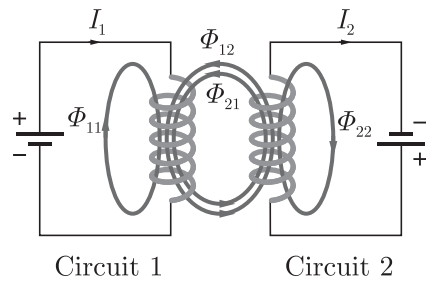
where N_1 is the number turns in coil 1. Similarly, the mutual inductance M_{21} is defined as the ratio of flux linkage on coil 2 (produced by current in coil 1) to current I_1 , i.e.

$$M_{21} = \frac{N_2 \Phi_{21}}{I_1}$$

The unit of mutual inductance is Henry (H). If the medium surrounding the circuits is linear, then

$$M_{12} = M_{21}$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)



Page 359

Chap 6

Time Varying Fields and
Maxwell Equations

Figure 6.2 : Mutual Inductance between Two Current Carrying Coils

Expression for Induced EMF in terms of Mutual Inductance

If a variable current i_2 is introduced in coil 2 then, the magnetic flux linked with coil 1 also varies depending on current i_2 . So, the mutual inductance can be given as

$$M_{12} = \frac{d\Phi_{12}}{di_2} \quad \dots(6.6)$$

The change in the magnetic flux linked with coil 1 induces an emf in coil 1 given as

$$(V_{\text{emf}})_1 = -\frac{d\Phi_{12}}{dt} \quad \dots(6.7)$$

So, from equations (6.6) and (6.7) we get

$$(V_{\text{emf}})_1 = -M_{12} \frac{di_2}{dt}$$

This is the induced emf in coil 1 produced by the current i_2 in coil 2. Similarly, the induced emf in the coil 2 due to a varying current in the coil 1 is given as

$$(V_{\text{emf}})_2 = -M_{21} \frac{di_1}{dt}$$

6.6 MAXWELL'S EQUATIONS

The set of four equations which have become known as Maxwell's equations are those which are developed in the earlier chapters and associated with them the name of other investigators. These equations describe the sources and the field vectors in the broad fields to electrostatics, magnetostatics and electro-magnetic induction.

6.6.1 Maxwell's Equations for Time Varying Fields

The four Maxwell's equation include Faraday's law, Ampere's circuital law, Gauss's law, and conservation of magnetic flux. There is no guideline for giving numbers to the various Maxwell's equations. However, it is customary to call the Maxwell's equation derived from Faraday's law as the first Maxwell's equation.

Maxwell's First Equation : Faraday's Law

The electromotive force around a closed path is equal to the time derivative of the magnetic displacement through any surface bounded by the path.

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad \text{(Differential form)}$$

$$\text{or} \quad \oint_L \mathbf{E} \cdot d\mathbf{L} = -\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot d\mathbf{S} \quad \text{(Integral form)}$$

Maxwell's Second Equation: Modified Ampere's Circuital law

The magnetomotive force around a closed path is equal to the conduction plus the time derivative of the electric displacement through any surface bounded by the path. i.e.

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \quad (\text{Differential form})$$

$$\oint_L \mathbf{H} \cdot d\mathbf{L} = \int_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S} \quad (\text{Integral form})$$

Maxwell's Third Equation : Gauss's Law for Electric Field

The total electric displacement through any closed surface enclosing a volume is equal to the total charge within the volume. i.e.,

$$\nabla \cdot \mathbf{D} = \rho_v \quad (\text{Differential form})$$

$$\text{or,} \quad \oint_S \mathbf{D} \cdot d\mathbf{S} = \int_v \rho_v dv \quad (\text{Integral form})$$

This is the Gauss' law for static electric fields.

Maxwell's Fourth Equation : Gauss's Law for Magnetic Field

The net magnetic flux emerging through any closed surface is zero. In other words, the magnetic flux lines do not originate and end anywhere, but are continuous. i.e.,

$$\nabla \cdot \mathbf{B} = 0 \quad (\text{Differential form})$$

$$\text{or,} \quad \oint_S \mathbf{B} \cdot d\mathbf{S} = 0 \quad (\text{Integral form})$$

This is the Gauss' law for static magnetic fields, which confirms the non-existence of magnetic monopole. Table 6.1 summarizes the Maxwell's equation for time varying fields.

Table 6.1: Maxwell's Equation for Time Varying Field

S.N.	Differential form	Integral form	Name
1.	$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$	$\oint_L \mathbf{E} \cdot d\mathbf{L} = -\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot d\mathbf{S}$	Faraday's law of electromagnetic induction
2.	$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$	$\oint_L \mathbf{H} \cdot d\mathbf{L} = \int_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S}$	Modified Ampere's circuital law
3.	$\nabla \cdot \mathbf{D} = \rho_v$	$\oint_S \mathbf{D} \cdot d\mathbf{S} = \int_v \rho_v dv$	Gauss' law of Electrostatics
4.	$\nabla \cdot \mathbf{B} = 0$	$\oint_S \mathbf{B} \cdot d\mathbf{S} = 0$	Gauss' law of Magnetostatic (non-existence of magnetic mono-pole)

6.6.2 Maxwell's Equations for Static Fields

For static fields, all the field terms which have time derivatives are zero, i.e.

$$\frac{\partial \mathbf{B}}{\partial t} = 0$$

$$\text{and} \quad \frac{\partial \mathbf{D}}{\partial t} = 0$$

Therefore, for a static field the four Maxwell's equations described above reduces to the following form.

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Table 6.2: Maxwell's equation for static field

Page 361

Chap 6

Time Varying Fields and
Maxwell Equations

S.N.	Differential Form	Integral form	Name
1.	$\nabla \times \mathbf{E} = 0$	$\oint_L \mathbf{E} \cdot d\mathbf{L} = 0$	Faraday's law of electromagnetic induction
2.	$\nabla \times \mathbf{H} = \mathbf{J}$	$\oint_L \mathbf{H} \cdot d\mathbf{L} = \int_S \mathbf{J} \cdot d\mathbf{S}$	Modified Ampere's circuital law
3.	$\nabla \cdot \mathbf{D} = \rho_v$	$\oint_S \mathbf{D} \cdot d\mathbf{S} = \int_v \rho_v dv$	Gauss' law of Electrostatics
4.	$\nabla \cdot \mathbf{B} = 0$	$\oint_S \mathbf{B} \cdot d\mathbf{S} = 0$	Gauss' law of Magnetostatic (non-existence of magnetic mono-pole)

6.6.3 Maxwell's Equations in Phasor Form

In a time-varying field, the field quantities $\mathbf{E}(x, y, z, t)$, $\mathbf{D}(x, y, z, t)$, $\mathbf{B}(x, y, z, t)$, $\mathbf{H}(x, y, z, t)$, $\mathbf{J}(x, y, z, t)$ and $\rho_v(x, y, z, t)$ can be represented in their respective phasor forms as below:

$$\mathbf{E} = \text{Re}\{\mathbf{E}_s e^{j\omega t}\} \quad \dots (6.8a)$$

$$\mathbf{D} = \text{Re}\{\mathbf{D}_s e^{j\omega t}\} \quad \dots (6.8b)$$

$$\mathbf{B} = \text{Re}\{\mathbf{B}_s e^{j\omega t}\} \quad \dots (6.8c)$$

$$\mathbf{H} = \text{Re}\{\mathbf{H}_s e^{j\omega t}\} \quad \dots (6.8d)$$

$$\mathbf{J} = \text{Re}\{\mathbf{J}_s e^{j\omega t}\} \quad \dots (6.8e)$$

$$\text{and } \rho_v = \text{Re}\{\rho_{vs} e^{j\omega t}\} \quad \dots (6.8f)$$

where $\mathbf{E}_s, \mathbf{D}_s, \mathbf{B}_s, \mathbf{H}_s, \mathbf{J}_s$ and ρ_{vs} are the phasor forms of respective field quantities. Using these relations, we can directly obtain the phasor form of Maxwell's equations as described below.

Maxwell's First Equation: Faraday's Law

In time varying field, first Maxwell's equation is written as

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad \dots (6.9)$$

Now, from equation (6.8a) we can obtain

$$\nabla \times \mathbf{E} = \nabla \times \text{Re}\{\mathbf{E}_s e^{j\omega t}\} = \text{Re}\{\nabla \times \mathbf{E}_s e^{j\omega t}\}$$

and using equation (6.8c) we get

$$\frac{\partial \mathbf{B}}{\partial t} = \frac{\partial}{\partial t} \text{Re}\{\mathbf{B}_s e^{j\omega t}\} = \text{Re}\{j\omega \mathbf{B}_s e^{j\omega t}\}$$

Substituting the two results in equation (6.9) we get

$$\text{Re}\{\nabla \times \mathbf{E}_s e^{j\omega t}\} = -\text{Re}\{j\omega \mathbf{B}_s e^{j\omega t}\}$$

$$\text{Hence, } \nabla \times \mathbf{E}_s = -j\omega \mathbf{B}_s \quad \text{(Differential form)}$$

$$\text{or, } \oint_L \mathbf{E}_s \cdot d\mathbf{L} = -j\omega \int_S \mathbf{B}_s \cdot d\mathbf{S} \quad \text{(Integral form)}$$

Maxwell's Second Equation: Modified Ampere's Circuital Law

In time varying field, second Maxwell's equation is written as

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \quad \dots (6.10)$$

From equation (6.8d) we can obtain

$$\nabla \times \mathbf{H} = \nabla \times \text{Re}\{\mathbf{H}_s e^{j\omega t}\} = \text{Re}\{\nabla \times \mathbf{H}_s e^{j\omega t}\}$$

Page 362

Chap 6

Time Varying Fields and
Maxwell Equations

From equation (6.8e), we have

$$\mathbf{J} = \text{Re}\{\mathbf{J}_s e^{j\omega t}\}$$

and using equation (6.8b) we get

$$\frac{\partial \mathbf{D}}{\partial t} = \frac{\partial}{\partial t} \text{Re}\{\mathbf{D}_s e^{j\omega t}\} = \text{Re}\{j\omega \mathbf{D}_s e^{j\omega t}\}$$

Substituting these results in equation (6.10) we get

$$\text{Re}\{\nabla \times \mathbf{H}_s e^{j\omega t}\} = \text{Re}\{\mathbf{J}_s e^{j\omega t} + j\omega \mathbf{D}_s e^{j\omega t}\}$$

Hence,

$$\nabla \times \mathbf{H}_s = \mathbf{J}_s + j\omega \mathbf{D}_s \quad \text{(Differential form)}$$

or,

$$\oint_L \mathbf{H}_s \cdot d\mathbf{L} = \int_S (\mathbf{J}_s + j\omega \mathbf{D}_s) \cdot d\mathbf{S} \quad \text{(Integral form)}$$

Maxwell's Third Equation : Gauss's Law for Electric Field

In time varying field, third Maxwell's equation is written as

$$\nabla \cdot \mathbf{D} = \rho_v \quad \dots(6.11)$$

From equation (6.8b) we can obtain

$$\nabla \cdot \mathbf{D} = \nabla \cdot \text{Re}\{\mathbf{D}_s e^{j\omega t}\} = \text{Re}\{\nabla \cdot \mathbf{D}_s e^{j\omega t}\}$$

and from equation (6.8f) we have

$$\rho_v = \text{Re}\{\rho_{vs} e^{j\omega t}\}$$

Substituting these two results in equation (6.11) we get

$$\text{Re}\{\nabla \cdot \mathbf{D}_s e^{j\omega t}\} = \text{Re}\{\rho_{vs} e^{j\omega t}\}$$

Hence,

$$\nabla \cdot \mathbf{D}_s = \rho_{vs} \quad \text{(Differential form)}$$

or,

$$\oint_S \mathbf{D}_s \cdot d\mathbf{S} = \int_v \rho_{vs} dv \quad \text{(Integral form)}$$

Maxwell's Fourth Equation : Gauss's Law for Magnetic Field

$$\nabla \cdot \mathbf{B} = 0 \quad \dots(6.12)$$

From equation (6.8c) we can obtain

$$\nabla \cdot \mathbf{B} = \nabla \cdot \text{Re}\{\mathbf{B}_s e^{j\omega t}\} = \text{Re}\{\nabla \cdot \mathbf{B}_s e^{j\omega t}\}$$

Substituting it in equation (6.12) we get

$$\text{Re}\{\nabla \cdot \mathbf{B}_s e^{j\omega t}\} = 0$$

Hence,

$$\nabla \cdot \mathbf{B}_s = 0 \quad \text{(Differential form)}$$

or,

$$\oint_S \mathbf{B}_s \cdot d\mathbf{S} = 0 \quad \text{(Integral form)}$$

Table 6.3 summarizes the Maxwell's equations in phasor form.

Table 6.3: Maxwell's Equations in Phasor Form

S.N.	Differential form	Integral form	Name
1.	$\nabla \times \mathbf{E}_s = -j\omega \mathbf{B}_s$	$\oint_L \mathbf{E}_s \cdot d\mathbf{L} = -j\omega \int_S \mathbf{B}_s \cdot d\mathbf{S}$	Faraday's law of electromagnetic induction
2.	$\nabla \times \mathbf{H}_s = \mathbf{J}_s + j\omega \mathbf{D}_s$	$\oint_L \mathbf{H}_s \cdot d\mathbf{L} = \int_S (\mathbf{J}_s + j\omega \mathbf{D}_s) \cdot d\mathbf{S}$	Modified Ampere's circuital law
3.	$\nabla \cdot \mathbf{D}_s = \rho_{vs}$	$\oint_S \mathbf{D}_s \cdot d\mathbf{S} = \int_v \rho_{vs} dv$	Gauss' law of Electrostatics
4.	$\nabla \cdot \mathbf{B}_s = 0$	$\oint_S \mathbf{B}_s \cdot d\mathbf{S} = 0$	Gauss' law of Magnetostatic (non-existence of magnetic mono-pole)

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

6.7 MAXWELL'S EQUATIONS IN FREE SPACE

Page 363

Chap 6

Time Varying Fields and
Maxwell Equations

For electromagnetic fields, free space is characterised by the following parameters:

1. Relative permittivity, $\epsilon_r = 1$
2. Relative permeability, $\mu_r = 1$
3. Conductivity, $\sigma = 0$
4. Conduction current density, $\mathbf{J} = 0$
5. Volume charge density, $\rho_v = 0$

As we have already obtained the four Maxwell's equations for time-varying fields, static fields, and harmonic fields; these equations can be easily written for the free space by just replacing the variables to their respective values in free space.

6.7.1 Maxwell's Equations for Time Varying Fields in Free Space

By substituting the parameters, $\mathbf{J} = 0$ and $\rho_v = 0$ in the Maxwell's equations given in Table 6.1, we get the Maxwell's equation for time-varying fields in free space as summarized below:

Table 6.4: Maxwell's Equations for Time Varying Fields in Free Space

S.N.	Differential form	Integral form	Name
1.	$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$	$\oint_L \mathbf{E} \cdot d\mathbf{L} = -\frac{\partial}{\partial t} \int_S \mathbf{B} \cdot d\mathbf{S}$	Faraday's law of electromagnetic induction
2.	$\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t}$	$\oint_L \mathbf{H} \cdot d\mathbf{L} = \int_S \frac{\partial \mathbf{D}}{\partial t} \cdot d\mathbf{S}$	Modified Ampere's circuital law
3.	$\nabla \cdot \mathbf{D} = 0$	$\oint_S \mathbf{D} \cdot d\mathbf{S} = 0$	Gauss' law of Electrostatics
4.	$\nabla \cdot \mathbf{B} = 0$	$\oint_S \mathbf{B} \cdot d\mathbf{S} = 0$	Gauss' law of Magnetostatic (non-existence of magnetic mono-pole)

6.7.2 Maxwell's Equations for Static Fields in Free Space

Substituting the parameters, $\mathbf{J} = 0$ and $\rho_v = 0$ in the Maxwell's equation given in Table 6.2, we get the Maxwell's equation for static fields in free space as summarized below.

Table 6.5: Maxwell's Equations for Static Fields in Free Space

S.N.	Differential Form	Integral Form	Name
1.	$\nabla \times \mathbf{E} = 0$	$\oint_L \mathbf{E} \cdot d\mathbf{L} = 0$	Faraday's law of electromagnetic induction
2.	$\nabla \times \mathbf{H} = 0$	$\oint_L \mathbf{H} \cdot d\mathbf{L} = 0$	Modified Ampere's circuital law
3.	$\nabla \cdot \mathbf{D} = 0$	$\oint_S \mathbf{D} \cdot d\mathbf{S} = 0$	Gauss' law of Electrostatics
4.	$\nabla \cdot \mathbf{B} = 0$	$\oint_S \mathbf{B} \cdot d\mathbf{S} = 0$	Gauss' law of Magnetostatic (non-existence of magnetic mono-pole)

Page 364
Chap 6
Time Varying Fields and
Maxwell Equations

Thus, all the four Maxwell’s equation vanishes for static fields in free space.

6.7.3 Maxwell’s Equations for Time Harmonic Fields in Free Space

Again, substituting the parameters, $J = 0$ and $\rho_v = 0$ in the Maxwell’s equations given in Table 6.3, we get the Maxwell’s equation for time harmonic fields in free space as summarized below.

Table 6.6 : Maxwell’s Equations for Time-Harmonic Fields in Free Space

S.N.	Differential form	Integral form	Name
1.	$\nabla \times \boldsymbol{E}_s = -j\omega \boldsymbol{B}_s$	$\oint_L \boldsymbol{E}_s \cdot d\boldsymbol{L} = -j\omega \int_S \boldsymbol{B}_s \cdot d\boldsymbol{S}$	Faraday’s law of electromagnetic induction
2.	$\nabla \times \boldsymbol{H}_s = j\omega \boldsymbol{D}_s$	$\oint_L \boldsymbol{H}_s \cdot d\boldsymbol{L} = \int_S j\omega \boldsymbol{D}_s \cdot d\boldsymbol{S}$	Modified Ampere’s circuital law
3.	$\nabla \cdot \boldsymbol{D}_s = 0$	$\oint_S \boldsymbol{D}_s \cdot d\boldsymbol{S} = 0$	Gauss’ law of Electrostatics
4.	$\nabla \cdot \boldsymbol{B}_s = 0$	$\oint_S \boldsymbol{B}_s \cdot d\boldsymbol{S} = 0$	Gauss’ law of Magnetostatic (non-existence of magnetic mono-pole)

EXERCISE 6.1

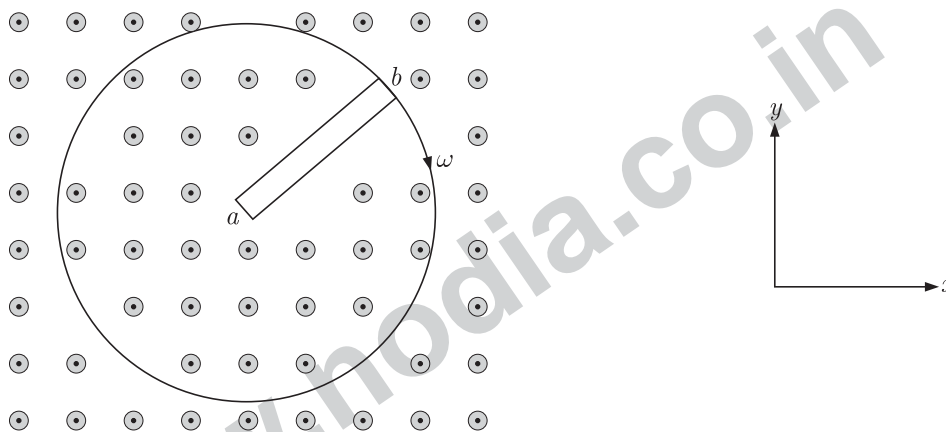
Page 365

Chap 6

Time Varying Fields and
Maxwell Equations

- MCQ 6.1.1 A perfect conducting sphere of radius r is such that its net charge resides on the surface. At any time t , magnetic field $\mathbf{B}(r, t)$ inside the sphere will be
- (A) 0
 - (B) uniform, independent of r
 - (C) uniform, independent of t
 - (D) uniform, independent of both r and t

- MCQ 6.1.2 A straight conductor ab of length l lying in the xy plane is rotating about the centre a at an angular velocity ω as shown in the figure.



If a magnetic field \mathbf{B} is present in the space directed along \mathbf{a}_z then which of the following statement is correct ?

- (A) V_{ab} is positive
- (B) V_{ab} is negative
- (C) V_{ba} is positive
- (D) V_{ba} is zero

- MCQ 6.1.3 **Assertion (A) :** A small piece of bar magnet takes several seconds to emerge at bottom when it is dropped down a vertical aluminum pipe where as an identical unmagnetized piece takes a fraction of second to reach the bottom.
Reason (R) : When the bar magnet is dropped inside a conducting pipe, force exerted on the magnet by induced eddy current is in upward direction.
- (A) Both A and R are true and R is correct explanation of A.
 - (B) Both A and R are true but R is not the correct explanation of A.
 - (C) A is true but R is false.
 - (D) A is false but R is true.

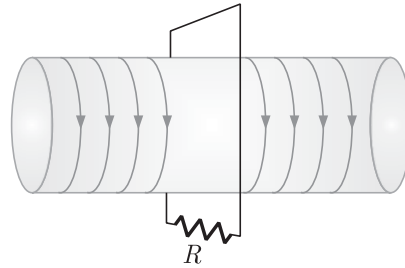
- MCQ 6.1.4 Self inductance of a long solenoid having n turns per unit length will be proportional to
- (A) n
 - (B) $1/n$
 - (C) n^2
 - (D) $1/n^2$

Page 366

Chap 6

Time Varying Fields and
Maxwell Equations

MCQ 6.1.5

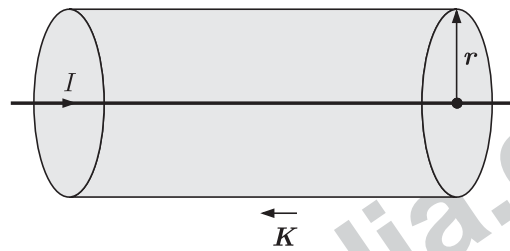
A wire with resistance R is looped on a solenoid as shown in figure.

If a constant current is flowing in the solenoid then the induced current flowing in the loop with resistance R will be

- (A) non uniform (B) constant
(C) zero (D) none of these

MCQ 6.1.6

A long straight wire carries a current $I = I_0 \cos(\omega t)$. If the current returns along a coaxial conducting tube of radius r as shown in figure then magnetic field and electric field inside the tube will be respectively.

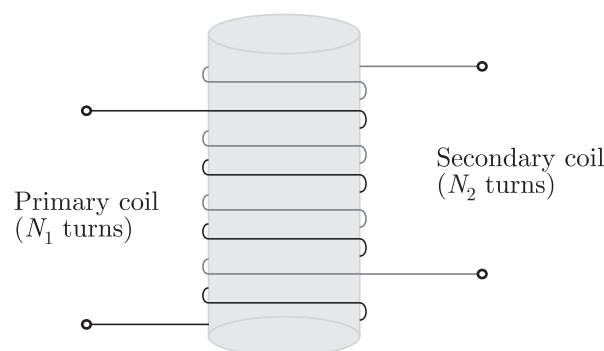


- (A) radial, longitudinal (B) circumferential, longitudinal
(C) circumferential, radial (D) longitudinal, circumferential

MCQ 6.1.7

Assertion (A) : Two coils are wound around a cylindrical core such that the primary coil has N_1 turns and the secondary coils has N_2 turns as shown in figure. If the same flux passes through every turn of both coils then the ratio of emf induced in the two coils is

$$\frac{V_{\text{emf } 2}}{V_{\text{emf } 1}} = \frac{N_2}{N_1}$$



Reason (R) : In a primitive transformer, by choosing the appropriate no. of turns, any desired secondary emf can be obtained.

- (A) Both A and R are true and R is correct explanation of A.
(B) Both A and R are true but R is not the correct explanation of A.
(C) A is true but R is false.
(D) A is false but R is true.

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 367

Chap 6

Time Varying Fields and
Maxwell Equations

- MCQ 6.1.8 In a non magnetic medium electric field $E = E_0 \cos \omega t$ is applied. If the permittivity of medium is ϵ and the conductivity is σ then the ratio of the amplitudes of the conduction current density and displacement current density will be
- (A) $\mu_0/\omega\epsilon$ (B) $\sigma/\omega\epsilon$
(C) $\sigma\mu_0/\omega\epsilon$ (D) $\omega\epsilon/\sigma$

- MCQ 6.1.9 In a medium, the permittivity is a function of position such that $\frac{\nabla \epsilon}{\epsilon} \approx 0$. If the volume charge density inside the medium is zero then $\nabla \cdot \mathbf{E}$ is roughly equal to
- (A) $\epsilon \mathbf{E}$ (B) $-\epsilon \mathbf{E}$
(C) 0 (D) $-\nabla \epsilon \cdot \mathbf{E}$

- MCQ 6.1.10 In free space, the electric field intensity at any point (r, θ, ϕ) in spherical coordinate system is given by

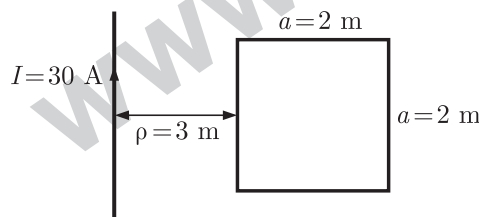
$$\mathbf{E} = \frac{\sin \theta \cos(\omega t - kr)}{r} \mathbf{a}_\theta$$

The phasor form of magnetic field intensity in the free space will be

- (A) $\frac{k \sin \theta}{\omega \mu_0 r} e^{-jkr} \mathbf{a}_\phi$ (B) $-\frac{k \sin \theta}{\omega \mu_0 r} e^{-jkr} \mathbf{a}_\phi$
(C) $\frac{k \omega \mu_0}{r} e^{-jkr} \mathbf{a}_\phi$ (D) $\frac{k \sin \theta}{r} e^{-jkr} \mathbf{a}_\phi$

Common Data For Q. 11 and 12 :

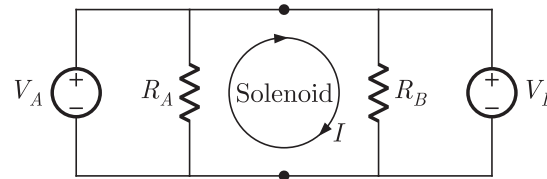
A conducting wire is formed into a square loop of side 2 m. A very long straight wire carrying a current $I = 30$ A is located at a distance 3 m from the square loop as shown in figure.



- MCQ 6.1.11 If the loop is pulled away from the straight wire at a velocity of 5 m/s then the induced e.m.f. in the loop after 0.6 sec will be
- (A) 5 μ volt (B) 2.5 μ volt
(C) 25 μ volt (D) 5 mvolt
- MCQ 6.1.12 If the loop is pulled downward in the parallel direction to the straight wire, such that distance between the loop and wire is always 3 m then the induced e.m.f. in the loop at any time t will be
- (A) linearly increasing with t (B) always 0
(C) linearly decreasing with t (D) always constant but not zero.
- MCQ 6.1.13 Two voltmeters A and B with internal resistances R_A and R_B respectively is connected to the diametrically opposite points of a long solenoid as shown in figure. Current in the solenoid is increasing linearly with time. The correct relation between the voltmeter's reading V_A and V_B will be

Page 368

Chap 6

Time Varying Fields and
Maxwell Equations

(A) $V_A = V_B$

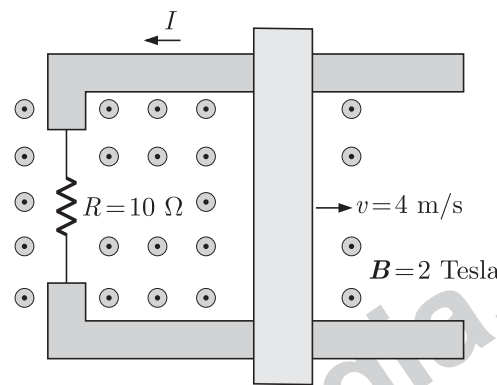
(B) $V_A = -V_B$

(C) $\frac{V_A}{V_B} = \frac{R_A}{R_B}$

(D) $\frac{V_A}{V_B} = -\frac{R_A}{R_B}$

Common Data For Q. 14 and 15 :

Two parallel conducting rails are being placed at a separation of 5 m with a resistance $R = 10\ \Omega$ connected across its one end. A conducting bar slides frictionlessly on the rails with a velocity of 4 m/s away from the resistance as shown in the figure.



MCQ 6.1.14

If a uniform magnetic field $B = 2$ Tesla pointing out of the page fills entire region then the current I flowing in the bar will be

(A) 0 A

(B) -40 A

(C) 4 A

(D) -4 A

MCQ 6.1.15

The force exerted by magnetic field on the sliding bar will be

(A) 4 N, opposes its motion

(B) 40 N, opposes its motion

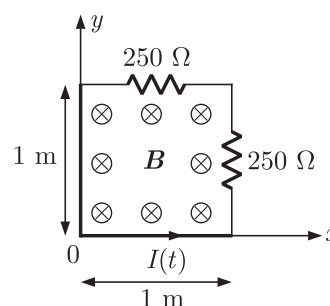
(C) 40 N, in the direction of its motion

(D) 0

MCQ 6.1.16

Two small resistor of $250\ \Omega$ each is connected through a perfectly conducting filament such that it forms a square loop lying in x - y plane as shown in the figure. Magnetic flux density passing through the loop is given as

$$\mathbf{B} = -7.5 \cos(120\pi t - 30^\circ) \mathbf{a}_z$$



Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 369

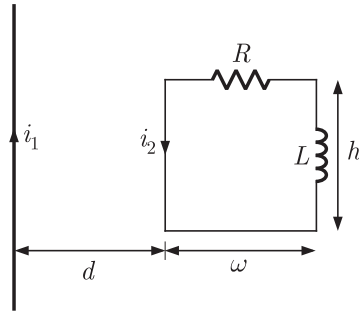
Chap 6

Time Varying Fields and
Maxwell EquationsThe induced current $I(t)$ in the loop will be

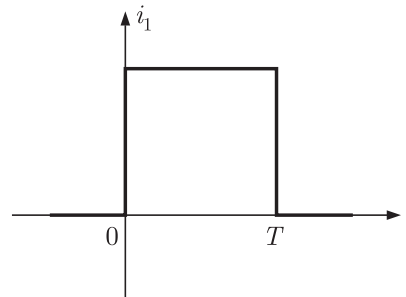
- (A) $0.02 \sin(120\pi t - 30^\circ)$ (B) $2.8 \times 10^3 \sin(120\pi t - 30^\circ)$
 (C) $-5.7 \sin(120\pi t - 30^\circ)$ (D) $5.7 \sin(120\pi t - 30^\circ)$

MCQ 6.1.17

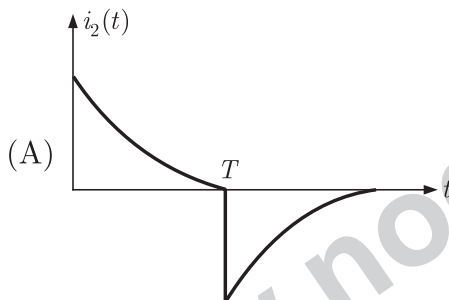
A rectangular loop of self inductance L is placed near a very long wire carrying current i_1 as shown in figure (a). If i_1 be the rectangular pulse of current as shown in figure (b) then the plot of the induced current i_2 in the loop versus time t will be (assume the time constant of the loop, $\tau \gg L/R$)



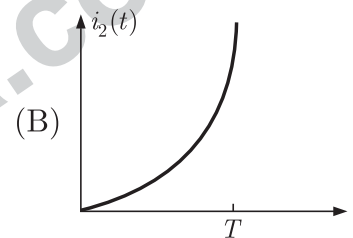
(a)



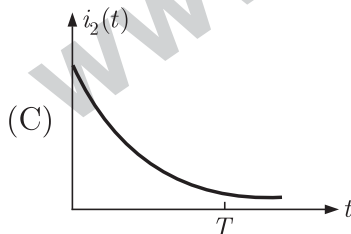
(b)



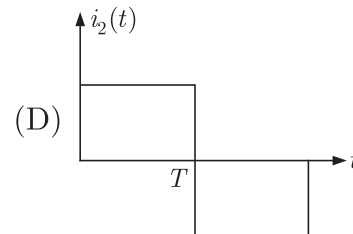
(A)



(B)



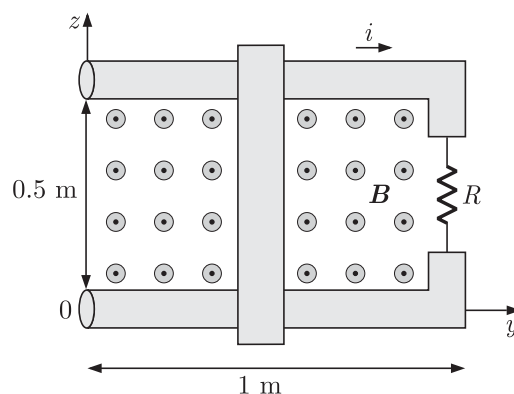
(C)



(D)

MCQ 6.1.18

Two parallel conducting rails are placed in a varying magnetic field $\mathbf{B} = 0.2 \cos \omega t \mathbf{a}_x$. A conducting bar oscillates on the rails such that its position is given by $y = 0.5(1 - \cos \omega t)$ m. If one end of the rails are terminated in a resistance $R = 5 \Omega$, then the current i flowing in the rails will be



Page 370

Chap 6

Time Varying Fields and
Maxwell Equations

(A) $0.01\omega \sin \omega t(1 + 2 \cos \omega t)$

(B) $-0.01\omega \sin \omega t(1 + 2 \cos \omega t)$

(C) $0.01\omega \cos \omega t(1 + 2 \sin \omega t)$

(D) $0.05\omega \sin \omega t(1 + 2 \sin \omega t)$

MCQ 6.1.19

Electric flux density in a medium ($\epsilon_r = 10$, $\mu_r = 2$) is given as

$$\mathbf{D} = 1.33 \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \mu\text{C/m}^2$$

Magnetic field intensity in the medium will be

(A) $10^{-5} \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \text{ A/m}$

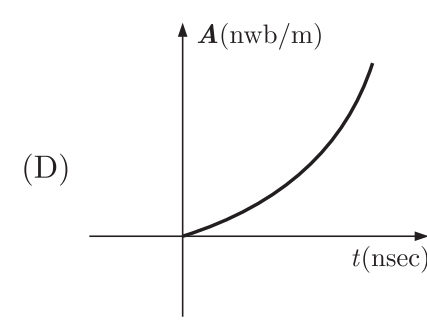
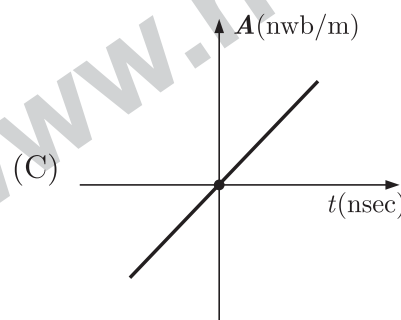
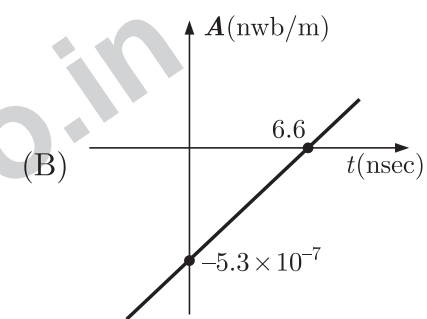
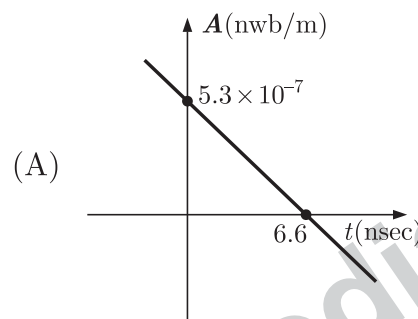
(B) $2 \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \text{ A/m}$

(C) $-4 \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \text{ A/m}$

(D) $4 \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \text{ A/m}$

MCQ 6.1.20

A current filament located on the x -axis in free space with in the interval $-0.1 < x < 0.1$ m carries current $I(t) = 8t$ A in \mathbf{a}_x direction. If the retarded vector potential at point $P(0, 0, 2)$ be $\mathbf{A}(t)$ then the plot of $\mathbf{A}(t)$ versus time will be

**Common Data For Q. 21 and 22 :**

In a region of electric and magnetic fields \mathbf{E} and \mathbf{B} , respectively, the force experienced by a test charge qC are given as follows for three different velocities.

Velocity m/sec

 \mathbf{a}_x \mathbf{a}_y \mathbf{a}_z

Force, N

 $q(\mathbf{a}_y + \mathbf{a}_z)$ $q\mathbf{a}_y$ $q(2\mathbf{a}_y + \mathbf{a}_z)$

MCQ 6.1.21

What will be the magnetic field \mathbf{B} in the region ?

(A) \mathbf{a}_x

(B) $\mathbf{a}_x - \mathbf{a}_y$

(C) \mathbf{a}_z

(D) $\mathbf{a}_y - \mathbf{a}_z$

Sample Chapter of **Electromagnetics (Vol-10, GATE Study Package)**

Page 371

Chap 6

Time Varying Fields and
Maxwell Equations

MCQ 6.1.22

What will be electric field \mathbf{E} in the region ?

- (A) $\mathbf{a}_x - \mathbf{a}_z$ (B) $\mathbf{a}_y - \mathbf{a}_z$
(C) $\mathbf{a}_y + \mathbf{a}_z$ (D) $\mathbf{a}_y + \mathbf{a}_z - \mathbf{a}_x$

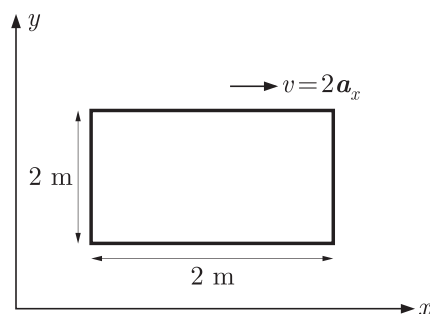
MCQ 6.1.23

In a non-conducting medium ($\sigma = 0$, $\mu_r = \epsilon_r = 1$), the retarded potentials are given as $V = y(x - ct)$ volt and $\mathbf{A} = y(\frac{x}{c} - t)\mathbf{a}_x$ Wb/m where c is velocity of waves in free space. The field (electric and magnetic) inside the medium satisfies Maxwell's equation if

- (A) $\mathbf{J} = 0$ only (B) $\rho_v = 0$ only
(C) $\mathbf{J} = \rho_v = 0$ (D) Can't be possible

MCQ 6.1.24

In Cartesian coordinates magnetic field is given by $\mathbf{B} = -2/x \mathbf{a}_z$. A square loop of side 2 m is lying in xy plane and parallel to the y -axis. Now, the loop is moving in that plane with a velocity $\mathbf{v} = 2\mathbf{a}_x$ as shown in the figure.



What will be the circulation of the induced electric field around the loop ?

- (A) $\frac{16}{x(x+2)}$ (B) $\frac{8}{x}$
(C) $\frac{8}{x(x+2)}$ (D) $\frac{x(x+2)}{16}$

Common Data For Q. 25 to 27 :

In a cylindrical coordinate system, magnetic field is given by

$$\mathbf{B} = \begin{cases} 0 & \text{for } \rho < 4 \text{ m} \\ 2 \sin \omega t \mathbf{a}_z & \text{for } 4 < \rho < 5 \text{ m} \\ 0 & \text{for } \rho > 5 \text{ m} \end{cases}$$

MCQ 6.1.25

The induced electric field in the region $\rho < 4$ m will be

- (A) 0 (B) $\frac{2\omega \cos \omega t}{\rho} \mathbf{a}_\phi$
(C) $-2 \cos \omega t \mathbf{a}_\phi$ (D) $\frac{1}{2 \sin \omega t} \mathbf{a}_\phi$

MCQ 6.1.26

The induced electric field at $\rho = 4.5$ m is

- (A) 0 (B) $-\frac{17\omega \cos \omega t}{18}$
(C) $\frac{4\omega \cos \omega t}{9}$ (D) $-\frac{17\omega \cos \omega t}{4}$

MCQ 6.1.27

The induced electric field in the region $\rho > 5$ m is

- (A) $-\frac{18}{\rho} \omega \cos \omega t \mathbf{a}_\phi$ (B) $-\frac{9\omega \cos \omega t}{\rho} \mathbf{a}_\phi$
(C) $-9\rho \cos \omega t \mathbf{a}_\phi$ (D) $\frac{9\omega \cos \omega t}{\rho} \mathbf{a}_\phi$

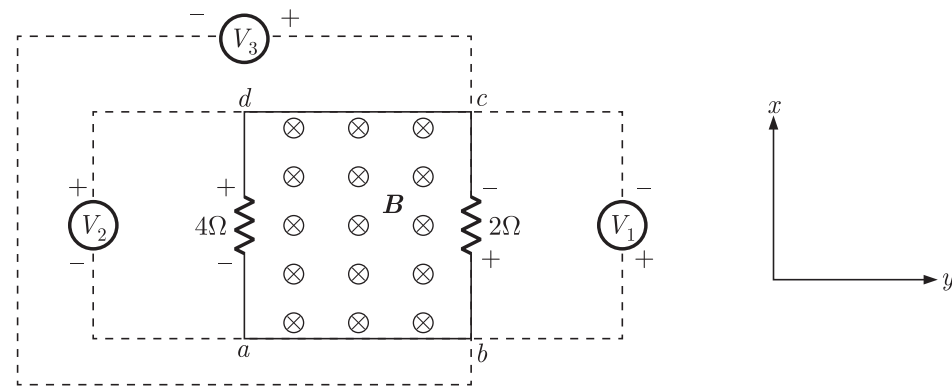
Page 372

Chap 6

Time Varying Fields and
Maxwell Equations

MCQ 6.1.28

Magnetic flux density, $\mathbf{B} = 0.1t \mathbf{a}_z$ Tesla threads only the loop $abcd$ lying in the plane xy as shown in the figure.

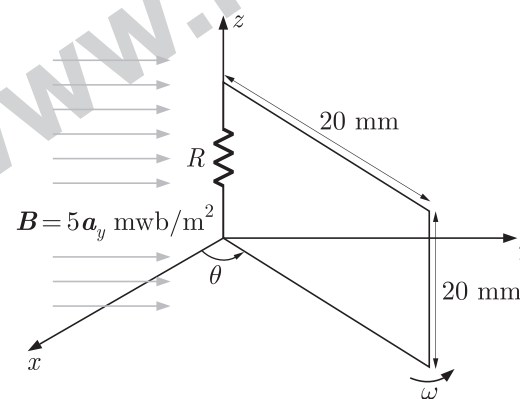


Consider the three voltmeters V_1 , V_2 and V_3 , connected across the resistance in the same xy plane. If the area of the loop $abcd$ is 1 m^2 then the voltmeter readings are

	V_1	V_2	V_3
(A)	66.7 mV	33.3 mV	66.7 mV
(B)	33.3 mV	66.7 mV	33.3 mV
(C)	66.7 mV	66.7 mV	33.3 mV
(D)	33.3 mV	66.7 mV	66.7 mV

Common Data For Q. 29 and 30 :

A square wire loop of resistance R rotated at an angular velocity ω in the uniform magnetic field $\mathbf{B} = 5\mathbf{a}_y \text{ mWb/m}^2$ as shown in the figure.



MCQ 6.1.29

If the angular velocity, $\omega = 2 \text{ rad/sec}$ then the induced e.m.f. in the loop will be

- | | |
|-----------------------------------|-----------------------------------|
| (A) $2 \sin \theta \mu\text{V/m}$ | (B) $2 \cos \theta \mu\text{V/m}$ |
| (C) $4 \cos \theta \mu\text{V/m}$ | (D) $4 \sin \theta \mu\text{V/m}$ |

MCQ 6.1.30

If resistance, $R = 40 \text{ m}\Omega$ then the current flowing in the square loop will be

- | | |
|----------------------------------|----------------------------------|
| (A) $0.2 \sin \theta \text{ mA}$ | (B) $0.1 \sin \theta \text{ mA}$ |
| (C) $0.1 \cos \theta \text{ mA}$ | (D) $0.5 \sin \theta \text{ mA}$ |

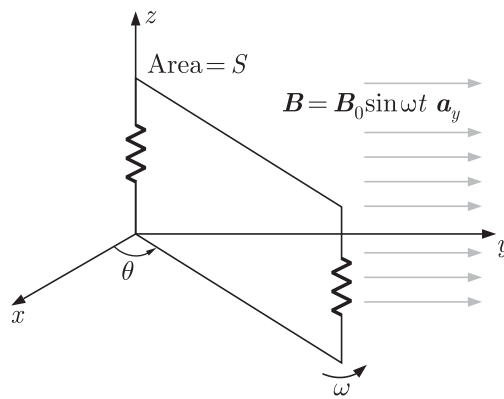
MCQ 6.1.31

In a certain region magnetic flux density is given as $\mathbf{B} = B_0 \sin \omega t \mathbf{a}_y$. A rectangular loop of wire is defined in the region with it's one corner at origin and one side along z -axis as shown in the figure.

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 373

Chap 6

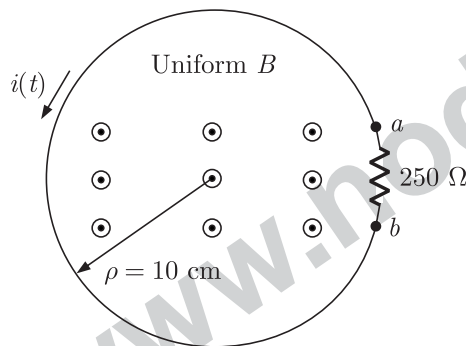
Time Varying Fields and
Maxwell Equations

If the loop rotates at an angular velocity ω (same as the angular frequency of magnetic field) then the maximum value of induced e.m.f in the loop will be

- (A) $\frac{1}{2} B_0 S \omega$ (B) $2 B_0 S \omega$
(C) $B_0 S \omega$ (D) $4 B_0 S \omega$

Common Data For Q. 32 and 33 :

Consider the figure shown below. Let $B = 10 \cos 120\pi t$ Wb/m² and assume that the magnetic field produced by $i(t)$ is negligible



MCQ 6.1.32

The value of v_{ab} is

- (A) $-118.43 \cos 120\pi t$ V (B) $118.43 \cos 120\pi t$ V
(C) $-118.43 \sin 120\pi t$ V (D) $118.43 \sin 120\pi t$ V

MCQ 6.1.33

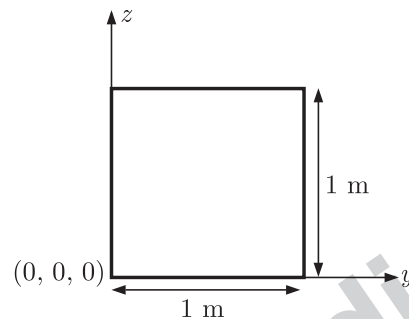
The value of $i(t)$ is

- (A) $-0.47 \cos 120\pi t$ A (B) $0.47 \cos 120\pi t$ A
(C) $-0.47 \sin 120\pi t$ A (D) $0.47 \sin 120\pi t$ A

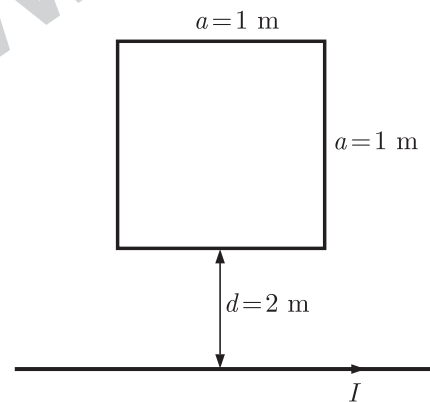
EXERCISE 6.2

QUES 6.2.1 A small conducting loop is released from rest with in a vertical evacuated cylinder. What is the voltage induced (in mV) in the falling loop ?
(Assume earth magnetic field = 10^{-6} T at a constant angle of 10° below the horizontal)

QUES 6.2.2 A square loop of side 1 m is located in the plane $x = 0$ as shown in figure. A non-uniform magnetic flux density through it is given as $\mathbf{B} = 4z^3 t^2 \mathbf{a}_x$. The emf induced in the loop at time $t = 2$ sec will be _____ Volt.



QUES 6.2.3 A very long straight wire carrying a current $I = 5$ A is placed at a distance of 2 m from a square loop as shown. If the side of the square loop is 1 m then the total flux passing through the square loop will be _____ $\times 10^{-7}$ wb



QUES 6.2.4 In a medium where no D.C. field is present, the conduction current density at any point is given as $\mathbf{J}_d = 20 \cos(1.5 \times 10^8 t) \mathbf{a}_y$ A/m². Electric flux density in the medium will be $D_0 \sin(1.5 \times 10^8 t) \mathbf{a}_y$ nC/m² such that $D_0 =$ _____

QUES 6.2.5 A conducting medium has permittivity, $\epsilon = 4\epsilon_0$ and conductivity, $\sigma = 1.14 \times 10^8$ s/m. The ratio of magnitude of displacement current and conduction current in the medium at 50 GHz will be _____ $\times 10^{-8}$.

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

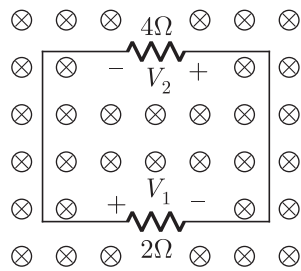
Page 375

Chap 6

Time Varying Fields and
Maxwell Equations

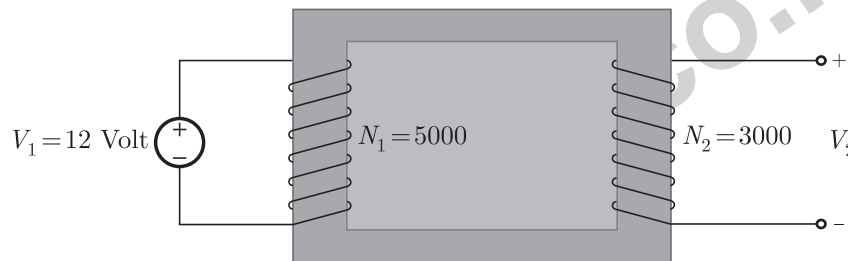
QUES 6.2.6

In a certain region magnetic flux density is given as $\mathbf{B} = 0.1t\mathbf{a}_z$ Wb/m². An electric loop with resistance 2Ω and 4Ω is lying in x - y plane as shown in the figure. If the area of the loop is 1 m^2 then, the voltage drop V_1 across the 2Ω resistance is _____ mV.



QUES 6.2.7

A magnetic core of uniform cross section having two coils (Primary and secondary) wound on it as shown in figure. The no. of turns of primary coil is 5000 and no. of turns of secondary coil is 3000. If a voltage source of 12 volt is connected across the primary coil then what will be the voltage (in Volt) across the secondary coil ?



QUES 6.2.8

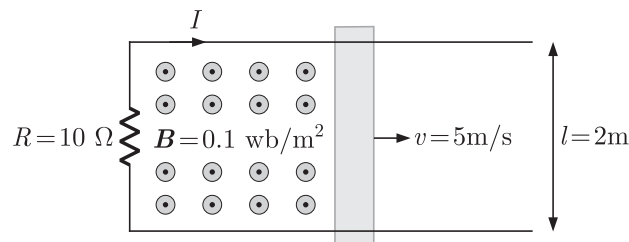
Magnetic field intensity in free space is given as

$$\mathbf{H} = 0.1 \cos(15\pi y) \sin(6\pi \times 10^9 t - bx) \mathbf{a}_z \text{ A/m}$$

It satisfies Maxwell's equation when $|b| = \text{_____}$

QUES 6.2.9

Two parallel conducting rails are being placed at a separation of 2 m as shown in figure. One end of the rail is being connected through a resistor $R = 10\Omega$ and the other end is kept open. A metal bar slides frictionlessly on the rails at a speed of 5 m/s away from the resistor. If the magnetic flux density $\mathbf{B} = 0.1\text{ Wb/m}^2$ pointing out of the page fills entire region then the current I flowing in the resistor will be _____ Ampere.



QUES 6.2.10

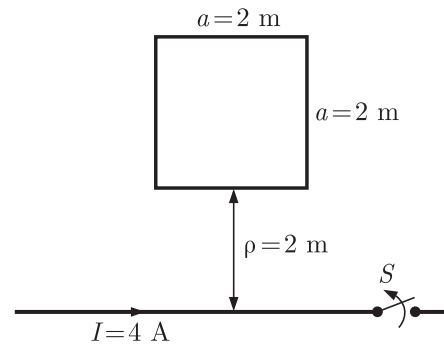
An infinitely long straight wire with a closed switch S carries a uniform current $I = 4\text{ A}$ as shown in figure. A square loop of side $a = 2\text{ m}$ and resistance

Page 376

Chap 6

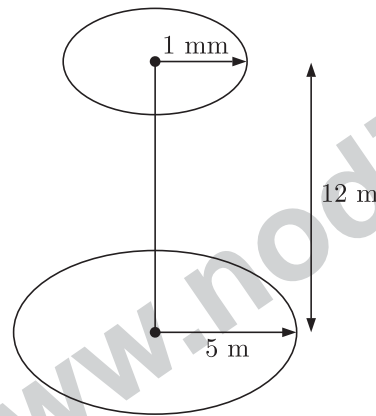
Time Varying Fields and
Maxwell Equations

$R = 4\ \Omega$ is located at a distance 2 m from the wire. Now at any time $t = t_0$ the switch is open so the current I drops to zero. What will be the total charge (in nC) that passes through a corner of the square loop after $t = t_0$?



QUES 6.2.11

A circular loop of radius 5 m carries a current $I = 2\text{ A}$. If another small circular loop of radius 1 mm lies a distance 12 m above the large circular loop such that the planes of the two loops are parallel and perpendicular to the common axis as shown in figure then total flux through the small loop will be _____ fermi-weber.



QUES 6.2.12

A non magnetic medium at frequency $f = 1.6 \times 10^8\text{ Hz}$ has permittivity $\epsilon = 54\epsilon_0$ and resistivity $\rho = 0.77\ \Omega\text{-m}$. What will be the ratio of amplitudes of conduction current to the displacement current ?

QUES 6.2.13

In a certain region a test charge is moving with an angular velocity 2 rad/sec along a circular path of radius 2 m centred at origin in the x - y plane. If the magnetic flux density in the region is $\mathbf{B} = 2\mathbf{a}_z\text{ Wb/m}^2$ then the electric field viewed by an observer moving with the test charge is _____ V/m in \mathbf{a}_ρ direction.

Common Data For Q. 13 and 14 :

In a non uniform magnetic field $\mathbf{B} = 8x^2\mathbf{a}_z\text{ Tesla}$, two parallel rails with a separation of 20 cm and connected with a voltmeter at it's one end is located in x - y plane as shown in figure. The Position of the bar which is sliding on the rails is given as

$$x = t(1 + 0.4t^2)$$

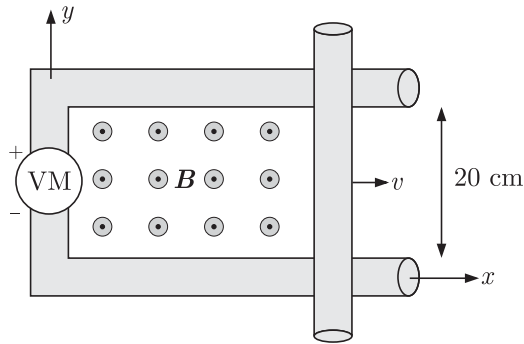
Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

QUES 6.2.14 What will be the voltmeter reading (in volt) at $t = 0.4$ sec ?

Page 377

Chap 6

Time Varying Fields and
Maxwell Equations



QUES 6.2.15 What will be the voltmeter reading (in volt) at $x = 12$ cm ?

QUES 6.2.16 In a non conducting medium ($\sigma = 0$) magnetic field intensity at any point is given by $\mathbf{H} = \cos(10^{10}t - bx)\mathbf{a}_z$ A/m. The permittivity of the medium is $\epsilon = 0.12$ nF/m and permeability of the medium is $\mu = 3 \times 10^{-5}$ H/m. D.C. field is not present in medium. Field satisfies Maxwell's equation, if $|b| =$ _____

QUES 6.2.17 Electric field in free space is given as

$$\mathbf{E} = 5 \sin(10\pi y) \cos(6\pi \times 10^9 - bx) \mathbf{a}_z$$

It satisfies Maxwell's equation for $|b| = ?$

QUES 6.2.18 8 A current is flowing along a straight wire from a point charge situated at the origin to infinity and passing through the point (2, 2, 2). The circulation of the magnetic field intensity around the closed path formed by the triangle having the vertices (2, 0, 0), (0, 2, 0) and (0, 0, 2) is equal to _____ Ampere.

QUES 6.2.19 A 50 turn rectangular loop of area 64 cm^2 rotates at 60 revolution per seconds in a magnetic field $\mathbf{B} = 0.25 \sin 377t$ Wb/m² directed normal to the axis of rotation. What is the rms value of the induced voltage (in volt) ?

EXERCISE 6.3

MCQ 6.3.1

Match List I with List II and select the correct answer using the codes given below (Notations have their usual meaning)

List-I

- a Ampere's circuital law
b Faraday's law
c Gauss's law

List-II

1. $\nabla \cdot \mathbf{D} = \rho_v$
2. $\nabla \cdot \mathbf{B} = 0$
3. $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$
4. $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$

Codes :

	a	b	c	d
(A)	4	3	2	1
(B)	4	1	3	2
(C)	2	3	1	4
(D)	4	3	1	2

MCQ 6.3.2

Magneto static fields is caused by

- (A) stationary charges
(B) steady currents
(C) time varying currents
(D) none of these

MCQ 6.3.3

Let \mathbf{A} be magnetic vector potential and \mathbf{E} be electric field intensity at certain time in a time varying EM field. The correct relation between \mathbf{E} and \mathbf{A} is

- (A) $\mathbf{E} = -\frac{\partial \mathbf{A}}{\partial t}$ (B) $\mathbf{A} = -\frac{\partial \mathbf{E}}{\partial t}$
(C) $\mathbf{E} = \frac{\partial \mathbf{A}}{\partial t}$ (D) $\mathbf{A} = \frac{\partial \mathbf{E}}{\partial t}$

MCQ 6.3.4

A closed surface S defines the boundary line of magnetic medium such that the field intensity inside it is \mathbf{B} . Total outward magnetic flux through the closed surface will be

- (A) $\mathbf{B} \cdot \mathbf{S}$ (B) 0
(C) $\mathbf{B} \times \mathbf{S}$ (D) none of these

MCQ 6.3.5

The total magnetic flux through a conducting loop having electric field $\mathbf{E} = 0$ inside it will be

- (A) 0
(B) constant
(C) varying with time only
(D) varying with time and area of the surface both

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 379

Chap 6

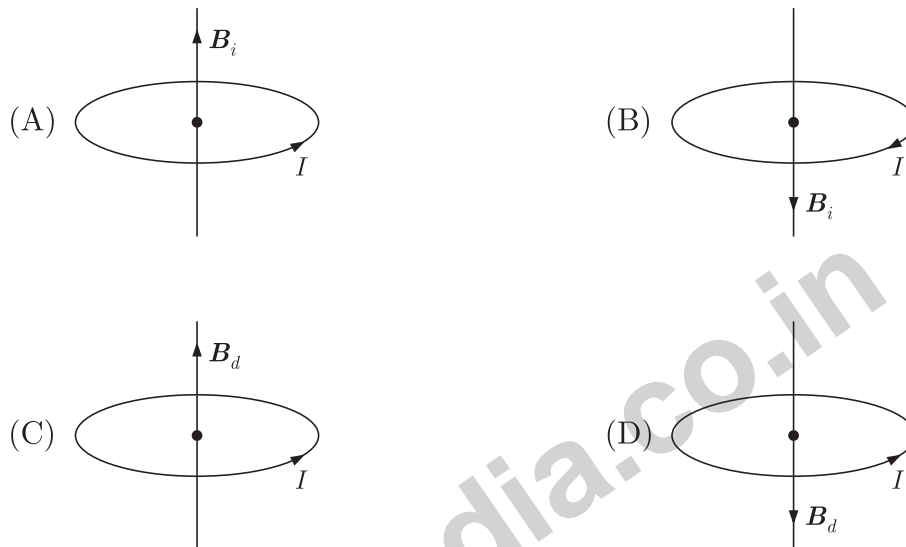
Time Varying Fields and
Maxwell Equations

MCQ 6.3.6

- A cylindrical wire of a large cross section made of super conductor carries a current I . The current in the superconductor will be confined.
- (A) inside the wire
 - (B) to the axis of cylindrical wire
 - (C) to the surface of the wire
 - (D) none of these

MCQ 6.3.7

- If B_i denotes the magnetic flux density increasing with time and B_d denotes the magnetic flux density decreasing with time then which of the configuration is correct for the induced current I in the stationary loop ?



MCQ 6.3.8

- A circular loop is rotating about z -axis in a magnetic field $\mathbf{B} = B_0 \cos \omega t \mathbf{a}_y$. The total induced voltage in the loop is caused by
- (A) Transformer emf
 - (B) motion emf.
 - (C) Combination of (A) and (B)
 - (D) none of these

MCQ 6.3.9

For static magnetic field,

- (A) $\nabla \times \mathbf{B} = \rho$
- (B) $\nabla \times \mathbf{B} = \mu \mathbf{J}$
- (C) $\nabla \cdot \mathbf{B} = \mu_0 J$
- (D) $\nabla \times \mathbf{B} = 0$

MCQ 6.3.10

Displacement current density is

- (A) \mathbf{D}
- (B) \mathbf{J}
- (C) $\partial \mathbf{D} / \partial t$
- (D) $\partial \mathbf{J} / \partial t$

MCQ 6.3.11

The time varying electric field is

- (A) $\mathbf{E} = -\nabla V$
- (B) $\mathbf{E} = -\nabla V - \dot{\mathbf{A}}$
- (C) $\mathbf{E} = -\nabla V - \mathbf{B}$
- (D) $\mathbf{E} = -\nabla V - \mathbf{D}$

MCQ 6.3.12

A field can exist if it satisfies

- (A) Gauss's law
- (B) Faraday's law
- (C) Coulomb's law
- (D) All Maxwell's equations

Page 380

Chap 6

Time Varying Fields and
Maxwell Equations

MCQ 6.3.13

Maxwell's equations give the relations between

- (A) different fields
- (B) different sources
- (C) different boundary conditions
- (D) none of these

MCQ 6.3.14

If \mathbf{E} is a vector, then $\nabla \cdot \nabla \times \mathbf{E}$ is

- (A) 0
- (B) 1
- (C) does not exist
- (D) none of these

MCQ 6.3.15

The Maxwell's equation, $\nabla \cdot \mathbf{B} = 0$ is due to

- (A) $\mathbf{B} = \mu \mathbf{H}$
- (B) $\mathbf{B} = \frac{\mathbf{H}}{\mu}$
- (C) non-existence of a mono pole
- (D) none of these

MCQ 6.3.16

For free space,

- (A) $\sigma = \infty$
- (B) $\sigma = 0$
- (C) $\mathbf{J} \neq 0$
- (D) none of these

MCQ 6.3.17

For time varying EM fields

- (A) $\nabla \times \mathbf{H} = \mathbf{J}$
- (B) $\nabla \times \mathbf{H} = \dot{\mathbf{D}} + \mathbf{J}$
- (C) $\nabla \times \mathbf{E} = 0$
- (D) none of these

EXERCISE 6.4

Page 381

Chap 6

Time Varying Fields and
Maxwell Equations

- MCQ 6.4.1 A magnetic field in air is measured to be $\mathbf{B} = B_0 \left(\frac{x}{x^2 + y^2} \mathbf{a}_y - \frac{y}{x^2 + y^2} \mathbf{a}_x \right)$. What current distribution leads to this field?
[Hint : The algebra is trivial in cylindrical coordinates.]
- (A) $\mathbf{J} = \frac{B_0 \mathbf{z}}{\mu_0} \left(\frac{1}{x^2 + y^2} \right), r \neq 0$ (B) $\mathbf{J} = -\frac{B_0 \mathbf{z}}{\mu_0} \left(\frac{2}{x^2 + y^2} \right), r \neq 0$
(C) $\mathbf{J} = 0, r \neq 0$ (D) $\mathbf{J} = \frac{B_0 \mathbf{z}}{\mu_0} \left(\frac{1}{x^2 + y^2} \right), r \neq 0$
- MCQ 6.4.2 For static electric and magnetic fields in an inhomogeneous source-free medium, which of the following represents the correct form of Maxwell's equations?
- (A) $\nabla \cdot \mathbf{E} = 0, \nabla \times \mathbf{B} = 0$ (B) $\nabla \cdot \mathbf{E} = 0, \nabla \cdot \mathbf{B} = 0$
(C) $\nabla \times \mathbf{E} = 0, \nabla \times \mathbf{B} = 0$ (D) $\nabla \times \mathbf{E} = 0, \nabla \cdot \mathbf{B} = 0$
- MCQ 6.4.3 If C is closed curve enclosing a surface S , then magnetic field intensity \mathbf{H} , the current density \mathbf{J} and the electric flux density \mathbf{D} are related by
- (A) $\iint_S \mathbf{H} \cdot d\mathbf{S} = \oint_C \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{l}$ (B) $\int_S \mathbf{H} \cdot d\mathbf{l} = \oint_C \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S}$
(C) $\oint_C \mathbf{H} \cdot d\mathbf{l} = \int_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{l}$ (D) $\oint_C \mathbf{H} \cdot d\mathbf{l} = \iint_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S}$
- MCQ 6.4.4 The unit of $\nabla \times \mathbf{H}$ is
- (A) Ampere (B) Ampere/meter
(C) Ampere/meter² (D) Ampere-meter
- MCQ 6.4.5 The Maxwell equation $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$ is based on
- (A) Ampere's law (B) Gauss' law
(C) Faraday's law (D) Coulomb's law
- MCQ 6.4.6 A loop is rotating about the y -axis in a magnetic field $\mathbf{B} = B_0 \cos(\omega t + \phi) \mathbf{a}_x$. The voltage in the loop is
- (A) zero
(B) due to rotation only
(C) due to transformer action only
(D) due to both rotation and transformer action
- MCQ 6.4.7 The credit of defining the following current is due to Maxwell
- (A) Conduction current (B) Drift current
(C) Displacement current (D) Diffusion current
- MCQ 6.4.8 A varying magnetic flux linking a coil is given by $\Phi = 1/3 \lambda t^3$. If at time $t = 3$ s, the emf induced is 9 V, then the value of λ is.
- (A) zero (B) 1 Wb/s²
(C) -1 Wb/s² (D) 9 Wb/s²

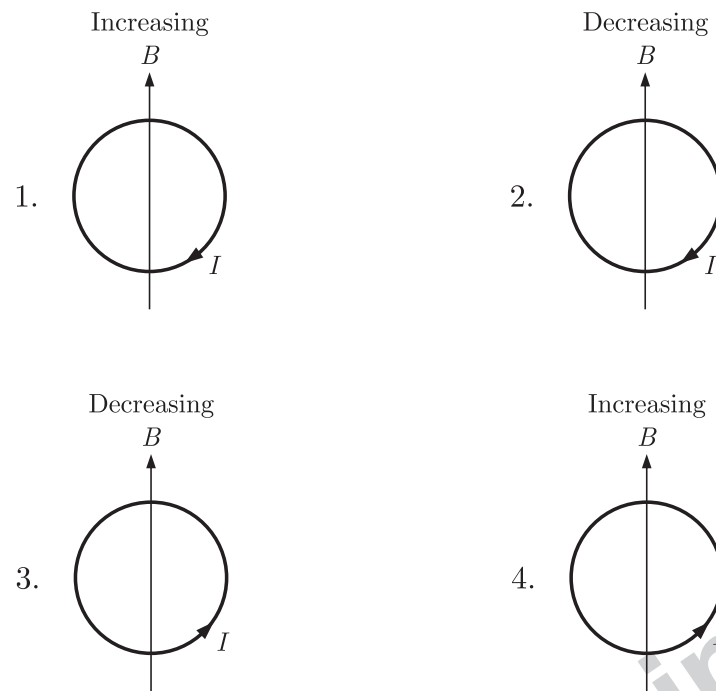
Page 382

Chap 6

Time Varying Fields and
Maxwell Equations

MCQ 6.4.9

Assuming that each loop is stationary and time varying magnetic field B , induces current I , which of the configurations in the figures are correct ?



- (A) 1, 2, 3 and 4
(C) 2 and 4 only

- (B) 1 and 3 only
(D) 3 and 4 only

MCQ 6.4.10

Assertion (A) : For time varying field the relation $\mathbf{E} = -\nabla V$ is inadequate.

Reason (R) : Faraday's law states that for time varying field $\nabla \times \mathbf{E} = 0$

- (A) Both **Assertion (A)** and **Reason (R)** are individually true and **Reason (R)** is the correct explanation of **Assertion (A)**
(B) Both **Assertion (A)** and **Reason (R)** are individually true but **Reason (R)** is not the correct explanation of **Assertion (A)**
(C) **Assertion (A)** is true but **Reason (R)** is false
(D) **Assertion (A)** is false but **Reason (R)** is true

MCQ 6.4.11

Who developed the concept of time varying electric field producing a magnetic field ?

- (A) Gauss (B) Faraday
(C) Hertz (D) Maxwell

MCQ 6.4.12

A single turn loop is situated in air, with a uniform magnetic field normal to its plane. The area of the loop is 5 m^2 and the rate of change of flux density is $2 \text{ Wb/m}^2/\text{s}$. What is the emf appearing at the terminals of the loop ?

- (A) -5 V (B) -2 V
(C) -0.4 V (D) -10 V

MCQ 6.4.13

Which of the following equations results from the circuital form of Ampere's law ?

- (A) $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$ (B) $\nabla \cdot \mathbf{B} = 0$
(C) $\nabla \cdot \mathbf{D} = \rho$ (D) $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$

MCQ 6.4.14

Assertion (A) : Capacitance of a solid conducting spherical body of radius a is given by $4\pi\epsilon_0 a$ in free space.

Sample Chapter of **Electromagnetics** (Vol-10, GATE Study Package)

Page 383

Chap 6

Time Varying Fields and
Maxwell Equations**Reason (R) :** $\nabla \times \mathbf{H} = j\omega\epsilon\mathbf{E} + \mathbf{J}$

- (A) Both A and R are individually true and R is the correct explanation of A.
- (B) Both A and R are individually true but R is not the correct explanation of A.
- (C) A is true but R is false
- (D) A is false but R is true

MCQ 6.4.15

Two conducting thin coils X and Y (identical except for a thin cut in coil Y) are placed in a uniform magnetic field which is decreasing at a constant rate. If the plane of the coils is perpendicular to the field lines, which of the following statement is correct ? As a result, emf is induced in

- (A) both the coils (B) coil Y only
- (C) coil X only (D) none of the two coils

MCQ 6.4.16

Assertion (A) : Time varying electric field produces magnetic fields.

Reason (R) : Time varying magnetic field produces electric fields.

- (A) Both A and R are true and R is the correct explanation of A
- (B) Both A and R are true but R is NOT the correct explanation of A
- (C) A is true but R is false
- (D) A is false but R is true

MCQ 6.4.17

Match List I (Electromagnetic Law) with List II (Different Form) and select the correct answer using the code given below the lists :

List-I

- a. Ampere's law
- b. Faraday's law
- c. Gauss law
- d. Current

List-II

1. $\nabla \cdot \mathbf{D} = \rho_v$
2. $\nabla \cdot \mathbf{J} = -\frac{\partial h}{\partial t}$
3. $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$
4. $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$

Codes :

- | | a | b | c | d |
|-----|---|---|---|---|
| (A) | 1 | 2 | 3 | 4 |
| (B) | 3 | 4 | 1 | 2 |
| (C) | 1 | 4 | 3 | 2 |
| (D) | 3 | 2 | 1 | 4 |

MCQ 6.4.18

Two metal rings 1 and 2 are placed in a uniform magnetic field which is decreasing with time with their planes perpendicular to the field. If the rings are identical except that ring 2 has a thin air gap in it, which one of the following statements is correct ?

- (A) No e.m.f is induced in ring 1
- (B) An e.m.f is induced in both the rings
- (C) Equal Joule heating occurs in both the rings
- (D) Joule heating does not occur in either ring.

Page 384

Chap 6

Time Varying Fields and
Maxwell Equations

MCQ 6.4.19

Which one of the following Maxwell's equations gives the basic idea of radiation ?

$$(A) \left. \begin{aligned} \nabla \times \mathbf{H} &= \frac{\partial \mathbf{D}}{\partial t} \\ \nabla \times \mathbf{E} &= \frac{\partial \mathbf{B}}{\partial t} \end{aligned} \right\}$$

$$(C) \left. \begin{aligned} \nabla \cdot \mathbf{D} &= \rho \\ \nabla \cdot \mathbf{D} &= 0 \end{aligned} \right\}$$

$$(B) \left. \begin{aligned} \nabla \times \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t} \\ \nabla \cdot \mathbf{D} &= -\frac{\partial \mathbf{B}}{\partial t} \end{aligned} \right\}$$

$$(D) \left. \begin{aligned} \nabla \cdot \mathbf{B} &= \rho \\ \nabla \times \mathbf{H} &= (\partial \mathbf{D} / \partial t) \end{aligned} \right\}$$

MCQ 6.4.20

Which one of the following is NOT a correct Maxwell equation ?

$$(A) \nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t} + \mathbf{J}$$

$$(C) \nabla \cdot \mathbf{D} = \rho$$

$$(B) \nabla \times \mathbf{E} = \frac{\partial \mathbf{H}}{\partial t}$$

$$(D) \nabla \cdot \mathbf{B} = 0$$

MCQ 6.4.21

Match List I (Maxwell equation) with List II (Description) and select the correct answer :

List I

a. $\oint \mathbf{B} \cdot d\mathbf{S} = 0$

b. $\oint \mathbf{D} \cdot d\mathbf{S} = \int_V \rho_v dv$

c. $\oint \mathbf{E} \cdot d\mathbf{l} = -\int \frac{\partial \mathbf{B}}{\partial t} \cdot d\mathbf{S}$

d. $\oint \mathbf{H} \cdot d\mathbf{l} = \int \frac{\partial(\mathbf{D} + \mathbf{J})}{\partial t} \cdot d\mathbf{S}$

List II

1. The mmf around a closed path is equal to the conduction current plus the time derivative of the electric displacement current through any surface bounded by the path.

2. The emf around a closed path is equal to the time derivative is equal to the time derivative of the magnetic displacement through any surface bounded by the path.

3. The total electric displacement through the surface enclosing a volume is equal to total charge within the volume

4. The net magnetic flux emerging through any closed surface is zero.

Codes :

	a	b	c	d
(A)	1	3	2	4
(B)	4	3	2	1
(C)	4	2	3	1
(D)	1	2	3	4

MCQ 6.4.22

The equation of continuity defines the relation between

(A) electric field and magnetic field

(B) electric field and charge density

(C) flux density and charge density

(D) current density and charge density

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 385

Chap 6

Time Varying Fields and
Maxwell Equations

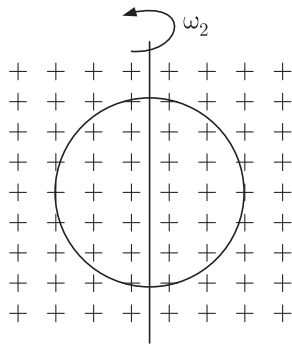
MCQ 6.4.23 What is the generalized Maxwell's equation $\nabla \times \mathbf{H} = \mathbf{J}_c + \frac{\partial \mathbf{D}}{\partial t}$ for the free space ?

- (A) $\nabla \times \mathbf{H} = 0$ (B) $\nabla \times \mathbf{H} = \mathbf{J}_c$
(C) $\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t}$ (D) $\nabla \times \mathbf{H} = \mathbf{D}$

MCQ 6.4.24 Magnetic field intensity is $\mathbf{H} = 3\mathbf{a}_x + 7y\mathbf{a}_y + 2x\mathbf{a}_z$ A/m. What is the current density \mathbf{J} A/m² ?

- (A) $-2\mathbf{a}_y$ (B) $-7\mathbf{a}_z$
(C) $3\mathbf{a}_x$ (D) $12\mathbf{a}_y$

MCQ 6.4.25 A circular loop placed perpendicular to a uniform sinusoidal magnetic field of frequency ω_1 is revolved about an axis through its diameter at an angular velocity ω_2 rad/sec ($\omega_2 < \omega_1$) as shown in the figure below. What are the frequencies for the e.m.f induced in the loop ?



- (A) ω_1 and ω_2 (B) $\omega_1, \omega_2 + \omega_2$ and ω_2
(C) $\omega_2, \omega_1 - \omega_2$ and ω_2 (D) $\omega_1 - \omega_2$ and $\omega_1 + \omega_2$

MCQ 6.4.26 Which one of the following is not a Maxwell's equation ?

- (A) $\nabla \times \mathbf{H} = (\sigma + j\omega\epsilon)\mathbf{E}$ (B) $\mathbf{F} = Q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$
(C) $\oint_c \mathbf{H} \cdot d\mathbf{l} = \oint_s \mathbf{J} \cdot d\mathbf{S} + \oint_s \frac{\partial \mathbf{D}}{\partial t} \cdot d\mathbf{S}$ (D) $\oint_s \mathbf{B} \cdot d\mathbf{S} = 0$

MCQ 6.4.27 Consider the following three equations :

1. $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$
2. $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$
3. $\nabla \cdot \mathbf{B} = 0$

Which of the above appear in Maxwell's equations ?

- (A) 1, 2 and 3 (B) 1 and 2
(C) 2 and 3 (D) 1 and 3

MCQ 6.4.28 In free space, if $\rho_v = 0$, the Poisson's equation becomes

- (A) Maxwell's divergence equation $\nabla \cdot \mathbf{B} = 0$
(B) Laplacian equation $\nabla^2 V = 0$
(C) Kirchhoff's voltage equation $\sum V = 0$
(D) None of the above

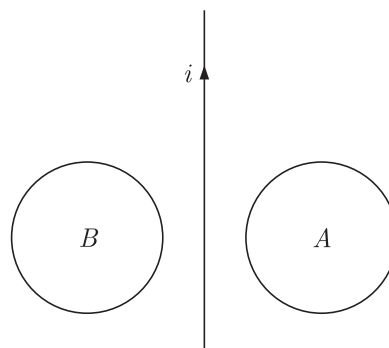
Page 386

Chap 6

Time Varying Fields and
Maxwell Equations

MCQ 6.4.29

A straight current carrying conductor and two conducting loops A and B are shown in the figure given below. What are the induced current in the two loops ?



- (A) Anticlockwise in A and clockwise in B
 (B) Clockwise in A and anticlockwise in B
 (C) Clockwise both in A and B
 (D) Anticlockwise both in A and B

MCQ 6.4.30

Which one of the following equations is not Maxwell's equation for a static electromagnetic field in a linear homogeneous medium ?

- (A) $\nabla \cdot \mathbf{B} = 0$ (B) $\nabla \times \mathbf{D} = \vec{0}$
 (C) $\oint_c \mathbf{B} \cdot d\mathbf{l} = \mu_0 I$ (D) $\nabla^2 \mathbf{A} = \mu_0 \mathbf{J}$

MCQ 6.4.31

Match **List I** with **List II** and select the correct answer using the codes given below :

List I

- a Continuity equation
 b Ampere's law
 c Displacement current
 d Faraday's law

List II

1. $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$
 2. $\mathbf{J} = \frac{\partial \mathbf{D}}{\partial t}$
 3. $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$
 4. $\nabla \times \mathbf{J} = -\frac{\partial \rho_v}{\partial t}$

Codes :

- | | a | b | c | d |
|-----|---|---|---|---|
| (A) | 4 | 3 | 2 | 1 |
| (B) | 4 | 1 | 2 | 3 |
| (C) | 2 | 3 | 4 | 1 |
| (D) | 2 | 1 | 4 | 3 |

MCQ 6.4.32

The magnetic flux through each turn of a 100 turn coil is $(t^3 - 2t)$ milli-Webers where t is in seconds. The induced e.m.f at $t = 2$ s is

- (A) 1 V (B) -1 V
 (C) 0.4 V (D) -0.4 V

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

MCQ 6.4.33

Match **List I** (Type of field denoted by **A**) with **List II** (Behaviour) and select the correct answer using the codes given below :

Page 387

Chap 6

Time Varying Fields and
Maxwell Equations

List I	List II
a A static electric field in a charge free region	1. $\nabla \cdot \mathbf{A} = 0$ $\nabla \times \mathbf{A} \neq 0$
b A static electric field in a charged region	2. $\nabla \cdot \mathbf{A} \neq 0$ $\nabla \times \mathbf{A} = 0$
c A steady magnetic field in a current carrying conductor	3. $\nabla \cdot \mathbf{A} \neq 0$ $\nabla \times \mathbf{A} \neq 0$
d A time-varying electric field in a charged medium with time-varying magnetic field	4. $\nabla \cdot \mathbf{A} = 0$ $\nabla \times \mathbf{A} = 0$

Codes :

	a	b	c	d
(A)	4	2	3	1
(B)	4	2	1	3
(C)	2	4	3	1
(D)	2	4	1	3

MCQ 6.4.34

Which one of the following pairs is not correctly matched ?

(A) Gauss Theorem :	$\oint_s \mathbf{D} \cdot d\mathbf{s} = \oint_v \nabla \cdot \mathbf{D} dv$
(B) Gauss's Law :	$\oint \mathbf{D} \cdot d\mathbf{s} = \oint_v \rho dv$
(C) Coulomb's Law :	$V = -\frac{d\phi_m}{dt}$
(D) Stoke's Theorem :	$\oint \boldsymbol{\xi} \cdot d\mathbf{l} = \oint_s (\nabla \times \boldsymbol{\xi}) \cdot d\mathbf{s}$

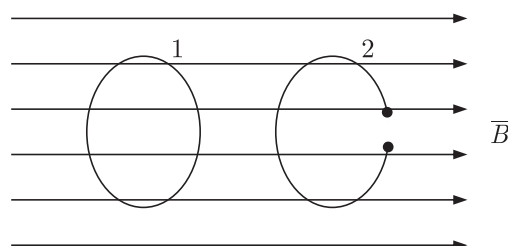
MCQ 6.4.35

Maxwell equation $\nabla \times \mathbf{E} = -(\partial \mathbf{B} / \partial t)$ is represented in integral form as

(A) $\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \oint \mathbf{B} \cdot d\mathbf{l}$	(B) $\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \int_s \mathbf{B} \cdot d\mathbf{s}$
(C) $\oint \mathbf{E} \times d\mathbf{l} = -\frac{\partial}{\partial t} \oint \mathbf{B} \cdot d\mathbf{l}$	(D) $\oint \mathbf{E} \times d\mathbf{l} = -\frac{\partial}{\partial t} \int_s \mathbf{B} \cdot d\mathbf{l}$

MCQ 6.4.36

Two conducting coils 1 and 2 (identical except that 2 is split) are placed in a uniform magnetic field which decreases at a constant rate as in the figure. If the planes of the coils are perpendicular to the field lines, the following statements are made :



1. an e.m.f is induced in the split coil 2
2. e.m.fs are induced in both coils

Page 388

Chap 6

Time Varying Fields and
Maxwell Equations

3. equal Joule heating occurs in both coils

4. Joule heating does not occur in any coil

Which of the above statements is/are true ?

(A) 1 and 4

(B) 2 and 4

(C) 3 only

(D) 2 only

MCQ 6.4.37

For linear isotropic materials, both \mathbf{E} and \mathbf{H} have the time dependence $e^{j\omega t}$ and regions of interest are free of charge. The value of $\nabla \times \mathbf{H}$ is given by(A) $\sigma \mathbf{E}$ (B) $j\omega \epsilon \mathbf{E}$ (C) $\sigma \mathbf{E} + j\omega \epsilon \mathbf{E}$ (D) $\sigma \mathbf{E} - j\omega \epsilon \mathbf{E}$

MCQ 6.4.38

Which of the following equations is/are not Maxwell's equations(s) ?

(A) $\nabla \cdot \mathbf{J} = -\frac{\partial \rho_v}{\partial t}$ (B) $\nabla \cdot \mathbf{D} = \rho_v$ (C) $\nabla \cdot \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$ (D) $\oint \mathbf{H} \cdot d\mathbf{l} = \int_s \left(\sigma \mathbf{E} + \epsilon \frac{\partial \mathbf{E}}{\partial t} \right) \cdot d\mathbf{s}$

Select the correct answer using the codes given below :

(A) 2 and 4

(B) 1 alone

(C) 1 and 3

(D) 1 and 4

MCQ 6.4.39

Assertion (A) : The relationship between Magnetic Vector potential \mathbf{A} and the current density \mathbf{J} in free space is

$$\nabla \times (\nabla \times \mathbf{A}) = \mu_0 \mathbf{J}$$

For a magnetic field in free space due to a dc or slowly varying current is $\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}$ **Reason (R) :** For magnetic field due to dc or slowly varying current $\nabla \cdot \mathbf{A} = 0$.

(A) Both A and R are true and R is the correct explanation of A

(B) Both A and R are true but R is NOT the correct explanation of A

(C) A is true but R is false

(D) A is false but R is true

MCQ 6.4.40

Given that $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$ **Assertion (A) :** In the equation, the additional term $\frac{\partial \mathbf{D}}{\partial t}$ is necessary.**Reason (R) :** The equation will be consistent with the principle of conservation of charge.

(A) Both A and R are true and R is the correct explanation of A

(B) Both A and R are true but R is NOT the correct explanation of A

(C) A is true but R is false

(D) A is false but R is true

MCQ 6.4.41

A circular loop is rotating about the y -axis as a diameter in a magnetic field $\mathbf{B} = B_0 \sin \omega t \mathbf{a}_x$ Wb/m². The induced emf in the loop is

(A) due to transformer emf only

(B) due to motional emf only

(C) due to a combination of transformer and motional emf

(D) zero

Sample Chapter of **Electromagnetics (Vol-10, GATE Study Package)**

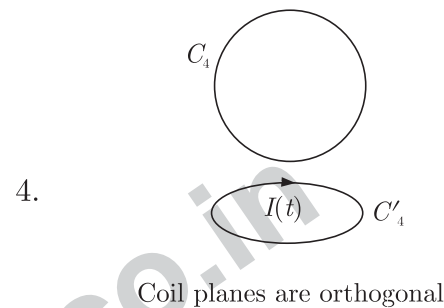
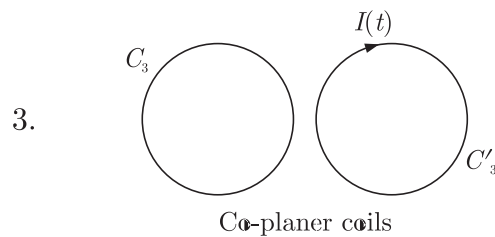
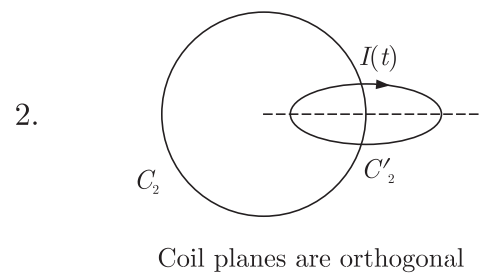
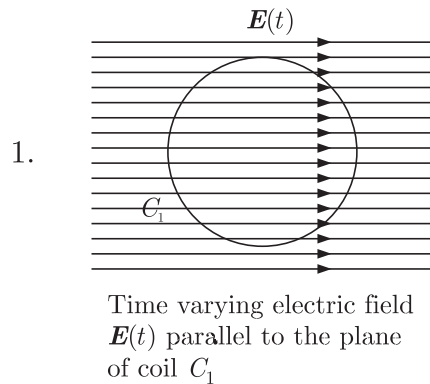
Page 389

Chap 6

Time Varying Fields and
Maxwell Equations

MCQ 6.4.42

Consider coils C_1 , C_2 , C_3 and C_4 (shown in the given figures) which are placed in the time-varying electric field $E(t)$ and electric field produced by the coils C'_2 , C'_3 and C'_4 carrying time varying current $I(t)$ respectively :



The electric field will induce an emf in the coils

- (A) C_1 and C_2 (B) C_2 and C_3
(C) C_1 and C_3 (D) C_2 and C_4

MCQ 6.4.43

Match **List I** (Law/quantity) with **List II** (Mathematical expression) and select the correct answer :

- | List I | List II |
|--------------------|--|
| a. Gauss's law | 1. $\nabla \cdot D = \rho$ |
| b. Ampere's law | 2. $\nabla \times E = -\frac{\partial B}{\partial t}$ |
| c. Faraday's law | 3. $\mathcal{P} = E \times H$ |
| d. Poynting vector | 4. $F = q(E + v \times B)$ |
| | 5. $\nabla \times H = J_c + \frac{\partial D}{\partial t}$ |

Codes :

- | | a | b | c | d |
|-----|---|---|---|---|
| (A) | 1 | 2 | 4 | 3 |
| (B) | 3 | 5 | 2 | 1 |
| (C) | 1 | 5 | 2 | 3 |
| (D) | 3 | 2 | 4 | 1 |

SOLUTIONS 6.1

SOL 6.1.1

Option (C) is correct.

From Faraday's law, the relation between electric field and magnetic field is

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

Since the electric field inside a conducting sphere is zero.

$$\text{i.e.} \quad \mathbf{E} = 0$$

So the rate of change in magnetic flux density will be

$$\frac{\partial \mathbf{B}}{\partial t} = -(\nabla \times \mathbf{E}) = 0$$

Therefore $\mathbf{B}(r, t)$ will be uniform inside the sphere and independent of time.

SOL 6.1.2

Option (A) is correct.

Electric field intensity experienced by the moving conductor ab in the presence of magnetic field \mathbf{B} is given as

$$\mathbf{E} = \mathbf{v} \times \mathbf{B} \quad \text{where } \mathbf{v} \text{ is the velocity of the conductor.}$$

So, electric field will be directed from b to a as determined by right hand rule for the cross vector. Therefore, the voltage difference between the two ends of the conductor is given as

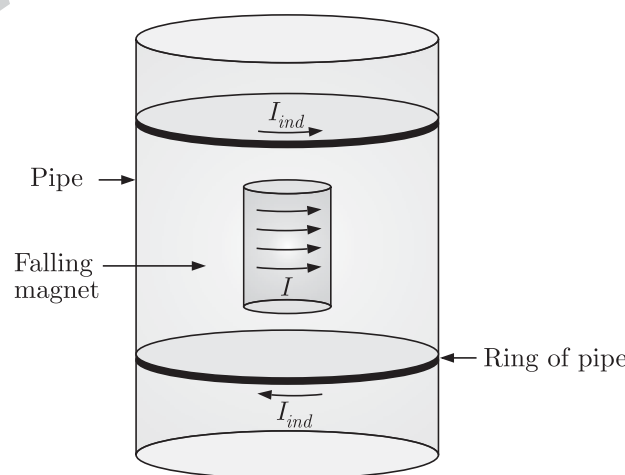
$$V_{ab} = -\int_a^b \mathbf{E} \cdot d\mathbf{l}$$

Thus, the positive terminal of voltage will be a and V_{ab} will be positive.

SOL 6.1.3

Option (A) is correct.

Consider a magnet bar being dropped inside a pipe as shown in figure.



Suppose the current I in the magnet flows counter clockwise (viewed from above) as shown in figure. So near the ends of pipe, it's field points upward. A ring of pipe below the magnet experiences an increasing upward flux as the magnet approaches and hence by Lenz's law a current will be induced in it such as to produce downward flux.

Thus, I_{ind} must flow clockwise which is opposite to the current in the magnet.

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 391

Chap 6

Time Varying Fields and
Maxwell Equations

Since opposite currents repel each other so, the force exerted on the magnet due to the induced current is directed upward. Meanwhile a ring above the magnet experiences a decreasing upward flux; so it's induced current parallel to I and it attracts magnet upward. And flux through the rings next to the magnet bar is constant. So no current is induced in them.

Thus, for all we can say that the force exerted by the eddy current (induced current according to Lenz's law) on the magnet is in upward direction which causes the delay to reach the bottom. Whereas in the cases of unmagnetized bar no induced current is formed. So it reaches in fraction of time.

Thus, A and R both true and R is correct explanation of A.

SOL 6.1.4

Option (C) is correct.

The magnetic flux density inside a solenoid of n turns per unit length carrying current I is defined as

$$B = \mu_0 n I$$

Let the length of solenoid be l and its cross sectional radius be r . So, the total magnetic flux through the solenoid is

$$\Phi = (\mu_0 n I) (\pi r^2) (nl) \quad (1)$$

Since the total magnetic flux through a coil having inductance L and carrying current I is given as

$$\Phi = LI$$

So comparing it with equation (1) we get,

$$L = \mu_0 n^2 I \pi^2 l$$

and as for a given solenoid, radius r and length l is constant therefore

$$L \propto n^2$$

SOL 6.1.5

Option (C) is correct.

The magnetic flux density inside the solenoid is defined as

$$B = \mu_0 n I$$

where

$n \rightarrow$ no. of turns per unit length

$I \rightarrow$ current flowing in it.

So the total magnetic flux through the solenoid is

$$\Phi = \int \mathbf{B} \cdot d\mathbf{S} = (\mu_0 n I) (\pi a^2)$$

where

$a \rightarrow$ radius of solenoid

Induced emf in a loop placed in a magnetic field is defined as

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

where Φ is the total magnetic flux passing through the loop. Since the resistance R is looped over the solenoid so total flux through the loop will be equal to the total flux through the solenoid and therefore the induced emf in the loop of resistance will be

$$V_{\text{emf}} = -\pi a^2 \mu_0 n \frac{dI}{dt}$$

Since current I flowing in the solenoid is constant so, the induced emf is

$$V_{\text{emf}} = 0$$

and therefore the induced current in the loop will be zero.

SOL 6.1.6

Option (B) is correct.

Page 392

Chap 6

Time Varying Fields and
Maxwell Equations

It will be similar to the current in a solenoid.

So, the magnetic field will be in circumferential while the electric field is longitudinal.

SOL 6.1.7

Option (B) is correct.

In Assertion (A) the magnetic flux through each turn of both coils are equal

So, the net magnetic flux through the two coils are respectively

$$\Phi_1 = N_1 \Phi$$

and

$$\Phi_2 = N_2 \Phi$$

where Φ is the magnetic flux through a single loop of either coil and N_1 , N_2 are the total no. of turns of the two coils respectively.

Therefore the induced emf in the two coils are

$$V_{\text{emf}1} = -\frac{d\Phi_1}{dt} = -N_1 \frac{d\Phi}{dt}$$

$$V_{\text{emf}2} = -\frac{d\Phi_2}{dt} = -N_2 \frac{d\Phi}{dt}$$

Thus, the ratio of the induced emf in the two loops are

$$\frac{V_{\text{emf}2}}{V_{\text{emf}1}} = \frac{N_2}{N_1}$$

Now, in Reason (R) : a primitive transformer is similar to the cylinder core carrying wound coils. It is the device in which by choosing the appropriate no. of turns, any desired secondary emf can be obtained.

So, both the statements are correct but R is not the explanation of A.

SOL 6.1.8

Option (B) is correct.

Electric flux density in the medium is given as

$$D = \epsilon E = \epsilon E_0 \cos \omega t \quad (E = E_0 \cos \omega t)$$

Therefore the displacement current density in the medium is

$$J_d = \frac{\partial D}{\partial t} = -\omega \epsilon E_0 \sin \omega t$$

and the conduction current density in the medium is

$$J_c = \sigma E = \sigma E_0 \cos \omega t$$

So, the ratio of amplitudes of conduction current density and displacement current density is

$$\frac{|J_c|}{|J_d|} = \frac{\sigma}{\omega \epsilon}$$

SOL 6.1.9

Option (C) is correct.

Given the volume charge density, $\rho_v = 0$

So, from Maxwell's equation we have

$$\nabla \cdot \mathbf{D} = \rho_v$$

$$\nabla \cdot \mathbf{D} = 0 \quad (1)$$

Now, the electric flux density in a medium is defined as

$$\mathbf{D} = \epsilon \mathbf{E} \quad (\text{where } \epsilon \text{ is the permittivity of the medium})$$

So, putting it in equation (1) we get,

$$\nabla \cdot (\epsilon \mathbf{E}) = 0$$

$$\text{or, } \mathbf{E} \cdot (\nabla \epsilon) + \epsilon (\nabla \cdot \mathbf{E}) = 0$$

$$\text{and since } \frac{\nabla \epsilon}{\epsilon} \approx 0 \Rightarrow \nabla \epsilon \approx 0 \quad (\text{given})$$

$$\text{Therefore, } \nabla \cdot \mathbf{E} \approx 0$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 393

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.1.10

Option (A) is correct.

Given the electric field intensity in time domain as

$$\mathbf{E} = \frac{\sin \theta \cos(\omega t - kr)}{r} \mathbf{a}_\theta$$

So, the electric field intensity in phasor form is given as

$$\mathbf{E}_s = \frac{\sin \theta}{r} e^{-jkr} \mathbf{a}_\theta$$

$$\text{and } \nabla \times \mathbf{E}_s = \frac{1}{r} \frac{\partial}{\partial r} (r E_{\theta s}) \mathbf{a}_\phi = (-jk) \frac{\sin \theta}{r} e^{-jkr} \mathbf{a}_\phi$$

Therefore, from Maxwell's equation we get the magnetic field intensity as

$$\mathbf{H}_s = -\frac{\nabla \times \mathbf{E}_s}{j\omega \mu_0} = \frac{k}{\omega \mu_0} \frac{\sin \theta}{r} e^{-jkr} \mathbf{a}_\phi$$

SOL 6.1.11

Option (B) is correct.

Magnetic flux density produced at a distance ρ from a long straight wire carrying current I is defined as

$$\mathbf{B} = \frac{\mu_0 I}{2\pi \rho} \mathbf{a}_\phi$$

where \mathbf{a}_ϕ is the direction of flux density as determined by right hand rule. So, the magnetic flux density produced by the straight conducting wire linking through the loop is normal to the surface of the loop.

Now consider a strip of width $d\rho$ of the square loop at distance ρ from the wire for which the total magnetic flux linking through the square loop is given as

$$\begin{aligned} \Phi &= \int_S \mathbf{B} \cdot d\mathbf{S} \\ &= \frac{\mu_0 I}{2\pi} \int_{\rho}^{\rho+a} \frac{1}{\rho} (a d\rho) \quad (\text{area of the square loop is } dS = a d\rho) \\ &= \frac{\mu_0 I a}{2\pi} \ln\left(\frac{\rho+a}{\rho}\right) \end{aligned}$$

The induced emf due to the change in flux (when pulled away) is given as

$$V_{\text{emf}} = -\frac{d\Phi}{dt} = -\frac{\mu_0 I a}{2\pi} \frac{d}{dt} \left[\ln\left(\frac{\rho+a}{\rho}\right) \right]$$

$$\text{Therefore, } V_{\text{emf}} = -\frac{\mu_0 I a}{2\pi} \left(\frac{1}{\rho+a} \frac{d\rho}{dt} - \frac{1}{\rho} \frac{d\rho}{dt} \right)$$

$$\text{Given } \frac{d\rho}{dt} = \text{velocity of loop} = 5 \text{ m/s}$$

and since the loop is currently located at 3 m distance from the straight wire, so after 0.6 sec it will be at

$$\begin{aligned} \rho &= 3 + (0.6) \times v \quad (v \rightarrow \text{velocity of the loop}) \\ &= 3 + 0.6 \times 5 = 6 \text{ m} \end{aligned}$$

$$\begin{aligned} \text{So, } V_{\text{emf}} &= -\frac{\mu_0 \times (30) \times 2}{2\pi} \left[\frac{1}{8} (5) - \frac{1}{6} (5) \right] \quad (a = 2 \text{ m}, I = 30 \text{ A}) \\ &= 25 \times 10^{-7} \text{ volt} = 2.5 \mu\text{volt} \end{aligned}$$

SOL 6.1.12

Option (B) is correct.

Since total magnetic flux through the loop depends on the distance from the straight wire and the distance is constant. So the flux linking through the loop will be constant, if it is pulled parallel to the straight wire. Therefore the induced emf in the loop is

$$V_{\text{emf}} = -\frac{d\Phi}{dt} = 0 \quad (\Phi \text{ is constant})$$

Page 394

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.1.13

Option (D) is correct.

Total magnetic flux through the solenoid is given as

$$\Phi = \mu_0 n I$$

where n is the no. of turns per unit length of solenoid and I is the current flowing in the solenoid.

Since the solenoid carries current that is increasing linearly with time

i.e. $I \propto t$

So the net magnetic flux through the solenoid will be

$$\Phi \propto t$$

or,

$$\Phi = kt$$

where k is a constant.

Therefore the emf induced in the loop consisting resistances R_A , R_B is

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

$$V_{\text{emf}} = -k$$

and the current through R_1 and R_2 will be

$$I_{\text{ind}} = -\frac{k}{R_1 + R_2}$$

Now according to Lenz's law the induced current I in a loop flows such as to produce a magnetic field that opposes the change in $\mathbf{B}(t)$.

i.e. the induced current in the loop will be opposite to the direction of current in solenoid (in anticlockwise direction).

So,

$$V_A = I_{\text{ind}} R_A = -\frac{k R_A}{R_A + R_B}$$

and

$$V_B = -I_{\text{ind}} R_B = \left(\frac{k R_B}{R_A + R_B} \right)$$

Thus, the ratio of voltmeter readings is

$$\frac{V_A}{V_B} = -\frac{R_A}{R_B}$$

SOL 6.1.14

Option (D) is correct.

Induced emf in the conducting loop formed by rail, bar and the resistor is given by

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

where Φ is total magnetic flux passing through the loop.

The bar is located at a distance x from the resistor at time t . So the total magnetic flux passing through the loop at time t is

$$\Phi = \int \mathbf{B} \cdot d\mathbf{S} = B l x \quad \text{where } l \text{ is separation between the}$$

rails

Now the induced emf in a loop placed in magnetic field is defined as

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

where Φ is the total magnetic flux passing through the loop. Therefore the induced emf in the square loop is

$$V_{\text{emf}} = -\frac{d}{dt}(B l x) = -B l \frac{dx}{dt} \quad (\Phi = B l x)$$

Since from the given figure, we have

$$l = 5 \text{ m}$$

$$B = 2 \text{ T}$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 395

Chap 6

Time Varying Fields and
Maxwell Equationsand $dx/dt \rightarrow$ velocity of bar = 4 m/s

So, induced emf is

$$V_{\text{emf}} = - (2) (5) (4) = -40 \text{ volt}$$

Therefore the current in the bar loop will be

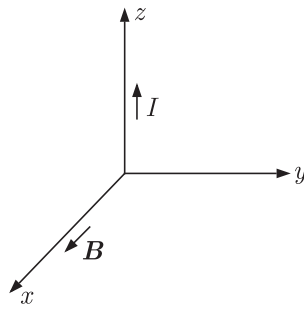
$$I = \frac{V_{\text{emf}}}{R} = -\frac{40}{10} = -4 \text{ A}$$

SOL 6.1.15

Option (B) is correct.

As obtained in the previous question the current flowing in the sliding bar is

$$I = -4 \text{ A}$$

Now we consider magnetic field acts in \mathbf{a}_x direction and current in the sliding bar is flowing in $+\mathbf{a}_z$ direction as shown in the figure.

Therefore, the force exerted on the bar is

$$\begin{aligned} \mathbf{F} &= \int Id\mathbf{l} \times \mathbf{B} = \int_0^5 (-4dz\mathbf{a}_z) \times (2\mathbf{a}_x) \\ &= -8\mathbf{a}_y [z]_0^5 = -40\mathbf{a}_y \text{ N} \end{aligned}$$

i.e. The force exerted on the sliding bar is in opposite direction to the motion of the sliding bar.

SOL 6.1.16

Option (C) is correct.

Given the magnetic flux density through the square loop is

$$\mathbf{B} = 7.5 \cos(120\pi t - 30^\circ) \mathbf{a}_z$$

So the total magnetic flux passing through the loop will be

$$\begin{aligned} \Phi &= \oint_S \mathbf{B} \cdot d\mathbf{S} \\ &= [-7.5 \cos(120\pi t - 30^\circ) \mathbf{a}_z] (1 \times 1) (-\mathbf{a}_z) \\ &= 7.5 \cos(120\pi t - 30^\circ) \end{aligned}$$

Now, the induced emf in the square loop is given by

$$V_{\text{emf}} = -\frac{d\Phi}{dt} = 7.5 \times 120\pi \sin(120\pi t - 30^\circ)$$

The polarity of induced emf (according to Lenz's law) will be such that induced current in the loop will be in opposite direction to the current $I(t)$ shown in the figure. So we have

$$\begin{aligned} I(t) &= -\frac{V_{\text{emf}}}{R} \\ &= -\frac{7.5 \times 120\pi}{500} \sin(120\pi t - 30^\circ) \quad (R = 250 + 250 = 500 \Omega) \\ &= -5.7 \sin(120\pi t - 30^\circ) \end{aligned}$$

SOL 6.1.17

Option (A) is correct.

Consider the mutual inductance between the rectangular loop and straight

Page 396

Chap 6

Time Varying Fields and
Maxwell Equations

wire be M . So applying KVL in the rectangular loop we get,

$$M \frac{di_1}{dt} = L \frac{di_2}{dt} + Ri_2 \quad \dots (1)$$

Now from the shown figure (b), the current flowing in the straight wire is given as

$$i_1 = I_1 u(t) - I_1 u(t - T) \quad (I_1 \text{ is amplitude of the current})$$

$$\text{or,} \quad \frac{di_1}{dt} = I_1 \delta(t) - I_1 \delta(t - T) \quad (2)$$

$$\text{So, at } t = 0 \quad \frac{di_1}{dt} = I_1$$

$$\text{and} \quad MI_1 = L \frac{di_2}{dt} + Ri_2 \quad (\text{from equation (1)})$$

Solving it we get

$$i_2 = \frac{M}{L} I_1 e^{-(R/L)t} \quad \text{for } 0 < t < T$$

Again in equation (2) at $t = T$ we have

$$\frac{di_1}{dt} = -I_1$$

$$\text{and} \quad -MI_1 = L \frac{di_2}{dt} + Ri_2 \quad (\text{from equation (1)})$$

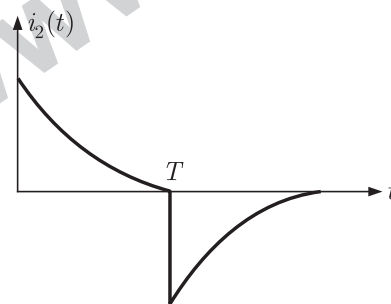
Solving it we get

$$i_2 = -\frac{M}{L} I_1 e^{-(R/L)(t-T)} \quad \text{for } t > T$$

Thus, the current in the rectangular loop is

$$i_2 = \begin{cases} \frac{M}{L} I_1 e^{-(R/L)t} & 0 < t < T \\ -\frac{M}{L} I_1 e^{-(R/L)(t-T)} & t > T \end{cases}$$

Plotting i_2 versus t we get



SOL 6.1.18

Option (A) is correct.

Total magnetic flux passing through the loop formed by the resistance, bar and the rails is given as:

$$\begin{aligned} \Phi &= \int_S \mathbf{B} \cdot d\mathbf{S} \\ &= \mathbf{B} \cdot \mathbf{S} = [0.2 \cos \omega t \mathbf{a}_x] \cdot [0.5(1-y) \mathbf{a}_x] \\ &= 0.1[1 - 0.5(1 - \cos \omega t)] \cos \omega t \quad (y = 0.5(1 - \cos \omega t) \text{ m}) \\ &= 0.05 \cos \omega t (1 + \cos \omega t) = 0.05(\cos \omega t + \cos^2 \omega t) \end{aligned}$$

So, the induced emf in the loop is

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

and as determined by Lenz's law, the induced current will be flowing in

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 397

Chap 6

Time Varying Fields and
Maxwell Equations

opposite direction to the current i . So the current i in the loop will be

$$\begin{aligned} i &= -\frac{V_{\text{emf}}}{R} = -\frac{1}{R} \left(-\frac{d\Phi}{dt} \right) \\ &= \frac{0.05}{5} [-\omega \sin \omega t - 2\omega \cos \omega t \sin \omega t] \\ &= -0.01\omega \sin \omega t (1 + 2 \cos \omega t) \end{aligned}$$

SOL 6.1.19

Option (D) is correct.

Given the electric flux density in the medium is

$$\mathbf{D} = 1.33 \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \mu\text{C}/\text{m}^2$$

So, the electric field intensity in the medium is given as

$$\mathbf{E} = \frac{\mathbf{D}}{\epsilon} \quad \text{where } \epsilon \text{ is the permittivity of the medium}$$

or,

$$\begin{aligned} \mathbf{E} &= \frac{\mathbf{D}}{\epsilon_r \epsilon_0} = \frac{1.33 \times 10^{-6} \sin(3 \times 10^8 t - 0.2x)}{10 \times 8.85 \times 10^{-12}} \mathbf{a}_y \quad (\epsilon_r = 10) \\ &= 1.5 \times 10^4 \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \end{aligned}$$

Now, from maxwell's equation we have

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

or,

$$\begin{aligned} \frac{\partial \mathbf{B}}{\partial t} &= -\nabla \times \mathbf{E} \\ &= -\frac{\partial E_y}{\partial x} \mathbf{a}_z \\ &= -(-0.2) \times (1.5 \times 10^4) \cos(3 \times 10^8 t - 0.2x) \mathbf{a}_y \\ &= 3 \times 10^3 \cos(3 \times 10^8 t - 0.2x) \mathbf{a}_y \end{aligned}$$

Integrating both sides, we get the magnetic flux density in the medium as

$$\begin{aligned} \mathbf{B} &= \int 3 \times 10^3 \cos(3 \times 10^8 t - 0.2x) \mathbf{a}_y \\ &= \frac{3 \times 10^3}{3 \times 10^8} \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \\ &= 10^{-5} \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \text{ Tesla} \end{aligned}$$

Therefore the magnetic field intensity in the medium is

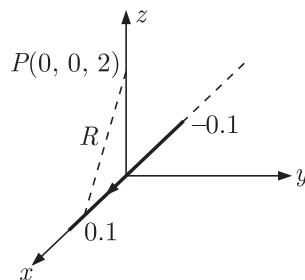
$$\mathbf{H} = \frac{\mathbf{B}}{\mu} = \frac{\mathbf{B}}{\mu_r \mu_0} = \frac{10^{-5} \sin(3 \times 10^8 t - 0.2x)}{2 \times 4\pi \times 10^{-7}} \mathbf{a}_y \quad \mu_r = 2$$

Thus

$$\mathbf{H} = 4 \sin(3 \times 10^8 t - 0.2x) \mathbf{a}_y \text{ A/m}$$

SOL 6.1.20

Option (B) is correct.



The magnetic vector potential for a direct current flowing in a filament is given as

$$\mathbf{A} = \int \frac{\mu_0 I}{4\pi R} \mathbf{a}_x dx$$

Here current $I(t)$ flowing in the filament shown in figure is varying with

Page 398

Chap 6

Time Varying Fields and
Maxwell Equations

time as

$$I(t) = 8t \text{ A}$$

So, the retarded vector potential at the point P will be given as

$$\mathbf{A} = \int \frac{\mu_0 I(t - R/c)}{4\pi R} \mathbf{a}_x dx$$

where R is the distance of any point on the filamentary current from P as shown in the figure and c is the velocity of waves in free space. So, we have

$$R = \sqrt{x^2 + 4} \text{ and } c = 3 \times 10^8 \text{ m/s}$$

Therefore,

$$\begin{aligned} \mathbf{A} &= \int_{x=-0.1}^{0.1} \frac{\mu_0 8(t - R/c)}{4\pi R} \mathbf{a}_x dx \\ &= \frac{8\mu_0}{4\pi} \left[\int_{-0.1}^{0.1} \frac{t}{\sqrt{x^2 + 4}} dx - \int_{-0.1}^{0.1} \frac{1}{c} dx \right] \\ &= 8 \times 10^{-7} t \left[\ln(x + \sqrt{x^2 + 4}) \right]_{-0.1}^{0.1} - \frac{8 \times 10^{-7}}{3 \times 10^8} [x]_{-0.1}^{0.1} \\ &= 8 \times 10^{-7} t \ln \left(\frac{0.1 + \sqrt{4.01}}{-0.1 + \sqrt{4.01}} \right) - 0.53 \times 10^{-15} \\ &= 8 \times 10^{-8} t - 0.53 \times 10^{-15} \end{aligned}$$

or,

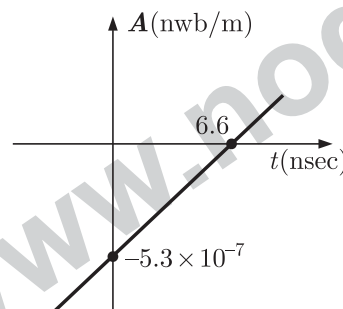
$$\mathbf{A} = (80t - 5.3 \times 10^{-7}) \mathbf{a}_x \text{ nWb/m} \quad (1)$$

So, when $\mathbf{A} = 0$

$$t = 6.6 \times 10^{-9} = 6.6 \text{ nsec}$$

and when $t = 0$

$$\mathbf{A} = -5.3 \times 10^{-7} \text{ nWb/m}$$

From equation (1) it is clear that \mathbf{A} will be linearly increasing with respect to time. Therefore the plot of \mathbf{A} versus t is

NOTE :

Time varying potential is usually called the retarded potential.

SOL 6.1.21

Option (A) is correct.

The force experienced by a test charge q in presence of both electric field \mathbf{E} and magnetic field \mathbf{B} in the region will be evaluated by using Lorentz force equation as

$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

So, putting the given three forces and their corresponding velocities in above equation we get the following relations

$$q(\mathbf{a}_y + \mathbf{a}_z) = q(\mathbf{E} + \mathbf{a}_x \times \mathbf{B}) \quad (1)$$

$$q\mathbf{a}_y = q(\mathbf{E} + \mathbf{a}_y \times \mathbf{B}) \quad (2)$$

$$q(2\mathbf{a}_y + \mathbf{a}_z) = q(\mathbf{E} + \mathbf{a}_z \times \mathbf{B}) \quad (3)$$

Subtracting equation (2) from (1) we get

$$\mathbf{a}_z = (\mathbf{a}_x - \mathbf{a}_y) \times \mathbf{B} \quad (4)$$

and subtracting equation (1) from (3) we get

$$\mathbf{a}_y = (\mathbf{a}_z - \mathbf{a}_x) \times \mathbf{B} \quad (5)$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 399

Chap 6

Time Varying Fields and
Maxwell Equations

Now we substitute $\mathbf{B} = B_x \mathbf{a}_x + B_y \mathbf{a}_y + B_z \mathbf{a}_z$ in eq (4) to get

$$\mathbf{a}_z = B_y \mathbf{a}_z - B_z \mathbf{a}_y + B_x \mathbf{a}_z - B_z \mathbf{a}_x$$

So, comparing the x, y and z components of the two sides we get

$$B_x + B_y = 1$$

and

$$B_z = 0$$

Again by substituting $\mathbf{B} = B_x \mathbf{a}_x + B_y \mathbf{a}_y + B_z \mathbf{a}_z$ in eq (5), we get

$$\mathbf{a}_y = B_x \mathbf{a}_y - B_y \mathbf{a}_x - B_y \mathbf{a}_z + B_z \mathbf{a}_y$$

So, comparing the x, y and z components of the two sides we get

$$B_x + B_z = 1$$

and

$$B_y = 0$$

as calculated above $B_z = 0$, therefore $B_x = 1$

Thus, the magnetic flux density in the region is

$$\mathbf{B} = \mathbf{a}_x \text{ Wb/m}^2 \quad (B_x = 1, B_y = B_z = 0)$$

SOL 6.1.22

Option (C) is correct.

As calculated in previous question the magnetic flux density in the region is

$$\mathbf{B} = \mathbf{a}_x \text{ Wb/m}^2$$

So, putting it in Lorentz force equation we get

$$\mathbf{F} = q(\mathbf{E} + \mathbf{V} \times \mathbf{B})$$

or,

$$q(\mathbf{a}_y + \mathbf{a}_z) = q(\mathbf{E} + \mathbf{a}_x \times \mathbf{a}_x)$$

Therefore, the electric field intensity in the medium is

$$\mathbf{E} = \mathbf{a}_y + \mathbf{a}_z \text{ V/m}$$

SOL 6.1.23

Option (C) is correct.

Given

Retarded scalar potential,

$$V = y(x - ct) \text{ volt}$$

and retarded vector potential,

$$\mathbf{A} = y\left(\frac{x}{c} - t\right) \mathbf{a}_x \text{ Wb/m}$$

Now the magnetic flux density in the medium is given as

$$\begin{aligned} \mathbf{B} &= \nabla \times \mathbf{A} \\ &= -\frac{\partial A_y}{\partial y} \mathbf{a}_z = \left(t - \frac{x}{c}\right) \mathbf{a}_z \text{ Tesla} \end{aligned} \quad (1)$$

So, the magnetic field intensity in the medium is

$$\begin{aligned} \mathbf{H} &= \frac{\mathbf{B}}{\mu_0} \quad (\mu_0 \text{ is the permeability of the medium}) \\ &= \frac{1}{\mu_0} \left(t - \frac{x}{c}\right) \mathbf{a}_z \text{ A/m} \end{aligned} \quad (2)$$

and the electric field intensity in the medium is given as

$$\begin{aligned} \mathbf{E} &= -\nabla V - \frac{\partial \mathbf{A}}{\partial t} \\ &= -(x - ct) \mathbf{a}_y - y \mathbf{a}_x + y \mathbf{a}_x = (ct - x) \mathbf{a}_y \end{aligned} \quad (3)$$

So, the electric flux density in the medium is

$$\begin{aligned} \mathbf{D} &= \epsilon_0 \mathbf{E} \quad (\epsilon_0 \text{ is the permittivity of the medium}) \\ &= \epsilon_0 (ct - x) \mathbf{a}_y \text{ C/m}^2 \end{aligned} \quad (4)$$

Now we determine the condition for the field to satisfy all the four Maxwell's equation.

$$(a) \quad \nabla \cdot \mathbf{D} = \rho_v$$

$$\text{or,} \quad \rho_v = \nabla \cdot [\epsilon_0 (ct - x) \mathbf{a}_y] \quad (\text{from equation (4)})$$

Page 400

Chap 6

Time Varying Fields and
Maxwell Equations

$$= 0$$

It means the field satisfies Maxwell's equation if $\rho_v = 0$.

$$(b) \quad \nabla \cdot \mathbf{B} = 0$$

$$\text{Now,} \quad \nabla \cdot \mathbf{B} = \nabla \cdot \left[\left(t - \frac{x}{c} \right) \mathbf{a}_z \right] = 0 \quad (\text{from equation (1)})$$

So, it already, satisfies Maxwell's equation

$$(c) \quad \nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

$$\text{Now,} \quad \nabla \times \mathbf{H} = -\frac{\partial H_z}{\partial x} \mathbf{a}_y = \frac{1}{\mu_0 c} \mathbf{a}_y = \sqrt{\frac{\epsilon_0}{\mu_0}} \mathbf{a}_y \quad (\text{from equation (2)})$$

and from equation (4) we have

$$\frac{\partial \mathbf{D}}{\partial t} = \epsilon_0 c \mathbf{a}_y = \sqrt{\frac{\epsilon_0}{\mu_0}} \mathbf{a}_y \quad (\text{Since in free space } c = \frac{1}{\sqrt{\mu_0 \epsilon_0}})$$

Putting the two results in Maxwell's equation, we get the condition

$$\mathbf{J} = 0$$

$$(d) \quad \nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\text{Now} \quad \nabla \times \mathbf{E} = \frac{\partial E_y}{\partial x} \mathbf{a}_z = -\mathbf{a}_z$$

$$\frac{\partial \mathbf{B}}{\partial t} = \mathbf{a}_z$$

So, it already satisfies Maxwell's equation. Thus, by combining all the results we get the two required conditions as $\mathbf{J} = 0$ and $\rho_v = 0$ for the field to satisfy Maxwell's equation.

SOL 6.1.24

Option (A) is correct.

Given the magnetic flux density through the loop is

$$\mathbf{B} = -2/x \mathbf{a}_z$$

So the total magnetic flux passing through the loop is given as

$$\begin{aligned} \Phi &= \int \mathbf{B} \cdot d\mathbf{S} = \int_x^{x+2} \int_y^{y+2} \left(-\frac{2}{x} \mathbf{a}_z \right) \cdot (-dx dy \mathbf{a}_z) \\ &= \left(2 \ln \frac{x+2}{x} \right) (2) = 4 \ln \left(\frac{x+2}{x} \right) \end{aligned}$$

Therefore, the circulation of induced electric field in the loop is

$$\begin{aligned} \oint_C \mathbf{E} \cdot d\mathbf{l} &= -\frac{d\Phi}{dt} = -\frac{d}{dt} \left[4 \ln \left(\frac{x+2}{x} \right) \right] \\ &= -\frac{4}{\left(\frac{x+2}{x} \right)} \frac{d}{dt} \left(\frac{x+2}{x} \right) \\ &= -\frac{4x}{x+2} \left(-\frac{2}{x^2} \frac{dx}{dt} \right) \\ &= \frac{8}{x(x+2)} (2) = \frac{16}{x(x+2)} \quad \left(\frac{dx}{dt} = v = 2\mathbf{a}_x \right) \end{aligned}$$

SOL 6.1.25

Option (A) is correct.

As the magnetic flux density for $\rho < 4$ is $\mathbf{B} = 0$ so, the total flux passing through the closed loop defined by $\rho = 4$ m is

$$\Phi = \int \mathbf{B} \cdot d\mathbf{S} = 0$$

So, the induced electric field circulation for the region $\rho < 4$ m is given as

$$\oint_C \mathbf{E} \cdot d\mathbf{l} = -\frac{d\Phi}{dt} = 0$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 401

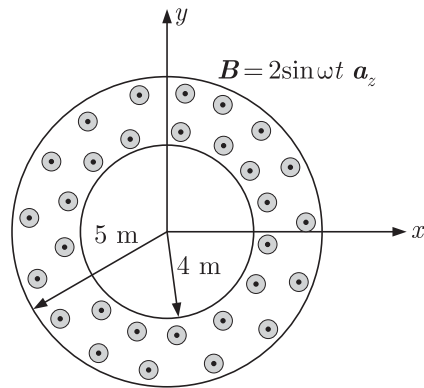
Chap 6

Time Varying Fields and
Maxwell Equationsor, $E = 0$ for $\rho < 4$ m

SOL 6.1.26

Option (B) is correct.

As the magnetic field for the region $\rho < 4$ m and $\rho > 5$ m is zero so we get the distribution of magnetic flux density as shown in figure below.



At any distance ρ from origin in the region $4 < \rho < 5$ m, the circulation of induced electric field is given as

$$\begin{aligned}\oint_C \mathbf{E} \cdot d\mathbf{l} &= -\frac{d\Phi}{dt} = -\frac{d}{dt} \left(\int \mathbf{B} \cdot d\mathbf{S} \right) \\ &= -\frac{d}{dt} [2 \sin \omega t (\pi \rho^2 - \pi 4^2)] \\ &= -2\omega \cos \omega t (\pi \rho^2 - 16\pi)\end{aligned}$$

or, $E(2\pi\rho) = -2\omega \cos \omega t (\pi \rho^2 - 16\pi)$

$$E = -\frac{2(\rho^2 - 16)\omega \cos \omega t}{2\rho}$$

So, the induced electric field intensity at $\rho = 4.5$ m is

$$\begin{aligned}\mathbf{E} &= -\frac{2}{4.5} ((4.5)^2 - 16)\omega \cos \omega t \\ &= -\frac{17}{18}\omega \cos \omega t\end{aligned}$$

SOL 6.1.27

Option (B) is correct.

For the region $\rho > 5$ m the magnetic flux density is 0 and so the total magnetic flux passing through the closed loop defined by $\rho = 5$ m is

$$\begin{aligned}\Phi &= \int_0^5 \mathbf{B} \cdot d\mathbf{S} = \int_0^4 \mathbf{B} \cdot d\mathbf{S} + \int_4^5 \mathbf{B} \cdot d\mathbf{S} \\ &= 0 + \int_4^5 (2 \sin \omega t) \mathbf{a}_z \cdot d\mathbf{S} \\ &= (2 \sin \omega t) [\pi(5)^2 - \pi(4)^2] = 18\pi \sin \omega t\end{aligned}$$

So, the circulation of magnetic flux density for any loop in the region $\rho > 5$ m is

$$\begin{aligned}\oint \mathbf{E} \cdot d\mathbf{l} &= -\frac{d\psi}{dt} \\ E(2\pi\rho) &= -\frac{d}{dt}(18\pi \sin \omega t) \\ &= -18\pi\omega \cos \omega t\end{aligned}$$

So, the induced electric field intensity in the region $\rho > 5$ m is

$$\mathbf{E} = \frac{-18\pi\omega \cos \omega t}{2\pi\rho} \mathbf{a}_\phi$$

Page 402

Chap 6

Time Varying Fields and
Maxwell Equations

$$= -\frac{9}{\rho} \omega \cos \omega t a_{\phi}$$

SOL 6.1.28

Option (D) is correct.

The distribution of magnetic flux density and the resistance in the circuit are same as given in section A (Q. 31) so, as calculated in the question, the two voltage drops in the loop due to magnetic flux density $\mathbf{B} = 0.1t \mathbf{a}_z$ are

$$V_1 = 33.3 \text{ mV}$$

and

$$V_2 = 66.67 \text{ mV} = 66.7 \text{ mV}$$

Now V_3 (voltmeter) which is directly connected to terminal cd is in parallel to both V_2 and V_1 . It must be kept in mind that the loop formed by voltmeter V_3 and resistance 2Ω also carries the magnetic flux density crossing through it. So, in this loop the induced emf will be produced which will be same as the field produced in loop $abcd$ at the enclosed fluxes will be same.

Therefore as calculated above induced emf in the loop of V_3 is

$$V_{\text{emf}} = 100 \text{ mV}$$

According to lenz's law it's polarity will be opposite to V_3 and so

$$-V_{\text{emf}} = V_1 + V_3$$

or,

$$V_3 = 100 - 33.3 = 66.7 \text{ mV}$$

SOL 6.1.29

Option (D) is correct.

The induced emf in a closed loop is defined as

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

where Φ is the total magnetic flux passing through the square loop

At any time t , angle between \mathbf{B} and $d\mathbf{S}$ is θ since \mathbf{B} is in \mathbf{a}_y direction so the total magnetic flux passing through the square loop is

$$\begin{aligned}\Phi &= \int \mathbf{B} \cdot d\mathbf{S} \\ &= (B)(S) \cos \theta \\ &= (5 \times 10^{-3})(20 \times 10^{-3} \times 20 \times 10^{-3}) \cos \theta \\ &= 2 \times 10^{-6} \cos \theta\end{aligned}$$

Therefore the induced emf in the loop is

$$\begin{aligned}V_{\text{emf}} &= -\frac{d\Phi}{dt} \\ &= -2 \times 10^{-6} \frac{d}{dt}(\cos \theta) \\ &= 2 \times 10^{-6} \sin \theta \frac{d\theta}{dt}\end{aligned}$$

and as $\frac{d\theta}{dt} = \text{angular velocity} = 2 \text{ rad/sec}$

$$\begin{aligned}\text{So, } V_{\text{emf}} &= (2 \times 10^{-6}) \sin \theta (2) \\ &= 4 \times 10^{-6} \sin \theta \text{ V/m} = 4 \sin \theta \mu\text{V/m}\end{aligned}$$

SOL 6.1.30

Option (B) is correct.

As calculated in previous question the induced emf in the closed square loop is

$$V_{\text{emf}} = 4 \sin \theta \mu\text{V/m}$$

So the induced current in the loop is

$$I = \frac{V_{\text{emf}}}{R} \quad \text{where } R \text{ is the resistance in the loop.}$$

Sample Chapter of **Electromagnetics** (Vol-10, GATE Study Package)

$$\begin{aligned}
 &= \frac{4 \sin \theta \times 10^{-6}}{40 \times 10^{-3}} & (R = 40 \text{ m}\Omega) \\
 &= 0.1 \sin \theta \text{ mA}
 \end{aligned}$$

Page 403

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.1.31

Option (C) is correct.

The total magnetic flux through the square loop is given as

$$\Phi = \oint \mathbf{B} \cdot d\mathbf{S} = (B_0 \sin \omega t)(S) \cos \theta$$

So, the induced emf in the loop is

$$\begin{aligned}
 V_{\text{emf}} &= -\frac{d\Phi}{dt} = -\frac{d}{dt}[(B_0 \sin \omega t)(S) \cos \theta] \\
 &= -B_0 S \frac{d}{dt}[\sin \omega t \cos \omega t] & (\theta = \omega t) \\
 &= -B_0 S \cos 2\omega t
 \end{aligned}$$

Thus, the maximum value of induced emf is

$$|V_{\text{emf}}| = B_0 S \omega$$

SOL 6.1.32

Option (C) is correct.

e.m.f. induced in the loop due to the magnetic flux density is given as

$$\begin{aligned}
 V_{\text{emf}} &= -\frac{\partial \Phi}{\partial t} = -\frac{\partial}{\partial t}(10 \cos 120\pi t)(\pi \rho^2) \\
 &= -\pi(10 \times 10^{-2})^2 \times (120\pi)(-10 \sin 120\pi t) \\
 &= 12\pi^2 \sin 120\pi t
 \end{aligned}$$

As determined by Lenz's law the polarity of induced e.m.f will be such that b is at positive terminal with respect to a .

$$\text{i.e. } V_{ba} = V_{\text{emf}} = 12\pi^2 \sin 120\pi t$$

$$\begin{aligned}
 \text{or } V_{ab} &= -12\pi^2 \sin 120\pi t \\
 &= -118.43 \sin 120\pi t \text{ Volt}
 \end{aligned}$$

SOL 6.1.33

Option (D) is correct.

As calculated in previous question, the voltage induced in the loop is

$$V_{ab} = -12\pi^2 \sin 120\pi t$$

Therefore, the current flowing in the loop is given as

$$\begin{aligned}
 I(t) &= -\frac{V_{ab}}{250} = \frac{12\pi^2 \sin 120\pi t}{250} \\
 &= 0.47 \sin 120\pi t
 \end{aligned}$$

SOLUTIONS 6.2

SOL 6.2.1

Correct answer is 0.

As the conducting loop is falling freely So, the flux through loop will remain constant. Therefore, the voltage induced in the loop will be zero.

SOL 6.2.2

Correct answer is -4 .

The magnetic flux density passing through the loop is given as

$$\mathbf{B} = 4z^3 t^2 \mathbf{a}_x$$

Since the flux density is directed normal to the plane $x = 0$ so the total magnetic flux passing through the square loop located in the plane $x = 0$ is

$$\Phi = \int \mathbf{B} \cdot d\mathbf{S} = \int_{y=0}^1 \int_{z=0}^1 (4z^3 t^2) dydz = t^2 \quad (d\mathbf{S} = (dydz) \mathbf{a}_x)$$

Induced emf in a loop placed in magnetic field is defined as

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

where Φ is the total magnetic flux passing through the loop. So the induced emf in the square loop is

$$V_{\text{emf}} = -\frac{d(t^2)}{dt} = -2t \quad (\Phi = t^2)$$

Therefore at time $t = 2$ sec the induced emf is

$$V_{\text{emf}} = -4 \text{ volt}$$

SOL 6.2.3

Correct answer is 4.05 .

Magnetic flux density produced at a distance ρ from a long straight wire carrying current I is defined as

$$\mathbf{B} = \frac{\mu_0 I}{2\pi\rho} \mathbf{a}_\phi$$

where \mathbf{a}_ϕ is the direction of flux density as determined by right hand rule. So the flux density produced by straight wire at a distance ρ from it is

$$\mathbf{B} = \frac{\mu_0 I}{2\pi\rho} \mathbf{a}_n \quad (\mathbf{a}_n \text{ is unit vector normal to the loop})$$

Therefore the total magnet flux passing through the loop is

$$\Phi = \int \mathbf{B} \cdot d\mathbf{S} = \int_d^{d+a} \frac{\mu_0 I}{2\pi\rho} a d\rho \quad (d\mathbf{S} = a d\rho \mathbf{a}_n)$$

where $d\rho$ is width of the strip of loop at a distance ρ from the straight wire. Thus,

$$\begin{aligned} \Phi &= \int_2^3 \left(\frac{\mu_0 I}{2\pi} \right) \frac{d\rho}{\rho} = \frac{\mu_0 I}{2\pi} \ln\left(\frac{3}{2}\right) = \frac{\mu_0 (5)}{2\pi} \ln(1.5) \\ &= (2 \times 10^{-7}) (5) \ln(1.5) = 4.05 \times 10^{-7} \text{ Wb} \end{aligned}$$

SOL 6.2.4

Correct answer is 133.3 .

The displacement current density in a medium is equal to the rate of change in electric flux density in the medium.

$$\mathbf{J}_d = \frac{\partial \mathbf{D}}{\partial t}$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 405

Chap 6

Time Varying Fields and
Maxwell Equations

Since the displacement current density in the medium is given as

$$\mathbf{J}_d = 20 \cos(1.5 \times 10^8 t) \mathbf{a}_y \text{ A/m}^2$$

So, the electric flux density in the medium is

$$\begin{aligned} \mathbf{D} &= \int \mathbf{J}_d dt + C && (C \rightarrow \text{constant}) \\ &= \int 20 \cos(1.5 \times 10^8 t) \mathbf{a}_y dt + C \end{aligned}$$

As there is no D.C. field present in the medium so, we get $C = 0$ and thus,

$$\begin{aligned} \mathbf{D} &= \frac{20 \sin(1.5 \times 10^8 t)}{1.5 \times 10^8} \mathbf{a}_y = 1.33 \times 10^{-7} \sin(1.5 \times 10^8 t) \mathbf{a}_y \\ &= 133.3 \sin(1.5 \times 10^8 t) \mathbf{a}_y \text{ nC/m}^2 \end{aligned}$$

Since, from the given problem we have the flux density

$$\mathbf{D} = D_0 \sin(1.5 \times 10^8 t) \mathbf{a}_y \text{ nC/m}^2$$

So, we get

$$D_0 = 133.3$$

SOL 6.2.5

Correct answer is 9.75 .

The ratio of magnitudes of displacement current to conduction current in any medium having permittivity ϵ and conductivity σ is given as

$$\left| \frac{\text{Displacement current}}{\text{Conduction current}} \right| = \frac{\omega \epsilon}{\sigma}$$

where ω is the angular frequency of the current in the medium.

Given frequency, $f = 50 \text{ GHz}$

Permittivity, $\epsilon = 4\epsilon_0 = 4 \times 8.85 \times 10^{-12}$

Conductivity, $\sigma = 1.14 \times 10^8 \text{ s/m}$

So, $\omega = 2\pi f = 2\pi \times 50 \times 10^9 = 100\pi \times 10^9$

Therefore, the ratio of magnitudes of displacement current to the conduction current is

$$\left| \frac{I_d}{I_c} \right| = \frac{100\pi \times 10^9 \times 4 \times 8.85 \times 10^{-12}}{1.14 \times 10^8} = 9.75 \times 10^{-8}$$

SOL 6.2.6

Correct answer is 33.3 .

Given magnetic flux density through the square loop is

$$\mathbf{B} = 0.1t \mathbf{a}_z \text{ Wb/m}^2$$

So, total magnetic flux passing through the loop is

$$\Phi = \mathbf{B} \cdot d\mathbf{S} = (0.1t)(1) = 0.1t$$

The induced emf (voltage) in the loop is given as

$$V_{\text{emf}} = -\frac{d\Phi}{dt} = -0.1 \text{ Volt}$$

As determined by Lenz's law the polarity of induced emf will be such that

$$V_1 + V_2 = -V_{\text{emf}}$$

Therefore, the voltage drop in the 2Ω resistance is

$$V_1 = \left(\frac{2}{2+4} \right) (-V_{\text{emf}}) = \frac{0.1}{3} = 33.3 \text{ mV}$$

SOL 6.2.7

Correct answer is 7.2 .

Voltage, $V_1 = -N_1 \frac{d\Phi}{dt}$

where Φ is total magnetic flux passing through it.

Page 406

Chap 6

Time Varying Fields and
Maxwell Equations

Again
$$V_2 = -N_2 \frac{d\Phi}{dt}$$

Since both the coil are in same magnetic field so, change in flux will be same for both the coil.

Comparing the equations (1) and (2) we get

$$\frac{V_1}{V_2} = \frac{N_1}{N_2}$$

$$V_2 = V_1 \frac{N_2}{N_1} = (12) \frac{3000}{5000} = 7.2 \text{ volt}$$

SOL 6.2.8

Correct answer is 41.6 .

In phasor form the magnetic field intensity can be written as

$$\mathbf{H}_s = 0.1 \cos(15\pi y) e^{-jbx} \mathbf{a}_z \text{ A/m}$$

Similar as determined in MCQ 42 using Maxwell's equation we get the relation

$$(15\pi)^2 + b^2 = \omega^2 \pi_0 \epsilon_0$$

Here
$$\omega = 6\pi \times 10^9$$

So,
$$(15\pi)^2 + b^2 = \left(\frac{6\pi \times 10^9}{3 \times 10^8} \right)^2$$

$$(15\pi)^2 + b^2 = 400\pi^2$$

$$b^2 = 175\pi^2 \Rightarrow b = \pm 41.6 \text{ rad/m}$$

So,
$$|b| = 41.6 \text{ rad/m}$$

SOL 6.2.9

Correct answer is 0.01 .

Induced emf. in the conducting loop formed by rail, bar and the resistor is given by

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

where Φ is total magnetic flux passing through the loop.

Consider the bar be located at a distance x from the resistor at time t . So the total magnetic flux passing through the loop at time t is

$$\Phi = \int \mathbf{B} \cdot d\mathbf{S} = Blx \quad (\text{area of the loop is } S = lx)$$

Now the induced emf in a loop placed in magnetic field is defined as

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

where Φ is the total magnetic flux passing through the loop. Therefore the induced emf in the square loop is

$$V_{\text{emf}} = -\frac{d}{dt}(Blx) = -Bl \frac{dx}{dt} \quad (\Phi = Blx)$$

Since from the given figure, we have

$$l = 2 \text{ m and } B = 0.1 \text{ Wb/m}^2$$

and
$$dx/dt = \text{velocity of bar} = 5 \text{ m/s}$$

So, induced emf is

$$V_{\text{emf}} = - (0.1) (2) (5) = -1 \text{ volt}$$

According to Lenz's law the induced current I in a loop flows such as to produce magnetic field that opposes the change in $\mathbf{B}(t)$. As the bar moves away from the resistor the change in magnetic field will be out of the page so the induced current will be in the same direction of I shown in figure.

Thus, the current in the loop is

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 407

Chap 6

Time Varying Fields and
Maxwell Equations

$$I = -\frac{V_{\text{emf}}}{R} = -\frac{(-1)}{10} = 0.01 \text{ A} \quad (R = 10 \Omega)$$

SOL 6.2.10

Correct answer is 277.

Magnetic flux density produced at a distance ρ from a long straight wire carrying current I is defined as

$$\mathbf{B} = \frac{\mu_0 I}{2\pi\rho} \mathbf{a}_\phi$$

where \mathbf{a}_ϕ is the direction of flux density as determined by right hand rule.

Since the direction of magnetic flux density produced at the loop is normal to the surface of the loop So, total flux passing through the loop is given by

$$\begin{aligned} \Phi &= \int_S \mathbf{B} \cdot d\mathbf{S} = \int_{\rho=2}^4 \left(\frac{\mu_0 I}{2\pi\rho} \right) (ad\rho) \quad (dS = ad\rho) \\ &= \frac{\mu_0 I a}{2\pi} \int_2^4 \frac{d\rho}{\rho} \\ &= \frac{\mu_0 I a}{2\pi} \ln 2 = \frac{\mu_0 I}{\pi} \ln(2) \end{aligned}$$

The current flowing in the loop is I_{loop} and induced e.m.f. is V_{emf} .

$$\text{So,} \quad V_{\text{emf}} = I_{\text{loop}} R = -\frac{d\Phi}{dt}$$

$$\frac{dQ}{dt} (R) = -\frac{\mu_0}{\pi} \ln(2) \frac{dI}{dt}$$

where Q is the total charge passing through a corner of square loop.

$$\frac{dQ}{dt} = -\frac{\mu_0}{4\pi} \ln(2) \frac{dI}{dt} \quad (R = 4 \Omega)$$

$$dQ = -\frac{\mu_0}{4\pi} \ln(2) dI$$

Therefore the total charge passing through a corner of square loop is

$$\begin{aligned} Q &= -\frac{\mu_0}{4\pi} \ln(2) \int_4^0 dI \\ &= -\frac{\mu_0}{4\pi} \ln(2) (0 - 4) \\ &= \frac{4 \times 4\pi \times 10^{-7}}{4\pi} \ln(2) \\ &= 2.77 \times 10^{-7} \text{ C} = 277 \text{ nC} \end{aligned}$$

SOL 6.2.11

Correct answer is 44.9 .

Since the radius of small circular loop is negligible in comparison to the radius of the large loop. So, the flux density through the small loop will be constant and equal to the flux on the axis of the loops.

$$\text{So,} \quad \mathbf{B} = \frac{\mu_0 I}{2} \frac{R^2}{(z^2 + R^2)^{3/2}} \mathbf{a}_z$$

where

$R \rightarrow$ radius of large loop = 5 m

$z \rightarrow$ distance between the loops = 12 m

$$\mathbf{B} = \frac{\mu_0 \times 2}{2} \times \frac{(5)^2}{[(12)^2 + (5)^2]^{3/2}} \mathbf{a}_z = \frac{25\mu_0}{(13)^3} \mathbf{a}_z$$

Therefore, the total flux passing through the small loop is

$$\begin{aligned} \Phi &= \int \mathbf{B} \cdot d\mathbf{S} = \frac{25\mu_0}{(13)^3} \times \pi r^2 \quad \text{where } r \text{ is radius of small circular loop.} \\ &= \frac{25 \times 4\pi \times 10^{-7}}{(13)^3} \times \pi (10^{-3})^2 = 44.9 \text{ fWb} \end{aligned}$$

Page 408

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.2.12

Correct answer is 2.7 .

Electric field in any medium is equal to the voltage drop per unit length.

$$\text{i.e.} \quad E = \frac{V}{d}$$

where

 $V \rightarrow$ potential difference between two points. $d \rightarrow$ distance between the two points.

The voltage difference between any two points in the medium is

$$V = V_0 \cos 2\pi ft$$

So the conduction current density in the medium is given as

$$J_c = \sigma E \quad (\sigma \rightarrow \text{conductivity of the medium})$$

$$= \frac{E}{\rho} \quad (\rho \rightarrow \text{resistivity of the medium})$$

$$= \frac{V}{\rho d} = \frac{V_0 \cos 2\pi ft}{\rho d} \quad (V = V_0 \cos 2\pi ft)$$

$$\text{or,} \quad |J_c| = \frac{V_0}{\rho d}$$

and displacement current density in the medium is given as

$$\begin{aligned} J_d &= \frac{\partial D}{\partial t} = \epsilon \frac{\partial E}{\partial t} = \epsilon \frac{\partial}{\partial t} \left[\frac{V_0 \cos(2\pi ft)}{d} \right] \quad (V = V_0 \cos 2\pi ft) \\ &= \frac{\epsilon V_0}{d} [-2\pi f \sin(2\pi ft)] \end{aligned}$$

$$\text{or,} \quad |J_d| = \frac{2\pi f \epsilon V_0}{d}$$

Therefore, the ratio of amplitudes of conduction current and displacement current in the medium is

$$\begin{aligned} \frac{|I_c|}{|I_d|} &= \frac{|J_c|}{|J_d|} = \frac{(V_0) / (\rho d)}{(d) / (2\pi f \epsilon V_0)} = \frac{1}{2\pi f \epsilon \rho} \\ &= \frac{1}{2\pi \times (1.6 \times 10^8) \times (54 \times 8.85 \times 10^{-12}) \times 0.77} \\ &= 2.7 \end{aligned}$$

SOL 6.2.13

Correct answer is 8.

Let the test charge be q coulomb So the force presence of experienced by the test charge in the presence of magnetic field is

$$\mathbf{F} = q(\mathbf{v} \times \mathbf{B})$$

and the force experienced can be written in terms of the electric field intensity as

$$\mathbf{F} = q\mathbf{E}$$

Where \mathbf{E} is field viewed by observer moving with test charge.

Putting it in Eq. (i)

$$q\mathbf{E} = q(\mathbf{v} \times \mathbf{B})$$

$$\mathbf{E} = (\omega \rho \mathbf{a}_\phi) \times (2\mathbf{a}_z)$$

where ω is angular velocity and ρ is radius of circular loop.

$$= (2)(2)(2)\mathbf{a}_\rho = 8\mathbf{a}_\rho \text{ V/m}$$

SOL 6.2.14

Correct answer is -0.35 .

As shown in figure the bar is sliding away from origin.

Now when the bar is located at a distance dx from the voltmeter, then, the vector area of the loop formed by rail and the bar is

$$d\mathbf{S} = (20 \times 10^{-2}) (dx) \mathbf{a}_z$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 409

Chap 6

Time Varying Fields and
Maxwell Equations

So, the total magnetic flux passing through the loop is

$$\begin{aligned}\Phi &= \int_S \mathbf{B} \cdot d\mathbf{S} \\ &= \int_0^x (8x^2 \mathbf{a}_z) (20 \times 10^{-2} dx \mathbf{a}_z) \\ &= \frac{1.6[t(1 + 0.4t^2)]^3}{3}\end{aligned}$$

Therefore, the induced e.m.f. in the loop is given as

$$\begin{aligned}V_{\text{emf}} &= -\frac{d\Phi}{dt} = -\frac{1.6}{3} \times 3(t + 0.4t^3)^2 \times (1 + 1.2t^2) \\ V_{\text{emf}} &= -1.6[(0.4) + (0.4)^4]^2 \times [1 + (1.2)(0.4)^2] \quad (t = 0.4 \text{ sec}) \\ &= -0.35 \text{ volt}\end{aligned}$$

Since the voltmeter is connected in same manner as the direction of induced emf (determined by Lenz's law).

So the voltmeter reading will be

$$V = V_{\text{emf}} = -0.35 \text{ volt}$$

SOL 6.2.15

Correct answer is -23.4 .

Since the position of bar is give as

$$x = t(1 + 0.4t^2)$$

So for the position $x = 12 \text{ cm}$ we have

$$0.12 = t(1 + 0.4t^2)$$

or,

$$t = 0.1193 \text{ sec}$$

As calculated in previous question, the induced emf in the loop at a particular time t is

$$V_{\text{emf}} = -(1.6)[t + 0.4t^3]^2(1 + 1.2t^2)$$

So, at $t = 0.1193 \text{ sec}$,

$$\begin{aligned}V_{\text{emf}} &= -1.6[(0.1193) + 0.4(0.1193)^3]^2[1 + (1.2)(0.1193)^2] \\ &= -0.02344 = -23.4 \text{ mV}\end{aligned}$$

Since the voltmeter is connected in same manner as the direction of induced emf as determined by Lenz's law. Therefore, the voltmeter reading at $x = 12 \text{ cm}$ will be

$$V = V_{\text{emf}} = -23.4 \text{ mvolt}$$

SOL 6.2.16

Correct answer is ± 600 .

Given the magnetic field intensity in the medium is

$$\mathbf{H} = \cos(10^{10}t - bx)\mathbf{a}_z \text{ A/m}$$

Now from the Maxwell's equation, we have

$$\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t}$$

$$\text{or, } \frac{\partial \mathbf{D}}{\partial t} = -\frac{\partial H_z}{\partial x} \mathbf{a}_y = -b \sin(10^{10}t - bx) \mathbf{a}_y$$

$$\mathbf{D} = \int -b \sin(10^{10}t - bx) dt + C \quad \text{where } C \text{ is a constant.}$$

Since no D.C. field is present in the medium so, we get $C = 0$ and therefore,

$$\mathbf{D} = \frac{b}{10^{10}} \cos(10^{10}t - bx) \mathbf{a}_y \text{ C/m}^2$$

and the electric field intensity in the medium is given as

$$\mathbf{E} = \frac{\mathbf{D}}{\epsilon} = \frac{b}{0.12 \times 10^{-9} \times 10^{10}} \cos(10^{10}t - bx) \mathbf{a}_y \quad (\epsilon = 0.12 \text{ nF/m})$$

Page 410

Chap 6

Time Varying Fields and
Maxwell Equations

Again From the Maxwell's equation

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\text{or, } \frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \left[\frac{b}{1.2} \cos(10^{10}t - bx) \mathbf{a}_y \right]$$

$$= -\frac{b^2}{1.2} \sin(10^{10}t - bx) \mathbf{a}_z$$

So, the magnetic flux density in the medium is

$$\mathbf{B} = -\int \frac{b^2}{1.2} \sin(10^{10}t - bx) \mathbf{a}_z dt$$

$$= \frac{b^2}{(1.2) \times 10^{10}} \cos(10^{10}t - bx) \mathbf{a}_z \quad (1)$$

We can also determine the value of magnetic flux density as :

$$\mathbf{B} = \mu \mathbf{H}$$

$$= (3 \times 10^{-5}) \cos(10^{10}t - bx) \mathbf{a}_z \quad (2)$$

Comparing the results of equation (1) and (2) we get,

$$\frac{b^2}{(1.2) \times 10^{10}} = 3 \times 10^{-5}$$

$$b^2 = 3.6 \times 10^5$$

$$b = \pm 600 \text{ rad/m}$$

SOL 6.2.17

Correct answer is 54.414 .

Given the electric field in time domain as

$$\mathbf{E} = 5 \sin(10\pi y) \cos(6\pi \times 10^9 - bx) \mathbf{a}_z$$

Comparing it with the general equation for electric field intensity given as

$$\mathbf{E} = E_0 \cos(\omega t - \beta x) \mathbf{a}_z$$

We get, $\omega = 6\pi \times 10^9$

Now in phasor form, the electric field intensity is

$$\mathbf{E}_s = 5 \sin(10\pi y) e^{-jbx} \mathbf{a}_z \quad (1)$$

From Maxwell's equation we get the magnetic field intensity as

$$\mathbf{H}_s = -\frac{1}{j\omega\mu_0} (\nabla \times \mathbf{E}_s) = \frac{j}{\omega\mu_0} \left[\frac{\partial E_{sz}}{\partial y} \mathbf{a}_x - \frac{\partial E_{sx}}{\partial z} \mathbf{a}_y \right]$$

$$= \frac{j}{\omega\mu_0} [50\pi \cos(10\pi y) e^{-jbx} \mathbf{a}_x + j5b \sin(10\pi y) \mathbf{a}_y] e^{-jbx}$$

Again from Maxwell's equation we have the electric field intensity as

$$\mathbf{E}_s = \frac{1}{j\omega\epsilon_0} (\nabla \times \mathbf{H}_s) = \frac{1}{j\omega\epsilon_0} \left[\frac{\partial H_{sy}}{\partial x} - \frac{\partial H_{sx}}{\partial y} \right] \mathbf{a}_z$$

$$= \frac{1}{\omega^2 \mu_0 \epsilon_0} [(j5b)(-jb) \sin(10\pi y) e^{-jbx} + (50\pi)(10\pi) \sin(10\pi y) e^{-jbx}] \mathbf{a}_z$$

$$= \frac{1}{\omega^2 \mu_0 \epsilon_0} [5b^2 + 500\pi^2] \sin 10\pi y e^{-jbx} \mathbf{a}_z$$

Comparing this result with equation (1) we get

$$\frac{1}{\omega^2 \mu_0 \epsilon_0} (5b^2 + 500\pi^2) = 5$$

or, $b^2 + 100\pi^2 = \omega^2 \mu_0 \epsilon_0$

$$b^2 + 100\pi^2 = (6\pi \times 10^9)^2 \times \frac{1}{(3 \times 10^8)^2} \quad \left(\omega = 6\pi \times 10^9, \sqrt{\mu_0 \epsilon_0} = \frac{1}{c} \right)$$

$$b^2 + 100\pi^2 = 400\pi^2$$

$$b^2 = 300\pi^2$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 411

Chap 6

Time Varying Fields and
Maxwell Equations

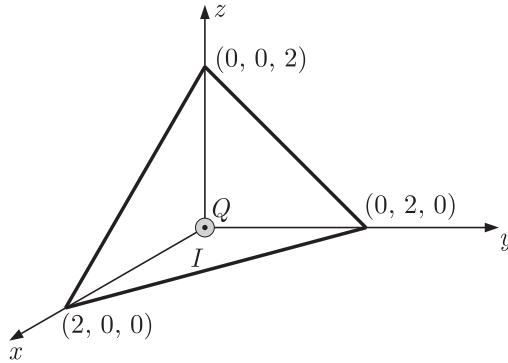
$$b = \pm \sqrt{300} \pi \text{ rad/m}$$

So, $|b| = \sqrt{300} \pi = 54.414 \text{ rad/m}$

SOL 6.2.18

Correct answer is 7.

Let the point charge located at origin be Q and the current I is flowing out of the page through the closed triangular path as shown in the figure.



As the current I flows away from the point charge along the wire, the net charge at origin will change with increasing time and given as

$$\frac{dQ}{dt} = -I$$

So the electric field intensity will also vary through the surface and for the varying field circulation of magnetic field intensity around the triangular loop is defined as

$$\oint \mathbf{H} \cdot d\mathbf{l} = [I_d]_{enc} + [I_c]_{enc}$$

where $[I_c]_{enc}$ is the actual flow of charge called enclosed conduction current and $[I_d]_{enc}$ is the current due to the varying field called enclosed displacement current which is given as

$$[I_d]_{enc} = \frac{d}{dt} \int_S (\epsilon_0 \mathbf{E}) \cdot d\mathbf{S} = \frac{d}{dt} \int_S \mathbf{D} \cdot d\mathbf{S} \quad (1)$$

From symmetry the total electric flux passing through the triangular surface is

$$\int_S \mathbf{D} \cdot d\mathbf{S} = \frac{Q}{8}$$

So, $[I_d]_{enc} = \frac{d}{dt} \left(\frac{Q}{8} \right) = \frac{1}{8} \frac{dQ}{dt} = -\frac{I}{8}$ (from equation (1))

whereas $[I_c]_{enc} = I$

So, the net circulation of the magnetic field intensity around the closed triangular loop is

$$\begin{aligned} \oint_C \mathbf{H} \cdot d\mathbf{l} &= [I_d]_{enc} + [I_c]_{enc} \\ &= -\frac{I}{8} + I = \frac{7}{8}(8) = 7 \text{ A} \quad (I = 8 \text{ A}) \end{aligned}$$

SOL 6.2.19

Correct answer is 21.33 .

As calculated in previous question the maximum induced voltage in the rotating loop is given as

$$|V_{emf}| = B_0 S \omega$$

From the given data, we have

$$B_0 = 0.25 \text{ Wb/m}^2$$

$$S = 64 \text{ cm}^2 = 64 \times 10^{-4} \text{ m}^2$$

Page 412

Chap 6

Time Varying Fields and
Maxwell Equations

and $\omega = 60 \times 2\pi = 377 \text{ rad/sec}$ (In one revolution 2π radian is covered)

So, the r.m.s. value of the induced voltage is

$$\begin{aligned}[V_{\text{emf}}]_{r.m.s} &= \frac{1}{\sqrt{2}} |V_{\text{emf}}| = \frac{1}{\sqrt{2}} B_0 S \omega \\ &= \frac{1}{\sqrt{2}} (0.25 \times 64 \times 10^{-4} \times 377) \\ &= 0.4265\end{aligned}$$

Since the loop has 50 turns so net induced voltage will be 50 times the calculated value.

$$\begin{aligned}\text{i.e. } [V_{\text{emf}}]_{r.m.s} &= 50 \times (0.4265) \\ &= 21.33 \text{ volt}\end{aligned}$$

www.nodia.co.in

SOLUTIONS 6.3

Page 413

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.3.1 Option (D) is correct.

SOL 6.3.2 Option (B) is correct.

The line integral of magnetic field intensity along a closed loop is equal to the current enclosed by it.

$$\text{i.e.} \quad \oint \mathbf{H} \cdot d\mathbf{l} = I_{enc}$$

So, for the constant current, magnetic field intensity will be constant i.e. magnetostatic field is caused by steady currents.

SOL 6.3.3 Option (A) is correct.

From Faraday's law the electric field intensity in a time varying field is defined as

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad \text{where } \mathbf{B} \text{ is magnetic flux density in the EM field.}$$

and since the magnetic flux density is equal to the curl of magnetic vector potential

$$\text{i.e.} \quad \mathbf{B} = \nabla \times \mathbf{A}$$

So, putting it in equation (1), we get

$$\nabla \times \mathbf{E} = -\frac{\partial}{\partial t}(\nabla \times \mathbf{A})$$

$$\text{or} \quad \nabla \times \mathbf{E} = \nabla \times \left(-\frac{\partial}{\partial t} \mathbf{A} \right)$$

$$\text{Therefore,} \quad \mathbf{E} = -\frac{\partial \mathbf{A}}{\partial t}$$

SOL 6.3.4 Option (B) is correct.

Since total magnetic flux through a surface S is defined as

$$\Phi = \int_S \mathbf{B} \cdot d\mathbf{S}$$

From Maxwell's equation it is known that curl of magnetic flux density is zero

$$\nabla \cdot \mathbf{B} = 0$$

$$\int_S \mathbf{B} \cdot d\mathbf{S} = \int_V (\nabla \cdot \mathbf{B}) dv = 0 \quad (\text{Stokes Theorem})$$

Thus, net outwards flux will be zero for a closed surface.

SOL 6.3.5 Option (B) is correct.

From the integral form of Faraday's law we have the relation between the electric field intensity and net magnetic flux through a closed loop as

$$\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{d\Phi}{dt}$$

Since electric field intensity is zero ($E = 0$) inside the conducting loop. So, the rate of change in net magnetic flux through the closed loop is

Page 414

Chap 6

Time Varying Fields and
Maxwell Equations

$$\frac{d\Phi}{dt} = 0$$

i.e. Φ is constant and doesn't vary with time.

SOL 6.3.6

Option (C) is correct.

A superconductor material carries zero magnetic field and zero electric field inside it.

i.e. $\mathbf{B} = 0$ and $\mathbf{E} = 0$

Now from Ampere-Maxwell equation we have the relation between the magnetic flux density and electric field intensity as

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} + \mu_0 \epsilon_0 \frac{\partial \mathbf{E}}{\partial t}$$

So, $\mathbf{J} = 0$ ($\mathbf{B} = 0, \mathbf{E} = 0$)

Since the net current density inside the superconductor is zero so all the current must be confined at the surface of the wire.

SOL 6.3.7

Option (C) is correct.

According to Lenz's law the induced current I in a loop flows such as to produce a magnetic field that opposes the change in $\mathbf{B}(t)$.

Now the configuration shown in option (A) and (B) for increasing magnetic flux \mathbf{B}_i , the change in flux is in same direction to \mathbf{B}_i as well as the current I flowing in the loop produces magnetic field in the same direction so it does not follow the Lenz's law.

For the configuration shown in option (D), as the flux \mathbf{B}_d is decreasing with time so the change in flux is in opposite direction to \mathbf{B}_d as well as the current I flowing in the loop produces the magnetic field in opposite direction so it also does not follow the Lenz's law.

For the configuration shown in option (C), the flux density \mathbf{B}_d is decreasing with time so the change in flux is in opposite direction to \mathbf{B}_d but the current I flowing in the loop produces magnetic field in the same direction to \mathbf{B}_d (opposite to the direction of change in flux density). Therefore this is the correct configuration.

SOL 6.3.8

Option (C) is correct.

Induced emf in a conducting loop is given by

$$V_{\text{emf}} = -\frac{d\Phi}{dt} \quad \text{where } \Phi \text{ is total magnetic flux passing}$$

through the loop.

Since, the magnetic field is non-uniform so the change in flux will be caused by it and the induced emf due to it is called transformer emf.

Again the field is in \mathbf{a}_y direction and the loop is rotating about z -axis so flux through the loop will also vary due to the motion of the loop. This causes the emf which is called motion emf. Thus, total induced voltage in the rotating loop is caused by the combination of both the transformer and motion emf.

SOL 6.3.9

Option (B) is correct.

SOL 6.3.10

Option (C) is correct.

SOL 6.3.11

Option (B) is correct.

Sample Chapter of **Electromagnetics** (Vol-10, GATE Study Package)

SOL 6.3.12 Option (D) is correct.

SOL 6.3.13 Option (A) is correct.

SOL 6.3.14 Option (A) is correct.

SOL 6.3.15 Option (C) is correct.

SOL 6.3.16 Option (B) is correct.

SOL 6.3.17 Option (B) is correct.

Page 415

Chap 6

Time Varying Fields and
Maxwell Equations

www.nodia.co.in

SOLUTIONS 6.4

SOL 6.4.1

Option (C) is correct.

Given, the magnetic flux density in air as

$$\mathbf{B} = B_0 \left(\frac{x}{x^2 + y^2} \mathbf{a}_y - \frac{y}{x^2 + y^2} \mathbf{a}_x \right) \quad \dots(1)$$

Now, we transform the expression in cylindrical system, substituting

$$x = r \cos \phi \quad \text{and} \quad y = r \sin \phi$$

$$\mathbf{a}_x = \cos \phi \mathbf{a}_r - \sin \phi \mathbf{a}_\phi$$

and

$$\mathbf{a}_y = \sin \phi \mathbf{a}_r + \cos \phi \mathbf{a}_\phi$$

So, we get

$$\mathbf{B} = B_0 \mathbf{a}_\phi$$

Therefore, the magnetic field intensity in air is given as

$$\mathbf{H} = \frac{\mathbf{B}}{\mu_0} = \frac{B_0 \mathbf{a}_\phi}{\mu_0}, \text{ which is constant}$$

So, the current density of the field is

$$\mathbf{J} = \nabla \times \mathbf{H} = 0 \quad (\text{since } \mathbf{H} \text{ is constant})$$

SOL 6.4.2

Option (D) is correct.

Maxwell equations for an EM wave is given as

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \cdot \mathbf{E} = \frac{\rho_v}{\epsilon}$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t} + \mathbf{J}$$

So, for static electric magnetic fields

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \cdot \mathbf{E} = \rho_v / \epsilon$$

$$\nabla \times \mathbf{E} = 0 \quad \left(\frac{\partial \mathbf{B}}{\partial t} = 0 \right)$$

$$\nabla \times \mathbf{H} = \mathbf{J} \quad \left(\frac{\partial \mathbf{D}}{\partial t} = 0 \right)$$

SOL 6.4.3

Option (D) is correct.

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

Maxwell Equations

$$\iint_S (\nabla \times \mathbf{H}) \cdot d\mathbf{S} = \iint_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S}$$

Integral form

$$\oint \mathbf{H} \cdot d\mathbf{l} = \iint_S \left(\mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \right) \cdot d\mathbf{S}$$

Stokes Theorem

SOL 6.4.4

Option (C) is correct.

From Maxwells equations we have

$$\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t} + \mathbf{J}$$

Thus, $\nabla \times \mathbf{H}$ has unit of current density \mathbf{J} (i.e., A/m²)

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 417

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.4.5

Option (A) is correct.

This equation is based on Ampere's law as from Ampere's circuital law we have

$$\oint_l \mathbf{H} \cdot d\mathbf{l} = I_{\text{enclosed}}$$

or,
$$\oint_l \mathbf{H} \cdot d\mathbf{l} = \int_S \mathbf{J} \cdot d\mathbf{S}$$

Applying Stoke's theorem we get

$$\int_S (\nabla \times \mathbf{H}) \cdot d\mathbf{S} = \int_S \mathbf{J} \cdot d\mathbf{S}$$

$$\nabla \times \mathbf{H} = \mathbf{J}$$

Then, it is modified using continuity equation as

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

SOL 6.4.6

Option (D) is correct.

When a moving circuit is put in a time varying magnetic field induced emf have two components. One due to time variation of magnetic flux density \mathbf{B} and other due to the motion of circuit in the field.

SOL 6.4.7

Option (C) is correct.

From maxwell equation we have

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

The term $\frac{\partial \mathbf{D}}{\partial t}$ defines displacement current.

SOL 6.4.8

Option (C) is correct.

Emf induced in a loop carrying a time varying magnetic flux Φ is defined as

$$V_{\text{emf}} = -\frac{d\Phi}{dt}$$

$$9 = -\frac{d}{dt}\left(\frac{1}{3}\lambda t^3\right)$$

$$9 = -\lambda t^2$$

at time, $t = 3$ s, we have

$$9 = -\lambda(3)^2$$

$$\lambda = -1 \text{ Wb/s}^2$$

SOL 6.4.9

Option (B) is correct.

According to Lenz's law the induced emf (or induced current) in a loop flows such as to produce a magnetic field that opposed the change in \mathbf{B} . The direction of the magnetic field produced by the current is determined by right hand rule.

Now, in figure (1), \mathbf{B} directed upward increases with time where as the field produced by current I is downward so, it obey's the Lenz's law.

In figure (2), \mathbf{B} directed upward is decreasing with time whereas the field produced by current I is downwards (i.e. additive to the change in \mathbf{B}) so, it doesn't obey Lenz's law.

In figure (3), \mathbf{B} directed upward is decreasing with time where as current I produces the field directed upwards (i.e. opposite to the change in \mathbf{B}) So, it also obeys Lenz's law.

In figure (4), \mathbf{B} directed upward is increasing with time whereas current I produces field directed upward (i.e. additive to the change in \mathbf{B}) So, it

Page 418

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.4.10

doesn't obey Lenz's law.

Thus, the configuration 1 and 3 are correct.

Option (C) is correct.

Faraday's law states that for time varying field,

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

Since, the curl of gradient of a scalar function is always zero

$$\text{i.e. } \nabla \times (\nabla V) = 0$$

So, the expression for the field, $\mathbf{E} = -\nabla V$ must include some other terms is

$$\mathbf{E} = -\nabla V - \frac{\partial \mathbf{A}}{\partial t}$$

i.e. A is true but R is false.

SOL 6.4.11

Option (B) is correct.

Faraday develops the concept of time varying electric field producing a magnetic field. The law he gave related to the theory is known as Faraday's law.

SOL 6.4.12

Option (D) is correct.

Given, the area of loop

$$S = 5 \text{ m}^2$$

Rate of change of flux density,

$$\frac{\partial B}{\partial t} = 2 \text{ Wb/m}^2/\text{S}$$

So, the emf in the loop is

$$\begin{aligned} V_{\text{emf}} &= -\frac{\partial}{\partial t} \int \mathbf{B} \cdot d\mathbf{S} \\ &= (5)(-2) = -10 \text{ V} \end{aligned}$$

SOL 6.4.13

Option (D) is correct.

The modified Maxwell's differential equation.

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

This equation is derived from Ampere's circuital law which is given as

$$\begin{aligned} \oint \mathbf{H} \cdot d\mathbf{l} &= I_{\text{enc}} \\ \oint (\nabla \times \mathbf{H}) \cdot d\mathbf{S} &= \int \mathbf{J} d\mathbf{S} \\ \nabla \times \mathbf{H} &= \mathbf{J} \end{aligned}$$

SOL 6.4.14

Option (B) is correct.

Electric potential of an isolated sphere is defined as

$$C = 4\pi\epsilon_0 a \quad (\text{free space})$$

The Maxwell's equation in phasor form is written as

$$\nabla \times \mathbf{H} = j\omega\epsilon\mathbf{E} + \sigma\mathbf{E} = j\omega\epsilon\mathbf{E} + \mathbf{J} \quad (\mathbf{J} = \sigma\mathbf{E})$$

So A and R both are true individually but R is not the correct explanation of A.

SOL 6.4.15

Option (A) is correct.

If a coil is placed in a time varying magnetic field then the e.m.f. will induce in coil. So here in both the coil e.m.f. will be induced.

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 419

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.4.16 Option (B) is correct.
Both the statements are individually correct but R is not explanation of A.

SOL 6.4.17 Option (B) is correct.

Ampere's law $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$ (a → 3)

Faraday's law $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$ (b → 4)

Gauss law $\nabla \cdot \mathbf{D} = \rho_v$ (c → 1)

Current continuity $\nabla \cdot \mathbf{J} = -\frac{\partial \rho}{\partial t}$ (d → 2)

SOL 6.4.18 Option (B) is correct.

Since, the magnetic field perpendicular to the plane of the ring is decreasing with time so, according to Faraday's law emf induced in both the ring is

$$V_{\text{emf}} = -\frac{\partial}{\partial t} \int \mathbf{B} \cdot d\mathbf{S}$$

Therefore, emf will be induced in both the rings.

SOL 6.4.19 Option (A) is correct.

The Basic idea of radiation is given by the two Maxwell's equation

$$\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t}$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

SOL 6.4.20 Option (B) is correct.

The correct Maxwell's equation are

$$\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t} \quad \nabla \cdot \mathbf{D} = \rho$$

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \quad \nabla \cdot \mathbf{B} = 0$$

SOL 6.4.21 Option (B) is correct.

In List I

a. $\oint \mathbf{B} \cdot d\mathbf{S} = 0$

The surface integral of magnetic flux density over the closed surface is zero or in other words, net outward magnetic flux through any closed surface is zero. (a → 4)

b. $\oint \mathbf{D} \cdot d\mathbf{S} = \int_v \rho_v dv$

Total outward electric flux through any closed surface is equal to the charge enclosed in the region. (b → 3)

c. $\int \mathbf{E} \cdot d\mathbf{l} = -\int \frac{\partial \mathbf{B}}{\partial t} d\mathbf{S}$

i.e. The line integral of the electric field intensity around a closed path is equal to the surface integral of the time derivative of magnetic flux density (c → 2)

d. $\oint \mathbf{H} \cdot d\mathbf{S} = \int \left(\frac{\partial \mathbf{D}}{\partial t} + \mathbf{J} \right) d\mathbf{a}$

i.e. The line integral of magnetic field intensity around a closed path is equal to the surface integral of sum of the current density and time derivative of electric flux density. (d → 1)

Page 420

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.4.22

Option (D) is correct.

The continuity equation is given as

$$\nabla \cdot \mathbf{J} = -\rho_v$$

i.e. it relates current density (\mathbf{J}) and charge density ρ_v .

SOL 6.4.23

Option (C) is correct.

Given Maxwell's equation is

$$\nabla \times \mathbf{H} = \mathbf{J}_c + \frac{\partial \mathbf{D}}{\partial t}$$

For free space, conductivity, $\sigma = 0$ and so,

$$\mathbf{J}_c = \sigma \mathbf{E} = 0$$

Therefore, we have the generalized equation

$$\nabla \times \mathbf{H} = \frac{\partial \mathbf{D}}{\partial t}$$

SOL 6.4.24

Option (A) is correct.

Given the magnetic field intensity,

$$\mathbf{H} = 3\mathbf{a}_x + 7y\mathbf{a}_y + 2x\mathbf{a}_z$$

So from Ampere's circuital law we have

$$\mathbf{J} = \nabla \times \mathbf{H}$$

$$= \begin{vmatrix} \mathbf{a}_x & \mathbf{a}_y & \mathbf{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 3 & 7y & 2x \end{vmatrix}$$

$$= \mathbf{a}_x(0) - \mathbf{a}_y(2 - 0) + \mathbf{a}_z(0) = -2\mathbf{a}_y$$

SOL 6.4.25

Option (A) is correct.

The emf in the loop will be induced due to motion of the loop as well as the variation in magnetic field given as

$$V_{\text{emf}} = - \int \frac{\partial \mathbf{B}}{\partial t} d\mathbf{S} + \oint (\mathbf{v} \times \mathbf{B}) d\mathbf{l}$$

So, the frequencies for the induced e.m.f. in the loop is ω_1 and ω_2 .

SOL 6.4.26

Option (B) is correct.

$$\mathbf{F} = Q(\mathbf{E} + \mathbf{v} \times \mathbf{B}) \text{ is Lorentz force equation.}$$

SOL 6.4.27

Option (A) is correct.

All of the given expressions are Maxwell's equation.

SOL 6.4.28

Option (B) is correct.

Poisson's equation for an electric field is given as

$$\nabla^2 V = -\frac{\rho_v}{\epsilon}$$

where, V is the electric potential at the point and ρ_v is the volume charge density in the region. So, for $\rho_v = 0$ we get,

$$\nabla^2 V = 0$$

Which is Laplacian equation.

SOL 6.4.29

Option (A) is correct.

The direction of magnetic flux due to the current ' i ' in the conductor is determined by right hand rule. So, we get the flux through A is pointing into the paper while the flux through B is pointing out of the paper.

According to Lenz's law the induced e.m.f. opposes the flux that causes it.

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 421

Chap 6

Time Varying Fields and
Maxwell Equations

So again by using right hand rule we get the direction of induced e.m.f. is anticlockwise in A and clockwise in B .

SOL 6.4.30 Option (D) is correct.

$$\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}$$

This is the wave equation for static electromagnetic field.
i.e. It is not Maxwell's equation.

SOL 6.4.31 Option (B) is correct.

Continuity equation $\nabla \times \mathbf{J} = -\frac{\partial \rho_v}{\partial t}$ (a \rightarrow 4)

Ampere's law $\nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$ (b \rightarrow 1)

Displacement current $\mathbf{J} = \frac{\partial \mathbf{D}}{\partial t}$ (c \rightarrow 2)

Faraday' law $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$ (d \rightarrow 3)

SOL 6.4.32 Option (B) is correct.

Induced emf in a coil of N turns is defined as

$$V_{\text{emf}} = -N \frac{d\Phi}{dt}$$

where Φ is flux linking the coil. So, we get

$$\begin{aligned} V_{\text{emf}} &= -100 \frac{d}{dt}(t^3 - 2t) \\ &= -100(3t^2 - 2) \\ &= -100(3(2)^2 - 2) = -1000 \text{ mV} \quad (\text{at } t = 2 \text{ s}) \\ &= -1 \text{ V} \end{aligned}$$

SOL 6.4.33 Option (B) is correct.

A static electric field in a charge free region is defined as

$$\nabla \cdot \mathbf{E} = 0 \quad (\text{a} \rightarrow 4)$$

and $\nabla \times \mathbf{E} = 0$

A static electric field in a charged region have

$$\nabla \cdot \mathbf{E} = \frac{\rho_v}{\epsilon} \neq 0 \quad (\text{b} \rightarrow 2)$$

and $\nabla \times \mathbf{E} = 0$

A steady magnetic field in a current carrying conductor have

$$\nabla \cdot \mathbf{B} = 0 \quad (\text{c} \rightarrow 1)$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J} \neq 0$$

A time varying electric field in a charged medium with time varying magnetic field have

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t} \neq 0 \quad (\text{d} \rightarrow 3)$$

$$\nabla \cdot \mathbf{E} = \frac{\rho_v}{\epsilon} \neq 0$$

SOL 6.4.34 Option (C) is correct.

$$V = -\frac{d\Phi_m}{dt}$$

It is Faraday's law that states that the change in flux through any loop induces e.m.f. in the loop.

Page 422

Chap 6

Time Varying Fields and
Maxwell Equations

SOL 6.4.35

Option (B) is correct.

From stokes theorem, we have

$$\int (\nabla \times \mathbf{E}) \cdot d\mathbf{S} = \oint \mathbf{E} \cdot d\mathbf{l} \quad (1)$$

Given, the Maxwell's equation

$$\nabla \times \mathbf{E} = -(\partial \mathbf{B} / \partial t)$$

Putting this expression in equation (1) we get,

$$\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{\partial}{\partial t} \int \mathbf{B} \cdot d\mathbf{S}$$

SOL 6.4.36

Option (D) is correct.

Since, the flux linking through both the coil is varying with time so, emf are induced in both the coils.

Since, the loop 2 is split so, no current flows in it and so joule heating does not occur in coil 2 while the joule heating occurs in closed loop 1 as current flows in it.

Therefore, only statement 2 is correct.

SOL 6.4.37

Option (C) is correct.

The electric field intensity is

$$\mathbf{E} = \mathbf{E}_0 e^{j\omega t} \quad \text{where } \mathbf{E}_0 \text{ is independent of time}$$

So, from Maxwell's equation we have

$$\begin{aligned} \nabla \times \mathbf{H} &= \mathbf{J} + \frac{\varepsilon \partial \mathbf{E}}{\partial t} \\ &= \sigma \mathbf{E} + \varepsilon(j\omega) \mathbf{E}_0 e^{j\omega t} = \sigma \mathbf{E} + j\omega \varepsilon \mathbf{E} \end{aligned}$$

SOL 6.4.38

Option (C) is correct.

Equation (1) and (3) are not the Maxwell's equation.

SOL 6.4.39

Option (A) is correct.

From the Maxwell's equation for a static field (DC) we have

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}$$

$$\nabla \times (\nabla \times \mathbf{A}) = \mu_0 \mathbf{J}$$

$$\nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = \mu_0 \mathbf{J}$$

For static field (DC),

$$\nabla \cdot \mathbf{A} = 0$$

therefore we have,

$$\nabla^2 \mathbf{A} = -\mu_0 \mathbf{J}$$

So, both A and R are true and R is correct explanation of A.

SOL 6.4.40

Option (A) is correct.

For a static field, Maxwells equation is defined as

$$\nabla \times \mathbf{H} = \mathbf{J}$$

and since divergence of the curl is zero

$$\text{i.e.} \quad \nabla \cdot (\nabla \times \mathbf{H}) = 0$$

$$\nabla \cdot \mathbf{J} = 0$$

but in the time varying field, from continuity equation (conservation of charges)

$$\nabla \cdot \mathbf{J} = -\frac{\partial \rho_v}{\partial t} \neq 0$$

So, an additional term is included in the Maxwell's equation.

$$\text{i.e.} \quad \nabla \times \mathbf{H} = \mathbf{J} + \frac{\partial \mathbf{D}}{\partial t}$$

Sample Chapter of Electromagnetics (Vol-10, GATE Study Package)

Page 423

Chap 6

Time Varying Fields and
Maxwell Equations

where $\frac{\partial \mathbf{D}}{\partial t}$ is displacement current density which is a necessary term.

Therefore A and R both are true and R is correct explanation of A.

SOL 6.4.41

Option (C) is correct.

Since, the circular loop is rotating about the y -axis as a diameter and the flux lines is directed in \mathbf{a}_x direction. So, due to rotation magnetic flux changes and as the flux density is function of time so, the magnetic flux also varies w.r.t time and therefore the induced e.m.f. in the loop is due to a combination of transformer and motional e.m.f. both.

SOL 6.4.42

Option (A) is correct.

For any loop to have an induced e.m.f., magnetic flux lines must link with the coil.

Observing all the given figures we conclude that loop C_1 and C_2 carries the flux lines through it and so both the loop will have an induced e.m.f.

SOL 6.4.43

Option (C) is correct.

Gauss's law $\nabla \cdot \mathbf{D} = \rho$ (a \rightarrow 1)

Ampere's law $\nabla \times \mathbf{H} = \mathbf{J}_c + \frac{\partial \mathbf{D}}{\partial t}$ (b \rightarrow 5)

Faraday's law $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$ (c \rightarrow 2)

Poynting vector $\mathcal{P} = \mathbf{E} \times \mathbf{H}$ (d \rightarrow 3)

www.nodia.co.in

