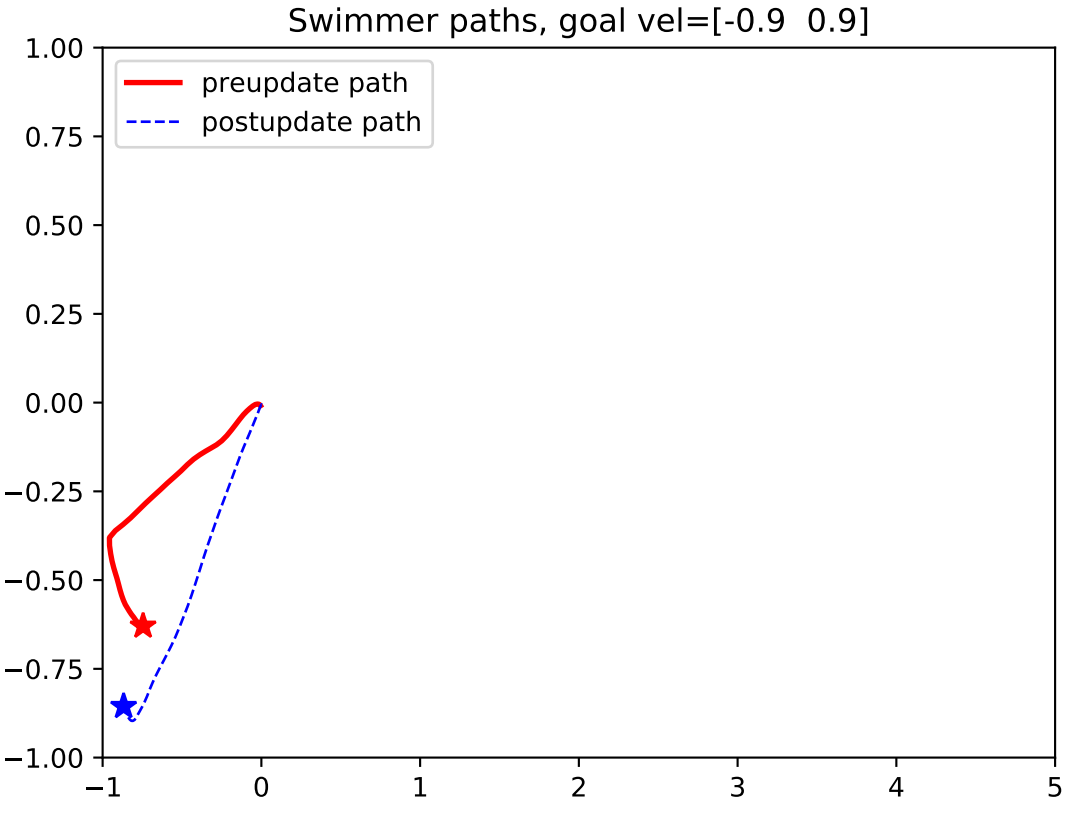
Swimmer paths, goal vel=[-0.9 0.9]
preupdate path
postupdate path
1.00
0.75
0.50
0.25
0.00
−0.25
−0.50
−0.75
−1.00
−1
0
1
2
3
4
5