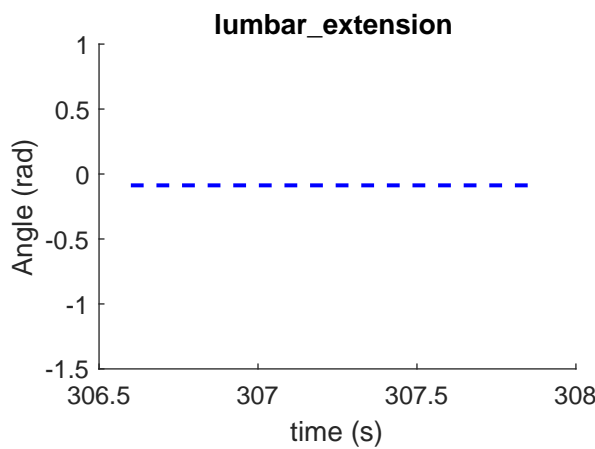
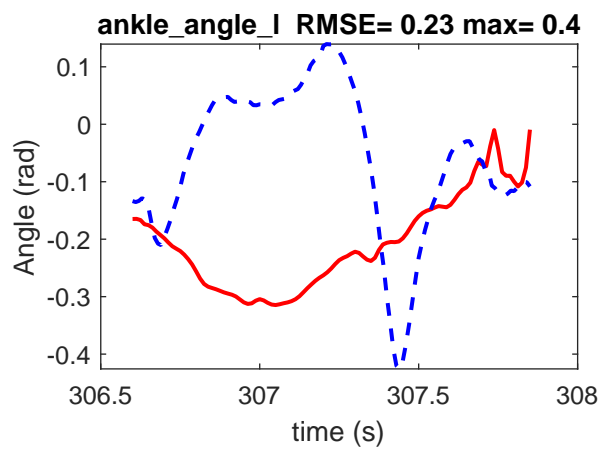
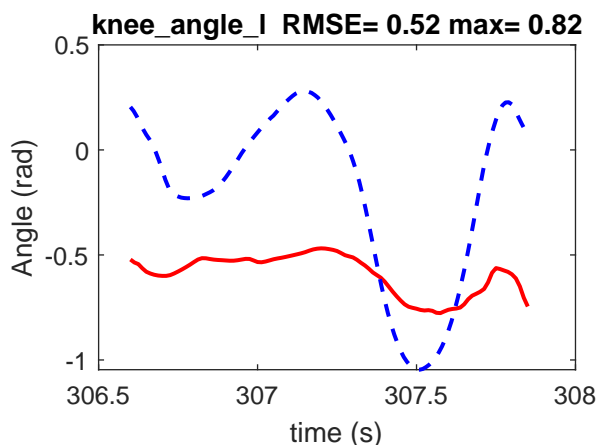
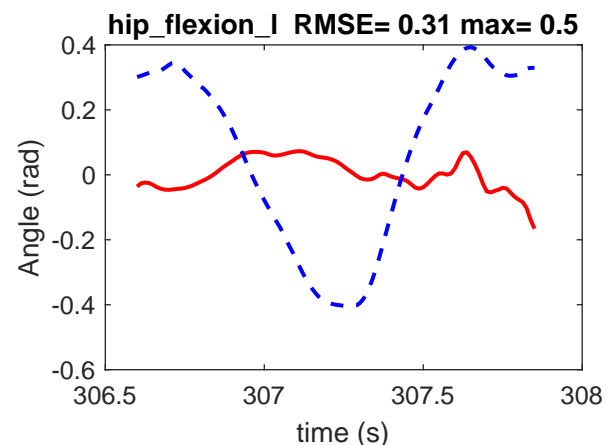
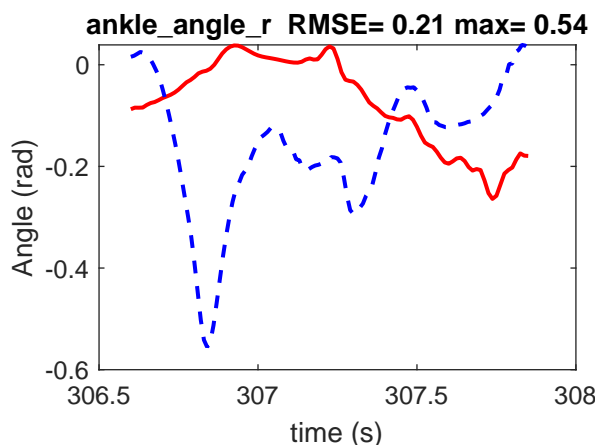
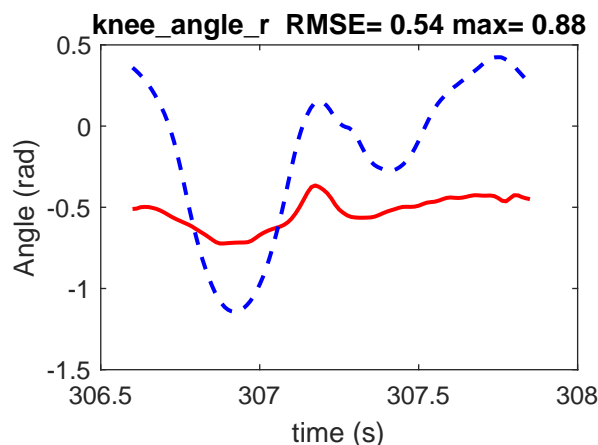
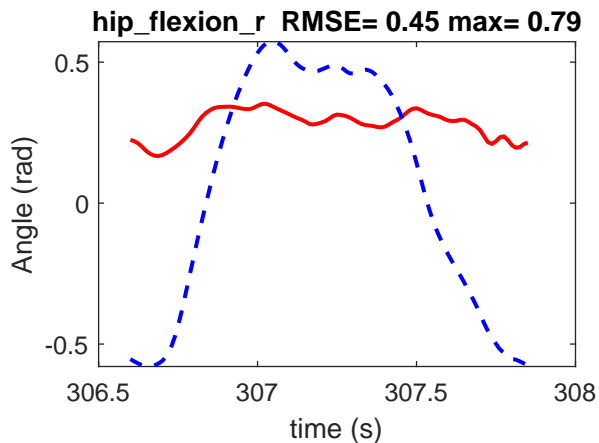
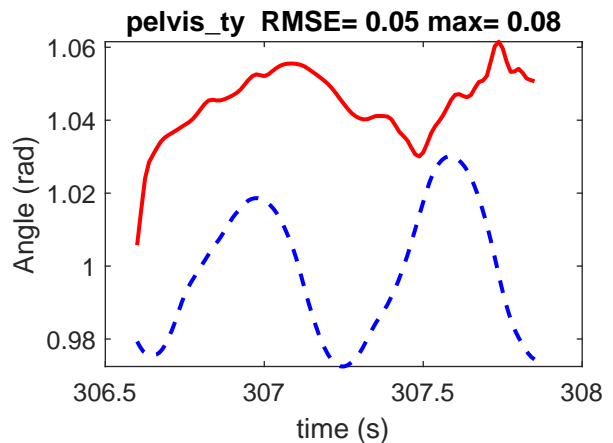
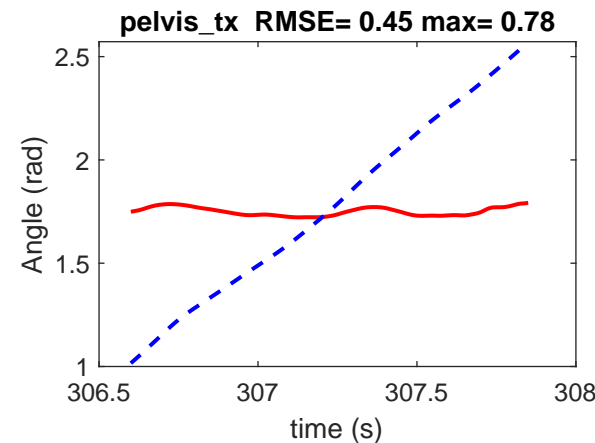
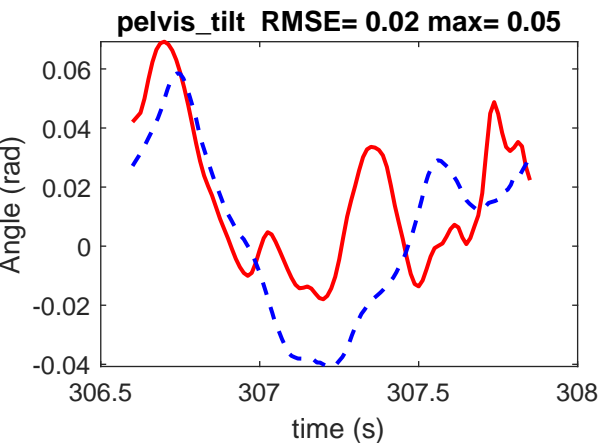
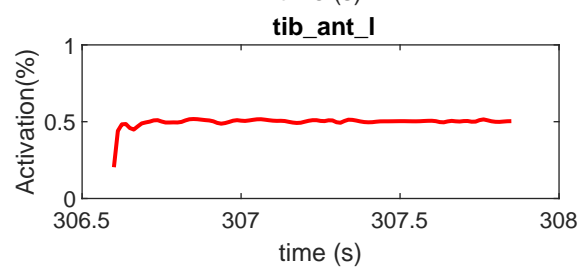
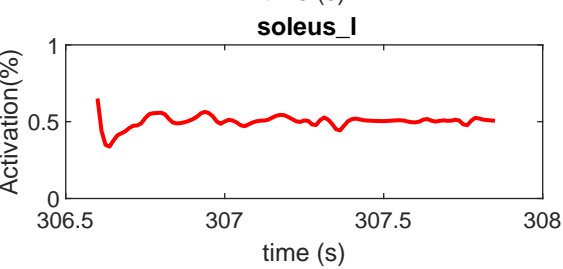
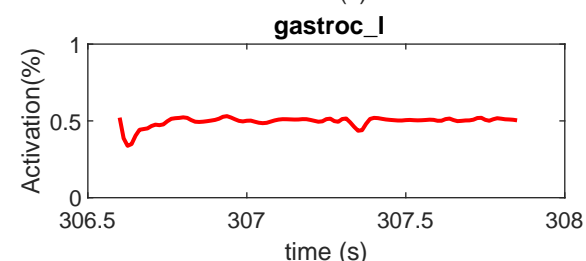
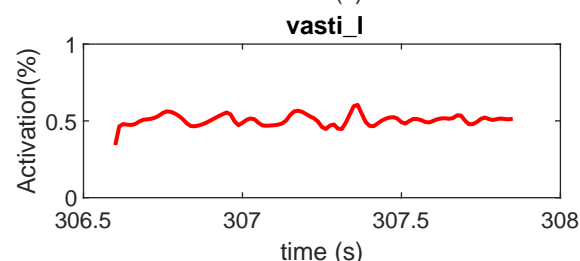
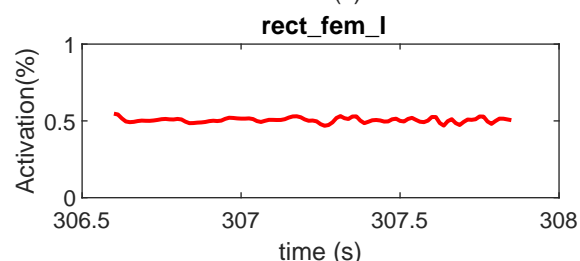
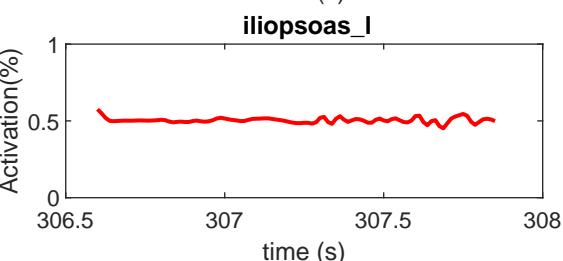
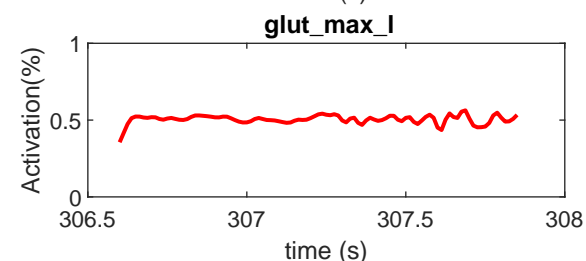
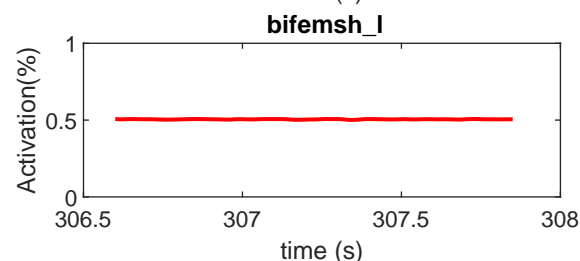
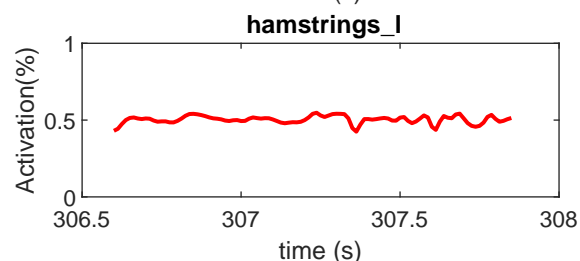
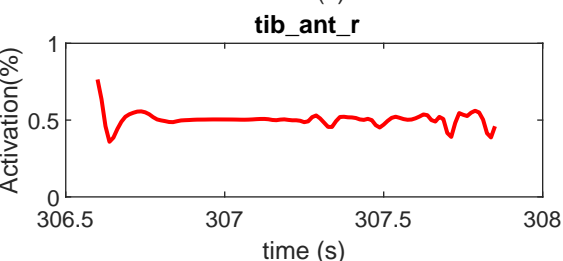
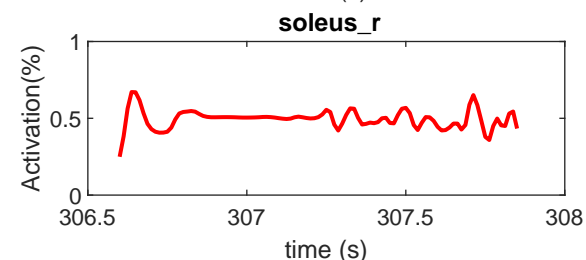
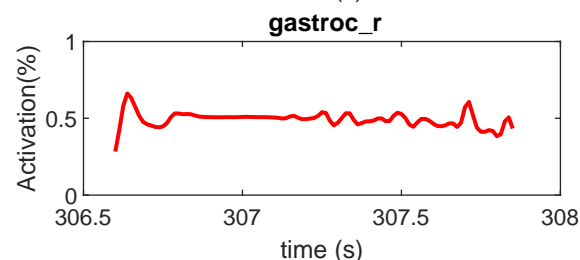
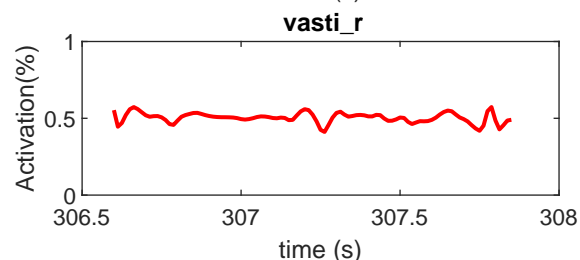
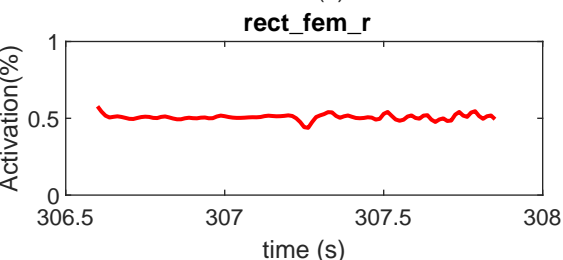
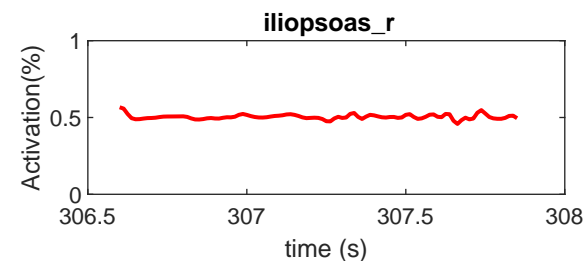
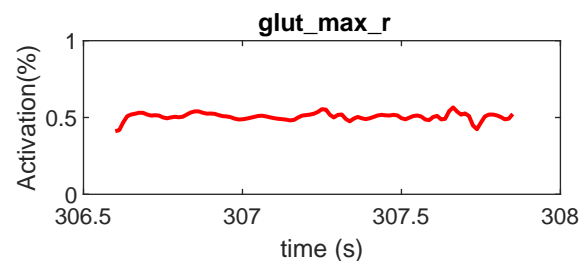
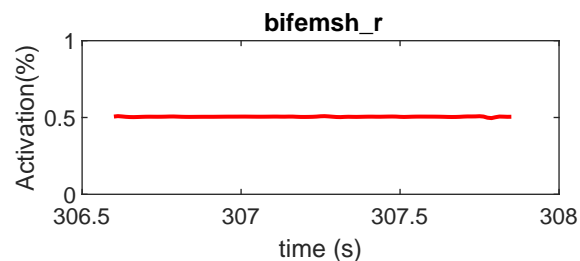
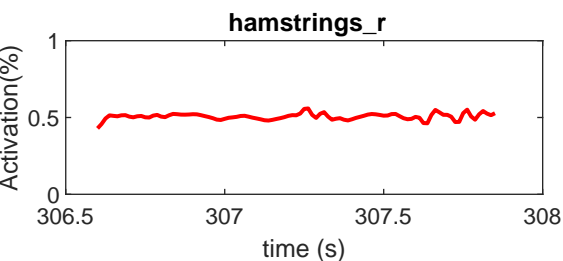


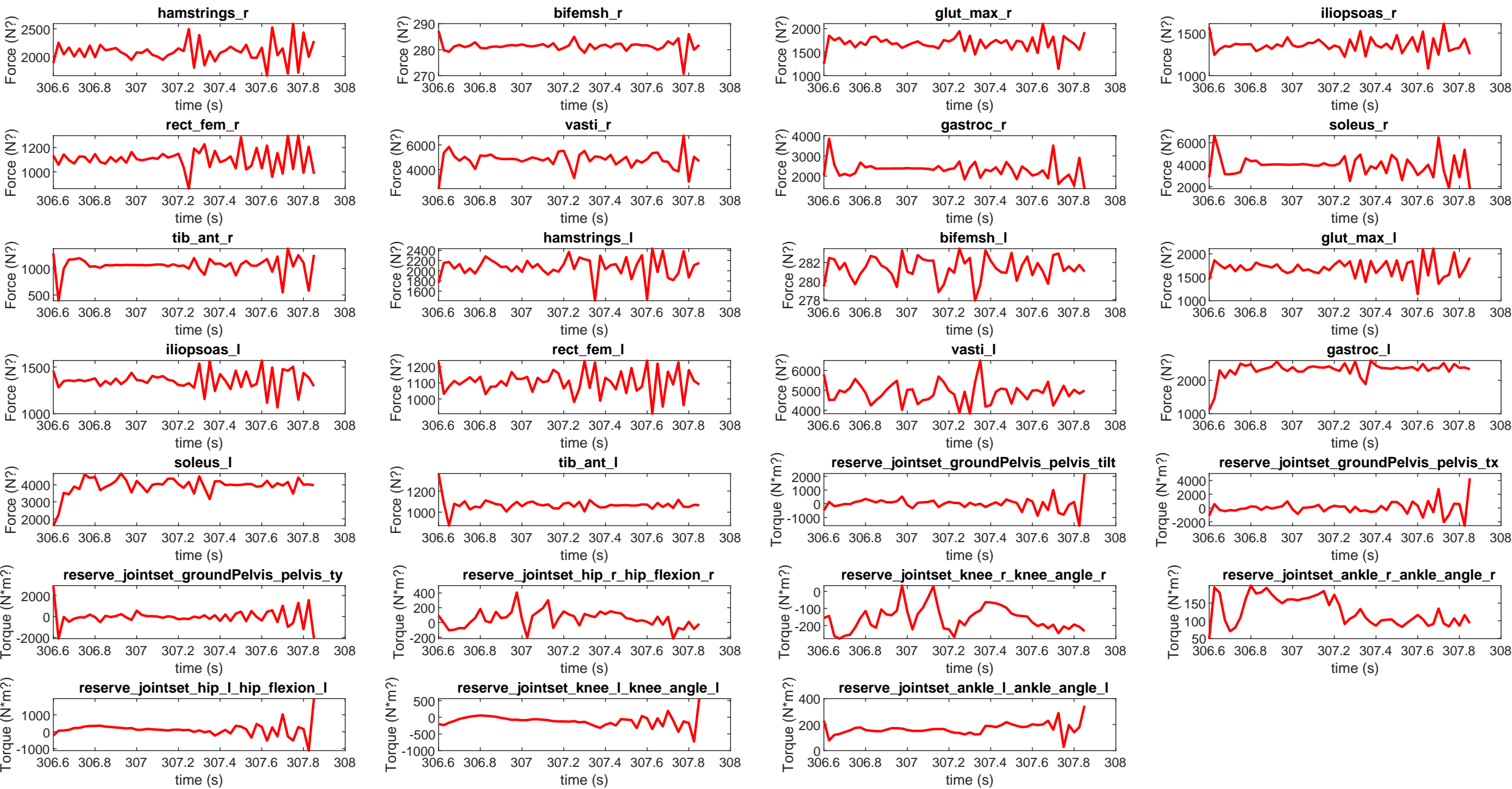
Joint Angles (red= tracking output , blue= reference ); avg, max RMSE = 0.31045 , 0.53627



# Muscle Activity (red=tracking output, blue=reference)



# Muscle Force (red=tracking output, blue=reference)



GRF (red= tracking output , blue= reference ); avg, max RMSE = 17.7096 , 126.9814

