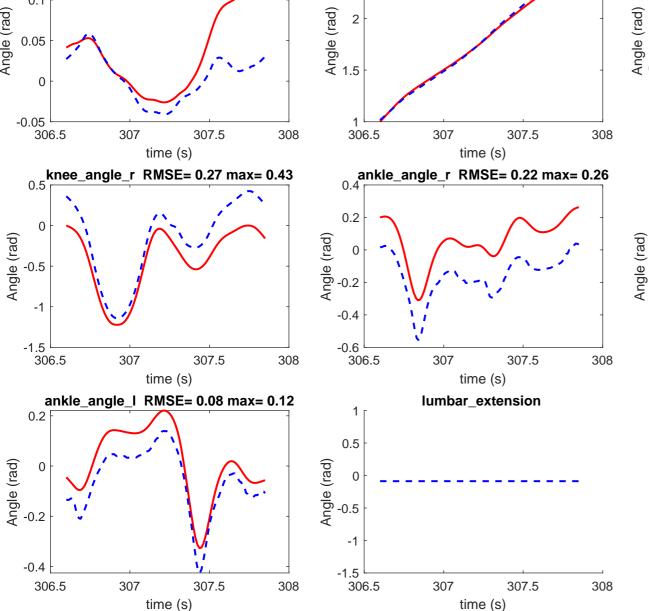
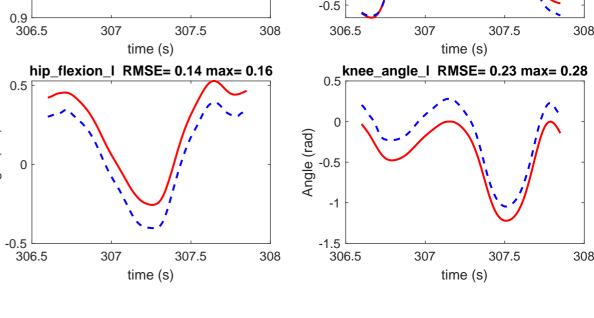
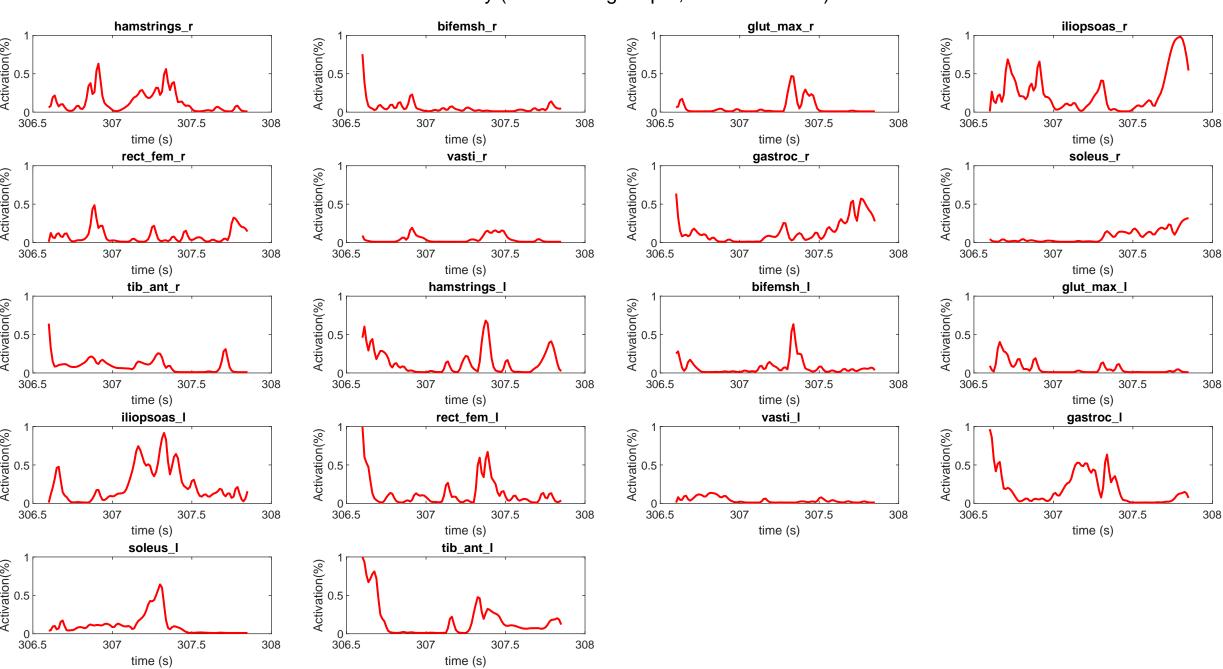
Joint Angles (red= tracking output, blue= reference); avg, max RMSE = 0.11796, 0.2709 pelvis_ty RMSE= 0.01 max= 0.05 pelvis_tilt RMSE= 0.05 max= 0.12 pelvis_tx RMSE= 0.03 max= 0.07 hip_flexion_r RMSE= 0.04 max= 0.09 0.15 2.5 0.5 0.1 Angle (rad) 5.1 Angle (rad) 26.0 26.0 Angle (rad) 0 -0.5 0.9 307 307.5 307 307.5 307 307.5 306.5 307 308 306.5 308 306.5 308 time (s) time (s) time (s) time (s)

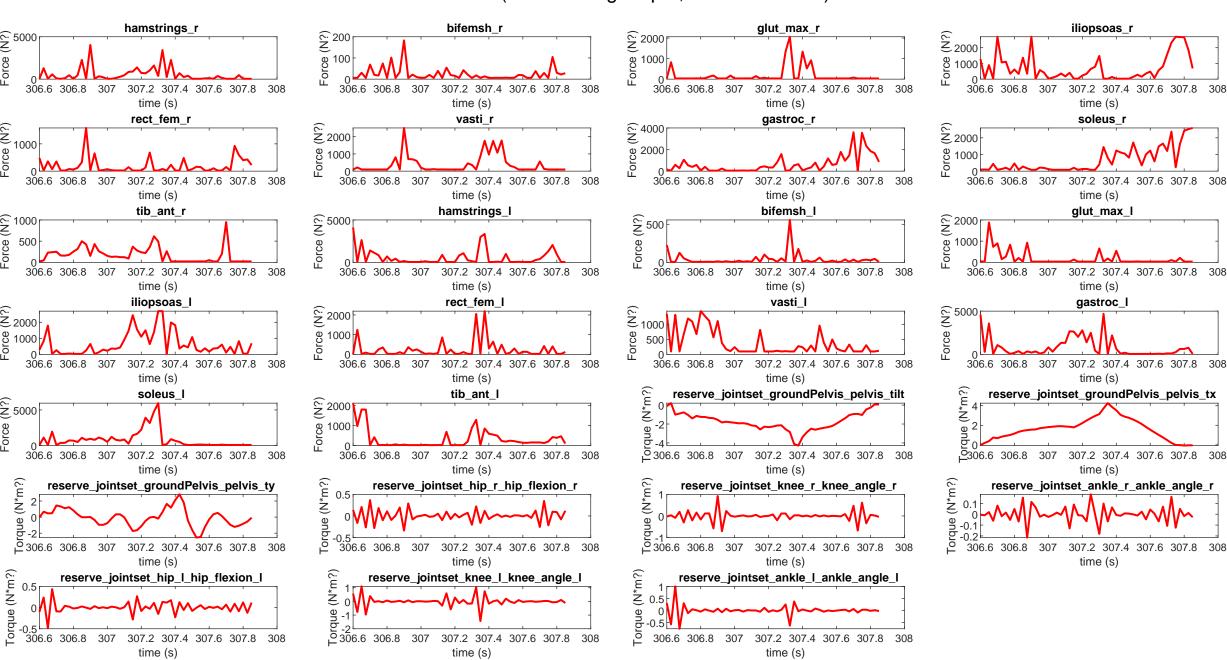




Muscle Activity (red=tracking output, blue=reference)



Muscle Force (red=tracking output, blue=reference)



GRF (red= tracking output, blue= reference); avg, max RMSE = 34.6353, 227.382

