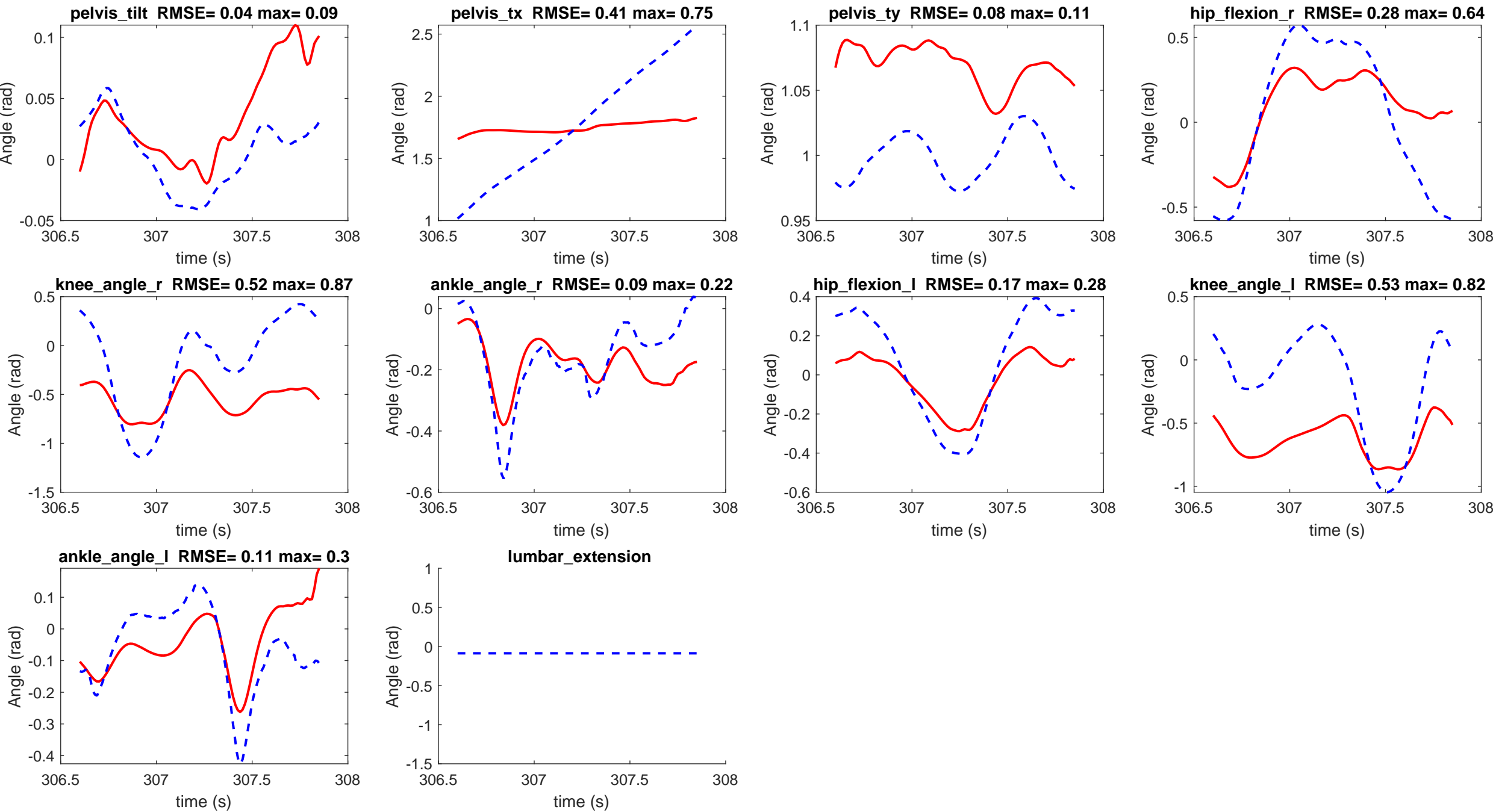
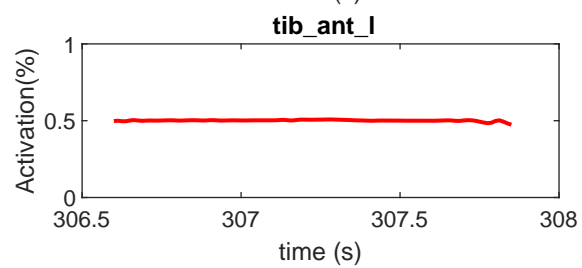
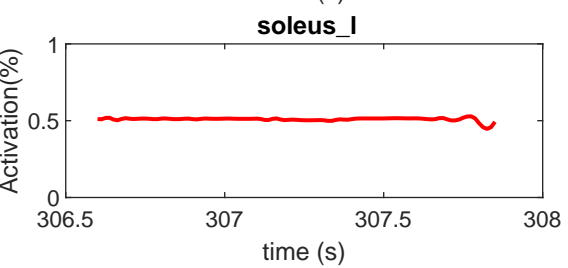
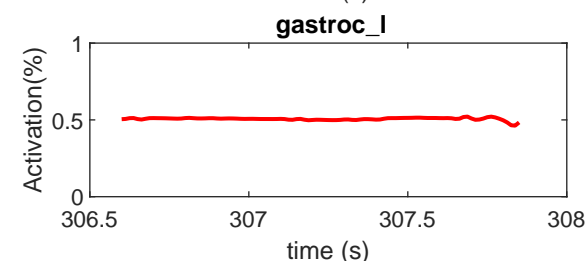
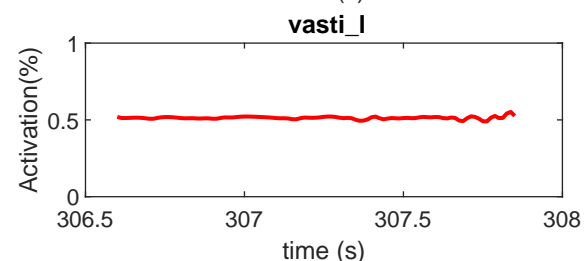
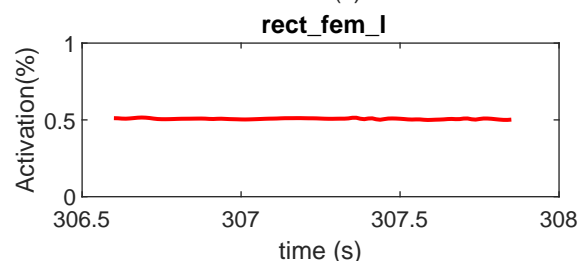
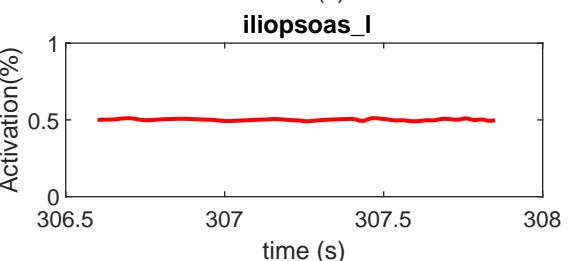
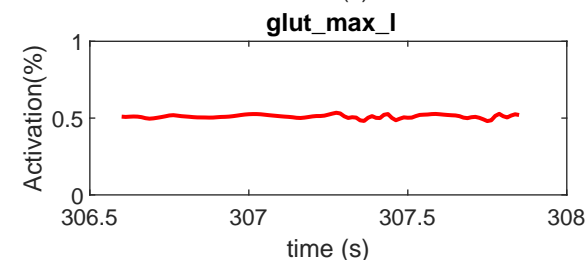
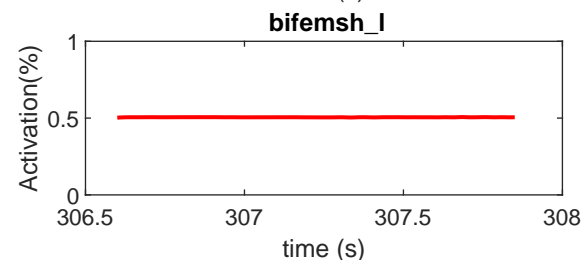
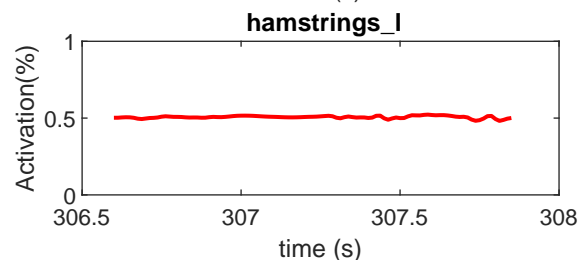
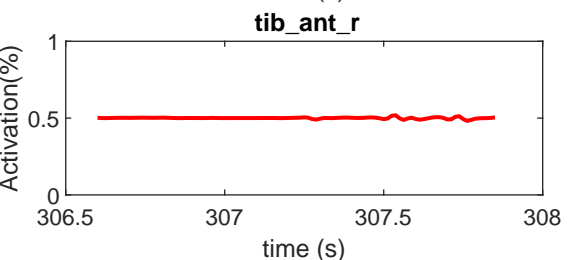
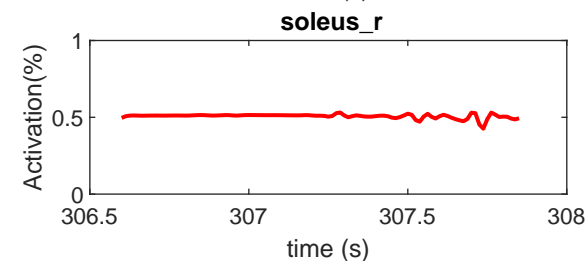
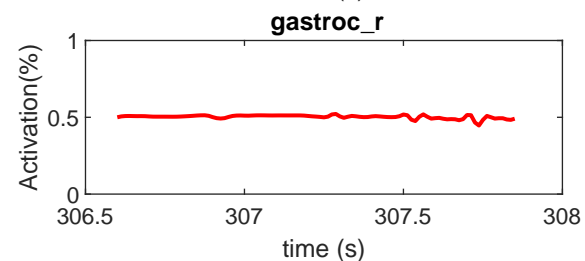
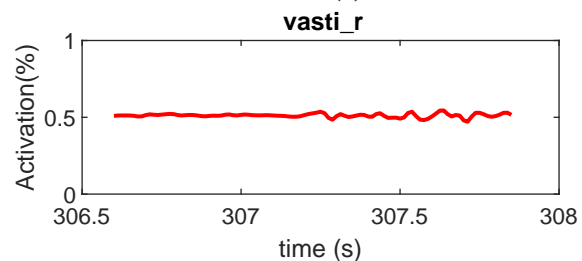
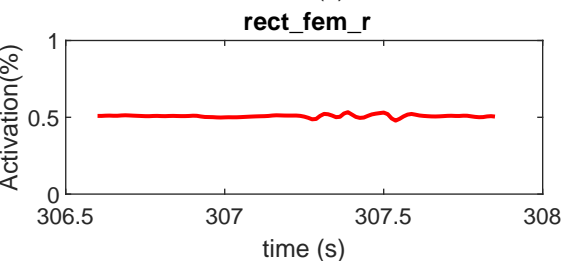
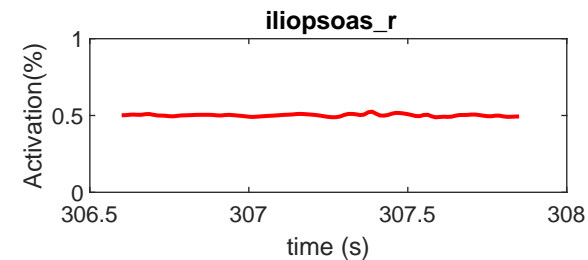
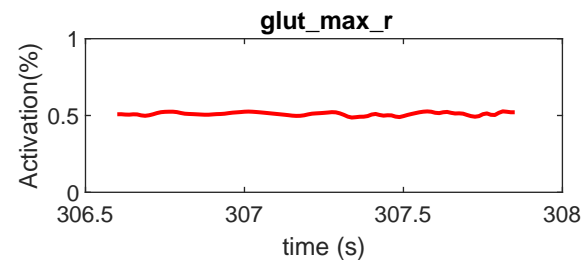
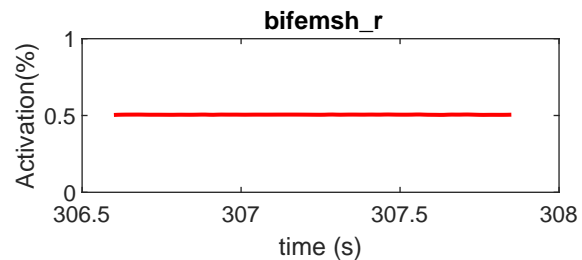
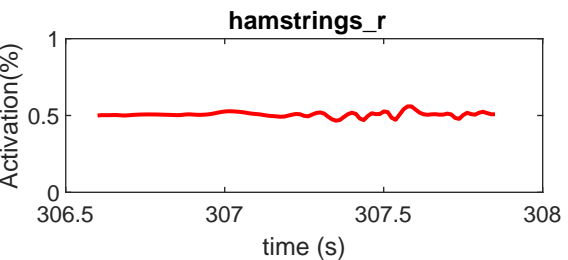


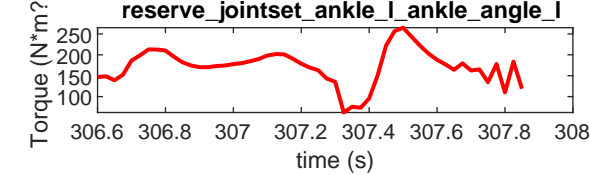
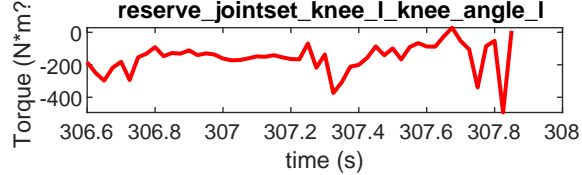
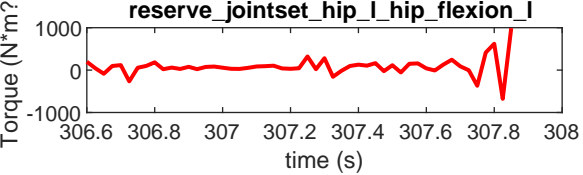
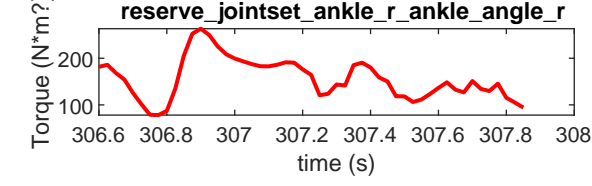
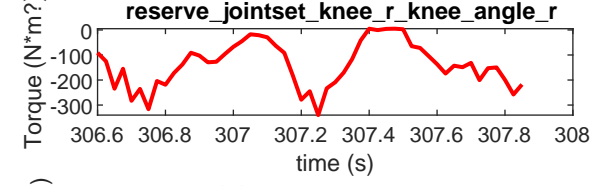
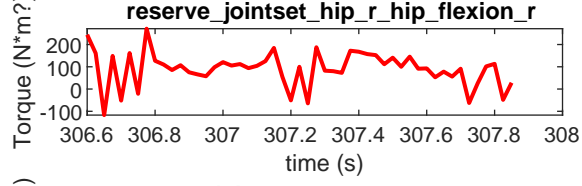
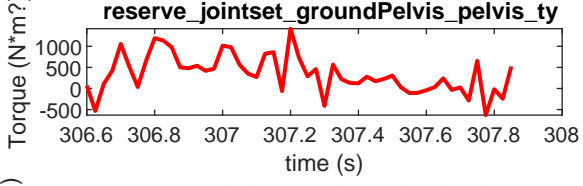
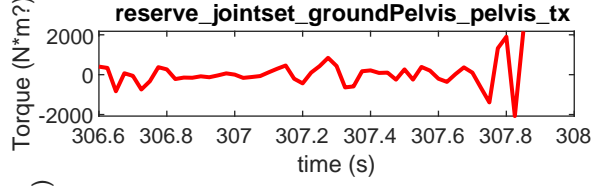
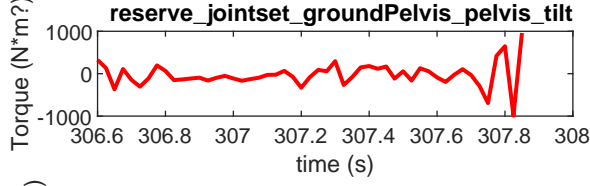
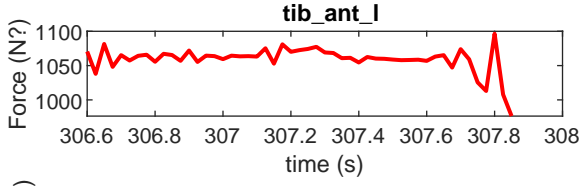
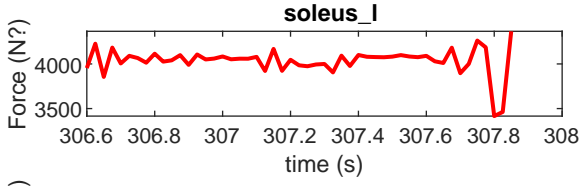
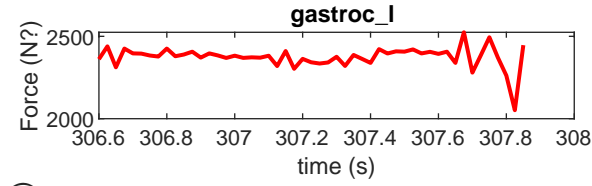
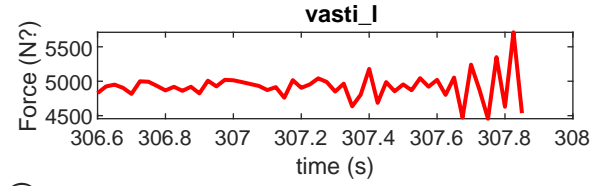
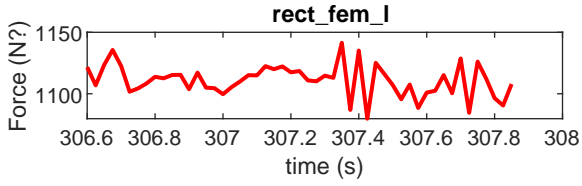
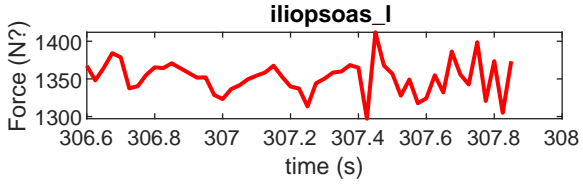
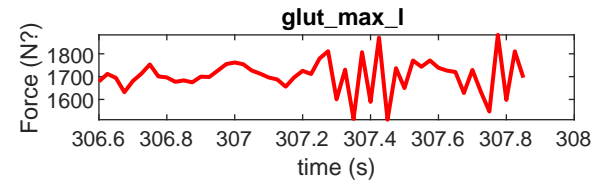
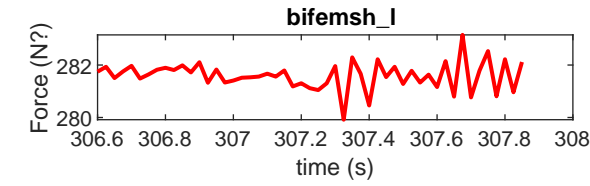
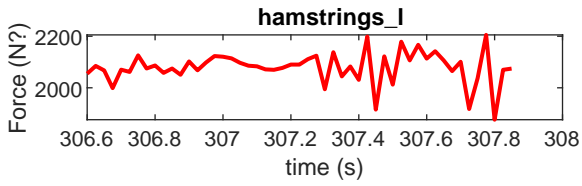
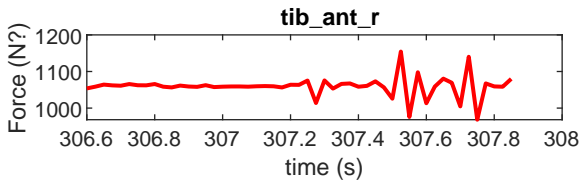
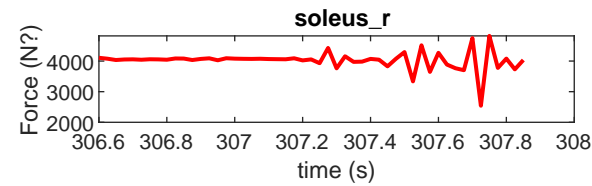
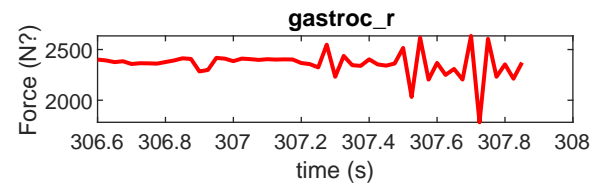
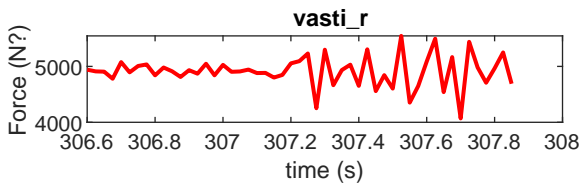
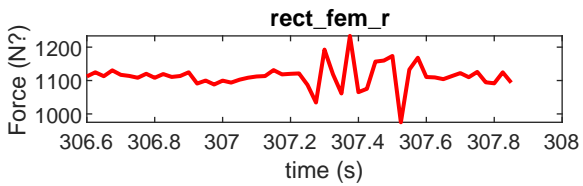
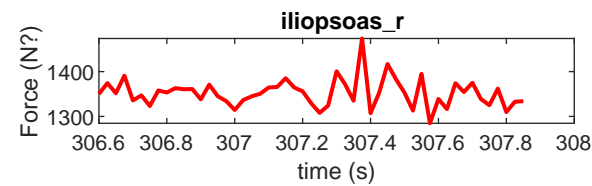
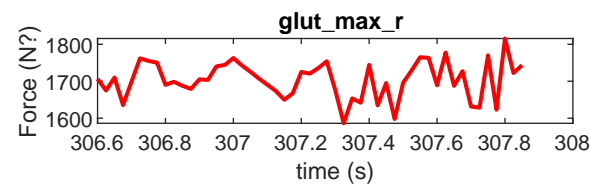
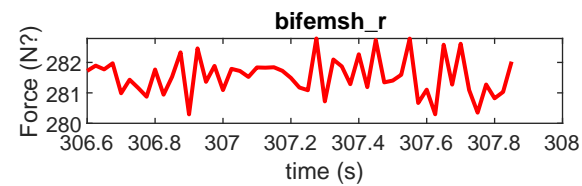
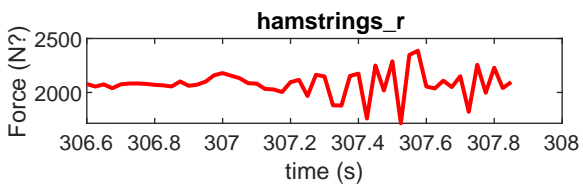
Joint Angles (red= tracking output , blue= reference ); avg, max RMSE = 0.24941 , 0.5327



Muscle Activity (red=tracking output, blue=reference)



# Muscle Force (red=tracking output, blue=reference)



GRF (red= tracking output , blue= reference); avg, max RMSE = 69.304 , 449.211

