

Getting Started Embedded Rust on micro:bit v2

Michael Schury

2023-06-28

Introduction to micro:bit v2

microbit.org PLEASE USE only microbit v2(!)

- ▶ Nordic nRF52833 ARM Cortex-M4
- ▶ Peripherals on board:
 - ▶ 5x5 LED matrix,
 - ▶ Buttons,
 - ▶ GPIOs,
 - ▶ Accelerometer,
 - ▶ Bluetooth,
 - ▶ Crocodile Clips, Light Sensor, Speaker, Microphone, External Power,
 - ▶ etc.

Live Demonstration

► Create Project

```
cargo generate microbit-rust-nostd \  
  --name myproject  
# or remote  
cargo generate \  
  --git https://github.com/br0kenpixel/microbit-rust-nostd
```

► Connect microbit USB-C cable

► Run (build and flash)

```
cargo run
```

Setting up the Development Environment

Platform specific parts

<https://docs.rust-embedded.org/discovery/microbit/03-setup/index.html>

```
# rustup (rust version > 1.57)
```

```
rustc -V
```

```
# cargo-binutils
```

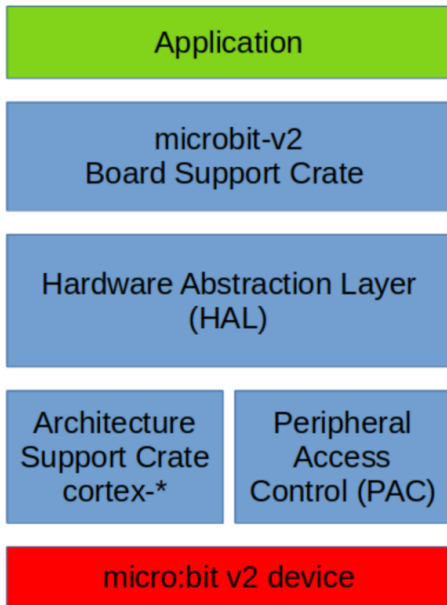
```
rustup component add llvm-tools-preview
```

```
cargo install cargo-binutils --vers 0.3.3
```

```
# cargo-embed
```

```
cargo install cargo-embed --vers 0.11.0
```

Rust Embedded Architecture



Walkthrough of the Created Project

- ▶ `.cargo/config` specifies runner, build target
- ▶ `Embed.toml` configures gdb, rtt
- ▶ `memory.x` describes where the RAM and FLASH are and their sizes
- ▶ `build.rs` ensures `memory.x` is in out directory

Walkthrough of the Created Project: src/main.rs

```
#![no_std] // core library
#![no_main] // custom entry point

use cortex_m_rt::entry;
use microbit::{board::Board, display::blocking::Display, hal::Timer};
use panic_rtt_target as _;
use rtt_target::{rprintln, rtt_init_print};

#[entry]
fn main() -> ! {
    rtt_init_print!();
    let board = Board::take().unwrap();
    ...
    loop {
        rprintln!("Hello!");
    }
}
```

Examples in microbit Crate

```
git clone https://github.com/nrf-rs/microbit
```

```
# example: display blocking
```

```
cargo run --release \  
  --features v2 --target thumbv7em-none-eabihf \  
  --manifest-path ./examples/display-blocking/Cargo.toml
```

```
# example text with Real-Time Interrupt-driven Concurrency (RTIC)
```

```
cargo run --release \  
  --features v2 --target thumbv7em-none-eabihf \  
  --manifest-path ./examples/display-text-rtic/Cargo.toml
```


Testing Embedded Rest

Ferrous Article Serie “Testing an embedded application”

<https://ferrous-systems.com/blog/test-embedded-app/>

Whenever possible you should test your firmware code on the host.

Debugging

Using GDB <https://docs.rust-embedded.org/discovery/microbit/05-led-roulette/debug-it.html>

probe-rs in vscode <https://probe.rs/docs/tools/vscode/>

Ressources

<https://docs.rust-embedded.org/>

<https://github.com/rust-embedded/awesome-embedded-rust>

<https://docs.rust-embedded.org/discovery/microbit/>

<https://embedded-trainings.ferrous-systems.com>

<https://docs.rust-embedded.org/embedonomicon>

Advanced Topics

- ▶ RTOS
- ▶ embassy: embedded async tools
- ▶ drogue-device
 - ▶ <https://github.com/drogue-iot/drogue-device>
 - ▶ <https://book.drogue.io/drogue-device/dev/examples/nrf52/microbit/ble/README.html> describes using Bluetooth on microbit for data and also supports updating the firmware via Bluetooth