Physics Formulae

1. Vectors

- ullet Seperating Vectors $\overrightarrow{A}+\overrightarrow{B}=\overrightarrow{A_x}+\overrightarrow{B_x}+\overrightarrow{A_y}+\overrightarrow{B_y}$
- $\begin{array}{ccc} \circ & \text{Unit vectors} & \overrightarrow{\frac{A}{|\overrightarrow{A}|}} \\ \circ & \text{Cross Product} & \overrightarrow{A} \times \overrightarrow{B} = |\overrightarrow{A}| \times |\overrightarrow{B}| sin(\theta) \end{array}$
- \circ Scalar product $\overrightarrow{A}\cdot\overrightarrow{B}=|\overrightarrow{A}| imes|\overrightarrow{B}|cos(\overrightarrow{ heta})=A_1B_1+A_2B_2+...A_nB_n$

2. Displacement Velocity and Acceleration

- \circ $s = \int v(t)dt$
- $\begin{array}{l} \circ \ \ v = \frac{d(s(t))}{dt} \text{ or } \int a(t) dt \\ \circ \ \ a = \frac{d(v(t))}{dt} \end{array}$
- $\circ v = u + at$
- \circ $s=rac{1}{2}(u+v)t$
- \circ $s = ut + \frac{1}{2}at^2$
- $v^2 = u^2 + 2as$

3. Moment of Inertia

- $I = ml^2$ for a point at distance I from axis
- $\circ~I=\int_0^M r^2 dm$
- For rod mass M with axis perpendicular to longest side length L
 - through center $I=rac{1}{12}ML^2$
 - through one end $I=\frac{1}{3}ML^2$
- \circ For rectangular plate axis a long, b wide
 - \perp , center of larger side $I=rac{1}{12}M(a^2+b^2)$
 - Along edge of longer side $I = \frac{1}{3} Ma^2$

For Cylinder R

- $I=rac{1}{2}MR^2$ Solid cylinder
- lacksquare Tube inner radius R_1 , $I=rac{1}{2}M(R^2+R_1^2)$
- lacksquare R-R1 neglectable $I=MR^2$

\circ Sphere with R

- $\begin{tabular}{ll} \bullet & {\rm solid} & I = \frac{2}{5}MR^2 \\ \bullet & {\rm hollow} & I = \frac{2}{3}MR^2 \\ \end{tabular}$

4. Inertia Changing Axis

- $\circ \;\;$ Parallelly shifted d $\;\; I = I + M d^2$
- $I=\frac{1}{2}I$ Perpendicular

5. Circular Motion

- Acceleration(a and lpha) $a=rac{v^2}{r}=r\omega^2=lpha r$
- Period $T = \frac{2\pi}{\omega}$

6. Newtons's Laws

- \circ F=ma
- $\circ F = \frac{\Delta P}{\Delta t}$

7. Moment

- $\circ T = Fd$
- $\circ T = I\alpha$

- 8. Momentum & Impulse
 - \circ p=mv
 - \circ J=Ft
 - $\circ \ J = \int_{t_1}^{t_2} \overrightarrow{F} dt$
- 9. Friction
 - \circ Limiting $f=\mu R$
- 10. Gravity

 - $F = -\frac{GMm}{r^2}$ $\phi = -\frac{Gm}{r}$
- 11. Charge
 - $\circ \ V = rac{Q}{4\piarepsilon_0 r}$
- 12. Gas
 - \circ Work done $W=p\Delta V$
 - Hydrostatic Pressure $p = \rho g h$
- 13. SHM
 - $\circ \ a = -\omega^2 x$
 - $\circ \ v = v_0 cos(\omega t)$
 - $\circ \ v=\pm \omega (x_0^2-x^2)$
- 14. Doppler Effect
 - \circ $f_0=rac{f_s v}{v\pm v_s}$
- 15. Capacitor
 - \circ Series $\frac{1}{C} = \sum_{1}^{n} \frac{1}{C_{n}}$
- o Parallel $C=\sum_1^n C_n$ 16. Resistors Series $R=\sum_1^n R_n$ Parallel $\frac{1}{R}=\sum_1^n \frac{1}{R_n}$
- 17. Hall Voltage
 - $\circ V_h = rac{BI}{nta}$
- 18. Energy
 - \circ Gravitational mgh
 - \circ Kinetic $\frac{1}{2}mv^2$
 - \circ Spring $\frac{1}{2}kx^2$
 - \circ Rotational $rac{1}{2}I\omega^2$
 - \circ Work done $w=\int F(x)dx$ \circ Power $P=\frac{\Delta W}{\Delta t}$

 - $\circ \;\;$ Power for Constant Speed P=FV
- 19. Rotational Bodies Angular Velocity and Acceleration
 - \circ Displacement s=r heta
 - \circ Velocity $\omega = rv = rac{\Delta heta}{\Delta t}$
 - Acceleration $lpha=ar=rac{\Delta\omega}{\Delta t}$
- 20. Elasticity

 - $\begin{array}{ll} \circ & \mathrm{strain} \; \varepsilon = \frac{x}{L} \\ \circ & \mathrm{stress} \; \sigma = \frac{F}{A} \end{array}$
 - \circ Young Modulus $Y = \frac{\sigma}{\varepsilon}$
 - $egin{array}{l} ullet & T = rac{\lambda x}{l} \ ullet & E = rac{\lambda x^2}{2l} \end{array}$