Vector Rotation

The Problem
Three Algorithms
Implementations

The Problem

The Problem

Rotate vector x[n] left by d positions.

For n=8 and d=3, change abcdefgh to defghabc.

Constraints: O(n) time, O(1) extra space.

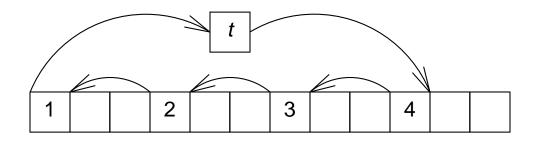
Pricey Solutions

Store d in intermediate vector, shift the rest, store back. [O(n)] extra space.

Rotate by 1 d times. [O(n) time.]

A Juggling Algorithm

The Idea (n=12, d=3)



The Code

```
for i = [0, gcd(d, n))
    /* move i-th values of blocks */
    t = x[i]
    j = i
    loop
        k = j + d
        if k >= n
            k -= n
        if k == i
            break
        x[j] = x[k]
        j = k
    x[j] = t
```

The Block-Swap Algorithm

The Idea: Change ab to ba

If a is shorter, divide b into b_I and b_r .

Swap a and b_r to change ab_lb_r into b_rb_la .

Recur on pieces of b.

The Code

```
if d == 0 || d == n
    return
i = p = d
j = n - p
while i != j
    if i > j
        swap(p-i, p, j)
        i -= j
    else
        swap(p-i, p+j-i, i)
        j -= i
swap(p-i, p, i)
```

The Reversal Algorithm

The Idea

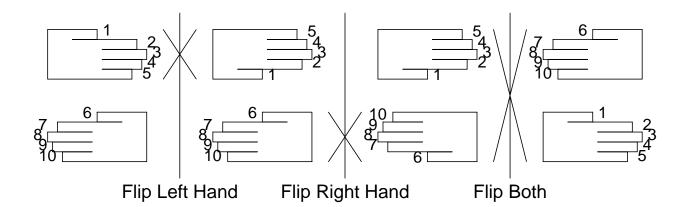
Reverse a to get a^rb.

Reverse b to get a^rb^r .

Reverse all to get $(a^rb^r)^r = ba$.

The Code /* rotate abcdefgh left three */

Doug McIlroy's Handwaving Description



An Experiment on Run Times

 $n = 10^6$, 400MHz Pentium II.

