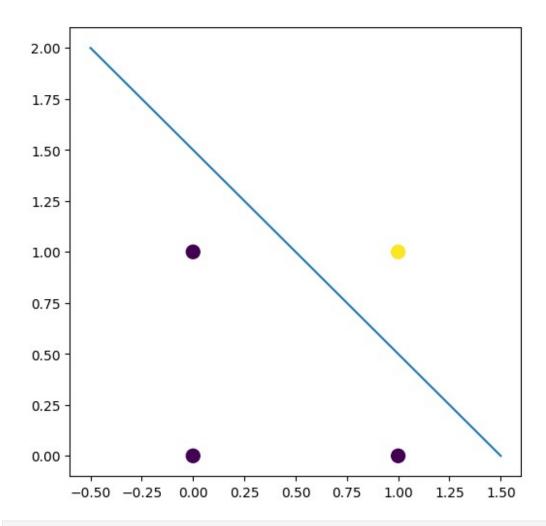
```
import numpy as np
def m p(inputs, weights, threshold):
    weight_sum=np.dot(inputs,weights)
    if weight sum>=threshold:
        output=1
    else:
        output=0
    return output
print("x1")
x1=[]
for i in range(4):
    a=int(input())
    x1.append(a)
print("x2")
x2=[1]
for i in range(4):
    a=int(input())
    x2.append(a)
def and_not(x1,x2):
    weights=[0.5, -0.5]
    threshold=0.5
    outputs=[]
    for i in range(len(x1)):
        inputs=np.array([x1[i],x2[i]])
        output=m p(inputs, weights, threshold)
        outputs.append(output)
    return outputs
result=and not(x1,x2)
print("output:", result)
x1
 0
 0
 1
 1
x2
 0
 1
 0
 1
output: [0, 0, 1, 0]
import numpy as np
def aggregation(inputs, weights, bias):
```

```
weight sum=np.dot(inputs,weights)+bias
    return weight sum
def tlu(weight_sum,threshold):
    if weight sum>=threshold:
        output=1
    else:
        output=0
    return output
a=[
    {'input':[1,1,0,0,0,0,0]},
    {'input':[1,1,0,0,0,1]},
    {'input':[1,1,0,0,1,0]},
    {'input':[1,1,0,0,1,1]},
    {'input':[1,1,0,1,0,0]},
    {'input':[1,1,0,1,0,1]},
    {'input':[1,1,0,1,1,0]},
    {'input':[1,1,0,1,1,1]},
    {'input':[1,1,1,0,0,0]},
    {'input':[1,1,1,0,0,1]},
threshold=float(input("enter threshold"))
n=float(input("enter eta"))
weights=[0,0,0,0,0,1]
bias=0.1
for data in a:
    inputs=np.array(data['input'])
    if np.sum(inputs)%2==0:
        d=0
    else:
        d=1
def error(d,output):
    error=d-output
    return error
def weight change(d,inputs,error):
    w=np.dot(d,error*inputs)
    weights+=w
    return weights
a=int(input("enter value between 0 to 9"))
inputs=np.array([int(bit) for bit in bin(a) [2:].zfill(6)])
weight sum=aggregation(inputs, weights, bias)
outputs=tlu(threshold,weight_sum)
if outputs==1:
    outputs='even'
else:
    outputs='odd'
print(outputs)
```

```
enter threshold 0.5
enter eta 0.1
enter value between 0 to 9 6
even
import numpy as np
import matplotlib.pyplot as plt
x=np.array([[0,0],[0,1],[1,0],[1,1]])
y=np.array([0,0,0,1])
w1, w2=1, 1
b = -1.5
def perceptron(x,w1,w2,b):
    if (w1*x[0]+w2*x[1]+b)>=0:
        return 1
    else:
        return 0
plt.figure(figsize=(6,6))
plt.scatter(x[:,0],x[:,1],c=y,s=100)
x_{line=np.linspace(-0.5,1.5,100)}
y line=(-w1*x line-b)/w2
plt.plot(x_line,y_line)
plt.show()
```



```
import numpy as np

# Activation function and its derivative (Sigmoid)
def sigmoid(x):
    return 1 / (1 + np.exp(-x))

def sigmoid_derivative(x):
    return x * (1 - x)

# Training data (XOR problem as a simple test)
X = np.array([
    [0, 0],
    [0, 1],
    [1, 0],
    [1, 1]
])

# Expected output (XOR)
y = np.array([[0], [1], [0]])
```

```
# Initialize weights and biases randomly
np.random.seed(42)
input layer size = 2
hidden layer size = 4
output layer size = 1
# Weights
weights input hidden = np.random.rand(input layer size,
hidden layer size)
weights hidden output = np.random.rand(hidden layer size,
output layer size)
# Biases
bias hidden = np.random.rand(1, hidden_layer_size)
bias output = np.random.rand(1, output layer size)
# Training loop
epochs = 10000
learning rate = 0.1
for epoch in range(epochs):
   # ----- FORWARD PROPAGATION ---
   # Hidden layer
   hidden input = np.dot(X, weights input hidden) + bias hidden
   hidden output = sigmoid(hidden input)
   # Output layer
   final input = np.dot(hidden output, weights hidden output) +
bias output
   final output = sigmoid(final input)
   # ----- BACKPROPAGATION -----
   # Error at output
   error = y - final_output
   d output = error * sigmoid derivative(final output)
   # Error at hidden layer
   error_hidden = d_output.dot(weights_hidden_output.T)
   d hidden = error hidden * sigmoid derivative(hidden output)
   # Update weights and biases
   weights hidden output += hidden output.T.dot(d output) *
learning rate
   bias output += np.sum(d output, axis=0, keepdims=True) *
learning rate
   weights input hidden += X.T.dot(d hidden) * learning rate
   bias hidden += np.sum(d hidden, axis=0, keepdims=True) *
learning rate
```

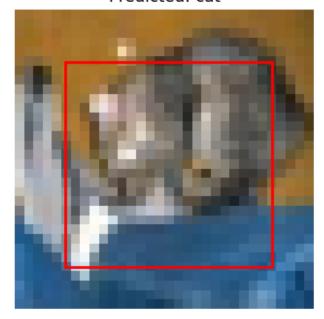
```
# Print loss every 1000 epochs
    if epoch % 1000 == 0:
        loss = np.mean(np.square(error))
        print(f"Epoch {epoch}, Loss: {loss:}")
# Final predictions
print("\nFinal Output After Training:")
print(final output.round(3))
print(final output.round())
Epoch 0, Loss: 0.38554734413938047
Epoch 1000, Loss: 0.2394687602093746
Epoch 2000, Loss: 0.18982505370553016
Epoch 3000, Loss: 0.1314434744618484
Epoch 4000, Loss: 0.04596551010834204
Epoch 5000, Loss: 0.016832860014460226
Epoch 6000, Loss: 0.008781204174560069
Epoch 7000, Loss: 0.005601136933785677
Epoch 8000, Loss: 0.00399949926402412
Epoch 9000, Loss: 0.0030629455034079504
Final Output After Training:
[[0.05]]
 [0.947]
 [0.957]
 [0.051]]
[[0.]
 [1.]
 [1.]
 [0.]]
import tensorflow as tf
from sklearn.datasets import load iris
from sklearn.model selection import train test split
from sklearn.preprocessing import StandardScaler
# 1. Load and prepare data
X, y = load iris(return X y=True)
X train, X test, y train, y test = train test split(X, y,
test size=0.2, random state=42)
# Scale features - FIXED: First fit, then transform
scaler = StandardScaler()
X train = scaler.fit transform(X train)
X test = scaler.transform(X test) # Use the same scaler that was fit
on training data
# 2. Build and train model
model = tf.keras.Sequential([
    tf.keras.layers.Dense(3, activation='softmax', input shape=(4,))
```

```
1)
model.compile(optimizer='adam',
              loss='sparse categorical crossentropy',
              metrics=['accuracy'])
model.fit(X train, y train, epochs=100, verbose=0)
# 3. Evaluate
loss, accuracy = model.evaluate(X_test, y_test, verbose=0)
print(f"Test Accuracy: {accuracy:.2f}")
C:\Users\Rutik\AppData\Local\Programs\Python\Python310\lib\site-
packages\keras\src\layers\core\dense.py:87: UserWarning: Do not pass
an `input shape`/`input dim` argument to a layer. When using
Sequential models, prefer using an `Input(shape)` object as the first
layer in the model instead.
  super(). init (activity regularizer=activity regularizer,
**kwargs)
Test Accuracy: 0.90
import numpy as np
vector=np.array([[1,1,1,-1],
                 [-1,0,1,-1],
                 [1, -1, 0, -1],
                 [-1,1,-1,0]
                1)
weights=np.zeros((4,4))
for i in range(4):
    for j in range(4):
        if i==j:
            weights[i][j]=(vector[i]@vector[j])/4
def activation(x):
    if x \ge 0:
        return 1
    else:
        return -1
def hopfield(x,weights):
    y=np.copy(x)
    for i in range(4):
        sum=0
        for j in range(4):
            sum+=weights[i][j]*y[j]
        y[i]=activation(sum)
    return y
for i in range(4):
    print("input vector:",vector[i])
```

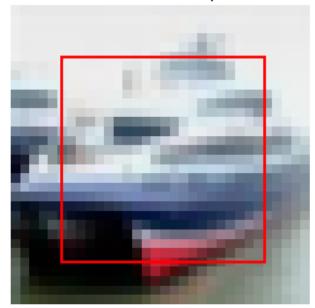
```
output=hopfield(vector[i], weights)
    print("output vector:",output)
input vector: [ 1 1 1 -1]
output vector: [ 1 1 1 -1]
input vector: [-1 0 1 -1]
output vector: [-1 1 1-1]
input vector: [ 1 -1 0 -1]
output vector: [ 1 -1 1 -1]
input vector: [-1 1 -1 0]
output vector: [-1 1 -1 1]
import numpy as np
import tensorflow as tf
from tensorflow.keras import layers, models, datasets
import matplotlib.pyplot as plt
# Load and preprocess data
(x_train, y_train), (x_test, y_test) = datasets.cifar10.load_data()
x train, x test = x train/255.0, x test/255.0
y train, y test = y train.flatten(), y test.flatten()
# Create fixed bounding boxes (5px margin)
bbox train = np.array([[5,27,5,27]]*len(x train))
bbox_test = np.array([[5,27,5,27]]*len(x_test))
# Build model
inputs = layers.Input(shape=(32,32,3))
x = layers.Conv2D(32, 3, activation='relu')(inputs)
x = layers.MaxPooling2D(2,2)(x)
x = layers.Conv2D(64, 3, activation='relu')(x)
x = layers.MaxPooling2D(2,2)(x)
x = layers.Flatten()(x)
x = layers.Dense(64, activation='relu')(x)
outputs = [
    layers.Dense(10, activation='softmax', name='class')(x),
    layers.Dense(4, name='bbox')(x)
1
model = models.Model(inputs, outputs)
# Compile and train
model.compile(optimizer='adam',
              loss=['sparse categorical crossentropy', 'mse'],
              metrics=['accuracy', 'mse'])
model.fit(x train, [y train, bbox train],
          epochs=3,
          validation_data=(x_test, [y_test, bbox_test]))
```

```
sample = x test[:5] # Take 5 images
class_pred, bbox_pred = model.predict(sample)
class_names = ['airplane', 'automobile', 'bird', 'cat', 'deer',
               'dog', 'frog', 'horse', 'ship', 'truck']
for i in range(5):
    img = sample[i]
    pred class = np.argmax(class_pred[i]) # predicted class index
                                           # predicted bounding box
    pred_box = bbox_pred[i]
    plt.figure(figsize=(4, 4))
    plt.imshow(img)
    plt.gca().add patch(plt.Rectangle(
        (pred box[2], pred box[0]),
                                           # (left, top)
        pred_box[3] - pred_box[2],
pred_box[1] - pred_box[0],
                                            # width
                                            # height
        linewidth=2, edgecolor='r', facecolor='none'
    ))
    plt.title(f"Predicted: {class names[pred class]}")
    plt.axis('off')
    plt.show()
Epoch 1/3
                      _____ 11s 7ms/step - bbox_loss: 13.5213 -
1563/1563 -
bbox mse: 13.5213 - class accuracy: 0.1831 - class loss: 2.5417 -
loss: 16.0630 - val bbox loss: 0.0480 - val bbox mse: 0.0481 -
val class accuracy: 0.3372 - val class loss: 1.8139 - val loss: 1.8623
Epoch 2/3
                         ----- 12s 8ms/step - bbox_loss: 0.0832 -
1563/1563 •
bbox mse: 0.0832 - class accuracy: 0.3857 - class loss: 1.6736 - loss:
1.7568 - val bbox loss: 0.0667 - val bbox mse: 0.0668 -
val class accuracy: 0.4399 - val class loss: 1.5410 - val loss: 1.6078
Epoch 3/3
                        _____ 13s 9ms/step - bbox_loss: 0.0633 -
1563/1563 -
bbox_mse: 0.0633 - class_accuracy: 0.4515 - class_loss: 1.5169 - loss:
1.5802 - val_bbox_loss: 0.0512 - val_bbox_mse: 0.0512 -
val class accuracy: 0.4659 - val class loss: 1.4991 - val loss: 1.5508
1/1 -
                Os 64ms/step
```

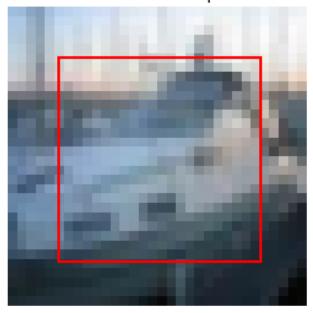
Predicted: cat



Predicted: ship



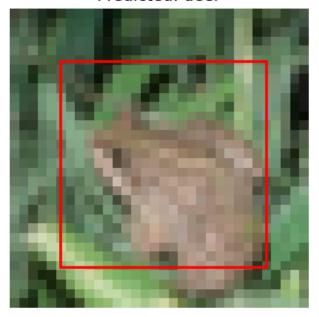
Predicted: ship



Predicted: ship



Predicted: deer



```
import numpy as np
import tensorflow as tf
from tensorflow.keras import layers, models
import matplotlib.pyplot as plt
# Load and prepare MNIST data
(x train, y train), (x test, y test) =
tf.keras.datasets.mnist.load data()
\#x\_train = x\_train.reshape(-1, 28, 28, 1).astype('float32') / 255.0
\#x \ test = x \ test.reshape(-1, 28, 28, 1).astype('float32') / 255.0
x train = x train/255.0
x \text{ test} = x \text{ test/}255.0
# Create simple bounding boxes (center 20x20 box)
#def make boxes(images):
    #return np.array([[4, 24, 4, 24] for _ in range(len(images))],
dtype='float32')
bbox train = np.array([[4,24,4,24]]*len(x train))
bbox test = np.array([[4,24,4,24]]*len(x test))
\#bbox\ test = make\ boxes(x\ test)
# Build model using Functional API
inputs = layers.Input(shape=(28, 28, 1))
x = layers.Conv2D(32, (3, 3), activation='relu')(inputs)
x = layers.MaxPooling2D((2, 2))(x)
x = layers.Conv2D(64, (3, 3), activation='relu')(x)
x = layers.MaxPooling2D((2, 2))(x)
x = layers.Flatten()(x)
x = layers.Dense(64, activation='relu')(x)
```

```
# Two output layers
outputs=[
    layers.Dense(10, activation='softmax', name='class')(x),
    layers.Dense(4, name='bbox')(x)
]
model = models.Model(inputs, outputs)
# Compile model
model.compile(optimizer='adam',
              loss=['sparse categorical crossentropy', 'mse'],
              metrics=[ 'accuracy', 'mse'])
# Train model
model.fit(x_train, [y_train,bbox_train],
          epochs=3,
          validation data=(x test,[y test,bbox test])
# Test predictions
sample = x test[:5]
class pred, bbox pred = model.predict(sample)
# Show results
for i in range(5):
    plt.imshow(sample[i].squeeze(), cmap='gray')
    box = bbox pred[i]
    plt.gca().add_patch(plt.Rectangle(
        (box[2], box[0]), box[3]-box[2], box[1]-box[0],
        linewidth=2, edgecolor='r', facecolor='none'))
    plt.title(f"Predicted: {np.argmax(class pred[i])}")
    plt.show()
Epoch 1/3
                      _____ 13s 7ms/step - bbox_loss: 11.2264 -
1875/1875 -
bbox mse: 11.2264 - class accuracy: 0.6105 - class_loss: 1.4554 -
loss: 12.6819 - val bbox loss: 0.0571 - val bbox mse: 0.0571 -
val class accuracy: 0.9364 - val class loss: 0.2132 - val loss: 0.2706
Epoch 2/3
                          ----- 12s 6ms/step - bbox_loss: 0.0368 -
1875/1875 -
bbox mse: 0.0368 - class_accuracy: 0.9431 - class_loss: 0.1884 - loss:
0.2252 - val bbox loss: 0.0169 - val bbox mse: 0.0169 -
val_class_accuracy: 0.9683 - val_class_loss: 0.1042 - val loss: 0.1212
Epoch 3/3
1875/1875 -
                            -- 12s 7ms/step - bbox_loss: 0.0247 -
bbox mse: 0.0247 - class accuracy: 0.9632 - class loss: 0.1206 - loss:
0.1454 - val bbox loss: 0.0165 - val bbox mse: 0.0165 -
```

