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In [1]:
        class Node():
            def __init__(self, parent=None, position=None):
                self.parent = parent
                self.position = position
                self.g = 0
                self.h = 0
                self.f = 0
            def eq (self, other):
                return self.position == other.position
        def astar(maze, start, end):
            start node = Node(None, start)
            start node.g = start node.h = start node.f = 0
            end node = Node(None, end)
            end node.g = end node.h = end node.f = 0
            open list = []
            closed list = []
            open list.append(start node)
            while len(open list) > 0:
                current_node = open_list[0]
                current index = 0
                for index, item in enumerate(open list):
                    if item.f < current_node.f:</pre>
                         current node = item
                         current index = index
                open_list.pop(current_index)
                closed_list.append(current_node)
                if current_node == end_node:
                     path = []
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current = current node
            while current is not None:
                path.append(current.position)
                current = current.parent
            return path[::-1]
        children = []
        for new position in [(0, -1), (0, 1), (-1, 0), (1, 0), (-1, -1), (-1, 1), (1, -1), (1, 1)]:
            node position = (current node.position[0] + new position[0], current node.position[1] + new position[1])
            if node position[0] > (len(maze) - 1) or node position[0] < 0 or node position[1] > (len(maze[len(maze)-1]
                 continue
            if maze[node position[0]][node position[1]] != 0:
                 continue
            new node = Node(current node, node position)
            children.append(new node)
        for child in children:
            for closed child in closed list:
                if child == closed child:
                     continue
            child.g = current node.g + 1
            child.h = ((\text{child.position}[0] - \text{end node.position}[0]) ** 2) + ((\text{child.position}[1] - \text{end node.position}[1])
            child.f = child.g + child.h
            for open node in open list:
                if child == open node and child.g > open node.g:
                     continue
            open list.append(child)
def main():
   maze = [[0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
            [0, 0, 0, 0, 1, 0, 0, 0, 0, 0],
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Path for found by A* algorithm is :-
[(0, 0), (1, 1), (2, 2), (3, 3), (4, 3), (5, 4), (6, 5), (7, 6)]
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In [ ]:
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