



Getting Started with CY8C6245AZI-S3D72 development platform – **RDK2**

Registration & Download





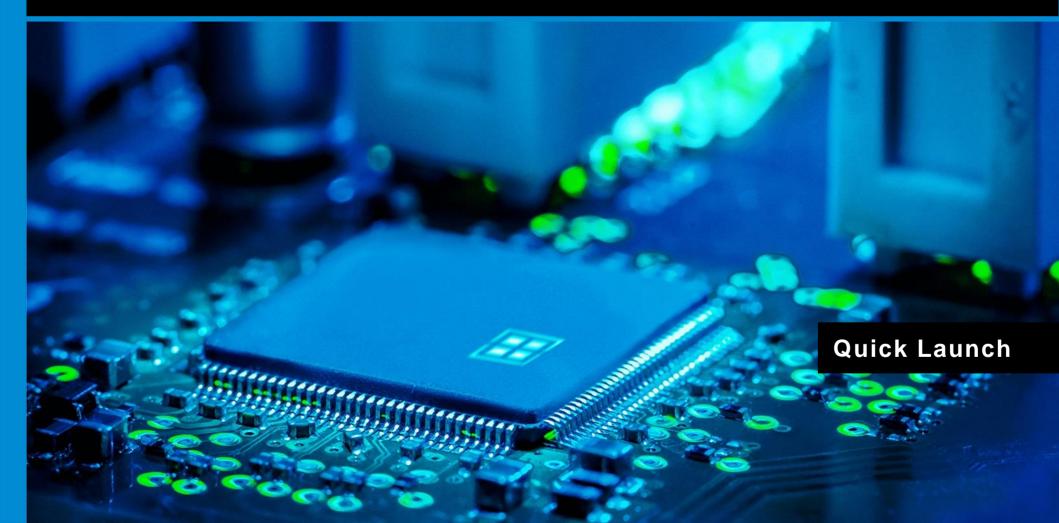
1.) Register or/and login to the Infineon website, press on "myInfineon" tab.

https://www.infineon.com

2.) Download and install the latest <u>ModusToolbox™</u> software.

3.) [Optional] Download and install yours prefered terminal emulator, for example: Putty, Tera Term, etc.

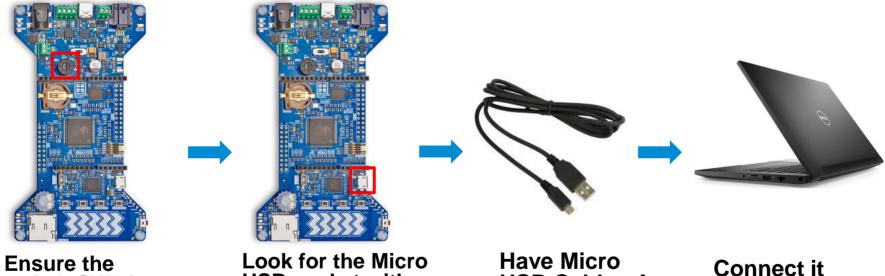




Connect the RDK2



Connect the RDK2 to your PC.



Ensure the switch SW1 is set to "3.3V" position

Look for the Micro USB socket with a marking "KitProg3"

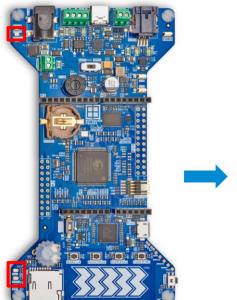
Have Micro USB Cable - A to Micro B

Connect it with your PC

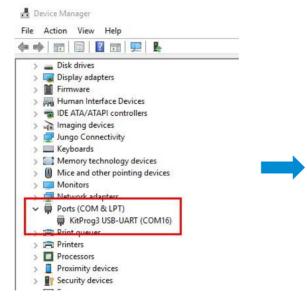
Connect the RDK2



Check if the RDK2 is ready.



"POWER" and "DEBUG" LEDs should shine constantly. The LED1 reacts to the touch on the slider.



The "KitProg3" must be seen in the "Device Manager" window.

All new RDK2s print out hardware test results to the KitProg3 serial terminal (115200 bit/s). Press the RESET on the RDK2 if necessary.

```
Session Special Command Window Logging Files Transfer Hangup?

PWM LED Initialized Successfully.
CapSense Initialized Successfully.
RTC Initialized Successfully.
RS485 Initialized Successfully.
USB CDC Initialized Successfully.
PSRAM check: PASS.
FLASH check: PASS.
Could not mount the uSD card.

CAN FD Data received in loop back mode:
0x00000000 0xDEADBEAF 0xCAFEBABE 0xFACEFEED
0x11111111 0x2222222 0x33333333 0x44444444
0x5555555 0x66666666 0x77777777 0x88888888
0x99999999 0xAAAAAAAA 0xBBBBBBBB 0xCCCCCCCC

Arduino ADC Input Values:
A0: 612mV, A1: 1042mV, A2: 1382mV, A3: 1612mV, A4: 1756mV, A5: 25mV
Sat Jan 1 00:00:15 2000
```

Working with the ModusToolbox and Rutronik PC

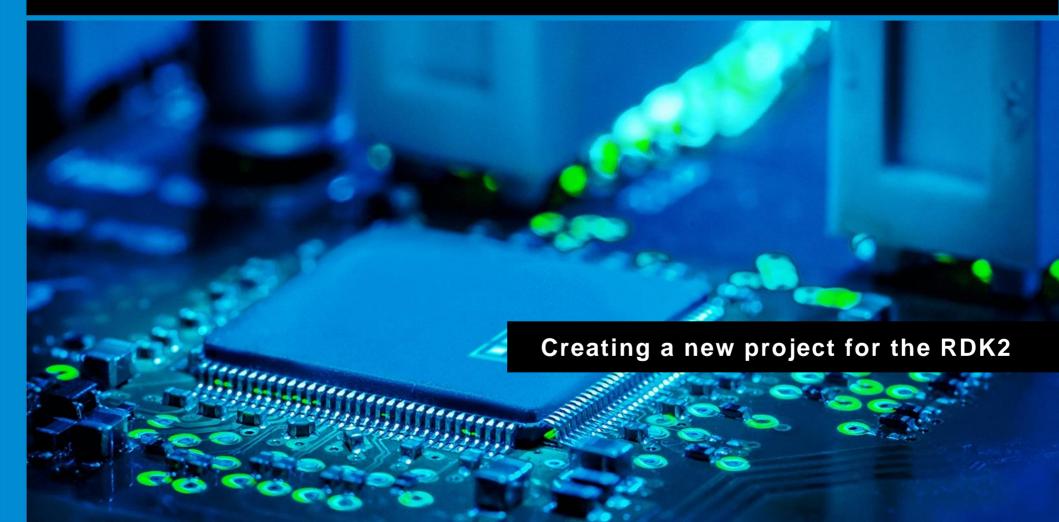


If you are working with your personal PC, (not the Rutronik provided Laptop PC) please skip this setup.

Open the File \rightarrow New \rightarrow "ModusToolbox Application" \rightarrow Settings \rightarrow Proxy server settings and enter the proxy address: http://iwsva.rut.local:8080

Proxy server	settings - Project Creator 2.0	×	
○ Direct ⑥ Manual [http://iwsva.rut.local:8080 OK	Cancel	







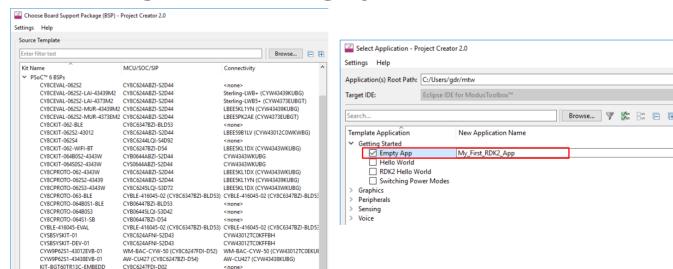
- 1.) Open the "Project Creator" tool: File → New → ModusToolbox™ Application
- 2.) Select the "RDK2" BSP. It is in PSoC™ 6 BSPs list.
- 3.) Click on "Next".

4.) Select a "Empty App" in a "Getting Started" category. Name it

"My_First_RDK2_App".

5.) Click on "Create".





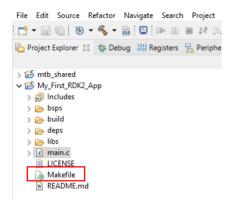
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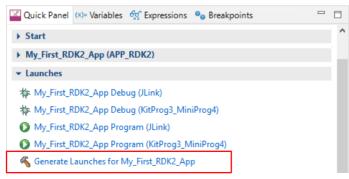


6.) Modify the "Makefile" to disable code optimisation*



APPNAME=my-first-rdk2-app CONFIG=Costum CFLAGS =-O0

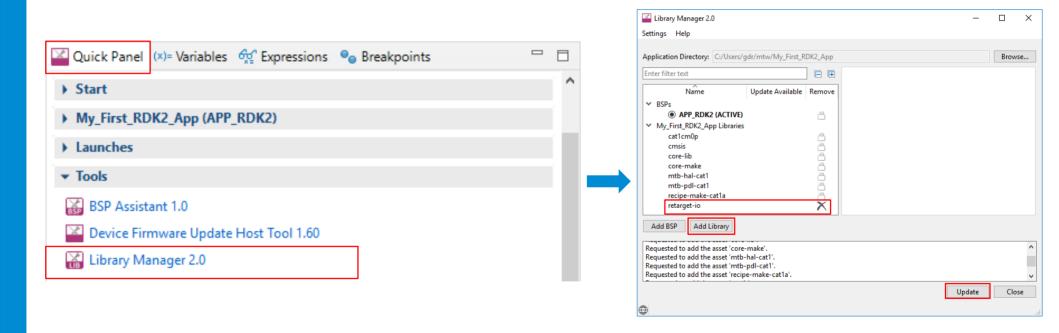
7.) Press "Generate Launches" in Quick Panel



*only for debugging, learning and demo purposes. Normally, code optimisations should never be disabled.



8.) Include the "retarget-io" library in a "Library Manager" tool and press "Update".



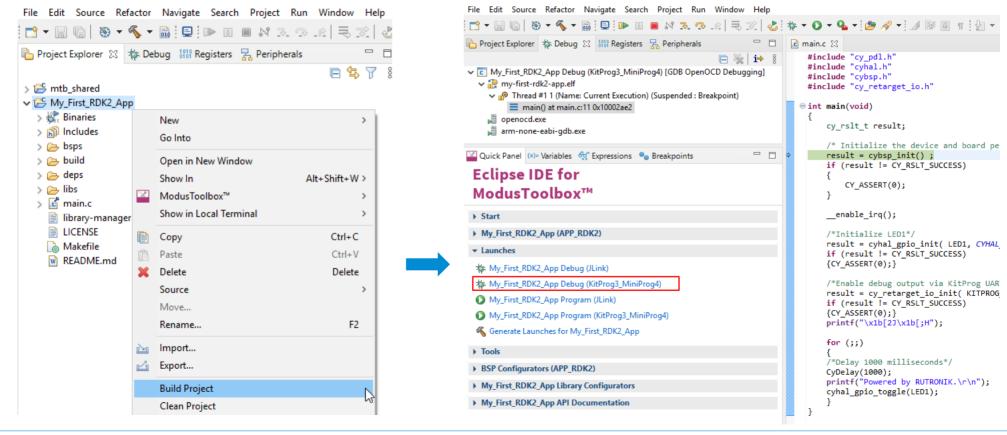


9.) Copy/Paste and save the code example to the "main.c" file.

```
#include "cy_pdl.h"
#include "cvhal.h"
#include "cvbsp.h"
#include "cy retarget io.h"
int main(void)
    cv rslt t result;
    /* Initialize the device and board peripherals */
    result = cybsp init();
    if (result != CY RSLT SUCCESS)
        CY ASSERT(0);
    __enable_irq();
    /*Initialize LED1*/
    result = cyhal gpio init( LED1, CYHAL GPIO DIR OUTPUT, CYHAL GPIO DRIVE STRONG, CYBSP LED STATE OFF);
    if (result != CY RSLT_SUCCESS)
    {CY ASSERT(0);}
    /*Enable debug output via KitProg UART*/
    result = cy retarget io init( KITPROG TX, KITPROG RX, CY RETARGET IO BAUDRATE);
    if (result != CY RSLT SUCCESS)
    {CY ASSERT(0);}
    printf("\x1b[2J\x1b[;H");
    for (;;)
    /*Delay 1000 milliseconds*/
    CyDelay(1000);
    printf("Powered by RUTRONIK.\r\n");
    cyhal gpio toggle(LED1);
```



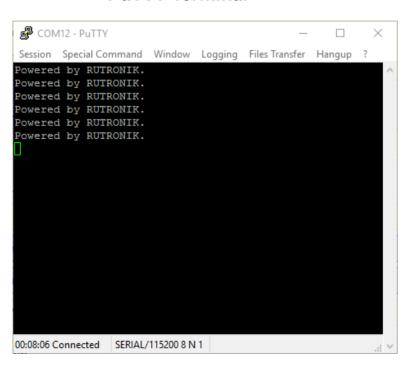
10.) Build and Debug the active project.



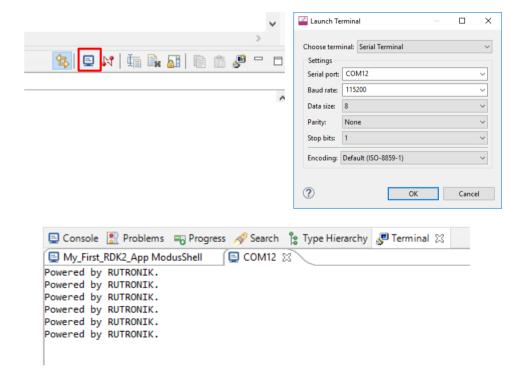


The final result is a blinking LED1 on the RDK2 board and text on the terminal window:

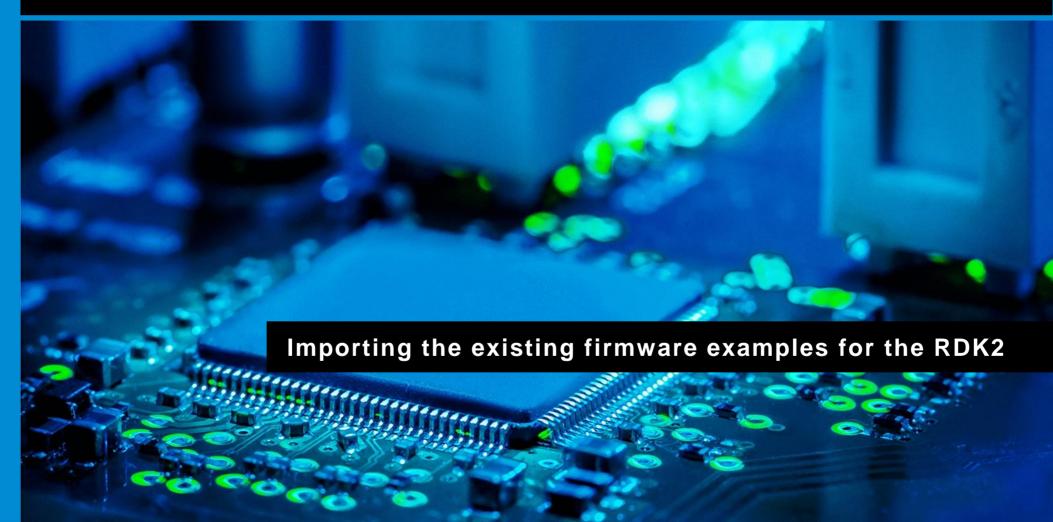
PuTTY Terminal



ModusToolbox Terminal



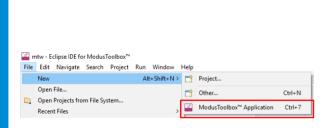


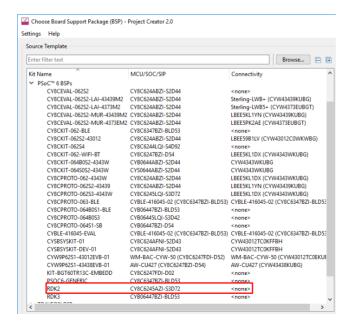


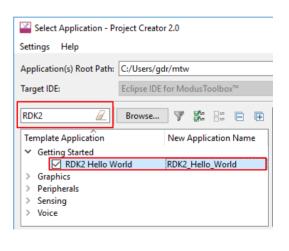
Importing firmware examples with "Project Creator" tool



- 1.) Open the "Project Creator" tool: File → New → ModusToolbox™ Application
- 2.) Select the "RDK2" BSP. It is in PSoC™ 6 BSPs list.
- 3.) Click on "Next".
- 4.) Write a "RDK2" in a Search... window. Select the example from given categories list.
- 5.) Click on "Create".



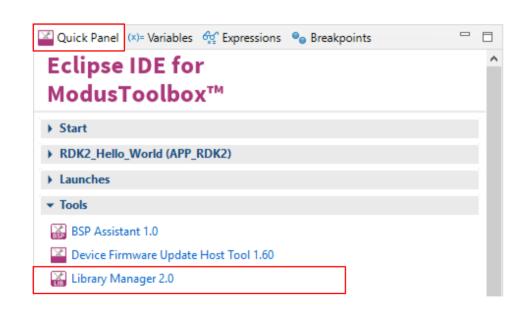




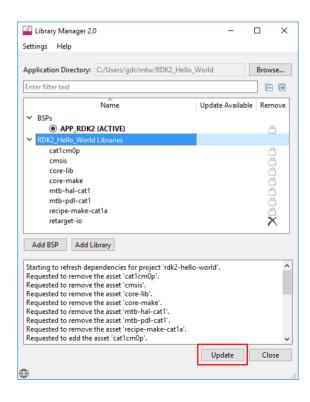
Importing firmware examples with "Project Creator" tool



6.) After project creation is finished - update libraries with "Library Manager" tool.

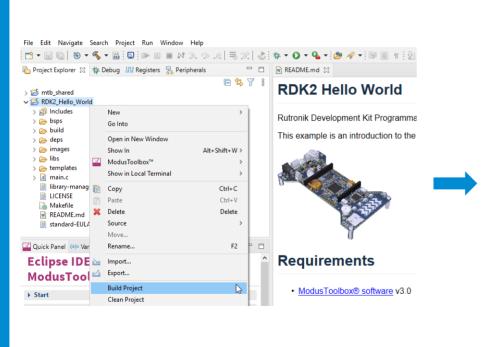


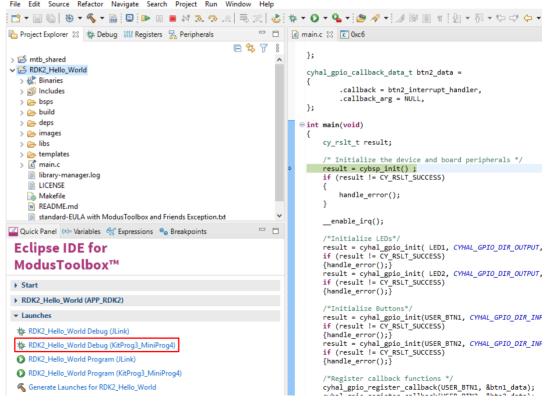






7.) Build and Debug the active project.

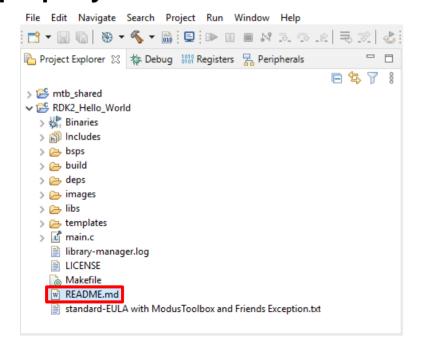




RDK2 README.md



Check the README.md file before starting to explore the code example. You may find important hints or what else is needed to have firmware running properly.









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