



Getting Started with CYB06447BZI-BLD53 Development Platform – **RDK3** 

## Registration & Download





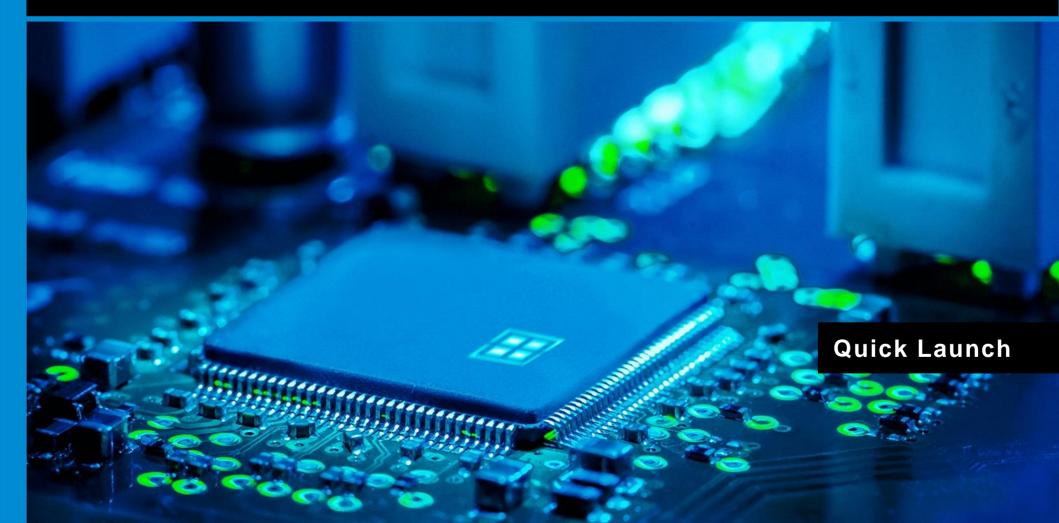
1.) Register or/and login to the Infineon website, press on "myInfineon" tab.

https://www.infineon.com

2.) Download and install the latest <u>ModusToolbox™</u> software.

3.) [Optional] Download and install yours prefered terminal emulator, for example: Putty, Tera Term, etc.





## Connect the RDK3



## Connect the RDK3 to your PC.



Look for the USB-C socket with a marking "KitProg3"

Connect it with your PC

## Connect the RDK3



## Check if the RDK3 is ready.



"POWER" and "DEBUG" LEDs must shine constantly. The "CHARGE" LED will be blinking if no battery is connected.







The "KitProg3" must be seen in the "Device Manager" window.

## Working with the ModusToolbox and Rutronik PC

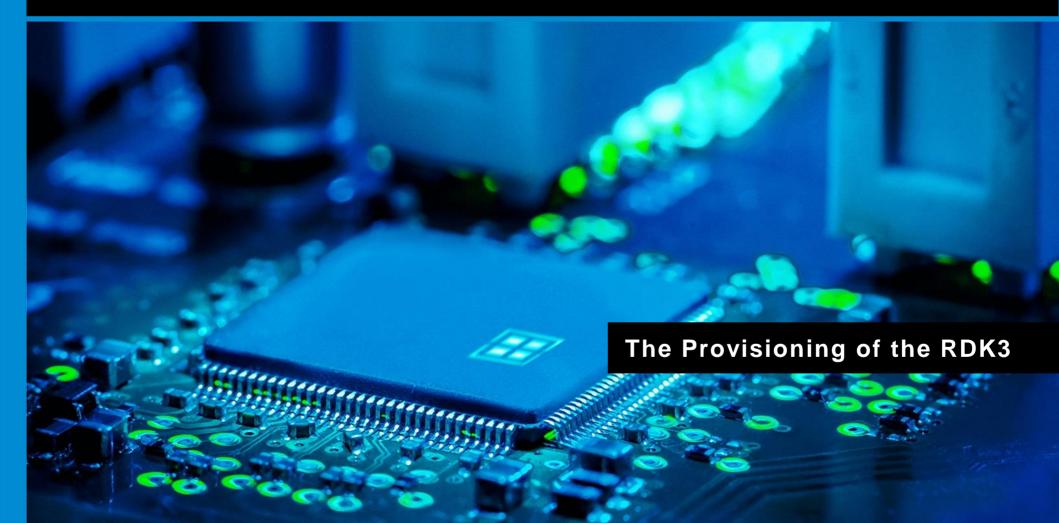


If you are working with your personal PC, (not the Rutronik provided Laptop PC) please skip this setup.

Open the File→New→ "ModusToolbox Application" → Settings → Proxy server settings and enter the proxy address: http://iwsva.rut.local:8080

Proxy server settings - Project Creator 2.0			×
○ Direct <b>⑥</b> Manual	http://iwsva.rut.local:8080 OK	Cancel	







- The RDK3 is equipped with a PSoC™ 64 "Secure" MCU CYB06447BZI-BLD53.
- The PSoC™64 device must be provisioned with keys and policies before being programmed.
- If the unsigned or not properly signed image will be written to the RDK3 PSoC™64 – the microcontroller will not startup.
- You may also refer to the <u>"Secure Policy" Configurator guide</u>.

Additional Information

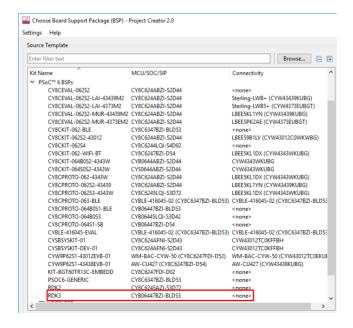
**PSoC™ 64 - Secured MCU** 

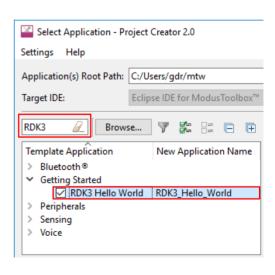
**PSoC™** 64 Provisioning Specification



- 1.) Open the "Project Creator" tool: File → New → ModusToolbox™ Application
- 2.) Select the "RDK3" BSP. It is in PSoC™ 6 BSPs list.
- 3.) Click on "Next".
- 4.) Write a "RDK3" in a Search... window. Select the example from given categories list.
- 5.) Click on "Create".





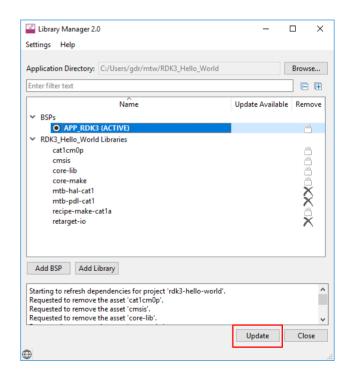




6.) After project creation is finished - update libraries with "Library Manager" tool.

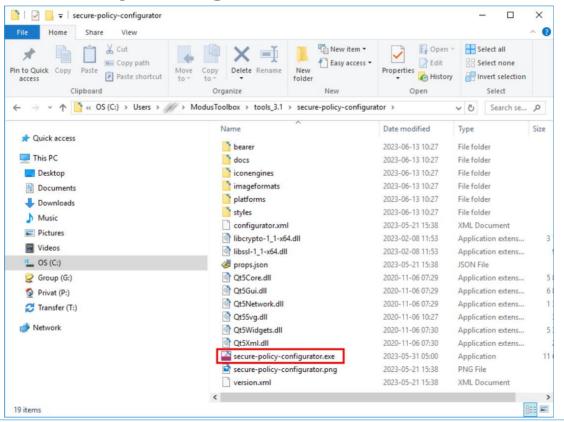






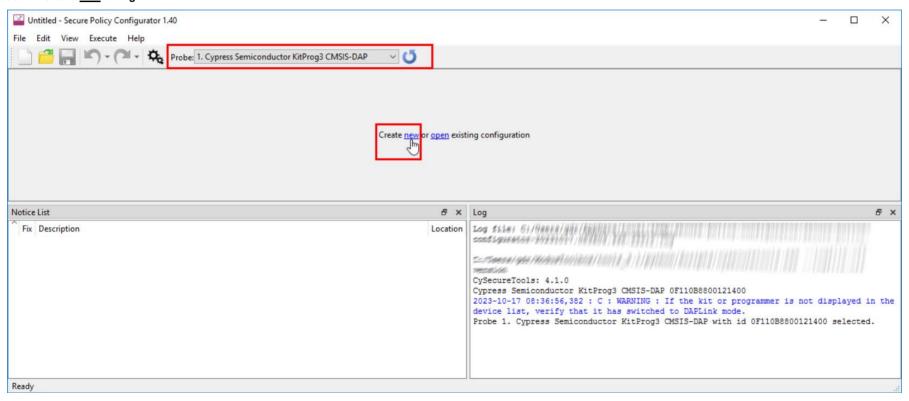


## 7.) Load the "Secure Policy Configurator".



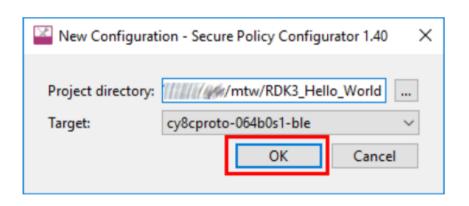


- 8.) Load the "Secure Policy Configurator".
- 9.) Select the probe: Cypress Semiconductor KitProg3 CMSIS-DAP [press the PROG MODE button if the CMSIS-DAP is not present in a list].
- 10.) Press on Create new configuration.

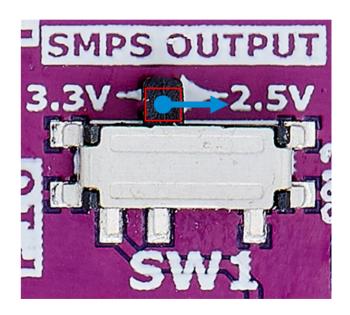




- 11.) Choose your RDK3\_Hello\_World Project Directory. The Target is cy8cproto-064b0s1-ble.
- 12.) Set the SW1 "SMPS OUTPUT" to the 2.5V position.

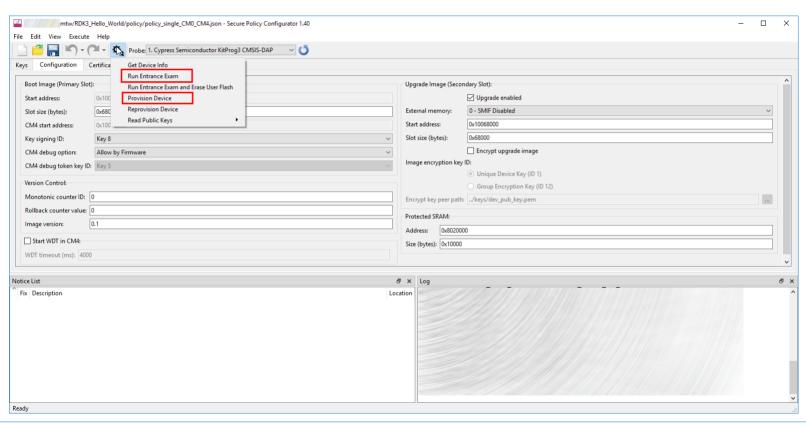






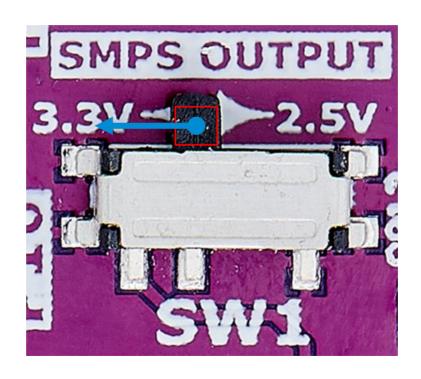


- 13.) Configure the settings according to your needs or leave them as it is.
- 14.) "Run The Entrance Exam" and then "Provision the Device"



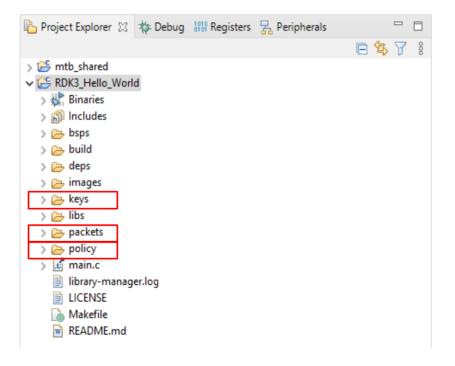


## 15.) Switch the power supply back to 3.3V

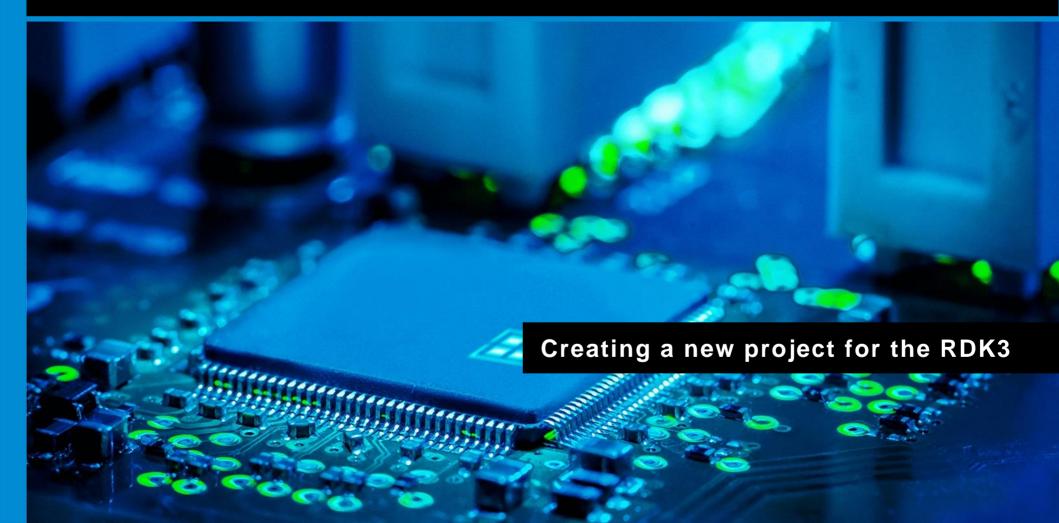




Please store the "keys", "policy" and "packets" folders with all the content in a safe location for later use.









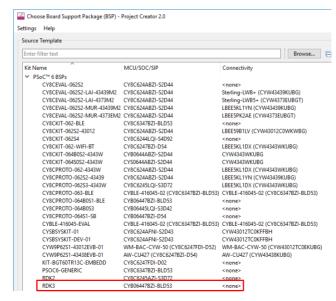
- 1.) Open the "Project Creator" tool: File → New → ModusToolbox™ Application
- 2.) Select the "RDK3" BSP. It is in PSoC™ 6 BSPs list.
- 3.) Click on "Next".

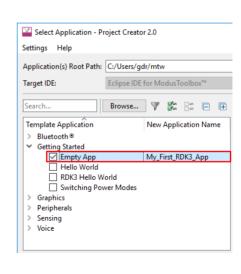
4.) Select a "Empty App" in a "Getting Started" category. Name it

"My\_First\_RDK3\_App".

5.) Click on "Create".

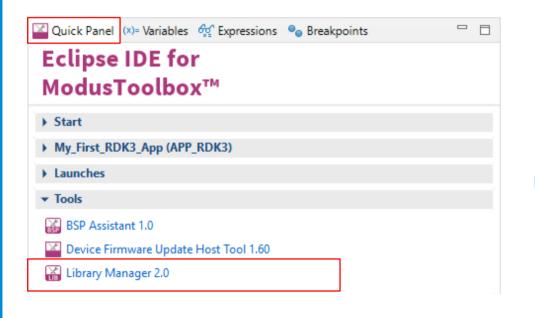


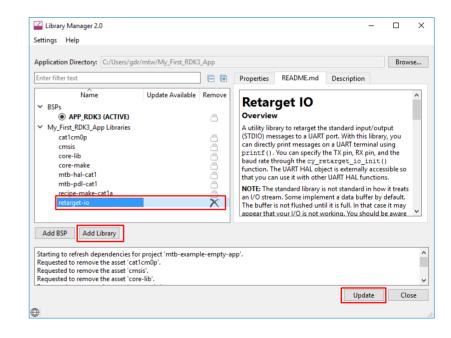






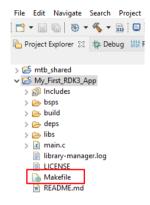
6.) Include the "retarget-io" library in a "Library Manager" tool and press "Update".





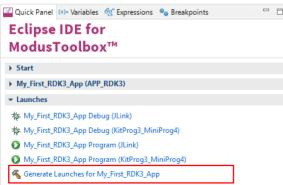


#### 7.) Modify the "Makefile" to disable code optimisation\*



APPNAME=my-first-rdk3-app CONFIG=Costum CFLAGS =-O0

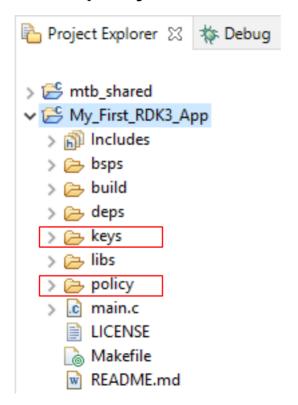
#### 8.) Press "Generate Launches" in Quick Panel



\*only for debugging, learning and demo purposes. Normally, code optimisations should never be disabled.



9.) Copy and paste the "keys" and "policy" folders with all the files into your project.



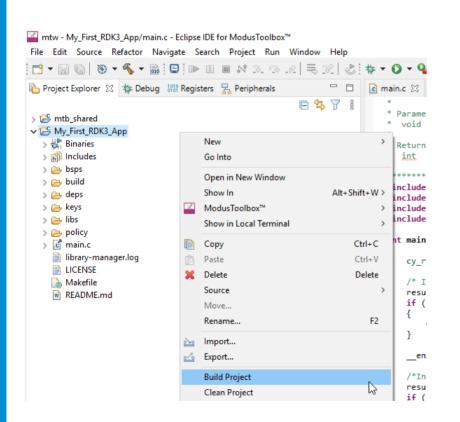


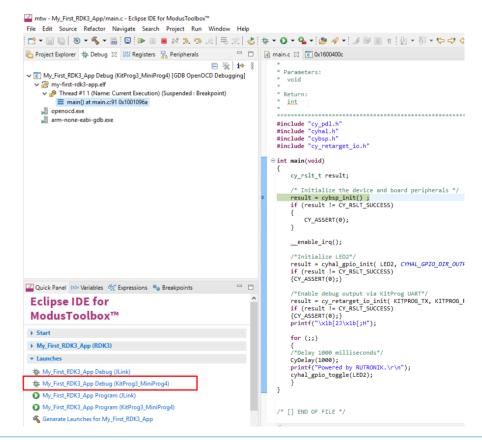
## 10.) Copy/Paste and save the code example to the "main.c" file.

```
#include "cy_pdl.h"
#include "cvhal.h"
#include "cvbsp.h"
#include "cy retarget io.h"
int main(void)
    cv rslt t result;
    /* Initialize the device and board peripherals */
    result = cybsp init();
    if (result != CY RSLT SUCCESS)
        CY ASSERT(0);
    __enable_irq();
    /*Initialize LED2*/
    result = cyhal gpio init( LED2, CYHAL GPIO DIR OUTPUT, CYHAL GPIO DRIVE STRONG, CYBSP LED STATE OFF);
    if (result != CY RSLT_SUCCESS)
    {CY ASSERT(0):}
    /*Enable debug output via KitProg UART*/
    result = cy retarget io init( KITPROG TX, KITPROG RX, CY RETARGET IO BAUDRATE);
    if (result != CY RSLT SUCCESS)
    {CY ASSERT(0);}
    printf("\x1b[2J\x1b[;H");
    for (;;)
    /*Delay 1000 milliseconds*/
    CyDelay(1000);
    printf("Powered by RUTRONIK.\r\n");
    cyhal gpio toggle(LED2);
```



## 11.) Build and Debug the active project.

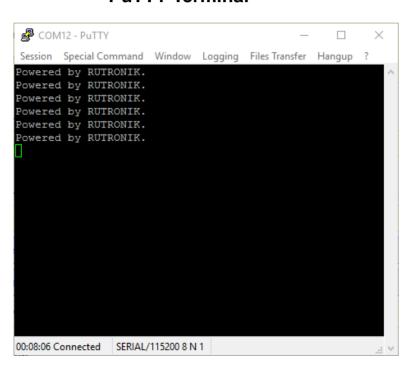




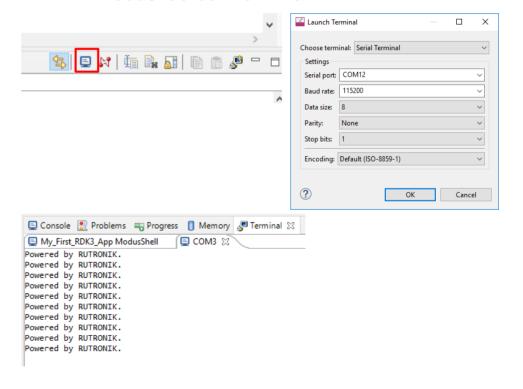


#### The final result is a blinking LED2 on the RDK3 board and text on the terminal window:

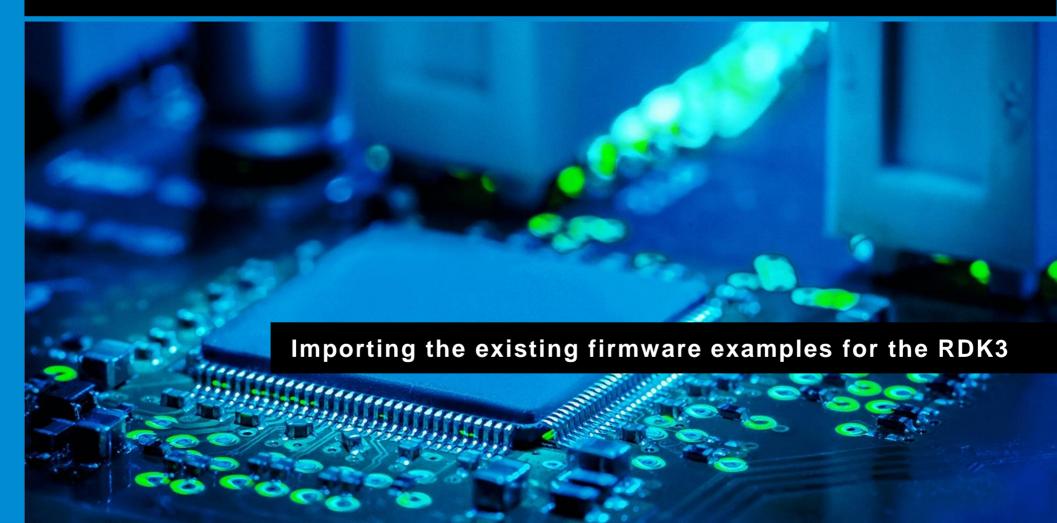
#### **PuTTY Terminal**



#### **ModusToolbox Terminal**



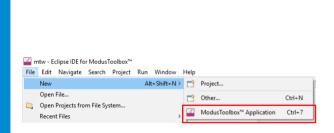


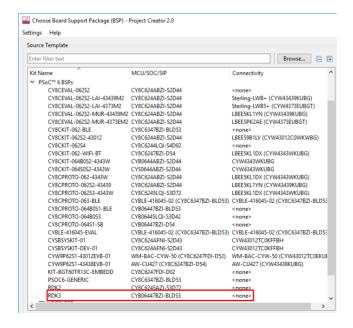


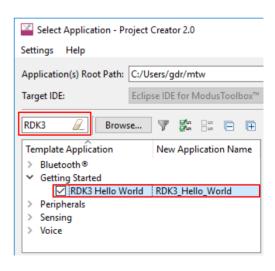
# Importing firmware examples with "Project Creator" tool



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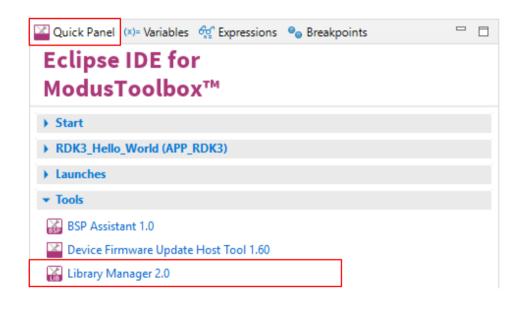




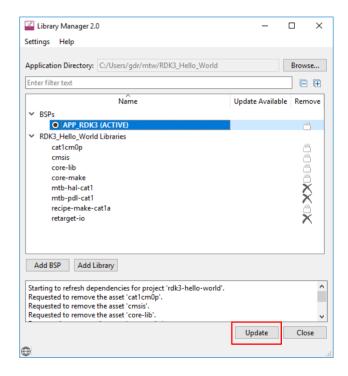
# Importing firmware examples with "Project Creator" tool



6.) After project creation is finished - update libraries with "Library Manager" tool.



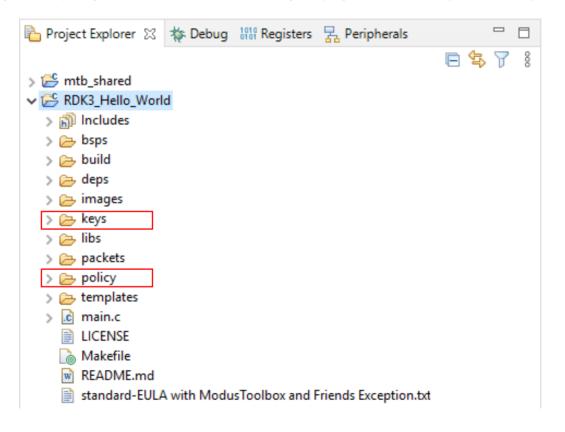




## Importing firmware examples with "Project Creator" too

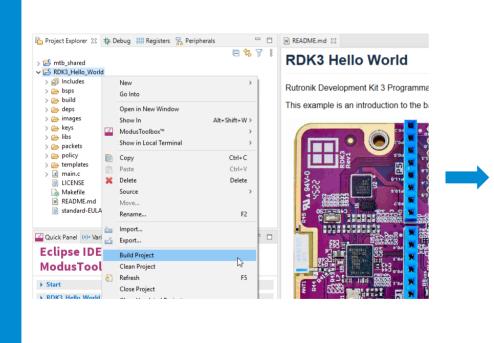


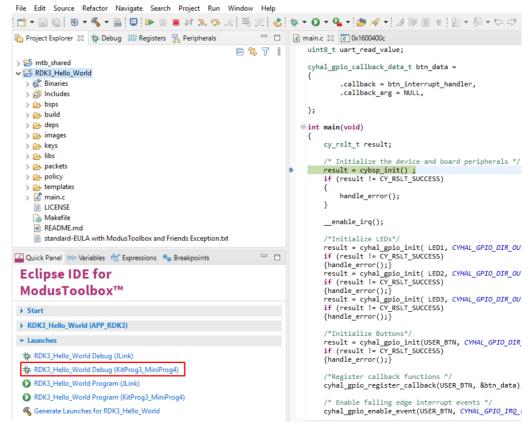
7.) Copy and paste the "keys" and "policy" folders with all the files into your project. The folder "packets" is optional, needed only for the provisioning.





## 8.) Build and Debug the project.

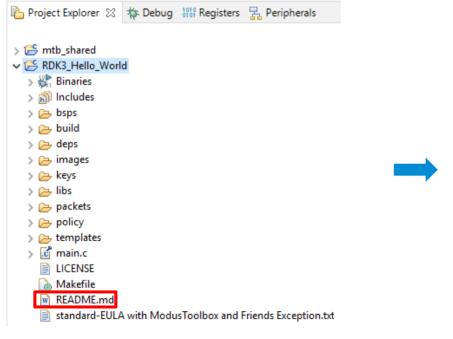




## RDK3 README.md



Check the README.md file before starting to explore the code example. You may find important hints or what else is needed to have firmware running properly.









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