



HMS EtherCAT TwinCAT Beckhoff Software Guideline

Industrial Communication





Demonstrator Consists of these Software tools:

- CubeMX -> L5 config
- CubeIDE -> L5 to NP40 and SGP30

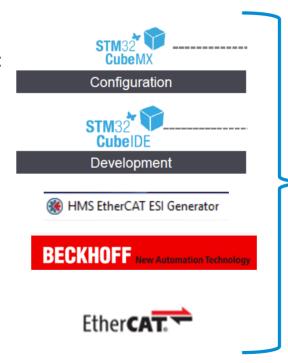
PLC Slave

- HMS ESI Generator
- Beckhoff -> TwinCAT VisualStudio 2013

PLC master

Visual Studio 2017 for GUI

TwinCAT and the GUI share Variables, so both must be running for the software at once.

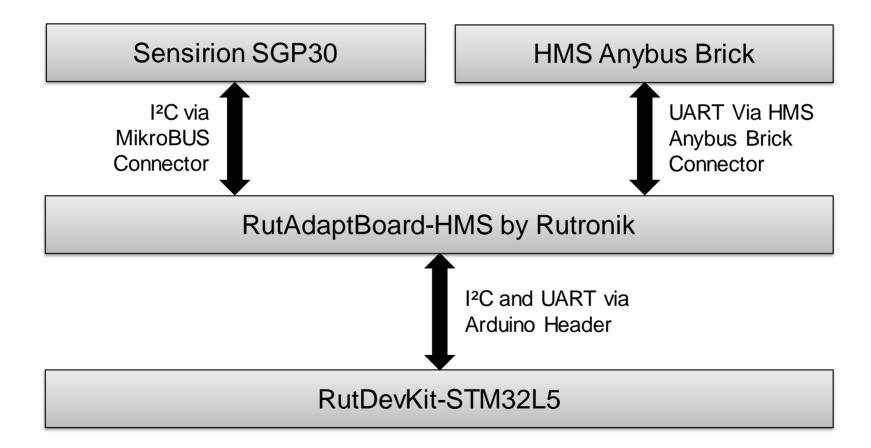






HMS Adapter Board















Necessity:

HMS_ABCC_ETH_RutDevKit.bin // Project Binary

COM PORT Connection:

Check our output in the Terminal:

Make sure your computer see the The plugged Ethernet cable

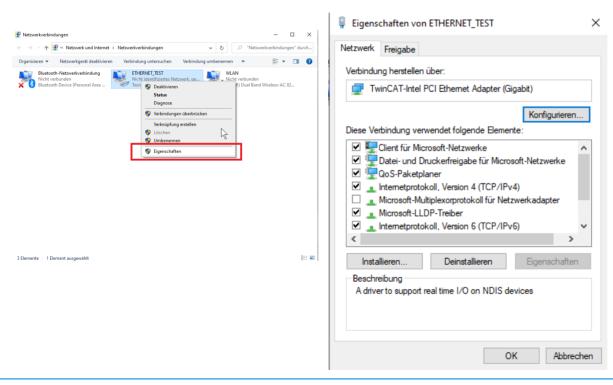


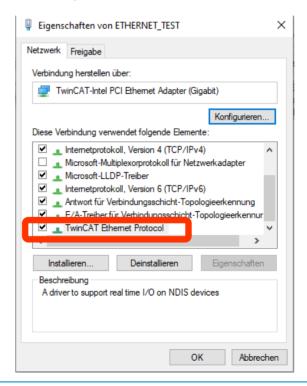
```
ПХ
nside APPL HandleAbco
 SP MSG GET PARAM SUPPORT: 1
 nside APPL HandleAbcc
ABP AND STATE PROCESS INACTIVE
Inside APPL HandleAbcc
APPL RUN:
ABP AND STATE PROCESS INACTIVE
Inside APPL HandleAbcc
APPL RUN:
SP MSG GET MODULE ID: 0x403
                           ABP ANB STATE PROCESS INACTIVE
Inside APPL HandleAbcc
ABP ANB STATE PROCESS INACTIVE
 Module Running
 nside APPL HandleAbcc
 BP AND STATE PROCESS INACTIVE
 nside APPL HandleAbcc
SP MSG GET NETWORK ID: 0x87
                           ABP AND STATE PROCESS INACTIVE
 nside APPL HandleAbcc
BP ANB STATE PROCESS INACTIVE
BP ANB STATE PROCESS INACTIVE
 nside APPL HandleAbcc
                              ABP AND STATE PROCESS INACTIVE
```



Necessity:

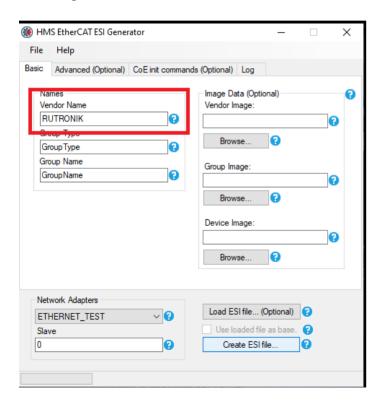
make sure your Ethernet Connection is TwinCAT ready:







Start your HMS ESI Generator



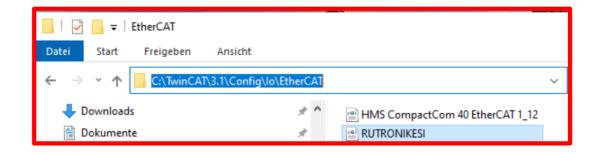
Check the Vendor name in

ABCC/Inc/abcc_adapt/abcc_identification.h (EtherCAT object: Attribute 6)

```
240 ** Attribute 6: Manufacturer device name (Array of CHAR)
241 */
242 #ifndef ECT_IA_MANF_DEVICE_NAME_ENABLE
243 | #define ECT_IA_MANF_DEVICE_NAME_ENABLE
244 | #define ECT_IA_MANF_DEVICE_NAME_VALUE "RUTRONIK"
245 #endif
```



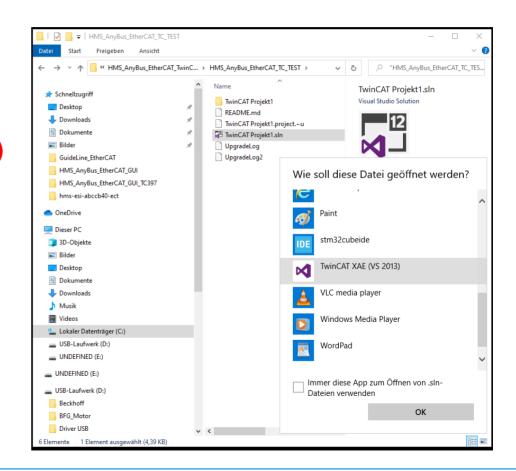
Put the generated Esi into the folder directory (RUTRONIKESI):





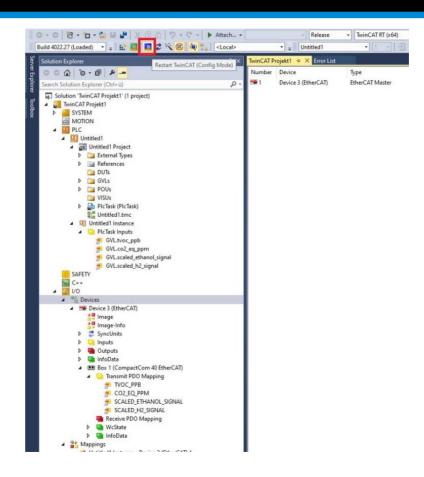
Start the PLC project: HMS_Anybus_EtherCAT_TwinCAT

Start it with TwinCAT XAE (VS 2013)



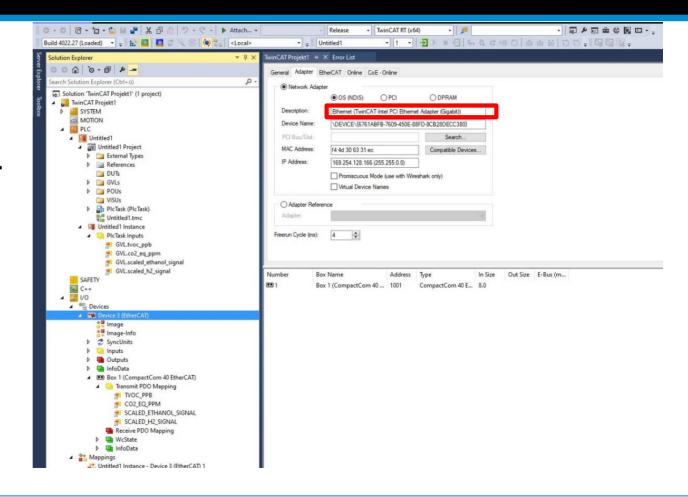


Check the settings:
Check if you are in
"Configuartion mode"
If not click on the icon
The I/Os will be loaded
And activate "free run"





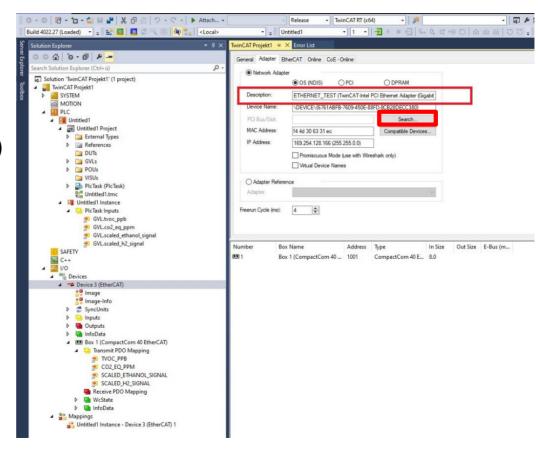
Check the settings:
Check if the Ethernet
Adapter is shown to
your Device 3 EtherCAT





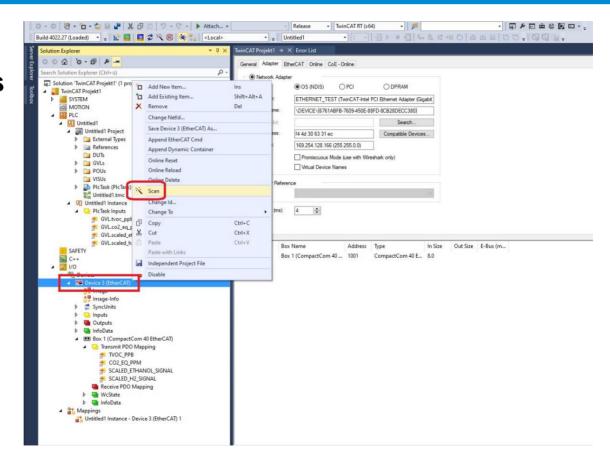
Check the settings:
you should see your
Ethernet Adapter:
(if not: press the search button)





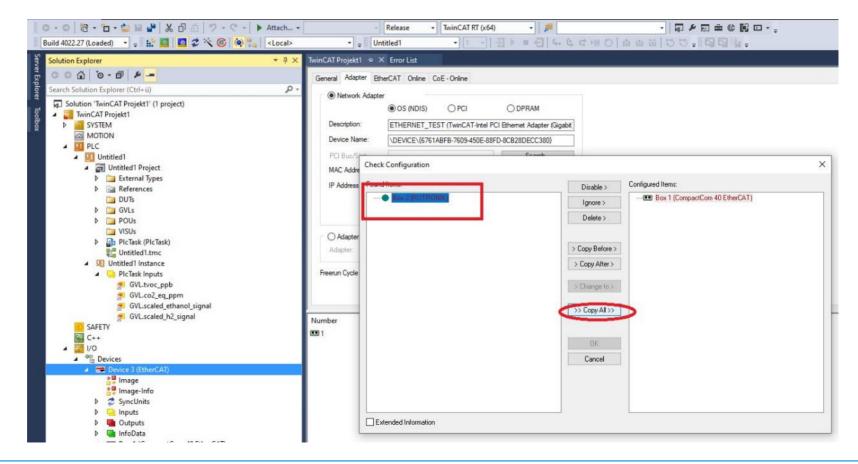


Check the settings:
Scan the Device 3 for Boxes
(if BOX "Rutronik"
is not available)



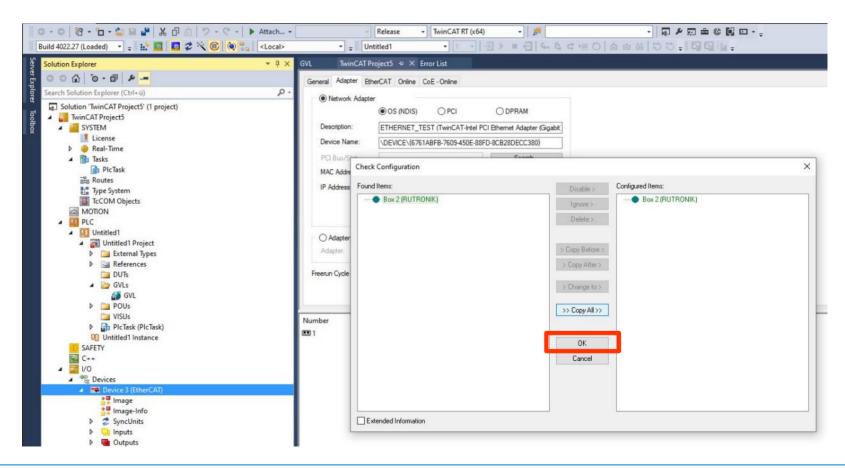


Box must be found than press "Copy All"





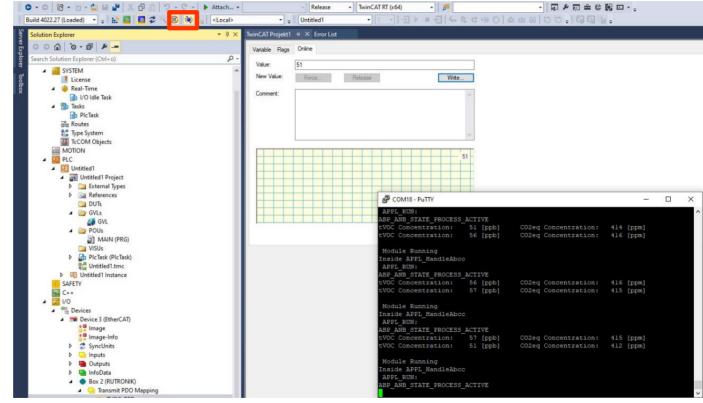
Press "OK"





Go Online by pressing the Icons "Showing Online Data" and "Toggle Free Run State"

Check now the
Console(PuTTY) output:
sensor data should be
shown there and
transferred via EtherCAT





If you scaned befor a new Box "RUTRONIK" you must now make availabe variables for PLC Global Variable List (GVL) this is most important for the GUI communication

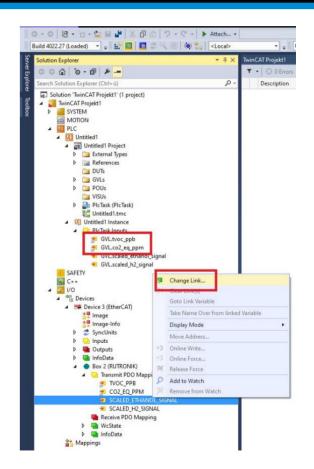
"Right Click" to one oft the variables than ...Change Link"

Linked variables will TVOC_PPB

consist an arrow CO2_EQ_PPM

SCALED_ETHANG

SCALED_H2_SIGN

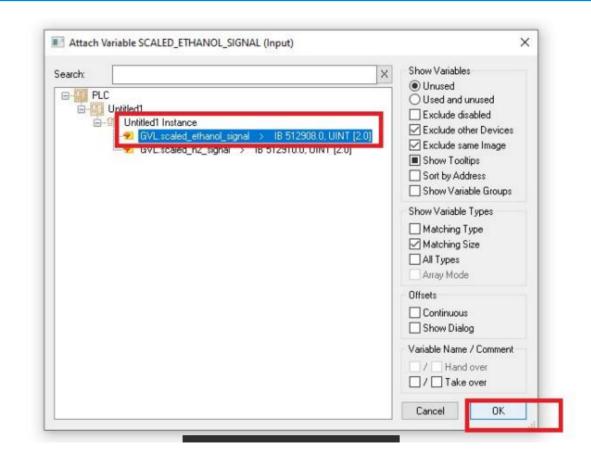




A new Window will open and you will select the variable which should be attached

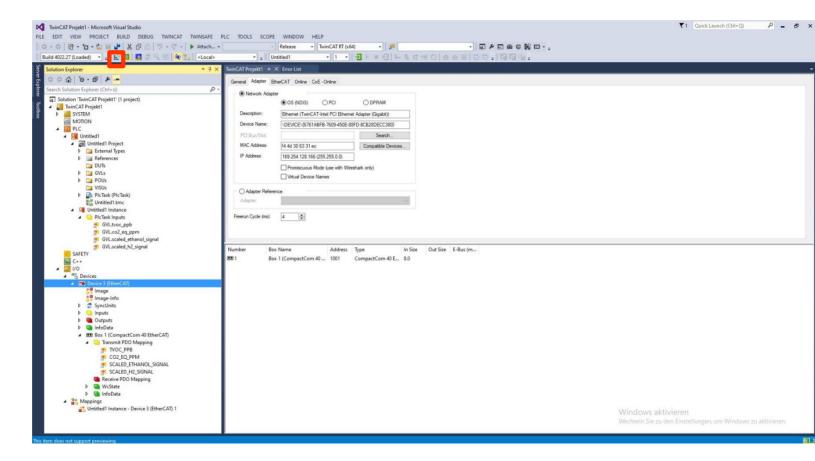
Press "ok"

After all variables are attached the main settings are done



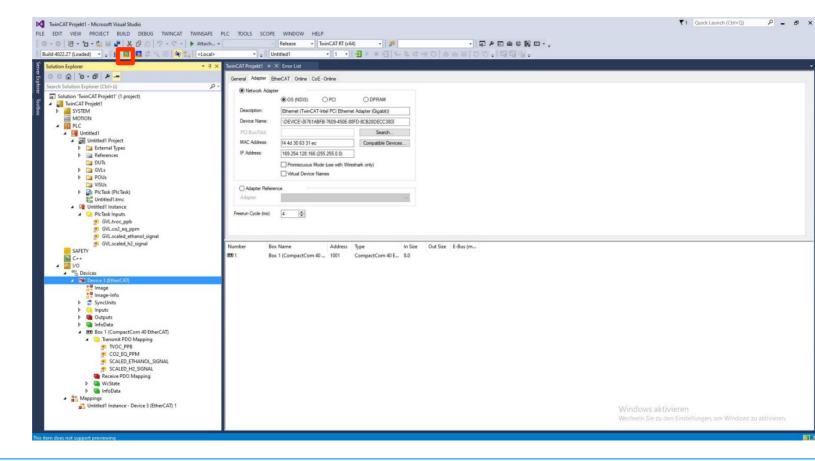


Now
Press the icon:
"Activate
Configuration"





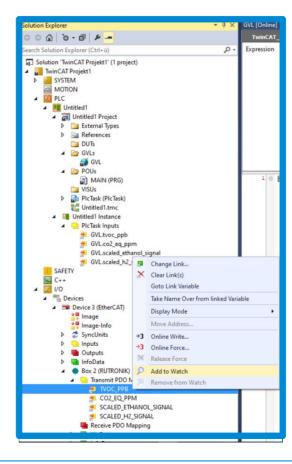
Now
Press the icon:
"Restart
TwinCat
System "





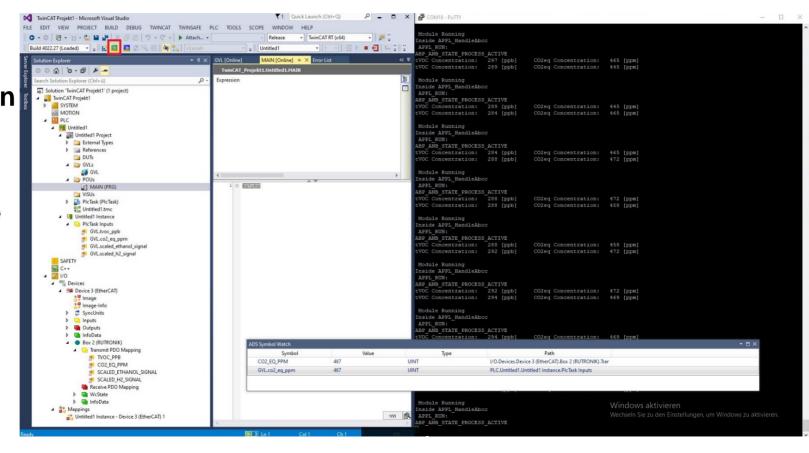
Check if your variables are available in the "Run Mode"

Check the Watch Mode See attached picture



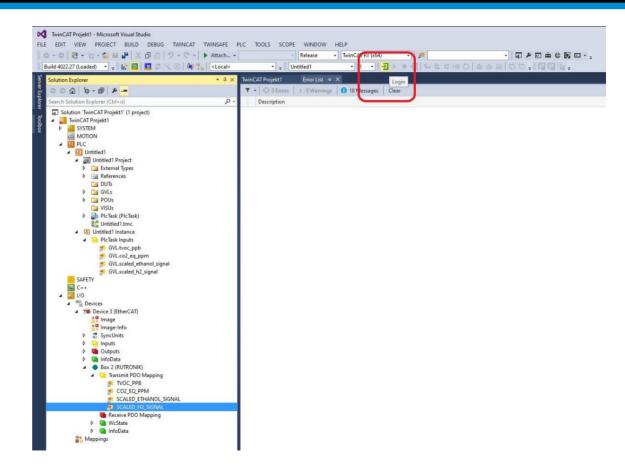


Yor Box Values and GVLs should be shown In the watch window and the console output should show also the data values





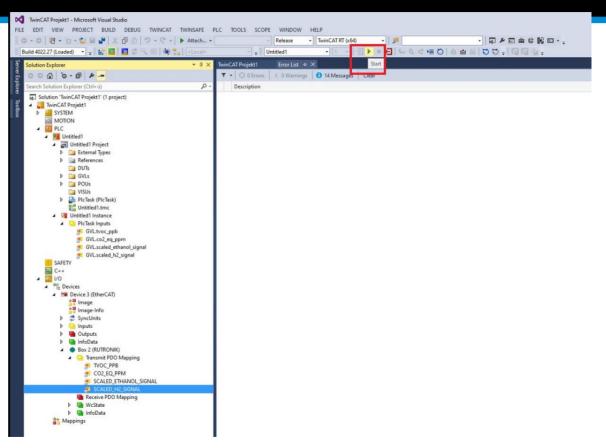
Now press the "Login" Icon





Now press the "Start" Icon

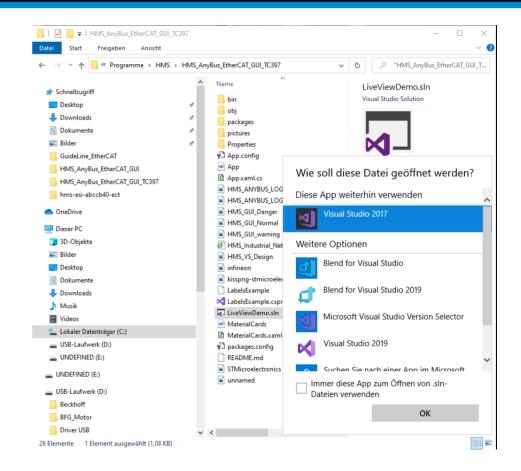
Now the data can be taken by the GUI application!





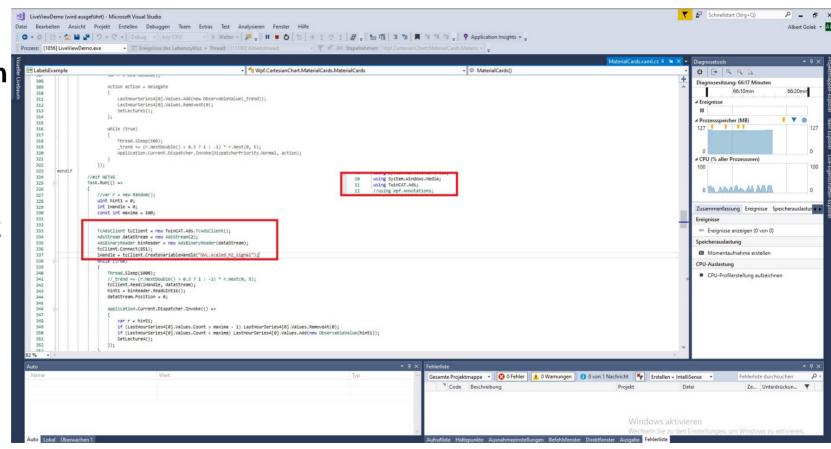
Start the GUI project:
HMS_Anybus_EtherCAT_GUI (TC379)

Start it with Visual Studio 2017



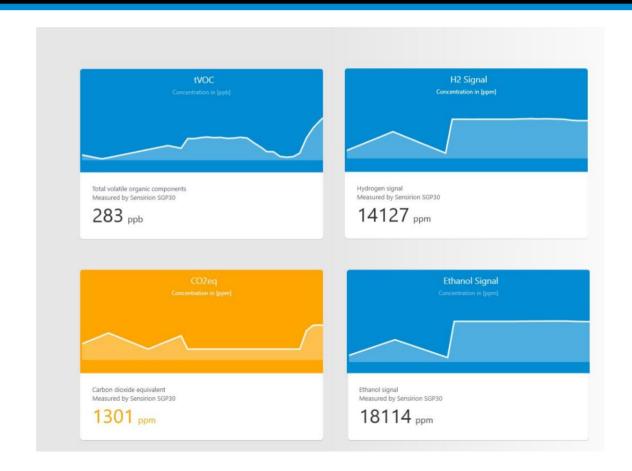


Start
the application
the GVL vals
are already
there
it should work
at once





GUI example consisting values from EtherCAT HMS Anybus







Albert Golek

Technical Support Engineer Phone: +4972318011741

eMail: albert.golek@rutronik.com