Assignment 3

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In [1]: import numpy as np
# Define input data and target values
input data = np.array([[1,1,1,0,1,1,1], # 0])
                      [0,0,1,0,0,1,0], # 1
                      [1,0,1,1,1,0,1], # 2
                      [1,0,1,1,0,1,1], # 3
                      [0,1,1,1,0,1,0], # 4
                      [1,1,0,1,0,1,1], # 5
                      [1,1,0,1,1,1], # 6
                      [1,0,1,0,0,1,0], # 7
                      [1,1,1,1,1,1,1], # 8
                      [1,1,1,1,0,1,1]) # 9
target_values = np.array([[1,0], # Even
                         [0,1], # Odd
                         [1,0], # Even
                         [0,1]]) # Odd
```

```
In [2]: | # Define the Perceptron Neural Network class
class PerceptronNN:
    def init (self, num inputs, num outputs):
        self.weights = np.zeros((num inputs, num outputs))
        self.bias = np.zeros(num_outputs)
    def activation(self, x):
        return 1 if x >= 0 else 0
    def feedforward(self, inputs):
        net = np.dot(inputs, self.weights) + self.bias
        output = np.array([self.activation(x) for x in net])
        return output
    def train(self, input data, target values, learning rate, epochs):
        for epoch in range(epochs):
            errors = 0
            for i, input in enumerate(input_data):
                target = target values[i]
                output = self.feedforward(input)
                error = target - output
                self.weights += learning rate * np.outer(input, error)
                self.bias += learning rate * error
                errors += np.abs(error).sum()
```

Odd Even Even