

Assignment 3Exercise : 1.

a) $\sin x = O(1)$ as $x \rightarrow \infty$

Since \sin oscillate between 1 and -1 $\forall x$

$$|\sin x| \leq 1 \cdot C \quad \forall x > t_0$$

Comparing with Big O notation $C=1$ and $t_0=0$.
True

b) $\sin x = O(1)$ as $x \rightarrow 0$

$$|\sin x| \leq 1 \quad \forall x \in [0, \pi/2]$$

$$|\sin x| \leq C \cdot 1 \quad \forall x \leq t_0$$

$$C=1 \text{ and } t_0 = \pi/2$$

True

c) $\ln x = O(x^{1/100})$ as $x \rightarrow \infty$

$$|\ln x| \leq C \cdot x^{1/100}.$$

$$\frac{1}{C} |\ln x| \leq x^{1/100}.$$

$$|\ln x^{1/C}| \leq x^{1/100}$$

$$(|\ln x| \leq k \quad \forall k > 1)$$

assume $C=100$.

$$(\ln x^{1/100}) \leq x^{1/100}.$$

$$|\ln x| \leq C \cdot x^{1/100} \quad \forall x > t_0$$

$$C=100 \text{ and } t_0=1.$$

True.

d) $n! = O\left(\left(\frac{n}{e}\right)^n\right)$ as $n \rightarrow \infty$ (Stirling's Approximation)

$$n! \leq C \left(\frac{n}{e}\right)^n$$

Stirling equation

$$e^{\frac{1}{12n+1}} \leq \frac{n!}{\sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n} \leq e^{\frac{1}{12n}}$$

$$e^{\frac{1}{12n+1}} \cdot \sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n \leq n! \leq e^{\frac{1}{12n}} \cdot \sqrt{2\pi n} \cdot \left(\frac{n}{e}\right)^n$$

$$n! \leq \underbrace{\left(e^{\frac{1}{12n}} \sqrt{2\pi n}\right)}_C \left(\frac{n}{e}\right)^n$$

Here $C = e^{(1/12n)} \sqrt{2\pi n}$ dependent on n . So
a constant value of C is not possible. as $(n \rightarrow \infty) \Rightarrow (C \rightarrow \infty)$

False.

e) $fl(\pi) - \pi = O(\epsilon_m)$ as $\epsilon_m \rightarrow 0$

$$fl(\pi) - \pi \leq c O(\epsilon_m)$$

Theorem 113.5) $fl(\pi) = \pi(1+\epsilon)$

$$|\epsilon| \leq \epsilon_{\text{machine}}$$

$$\begin{aligned} fl(\pi) - \pi &= \pi(1+\epsilon) - \pi \\ &= \pi\epsilon \end{aligned}$$

$$|\pi\epsilon| \leq \pi \epsilon_{\text{machine}}$$

$$\pi \epsilon \leq C(\epsilon_m)$$

$$\boxed{C = \pi}$$

$$10 = 100.$$

True.

f) $f_l(n\pi) - n\pi = O(\epsilon_m)$ as $\epsilon_m \rightarrow 0$.

$$f_l(n\pi) - n\pi \leq C O(\epsilon_m).$$

$$f_l(n\pi) = (1+\epsilon) n\pi.$$

$$f_l(n\pi) - n\pi = (1+\epsilon) n\pi - n\pi \\ = n\pi \epsilon$$

$$n\pi \epsilon \leq C O(\epsilon_m)$$

$$C = n\pi.$$

Here $n\pi$ monotonically increases with n . (and C is dependent on the value (variable n) not a constant value
False.

Exercise : 2.

a) $f(x) = 2x$ for $x \in \mathbb{Q}$ $f_l(x) = x + \epsilon x$

$$\therefore f_l(x) = x(1+\epsilon_1)$$

$$f_l(x) = x + \epsilon x.$$

$$[x(1+\epsilon_1) + x(1+\epsilon_1)](1+\epsilon_2)$$

$$= 2x(1+\epsilon_1)(1+\epsilon_2) \Rightarrow 2x(1+\epsilon_3).$$

$$= 2\tilde{x} \quad [\tilde{x} = x(1+\epsilon_3)]$$

accuracy condition $= \frac{\|f_l(x) - f(x)\|}{\|f(x)\|} = O(\epsilon_{\text{machine}})$.

$$= \frac{\|2x(1+\epsilon_3) - 2x\|}{\|2x\|}$$

$$= \frac{\|2x\epsilon_3\|}{\|2x\|} = \|\epsilon_3\| = O(\epsilon_{\text{machine}}).$$

Algorithm is accurate.

Backward stability $\Rightarrow \tilde{f}(x) = f(\tilde{x})$
 $\tilde{x} = \frac{\|y - x\|}{\|x\|} = 0 \text{ Emachine.}$

$$\begin{aligned}\tilde{f}(x) &= 2\tilde{x} \\ \tilde{f}(x) &= \tilde{x} + \tilde{x} = 2\tilde{x}\end{aligned}\quad \left| \begin{array}{l} \tilde{f}(x) = f(\tilde{x}) \\ \text{Backward stable.} \end{array} \right.$$

b) $f(x) = x^2$ for $x \in \mathbb{C}$ $\tilde{f}(x) = x \otimes x$
 $f_l(x) = x(1 + \epsilon_1)$

$$\begin{aligned}\tilde{f}(x) &= \tilde{x} \otimes \tilde{x} \\ &= f_l(x) \otimes f_l(x) \\ &= x(1 + \epsilon_1) \otimes x(1 + \epsilon_1) \\ &= x^2(1 + \epsilon_1)^2 (1 + \epsilon_2) \\ &= x^2(1 + 2\epsilon_1 + \epsilon_1^2)(1 + \epsilon_2) \\ &= x^2(1 + 2\epsilon_1 + \epsilon_1^2 + \epsilon_2 + 2\epsilon_1\epsilon_2 + \epsilon_1^2\epsilon_2) \\ &= x^2(1 + \epsilon_3). \\ (\text{Then}) \quad [\epsilon_3 &= 2\epsilon_1 + \epsilon_1^2 + \epsilon_2 + 2\epsilon_1\epsilon_2 + \epsilon_1^2\epsilon_2] \\ &= (\tilde{x})^2\end{aligned}$$

accuracy: $\frac{\|\tilde{f}(x) - f(x)\|}{\|f(x)\|} = 0 \text{ Emachine.}$

$$= \left\| \frac{x^2(1 + \epsilon_1)^2 - x^2}{\|x^2\|} \right\|$$

$$= \left\| \frac{x^2(1 + 2\epsilon_1 + \epsilon_1^2) - x^2}{\|x^2\|} \right\|$$

$$= \left\| \frac{x^2(2\epsilon_1 + \epsilon_1^2)}{\|x^2\|} \right\| = 0 \text{ Emachine.}$$

Accurate.

Backward stability $\Rightarrow \frac{\|\tilde{x} - x\|}{\|x\|} = 0$ Emachine.

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$$f(\tilde{x}) = \tilde{f}(x)$$

$$\tilde{f}(x) = (\tilde{x})^2$$

$$f(\tilde{x}) = (\tilde{x} \times \tilde{x}) = (\tilde{x}).$$

$$\left. \begin{array}{l} f(\tilde{x}) = \tilde{f}(x) \\ \end{array} \right\} f(\tilde{x}) = \tilde{f}(x)$$

Backward stable.

c) $f(x) = 1 \text{ for } x \in \mathbb{R} \setminus \{0\}$ $\tilde{f}(x) = x \oplus x$.

$$f_l(x) = x(1 + \epsilon_1)$$

$$\tilde{f}(x) = x \otimes x$$

$$= f_l(x) / f_l(x)$$

$$= \frac{x(1 + \epsilon_1)}{x(1 + \epsilon_1)} (1 + \epsilon_2)$$

$$= (1 + \epsilon_2)$$

$$\text{accuracy} = \frac{\|\tilde{f}(x) - f(x)\|}{\|\tilde{f}(x)\|} = 0 \text{ Emachine.}$$

$$= \frac{\|(1 + \epsilon_2) - 1\|}{\|1\|} = 0 \text{ Emachine}$$

$$= \|\epsilon_2\| = 0 \text{ Emachine.}$$

Accurate.

Backward stability $\Rightarrow \frac{\|\tilde{x} - x\|}{\|x\|} = 0$ Emachine.

$$f(\tilde{x}) = \tilde{f}(x)$$

$$f(\tilde{x}) = \tilde{x}/\tilde{x} = 1 \quad \left. \begin{array}{l} \\ \end{array} \right\} f(\tilde{x}) \neq \tilde{f}(x)$$

$$\tilde{f}(x) = (1 + \epsilon_2)$$

Not Backward stable.

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stability $\frac{\|\tilde{f}(x) - f(\tilde{x})\|}{\|f(\tilde{x})\|} \rightarrow 0 \text{ Emachine.}$

$$= \frac{\|(1 + \epsilon_2) - 1\|}{\|1\|} = \|\epsilon_2\| = 0 \text{ Emachine}$$

stable

d) $f(x) = 0 \text{ for } x \in \mathbb{Q}, f(x) = x \ominus x$

$$fl(x) = x(1 + \epsilon_1)$$

$$\tilde{f}(x) \quad \tilde{f}(x) = x \ominus x$$

$$= fl(x) \ominus fl(x)$$

$$= [x(1 + \epsilon_1) - x(1 + \epsilon_1)](1 + \epsilon_2) \\ = 0.$$

accuracy = $\frac{\|\tilde{f}(x) - f(x)\|}{\|f(x)\|} = 0 \text{ Emachine}$

$$= \frac{\|0 - (x - x)\|}{\|x - x\|} = \frac{0}{0} \neq 0 \text{ Emachine.}$$

not accurate.

Backward stability $\tilde{f}(x) = f(\tilde{x})$

$$\frac{\|\tilde{x} - x\|}{\|x\|} = 0 \text{ Emachine.}$$

$$\tilde{f}(x) = 0$$

$$f(\tilde{x}) = \tilde{x} - \tilde{x} = 0$$

$$f(\tilde{x}) = \tilde{f}(x)$$

Backward stable

a) $A \in \mathbb{C}^{(m+1) \times m}$

$\text{OR} = A$.

In the 1st column, we need to reduce $(m-1)$ elements to zero using row operation on $(n-1)$ non-trivial rows elements. But from the next column, we need to reduce $(m-2)$ element to zero.

Eg:

$$A \left\{ \begin{array}{c} \sim \\ \begin{bmatrix} x & x & x \\ x & x & x \\ x & x & x \end{bmatrix} \end{array} \right. \rightarrow \left[\begin{array}{c} \sim \\ \begin{bmatrix} x & x & + \\ x & x & x \\ 0 & x & x \end{bmatrix} \end{array} \right] \dots \left[\begin{array}{c} \sim \\ \begin{bmatrix} x & x & x \\ 0 & x & x \\ 0 & 0 & x \end{bmatrix} \end{array} \right]$$

↓ :

$$\left[\begin{array}{c} \sim \\ \begin{bmatrix} x & x & x \\ 0 & x & \otimes \\ 0 & 0 & x \end{bmatrix} \end{array} \right] = \text{IR.}$$

Computing Total Cost:

$$\sum_{k=1}^n (m-k)(n-k) = mn^2 - (m+n) \frac{n(n+1)}{2} + n(n+1) \frac{(2n+1)}{6}$$

$$= \frac{n(m-1)}{2} (m - \frac{n+1}{3})$$

$A \in \mathbb{C}^{(m+1) \times m}$

$$\text{Flops} = \frac{n(m-1)}{2} \left[(m+1) - \frac{(m+1)}{3} \right]$$

$$= \frac{n(m-1)}{2} \left[\frac{3m+3-m-1}{3} \right] = \frac{n(m-1)}{2} \left[\frac{2m+2}{3} \right]$$

$$= \frac{n(m-1)(m+1)}{3} = \frac{n(m^2-1)}{3}$$

b) $A \in \mathbb{C}^{(m+1) \times m}$ = Upper hessenberg matrix

Eg:

$$A = \begin{bmatrix} x & x & x & x \\ x & x & x & x \\ 0 & x & x & x \\ 0 & 0 & x & * \\ 0 & 0 & x & x \end{bmatrix}$$

needs to
be zero

Total no. of operation $n_{op} = \frac{1}{2} m(m+1) \times 6$
 $\sim O(m^2)$

$$n_{op}(m) = g \cdot m^2$$

$$g(m) = m^2$$

```
import numpy as np
from numpy.testing import assert_allclose

def givens_qr(H):
    H = H + 0.0
    dtype = np.complex128 if np.iscomplexobj(H) else np.float64
    m = np.shape(H)[1]
    i = 0
    R = np.copy(H)
    Q = np.zeros((m, 2)).astype(H.dtype)
    G = np.zeros((m, 2)).astype(H.dtype)

    def givens_rotation(a, b):
        r = np.sqrt(abs(a)**2 + abs(b)**2)
        c = np.conj(a)/r
        s = np.conj(b)/r
        return c, s

    for k in range(m):
        a = R[k, k]
        b = R[k + 1, k]

        c, s = givens_rotation(a, b)

        if b != 0:
            G = np.identity(2).astype(c.dtype)
            G[0] = c, s
            G[1, 0] = -s.conjugate()
            G[1, 1] = c.conjugate()

    return Q, G
```

```

34
35         R[k:k + 2, k:] = G @ R[k:k + 2, k:]
36
37         Q[i] = c, s
38     else:
39         Q[i] = 1, 0
40
41     i += 1
42
43 return Q, R
44
45 # Example usage with complex numbers:
46 H = np.array([[1,2,3],[4,5,6],[0,7,8],[0,0,9]])
47
48
49 print("Original Upper Hessenberg Matrix:")
50 print(H)
51 # Compute QR factorization using Givens rotations
52 R = givens_qr(H)
53 print("\nUpper Triangular Matrix R:")
54 print(R)
55
56 def form_q(G):
57     m = G.shape[0]
58     Q = np.identity(m + 1).astype(G.dtype)
59
60     for j in range(m):
61
62         K = np.identity(2).astype(G.dtype)
63         K[:, 0] = G[j].conjugate()
64         K[0, 1] = -G[j, 1]
65         K[1, 1] = G[j, 0]
66
67
68         Q[:, j:j + 2] = Q[:, j:j + 2] @ K
69
70 return Q
71

```