



# Digital Electronics & Logic Design

(EC 207)



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# Course Outline



- **PN DIODE AND TRANSITOR (04 Hours)**  
PN Diode Theory, PN Characteristic and Breakdown Region, PN Diode Application as Rectifier, Zener Diode Theory, Zener Voltage Regulator, Diode as Clamper and Clipper, Photodiode Theory, LED Theory, 7 Segment LED Circuit Diagram and Multi Colour LED, LASER Diode Theory and Applications, Bipolar Junction Transistor Theory, Transistor Symbols And Terminals, Common Collector, Emitter and Base Configurations, Different Biasing Techniques, Concept of Transistor Amplifier, Introduction to FET Transistor And Its Feature.
- **WAVESHAPING CIRCUITS AND OPERATIONAL AMPLIFIER (06 Hours)**  
Linear Wave Shaping Circuits, RC High Pass and Low Pass Circuits, RC Integrator and Differentiator Circuits, Nonlinear Wave Shaping Circuits, Two Level Diode Clipper Circuits, Clamping Circuits, Operational Amplifier OP-AMP with Block Diagram, Schematic Symbol of OP-AMP, The 741 Package Style and Pinouts, Specifications of Op-Amp, Inverting and Non-Inverting Amplifier, Voltage Follower Circuit, Multistage OP-AMP Circuit, OP-AMP Averaging Amplifier, OP-AMP Subtractor.
- **BOOLEAN ALGEBRA AND SWITCHING FUNCTIONS (04 Hours)**  
Basic Logic Operation and Logic Gates, Truth Table, Basic Postulates and Fundamental Theorems of Boolean Algebra, Standard Representations of Logic Functions- SOP and POS Forms, Simplification of Switching Functions-K-Map and Quine-Mccluskey Tabular Methods, Synthesis of Combinational Logic Circuits.
- **COMBINATIONAL LOGIC CIRCUIT USING MSI INTEGRATED CIRCUITS (07 Hours)**



# Course Outline



Binary Parallel Adder; BCD Adder; Encoder, Priority Encoder, Decoder; Multiplexer and Demultiplexer Circuits; Implementation of Boolean Functions Using Decoder and Multiplexer; Arithmetic and Logic Unit; BCD to 7-Segment Decoder; Common Anode and Common Cathode 7-Segment Displays; Random Access Memory, Read Only Memory And Erasable Programmable ROMS; Programmable Logic Array (PLA) and Programmable Array Logic (PAL).

- **INTRODUCTION TO SEQUENTIAL LOGIC CIRCUITS (04 Hours)**  
Basic Concepts of Sequential Circuits; Cross Coupled SR Flip-Flop Using NAND or NOR Gates; JK Flip-Flop Rise Condition; Clocked Flip-Flop; D-Type and Toggle Flip-Flops; Truth Tables and Excitation Tables for Flip-Flops; Master Slave Configuration; Edge Triggered and Level Triggered Flip-Flops; Elimination of Switch Bounce using Flip-Flops; Flip-Flops with Preset and Clear.
- **SEQUENTIAL LOGIC CIRCUIT DESIGN (06 Hours)**  
Basic Concepts of Counters and Registers; Binary Counters; BCD Counters; Up Down Counter; Johnson Counter, Module-N Counter; Design of Counter Using State Diagrams and Table; Sequence Generators; Shift Left and Right Register; Registers With Parallel Load; Serial-In-Parallel-Out (SIPO) And Parallel-In-Serial-Out(PISO); Register using Different Type of Flip-Flop.
- **REGISTER TRANSFER LOGIC (04 Hours)**  
Arithmetic, Logic and Shift Micro-Operation; Conditional Control Statements; Fixed-Point and Floating-Point Data; Arithmetic Shifts; Instruction Code and Design Of Simple Computer.
- **PROCESSOR LOGIC DESIGN (03 Hours)**  
Processor Organization; Design of Arithmetic Logic Unit; Design of Accumulator.
- **CONTROL LOGIC DESIGN (04 Hours)**  
Control Organization; Hard-Wired Control; Micro Program Control; Control Of Processor Unit; PLA Control.



# Course Text and Materials



1. Schilling Donald L. and Belove E., "Electronics Circuits- Discrete and Integrated", 3rd Ed., McGraw-Hill, 1989, Reprint 2008.
2. Millman Jacob, Halkias Christos C. and Parikh C., "Integrated Electronics", 2nd Ed., McGraw-Hill, 2009.
3. Taub H. and Mothibi Suryaprakash, Millman J., "Pulse, Digital and Switching Waveforms", 2nd Ed., McGraw-Hill, 2007.
4. Mano Morris, "Digital Logic and Computer Design", 5th Ed., Pearson Education, 2005.
5. Lee Samuel, "Digital Circuits and Logic Design", 1st Ed., PHI, 1998.



# Digital Logic Circuits



## COMBINATIONAL CIRCUITS

Output depends only on the present value of the inputs.

These circuits will not have any memory as their outputs change with the change in the input value.

There are no feedbacks involved.

Used in basic Boolean operations.

Implemented in: Half adder circuit, full adder circuit, multiplexers, de-multiplexers, decoders and encoders.

## SEQUENTIAL CIRCUITS

Output depends on both the present and previous state values of the inputs

Sequential circuits have some sort of memory as their output changes according to the previous and present values.

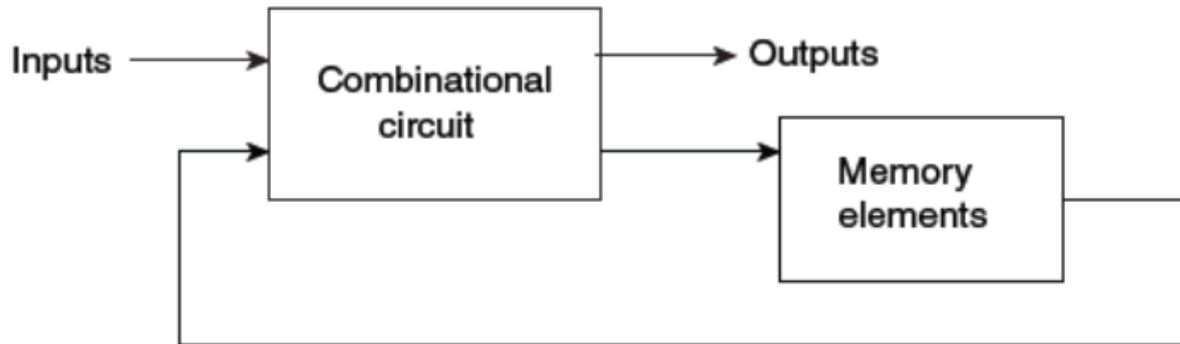
In a sequential circuit the outputs are connected to it as a feedback path.

Used in the designing of memory devices.

Implemented in: RAM, Registers, counters and other state retaining machines.



# Digital Logic Circuits



- ☐ Basic Memory element of a Digital Computer
- ☐ Stores 1 bit of information
- ☐ It's a Bistable device
- ☐ Has two outputs, one complement of another (Q and Q')
- ☐ Four Types
  - ☐ SR
  - ☐ D
  - ☐ JK
  - ☐ T



# Digital Logic Circuits



- ☐ Most basic type of FF circuit
- ☐ Can be constructed using NAND or NOR Gates
- ☐ These circuits latch to '1' or '0' immediately upon application of inputs
- ☐ Two types
  - ☐ NAND Gate Latch (Active Low)
  - ☐ NOR Gate Latch (Active High)

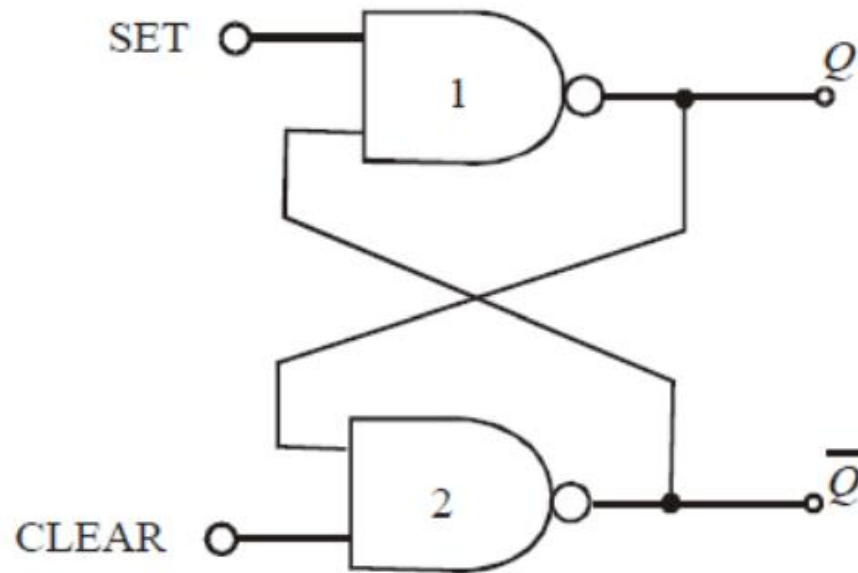




# Digital Logic Circuits



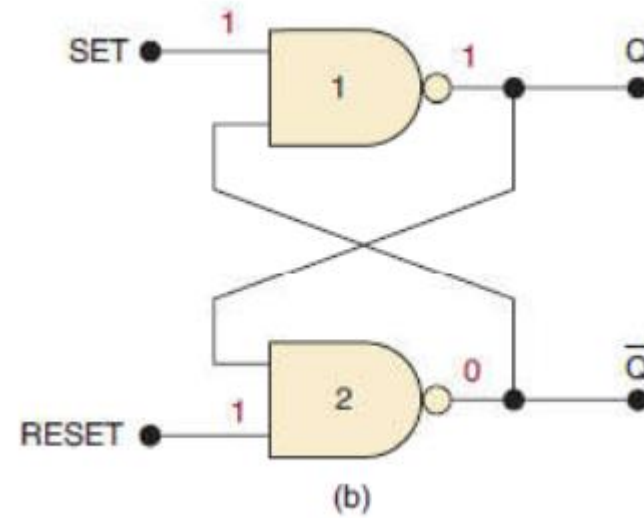
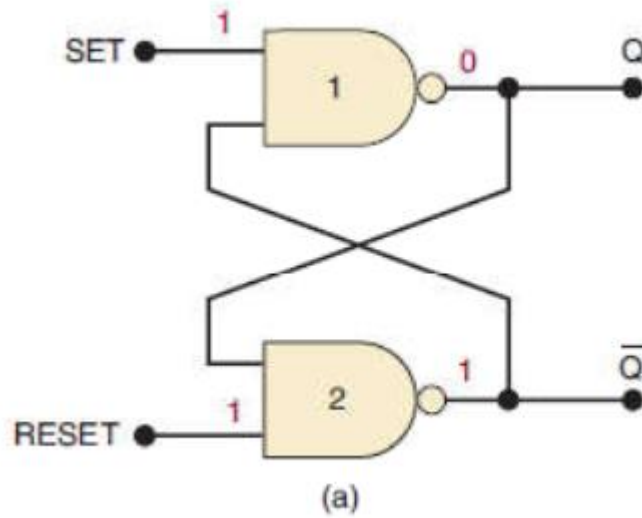
## NAND Gate SR Latch

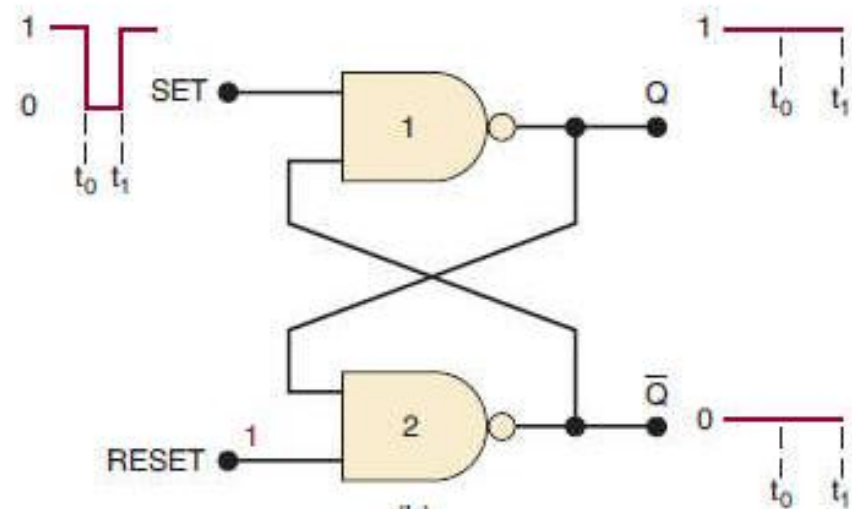
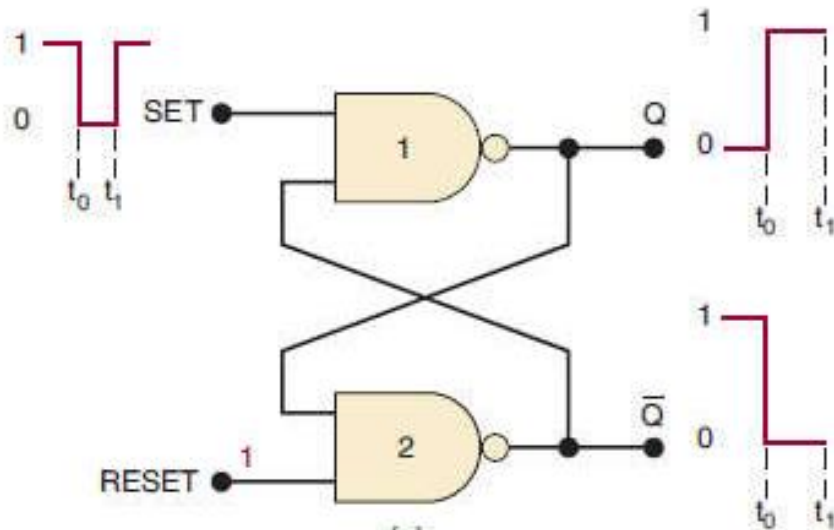






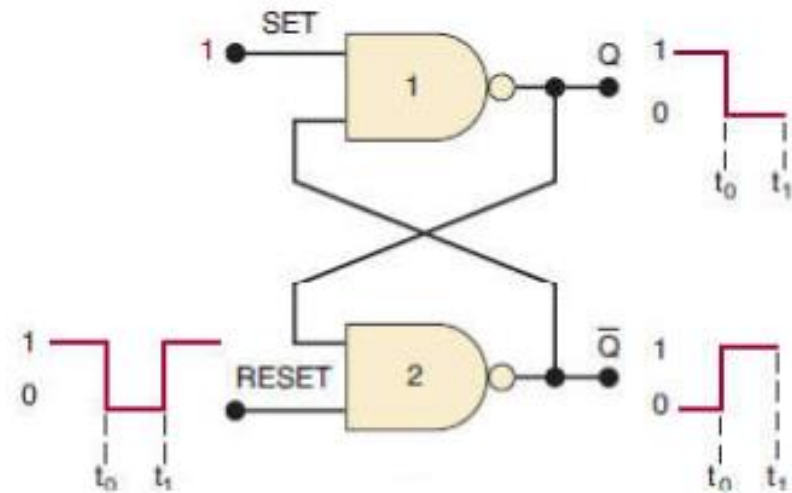
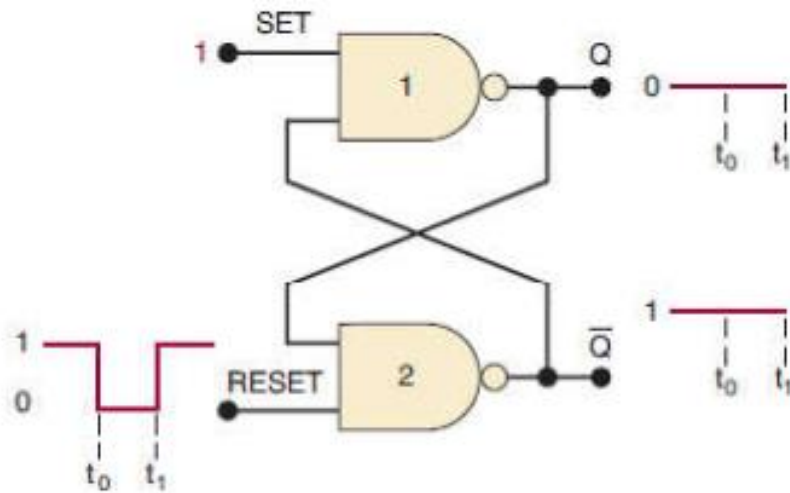
# Digital Logic Circuits







# Digital Logic Circuits

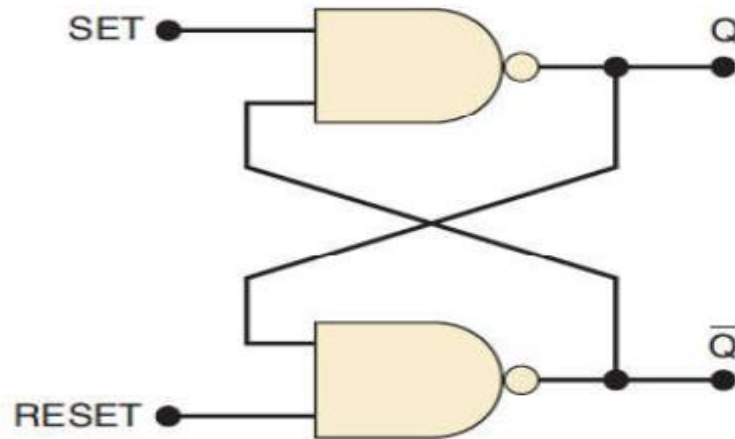




# Digital Logic Circuits



## NAND Gate SR Latch



Set	Reset	Output
1	1	No change
0	1	$Q = 1$
1	0	$Q = 0$
0	0	Invalid *

\*Produces  $Q = \bar{Q} = 1$ .

(b)

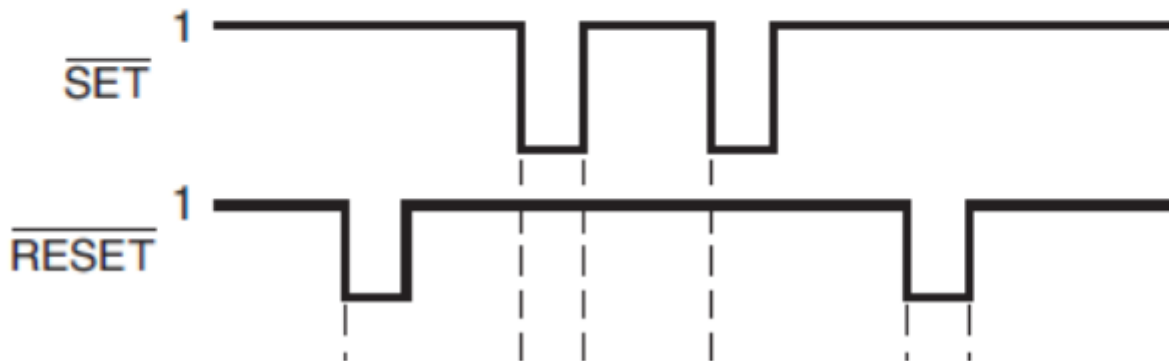
1.  $SET = RESET = 1$ . This condition is the normal resting state, and it has no effect on the output state. The  $Q$  and  $\bar{Q}$  outputs will remain in whatever state they were in prior to this input condition.
2.  $SET = 0, RESET = 1$ . This will always cause the output to go to the  $Q = 1$  state, where it will remain even after  $SET$  returns HIGH. This is called *setting* the latch.
3.  $SET = 1, RESET = 0$ . This will always produce the  $Q = 0$  state, where the output will remain even after  $RESET$  returns HIGH. This is called *clearing* or *resetting* the latch.
4.  $SET = RESET = 0$ . This condition tries to set and clear the latch at the same time, and it produces  $Q = \bar{Q} = 1$ . If the inputs are returned to 1 simultaneously, the resulting state is unpredictable. This input condition should not be used.



# Digital Logic Circuits

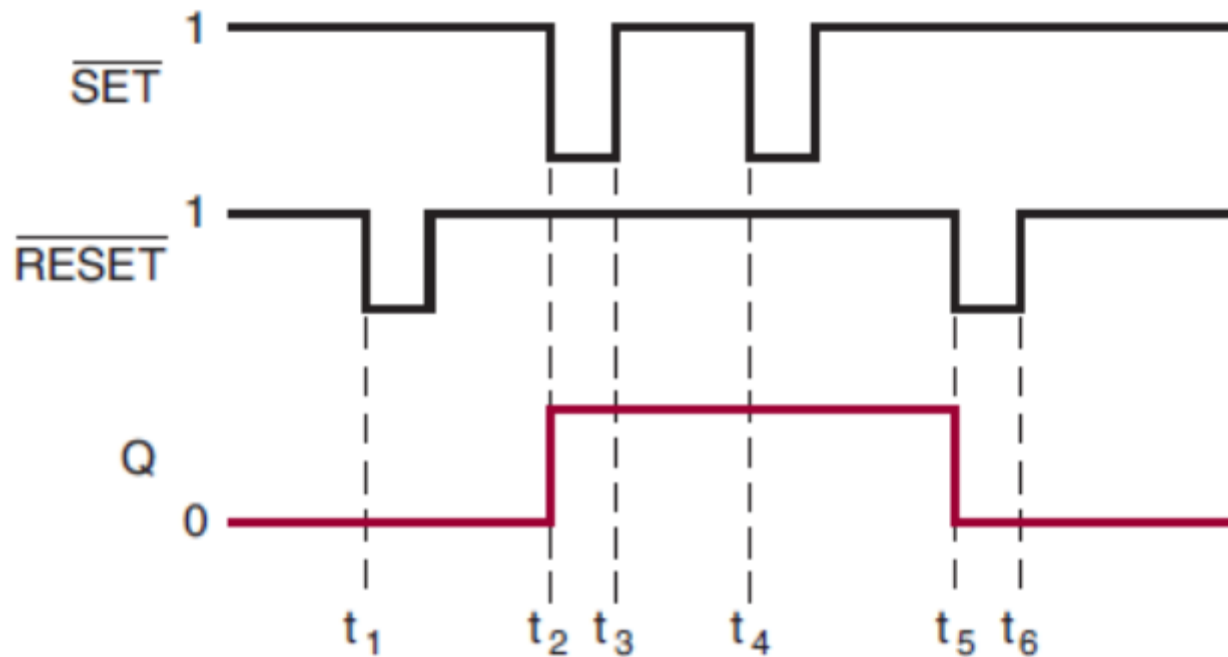


Assuming the  $Q=0$  initially, determine the  $Q$  waveform for the NAND Latch





# Digital Logic Circuits

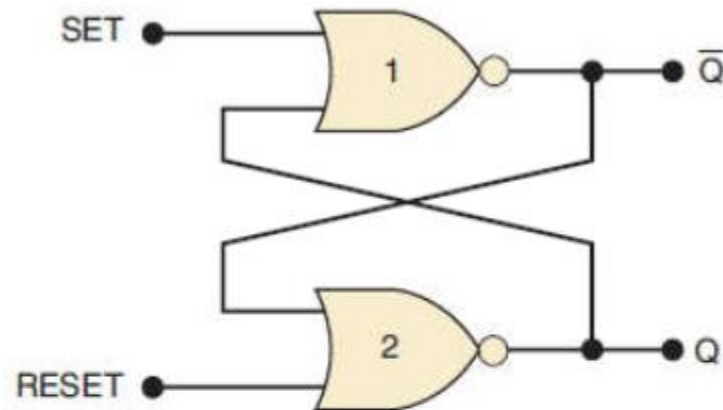




# Digital Logic Circuits

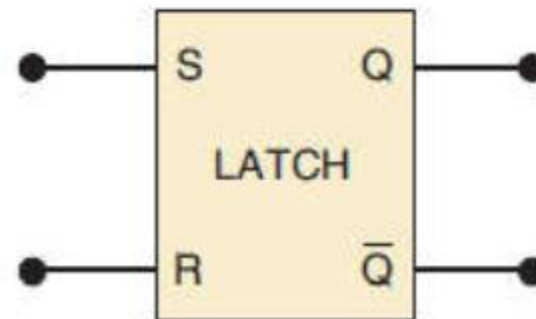


## NOR Gate SR Latch



Set	Reset	Output
0	0	No change
1	0	$Q = 1$
0	1	$Q = 0$
1	1	Invalid*

\*Produces  $Q = \bar{Q} = 0$ .







# Digital Logic Circuits



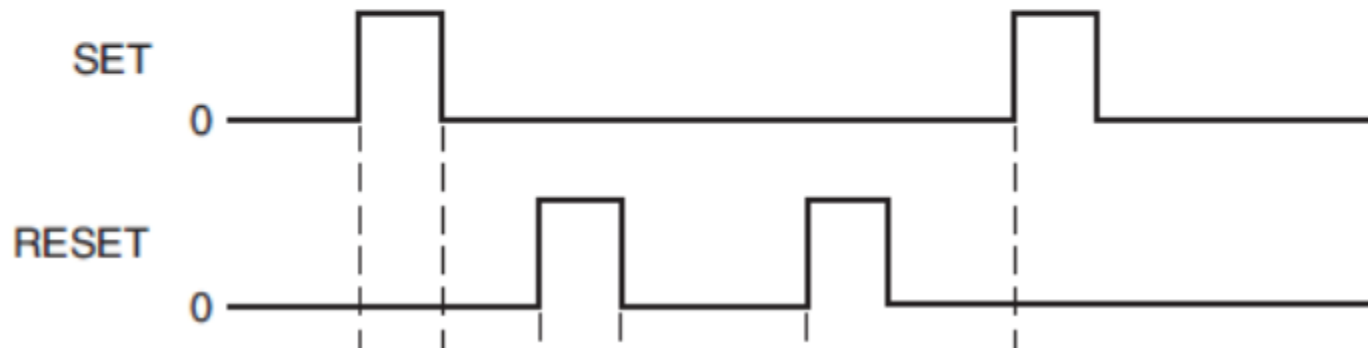
1.  $SET = RESET = 0$ . This is the normal resting state for the NOR latch, and it has no effect on the output state.  $Q$  and  $\bar{Q}$  will remain in whatever state they were in prior to the occurrence of this input condition.
2.  $SET = 1, RESET = 0$ . This will always set  $Q = 1$ , where it will remain even after  $SET$  returns to 0.
3.  $SET = 0, RESET = 1$ . This will always clear  $Q = 0$ , where it will remain even after  $RESET$  returns to 0.
4.  $SET = 1, RESET = 1$ . This condition tries to set and reset the latch at the same time, and it produces  $Q = \bar{Q} = 0$ . If the inputs are returned to 0 simultaneously, the resulting output state is unpredictable. This input condition should not be used.



# Digital Logic Circuits

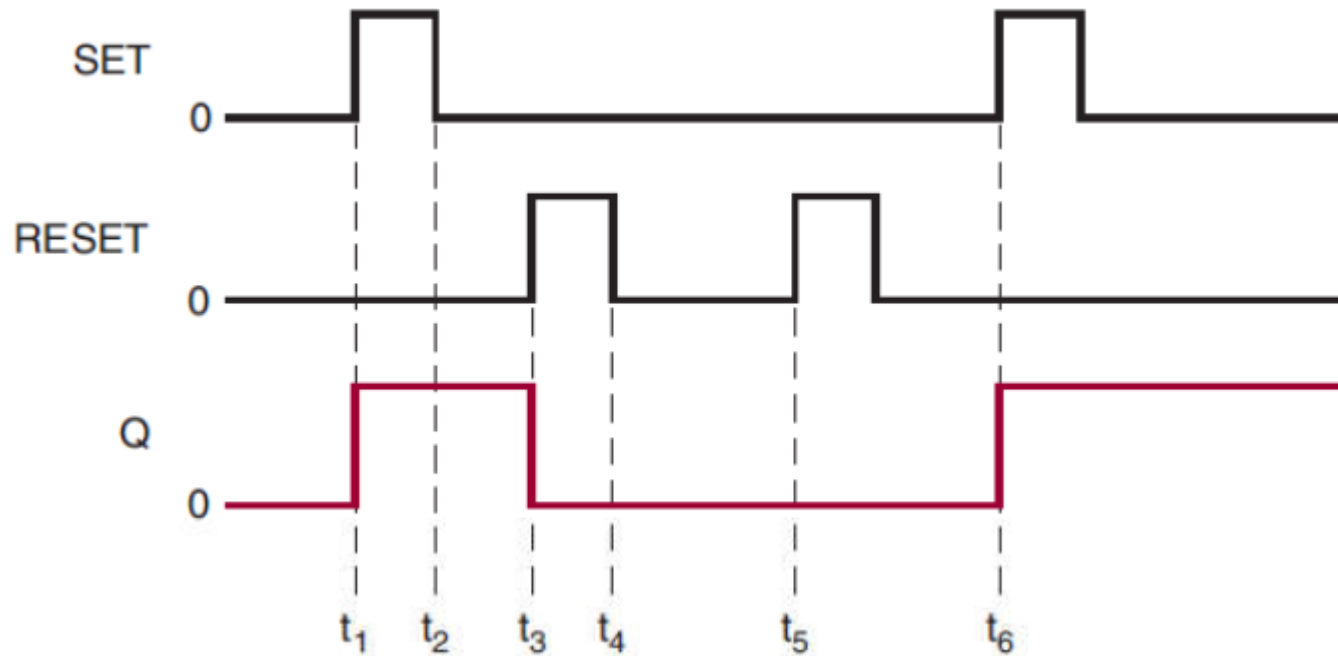


Assuming the  $Q=0$  initially, determine the  $Q$  waveform for the NOR Latch





# Digital Logic Circuits

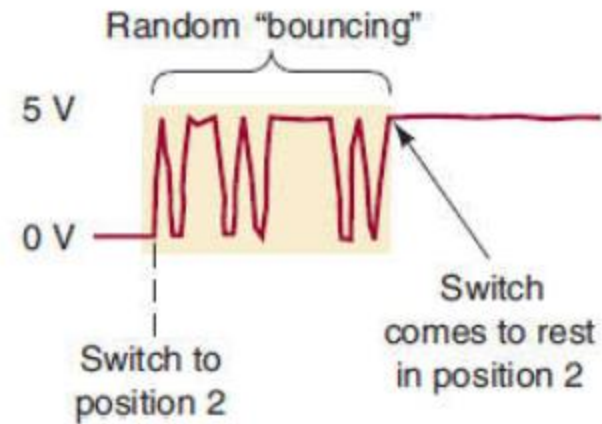
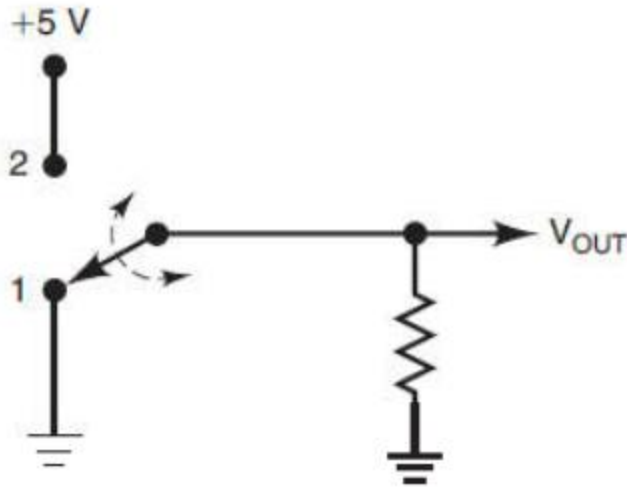




# Digital Logic Circuits

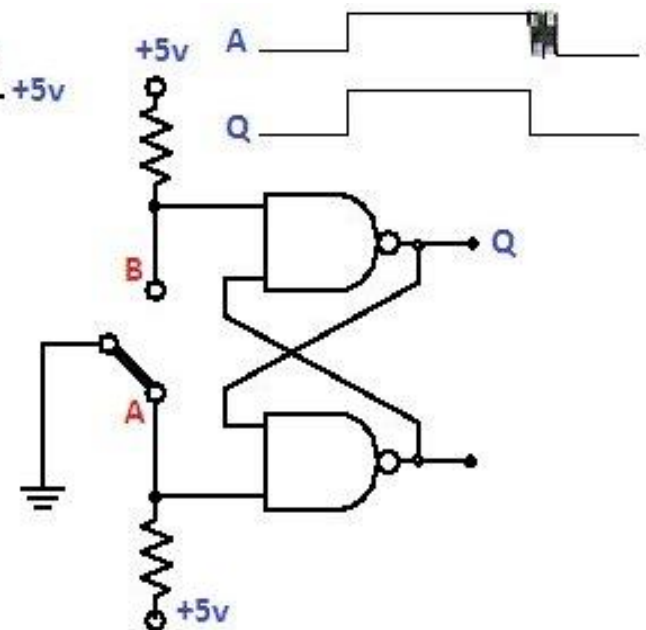
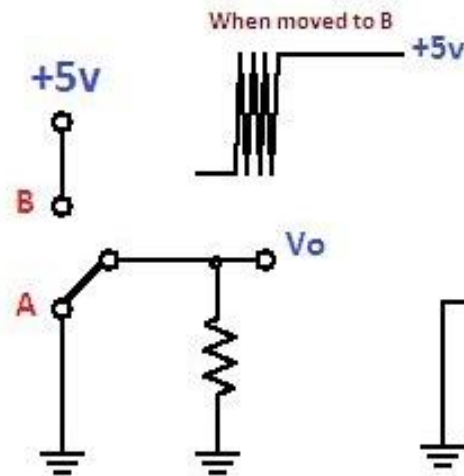
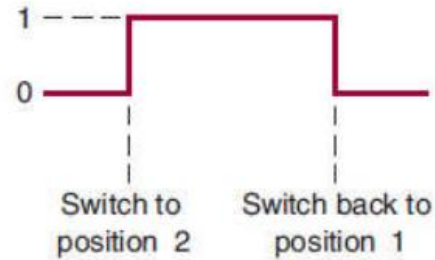
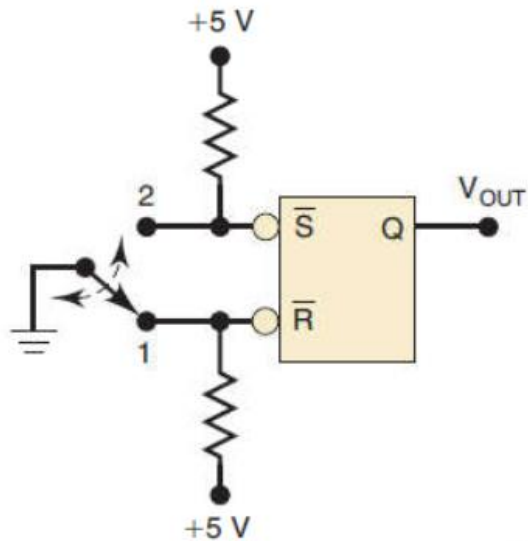


## Switch Debounce





# Digital Logic Circuits

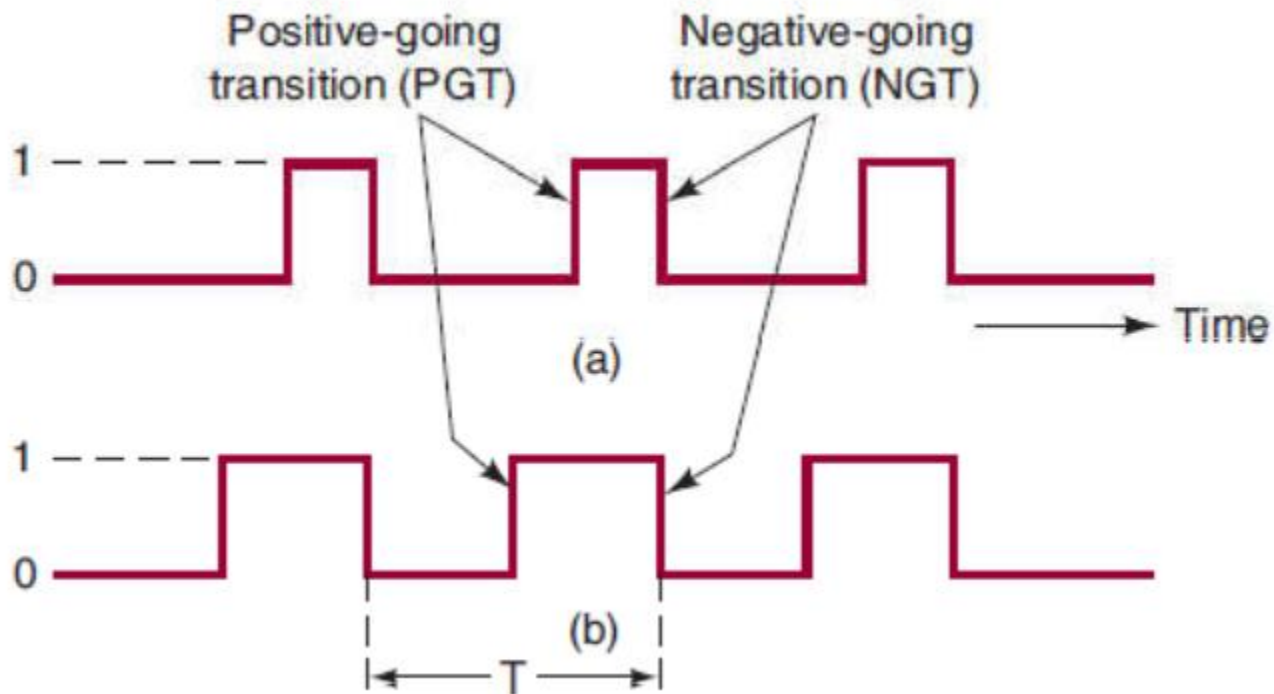




# Digital Logic Circuits



## Pulse triggering

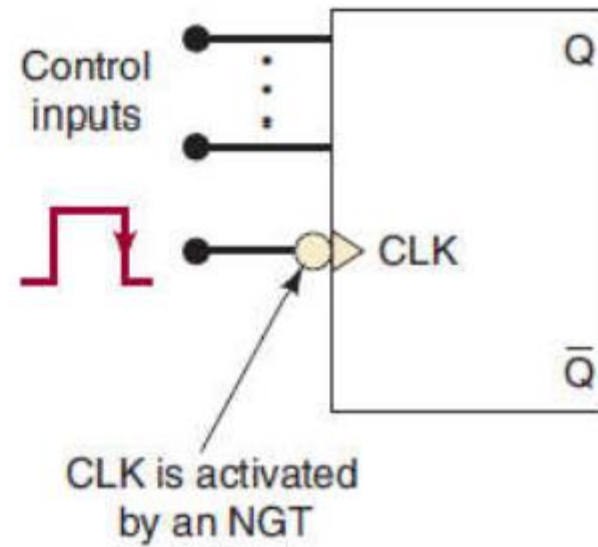
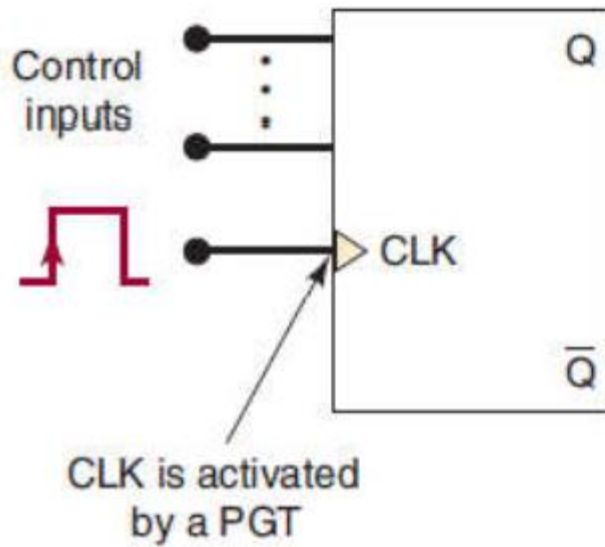




# Digital Logic Circuits



## Edge triggering



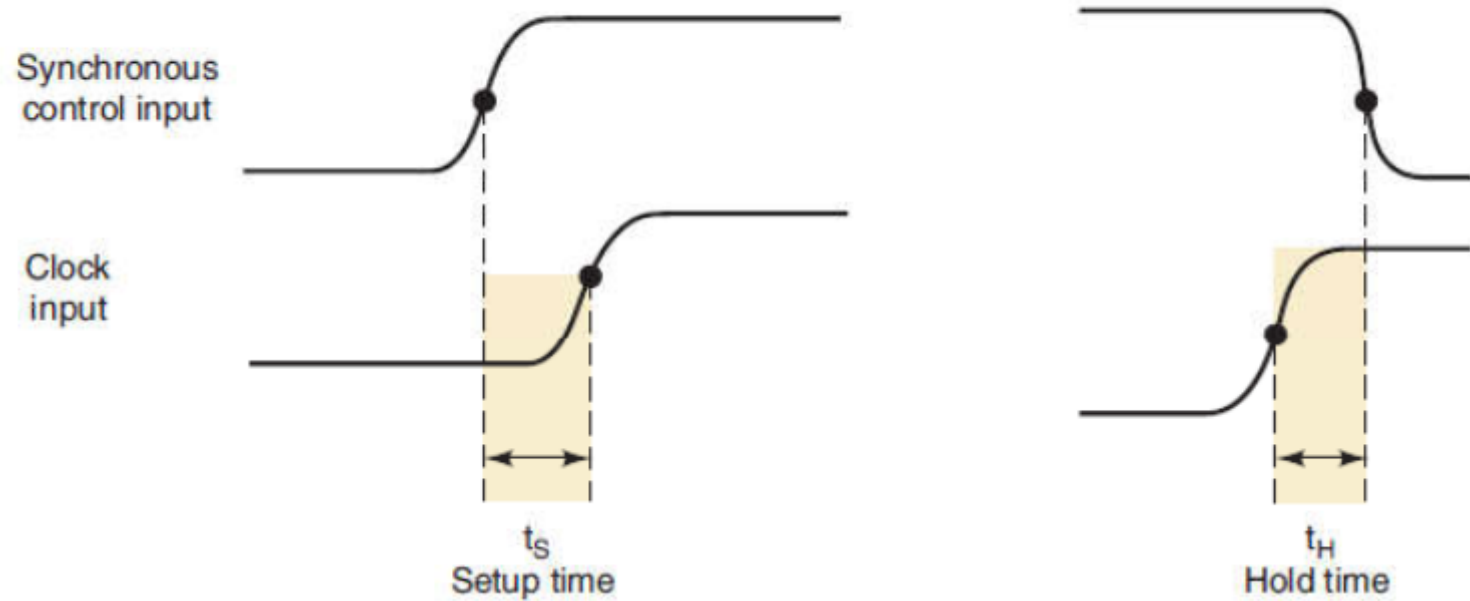




# Digital Logic Circuits



## Setup and Hold time

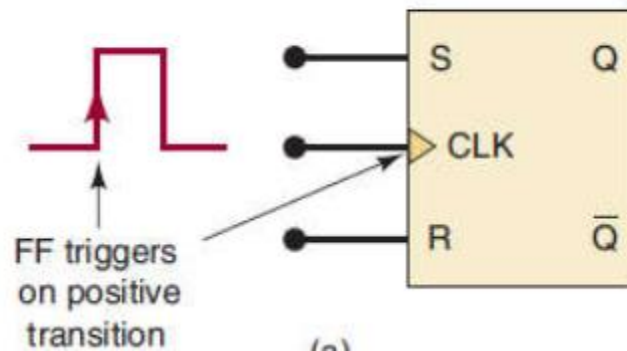




# Digital Logic Circuits



## Clocked SR Flip Flop



Inputs			Output
S	R	CLK	Q
0	0	↑	$Q_0$ (no change)
1	0	↑	1
0	1	↑	0
1	1	↑	Ambiguous

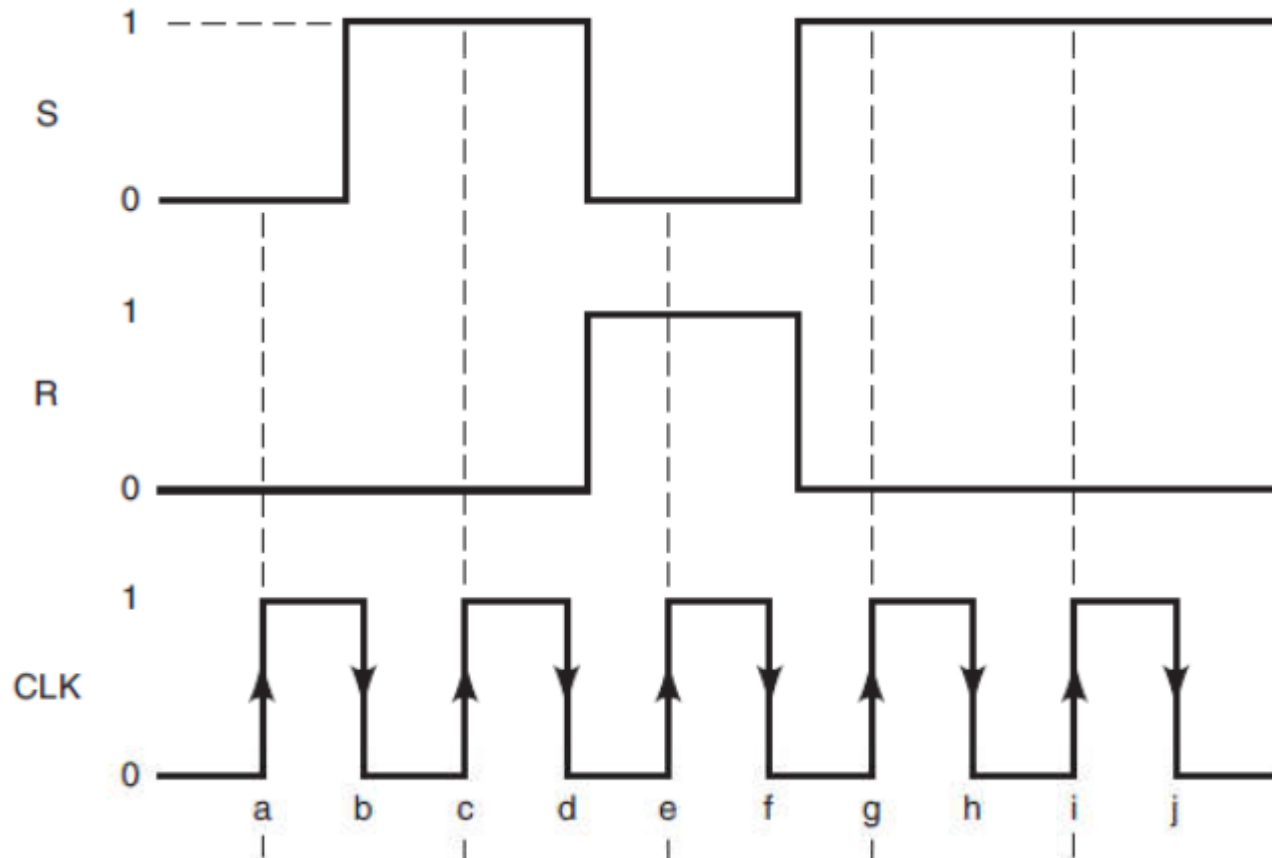
$Q_0$  is output level prior to ↑ of CLK.  
↓ of CLK produces no change in Q.



# Digital Logic Circuits

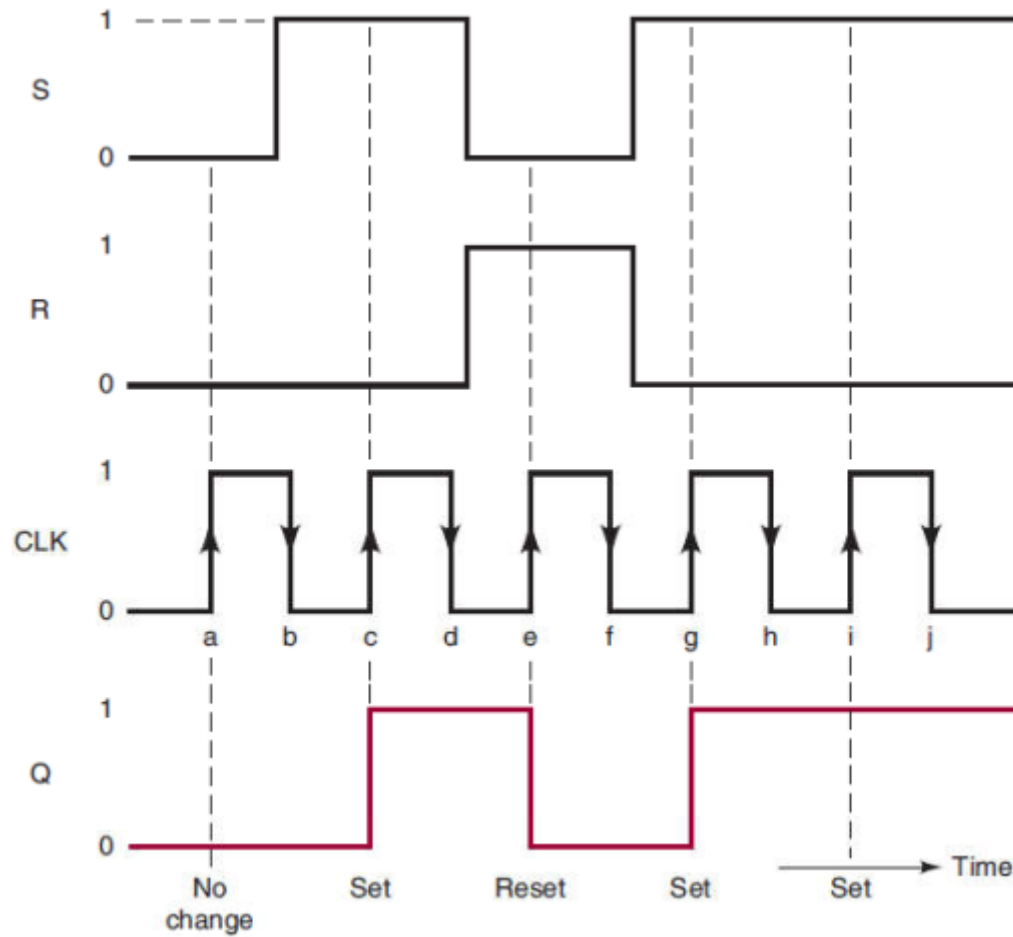


## Problem





# Digital Logic Circuits

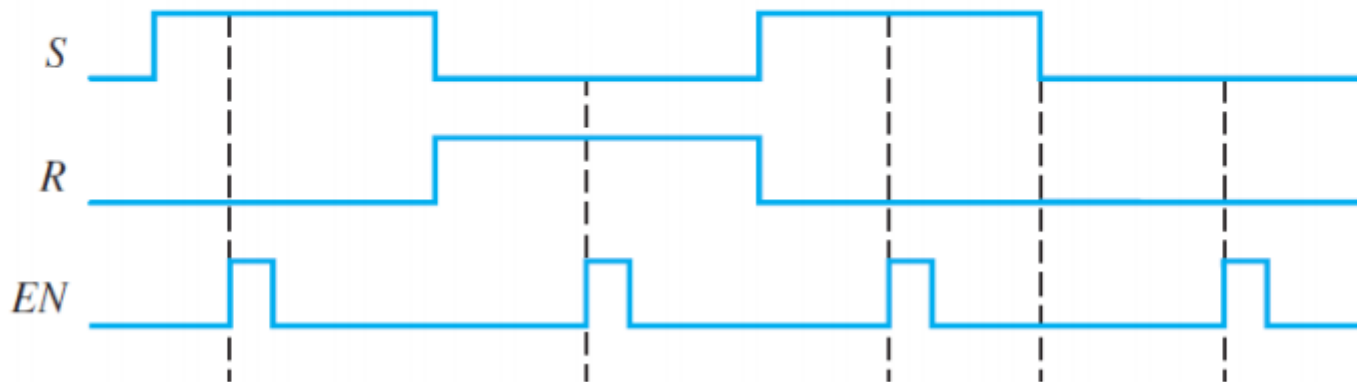




# Digital Logic Circuits



- Assuming  $Q=0$  initially, Predict the output Waveform For a Gated SR Latch.

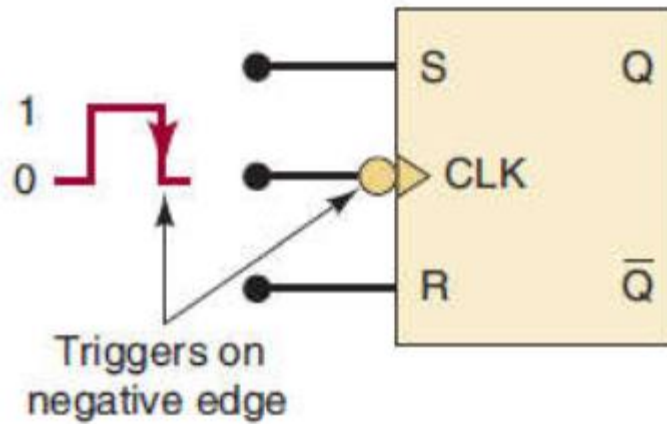




# Digital Logic Circuits



## Negative Edge triggered SR Flip Flop



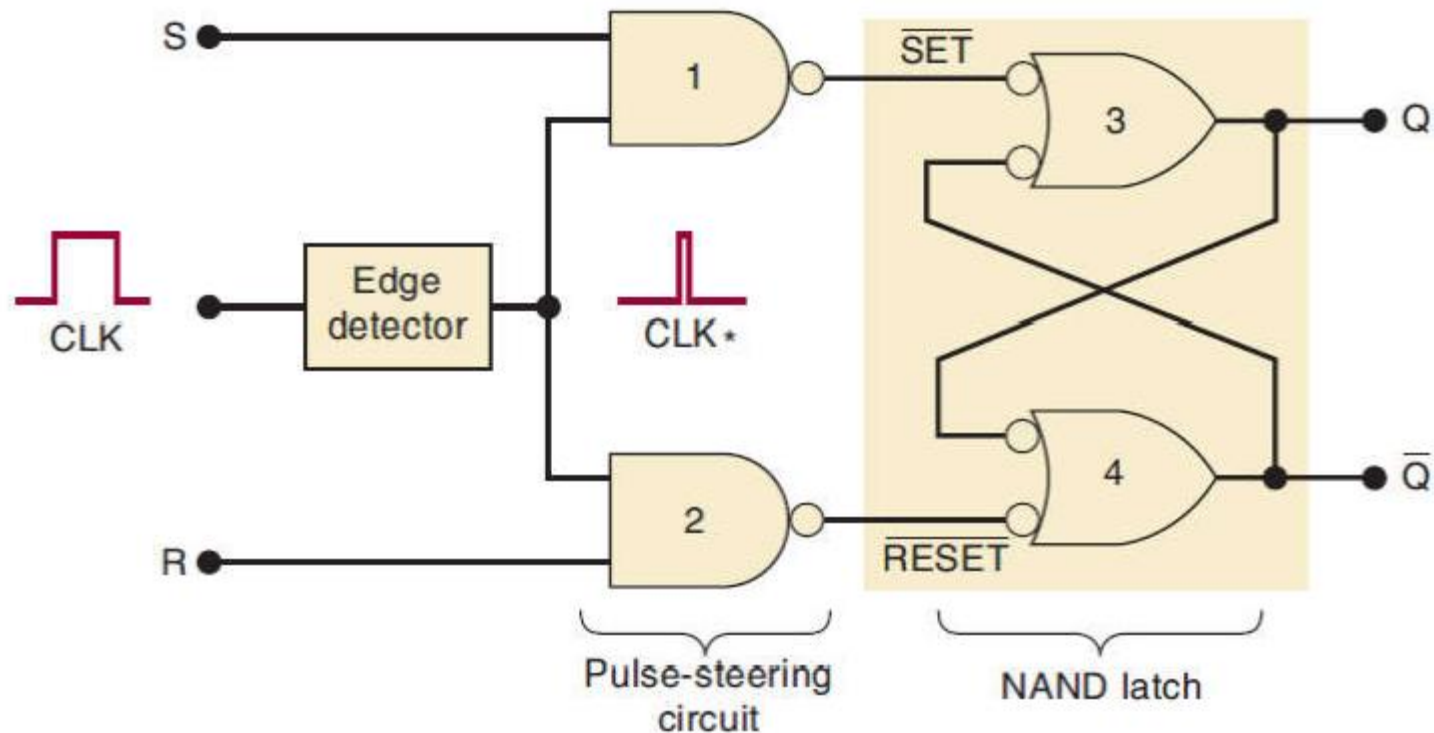
Inputs			Output
S	R	CLK	Q
0	0	↓	$Q_0$ (no change)
1	0	↓	1
0	1	↓	0
1	1	↓	Ambiguous



# Digital Logic Circuits



## Internal Circuit of Clocked SR Flip Flop



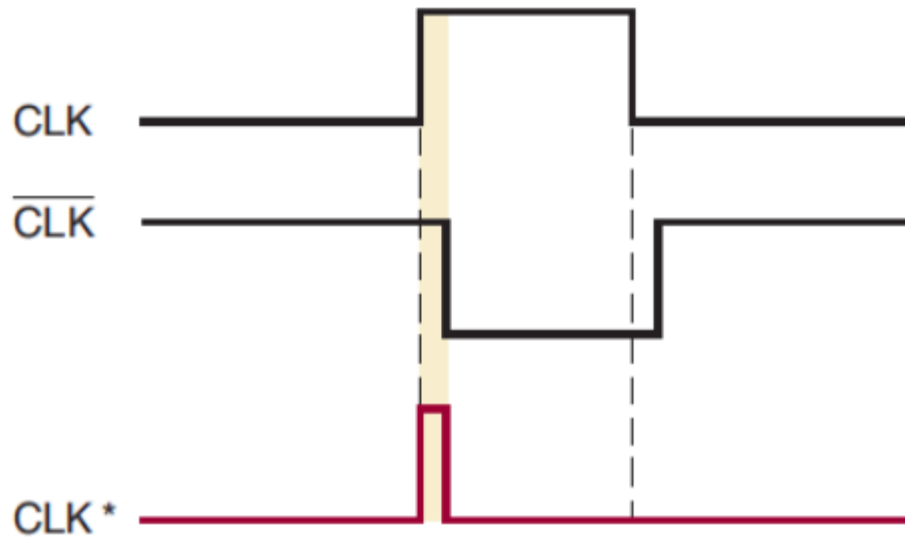
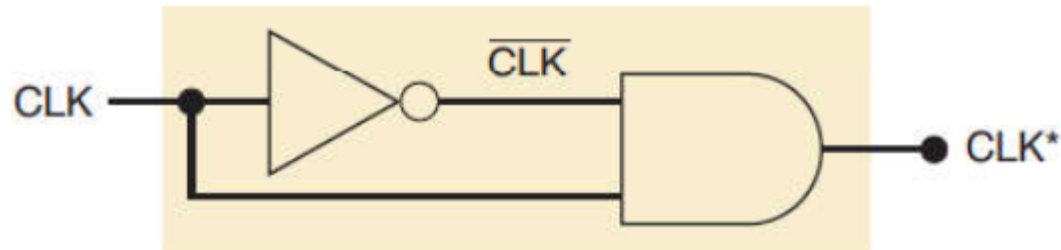




# Digital Logic Circuits



## Generation of Positive Edge Triggering

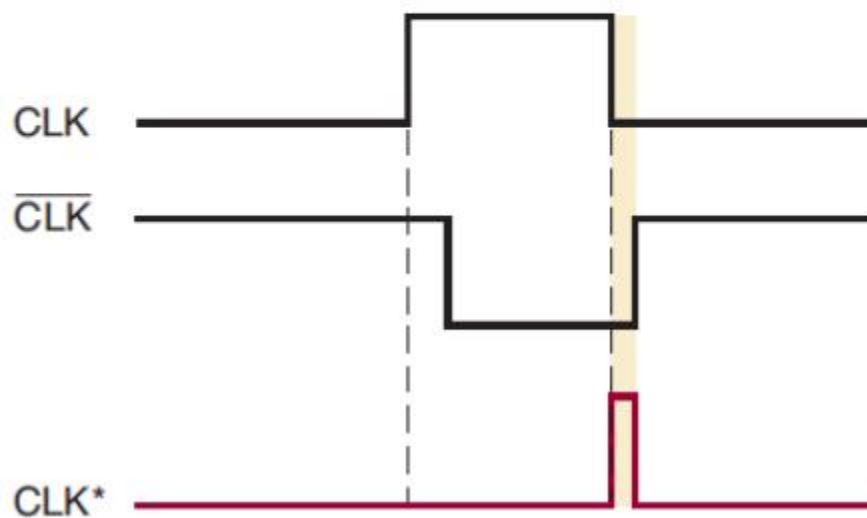
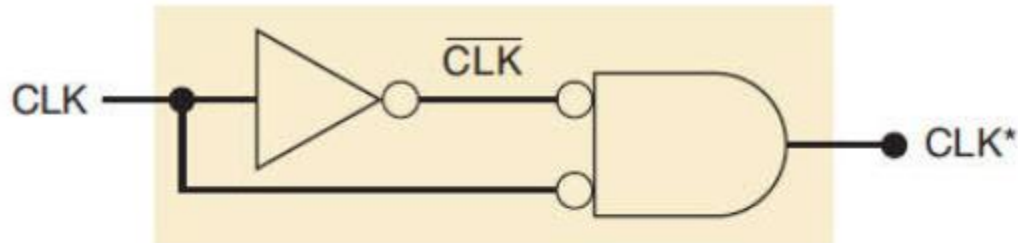




# Digital Logic Circuits



## Generation of Negative Edge Triggering

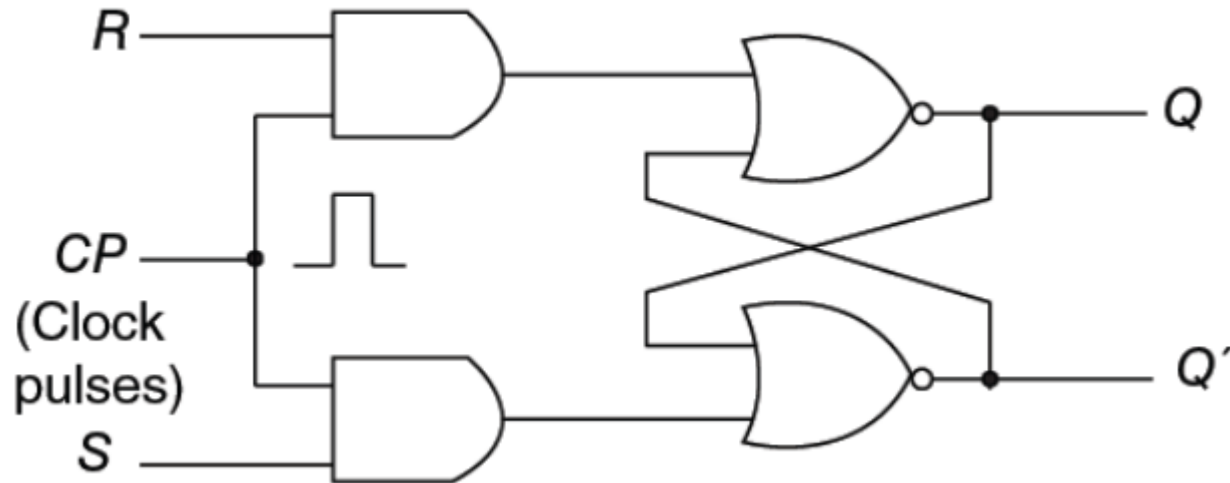




# Digital Logic Circuits



## Clocked RS Flip Flop

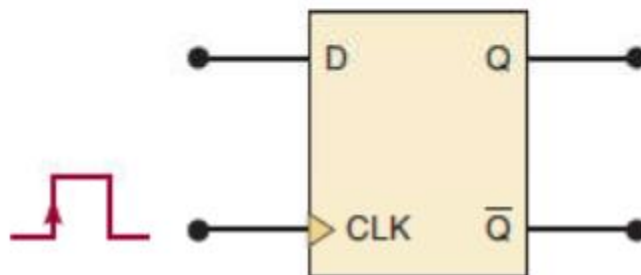
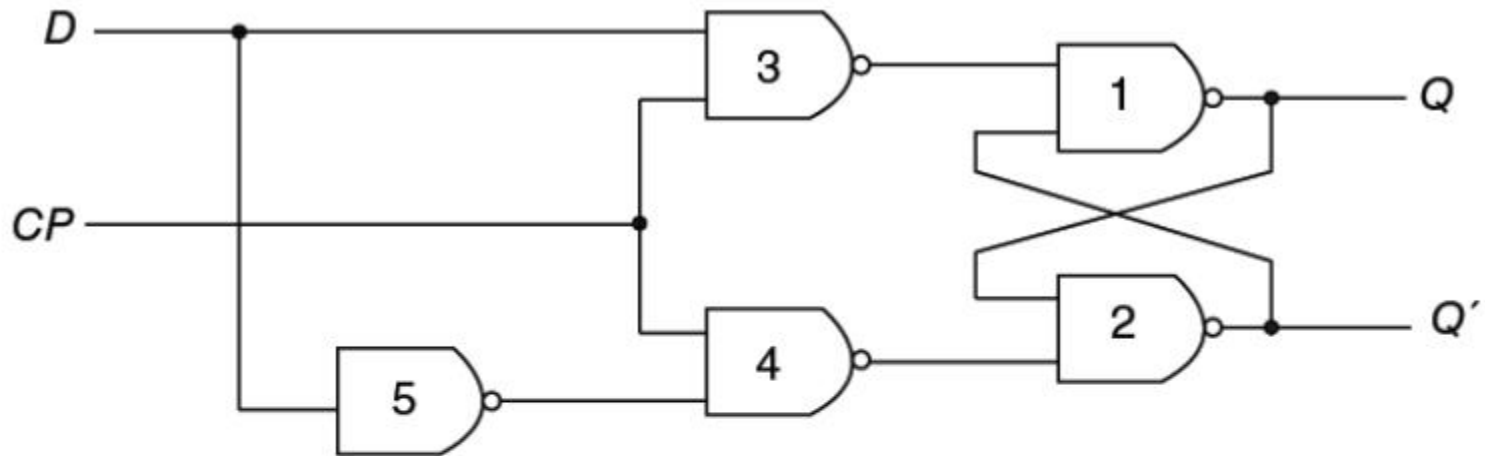




# Digital Logic Circuits



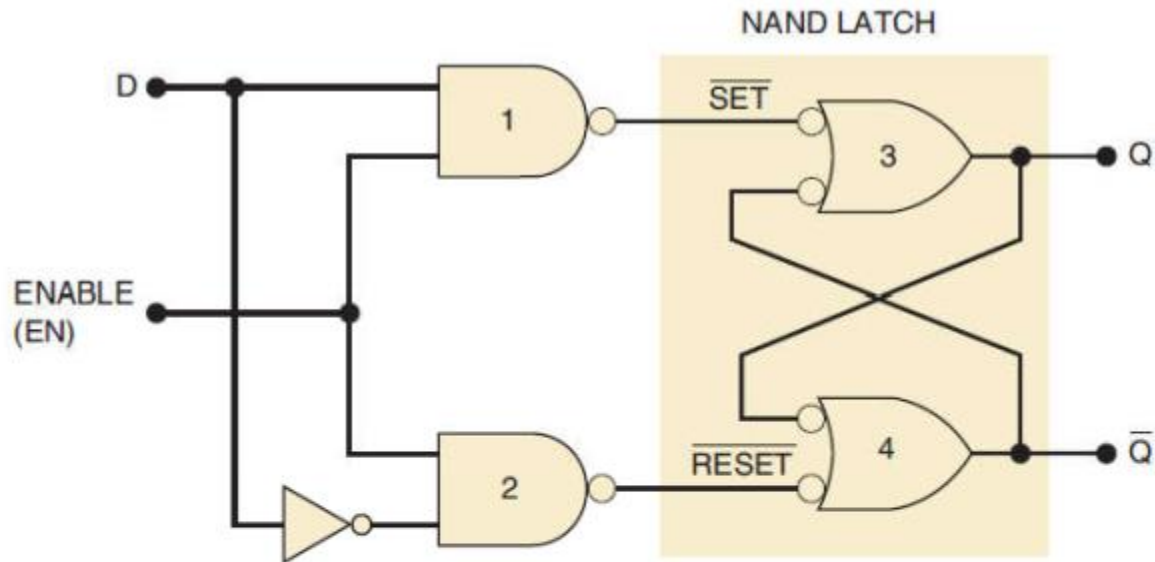
## D-Flip Flop



D	CLK	Q
0	↑	0
1	↑	1



# Digital Logic Circuits

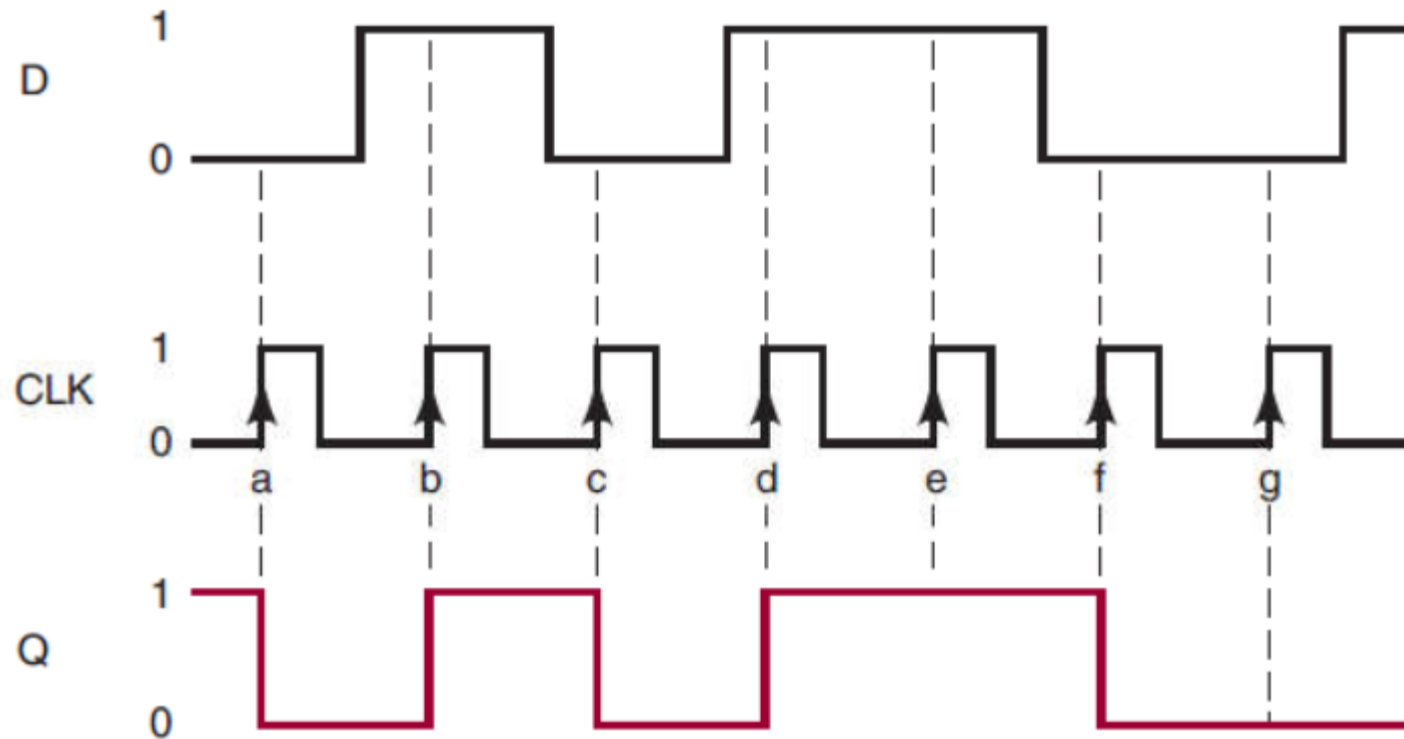


Inputs		Output
EN	D	Q
0	X	$Q_0$ (no change)
1	0	0
1	1	1

"X" indicates "don't care."  
 $Q_0$  is state Q just  
prior to EN going LOW.

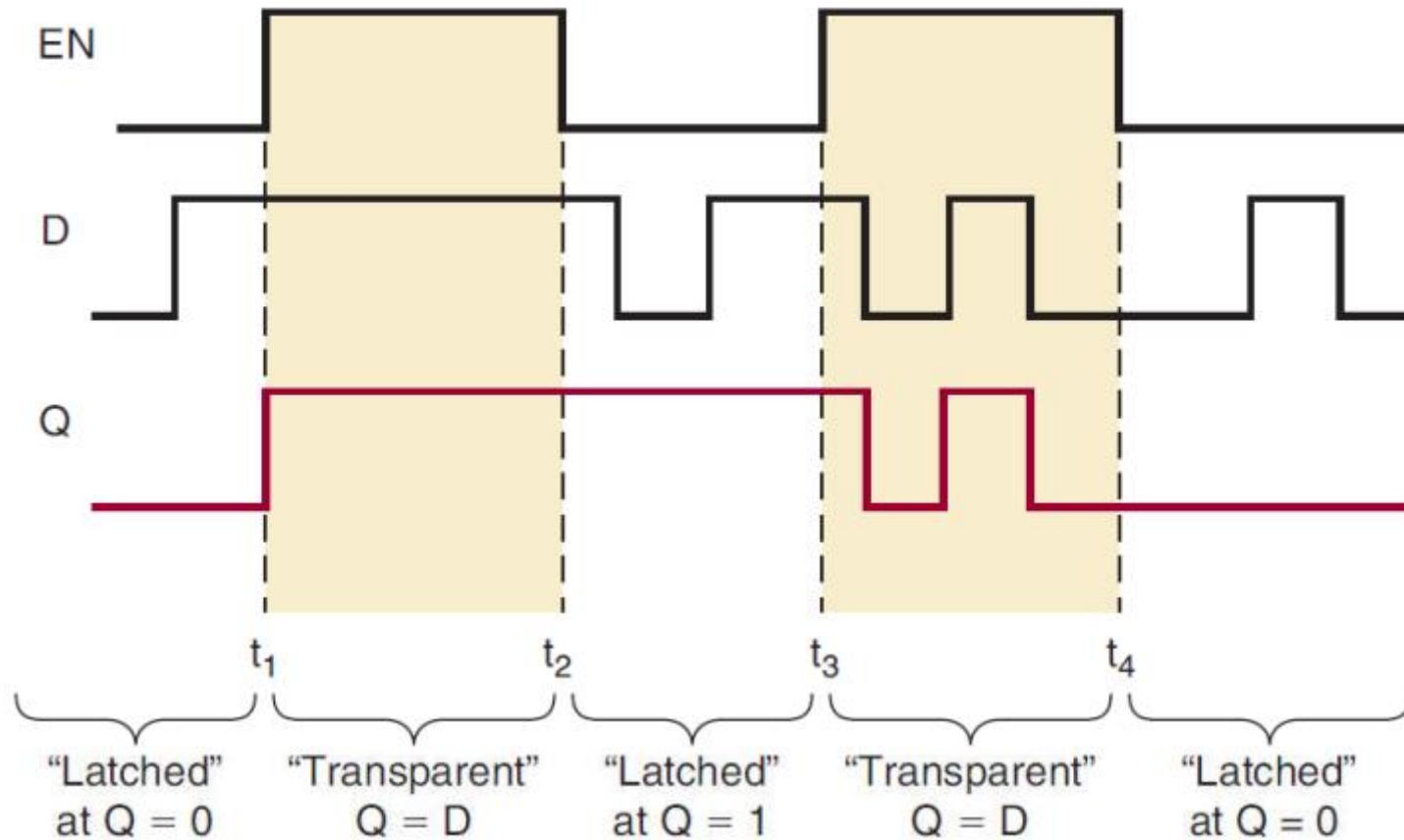


# Digital Logic Circuits





# Digital Logic Circuits



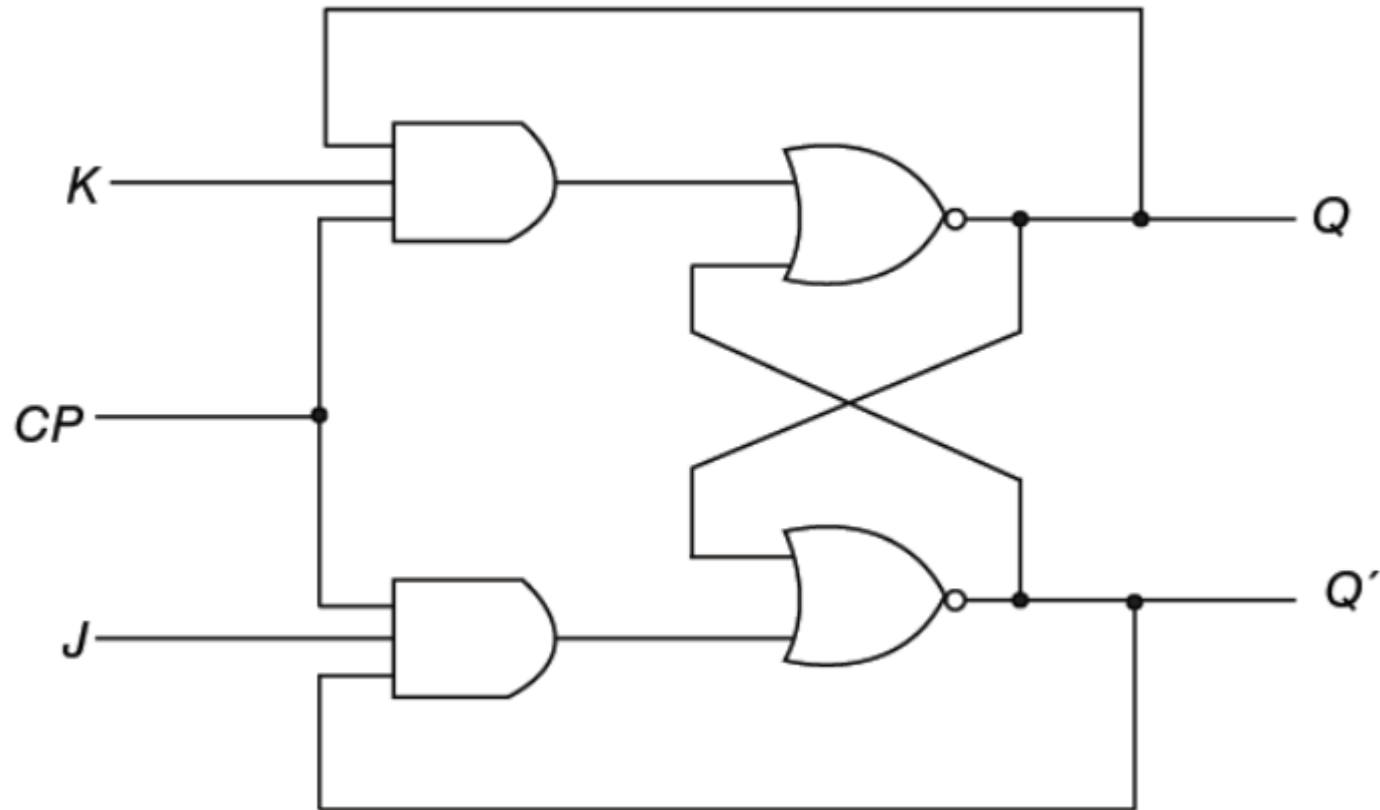




# Digital Logic Circuits

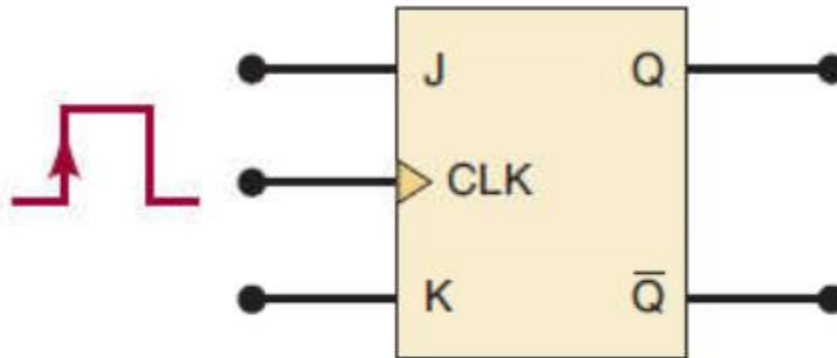


## Jack-Kibly (JK) Flip Flop





# Digital Logic Circuits



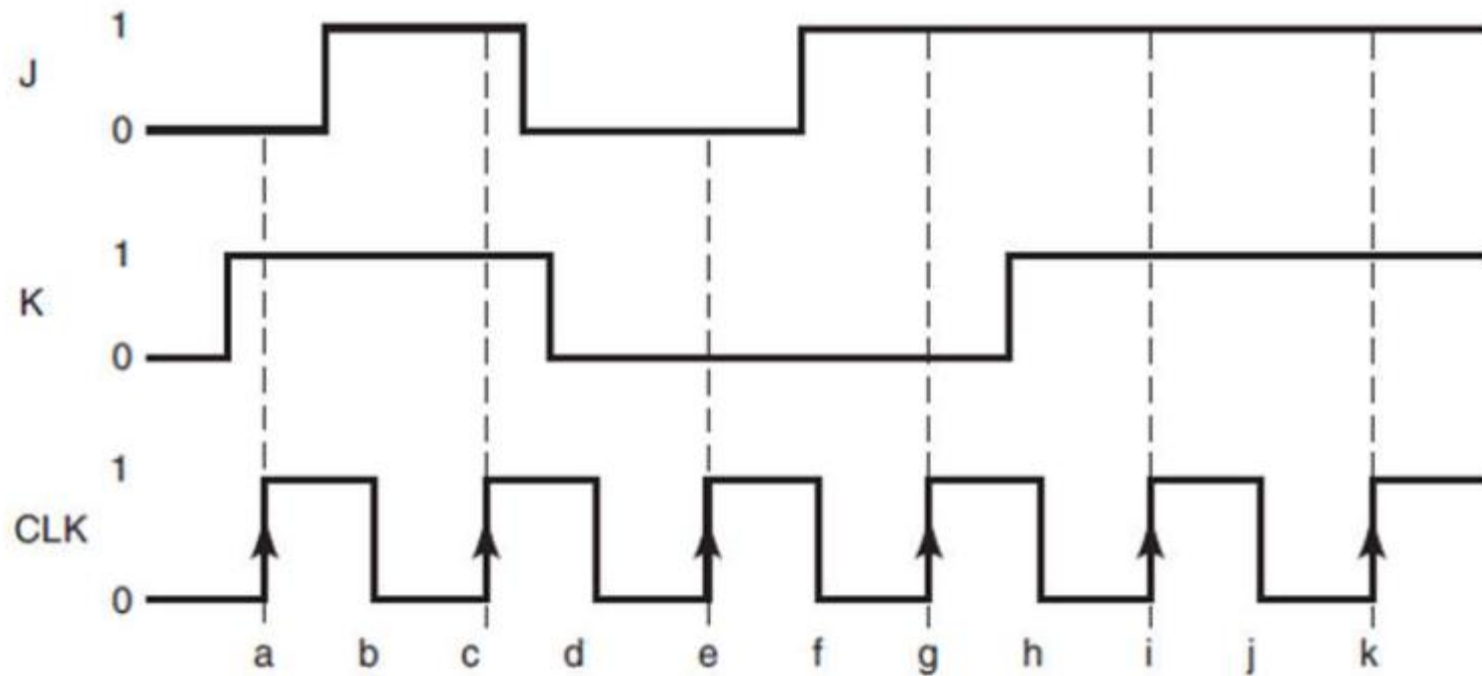
J	K	CLK	Q
0	0	↑	$Q_0$ (no change)
1	0	↑	1
0	1	↑	0
1	1	↑	$\overline{Q_0}$ (toggles)



# Digital Logic Circuits

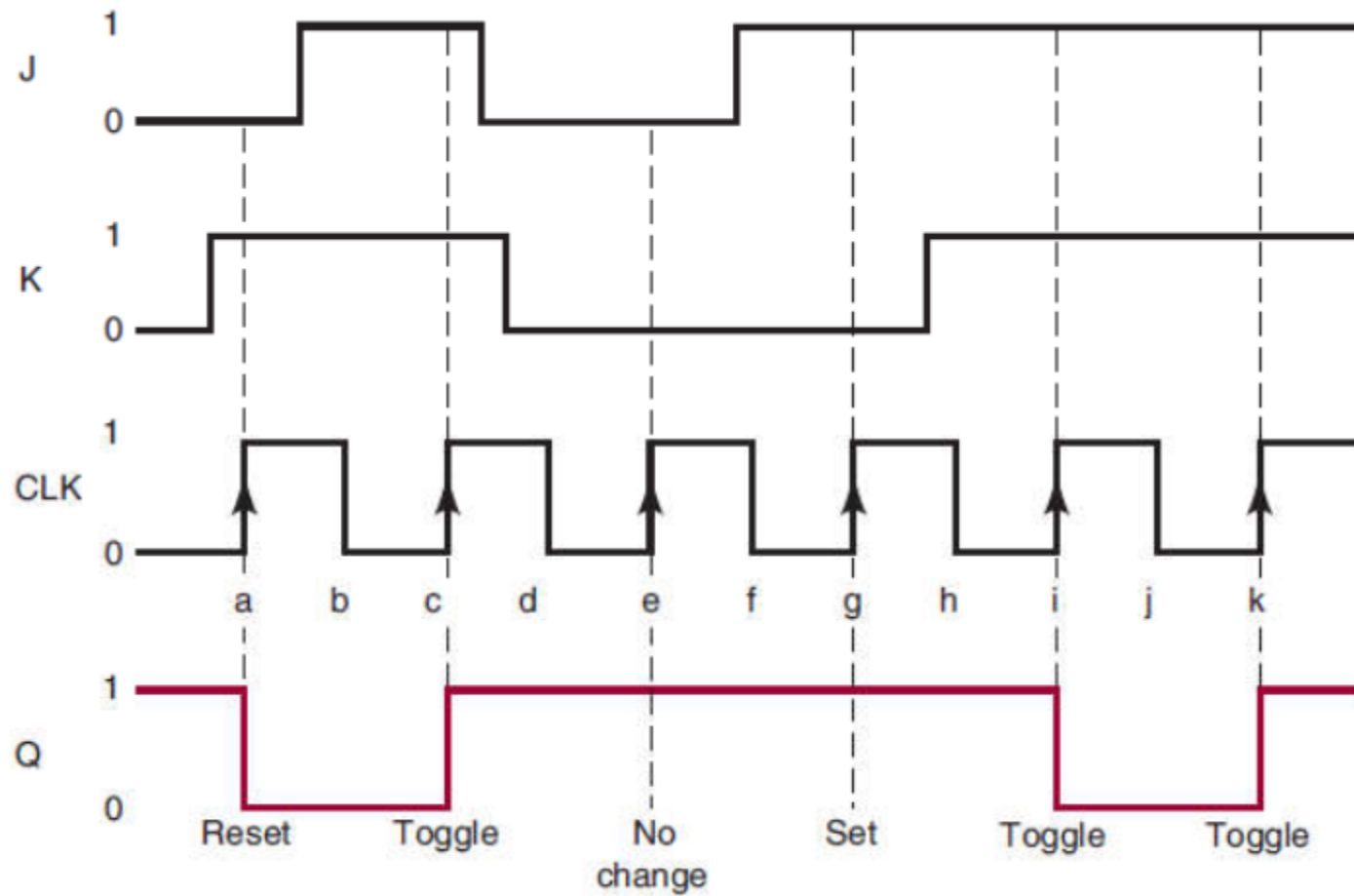


Assume  $Q=1$  initially



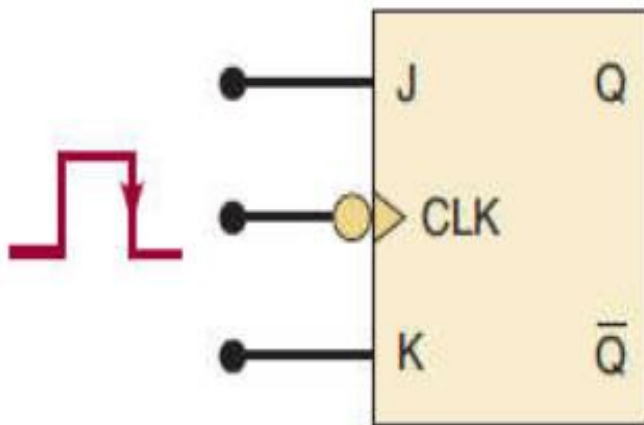


# Digital Logic Circuits





# Digital Logic Circuits



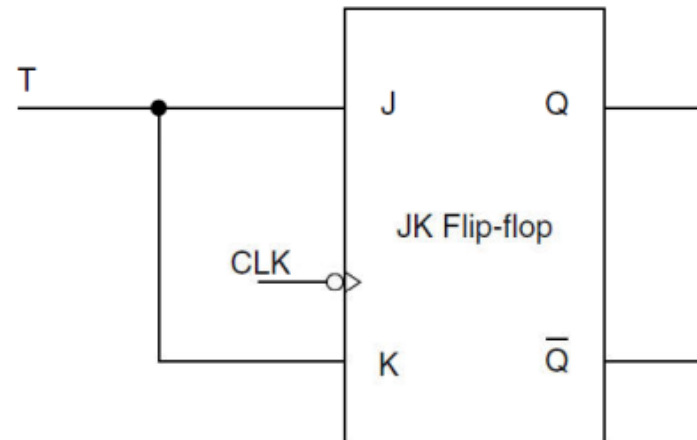
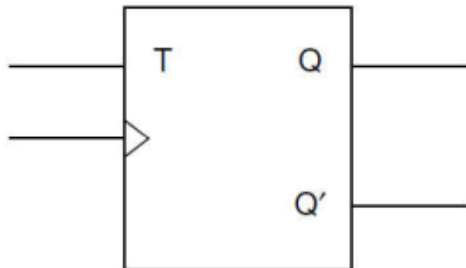
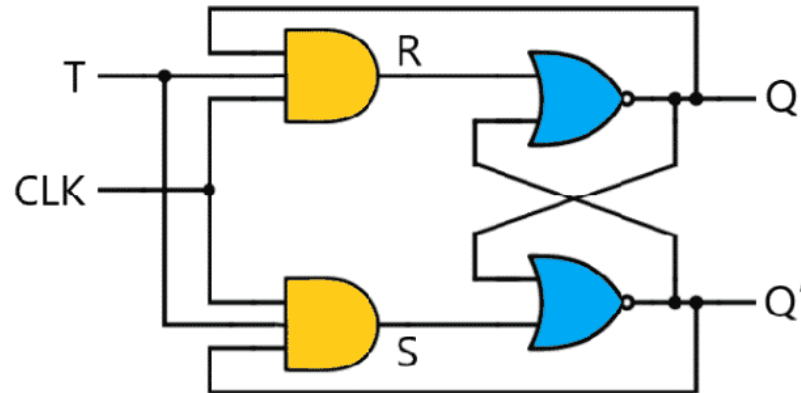
J	K	CLK	Q
0	0	↓	$Q_0$ (no change)
1	0	↓	1
0	1	↓	0
1	1	↓	$\overline{Q_0}$ (toggles)



# Digital Logic Circuits



## T Flip Flop

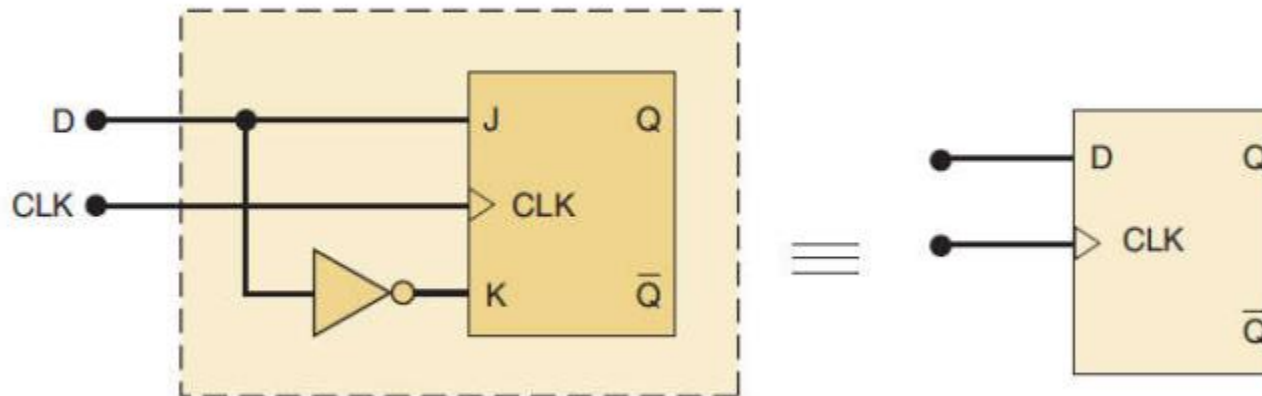




# Digital Logic Circuits



## D Flip Flop from JK Flip Flop

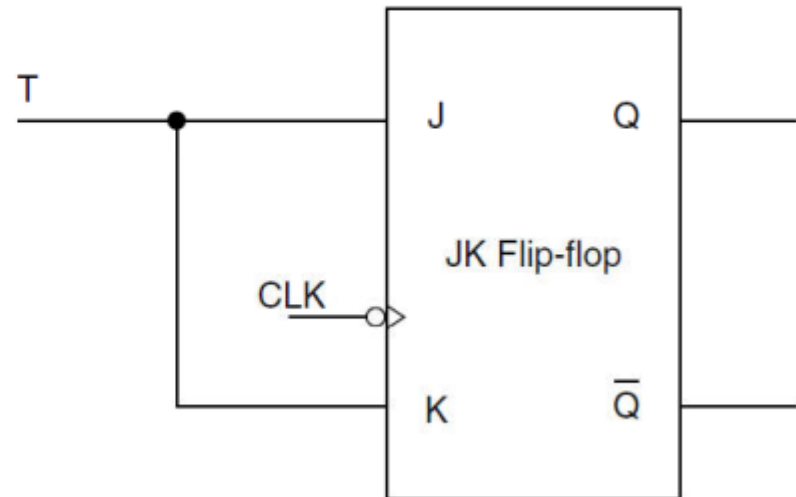
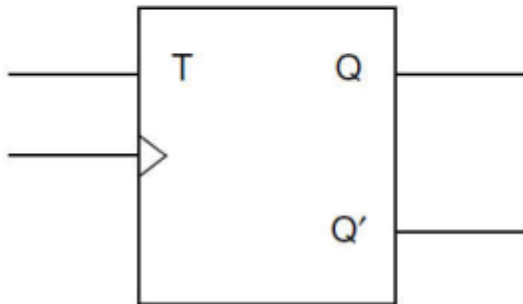




# Digital Logic Circuits



## T Flip Flop from JK Flip Flop





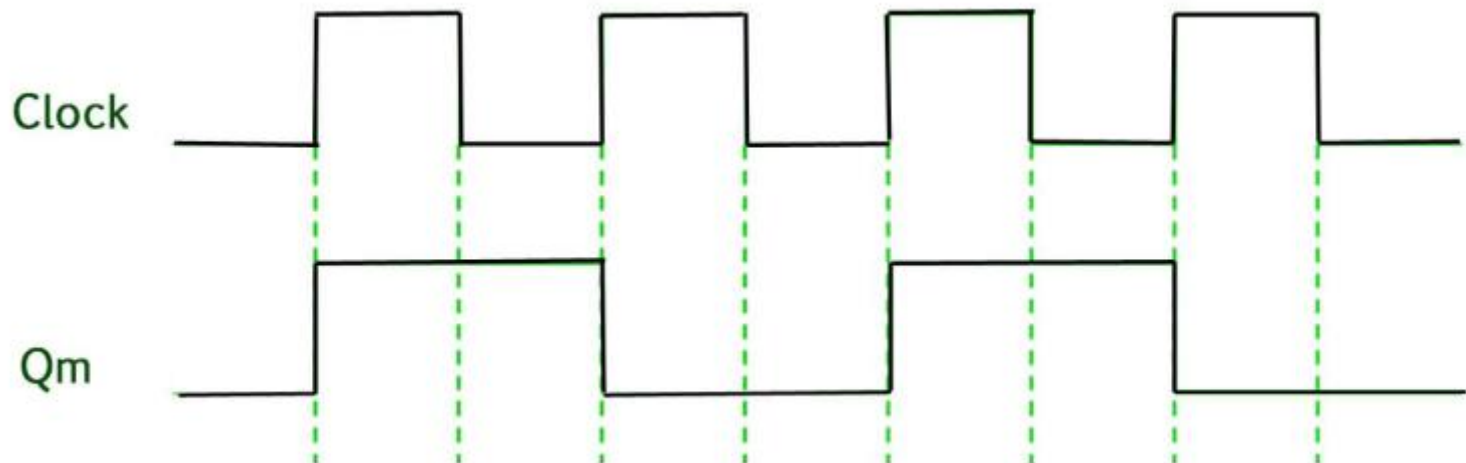


# Digital Logic Circuits



## Concept of Frequency Division

- ❑ Flip Flops can be used to divide input frequencies
- ❑ The frequency to be divided is applied as clock

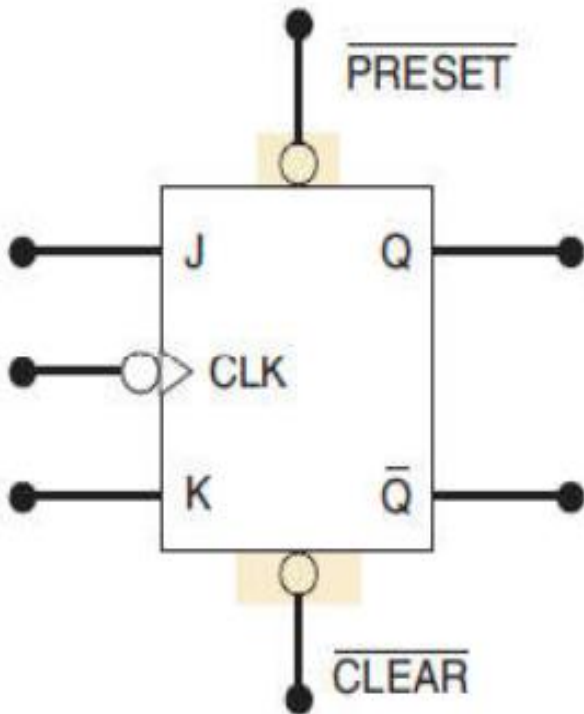




# Digital Logic Circuits



## Preset and Clear



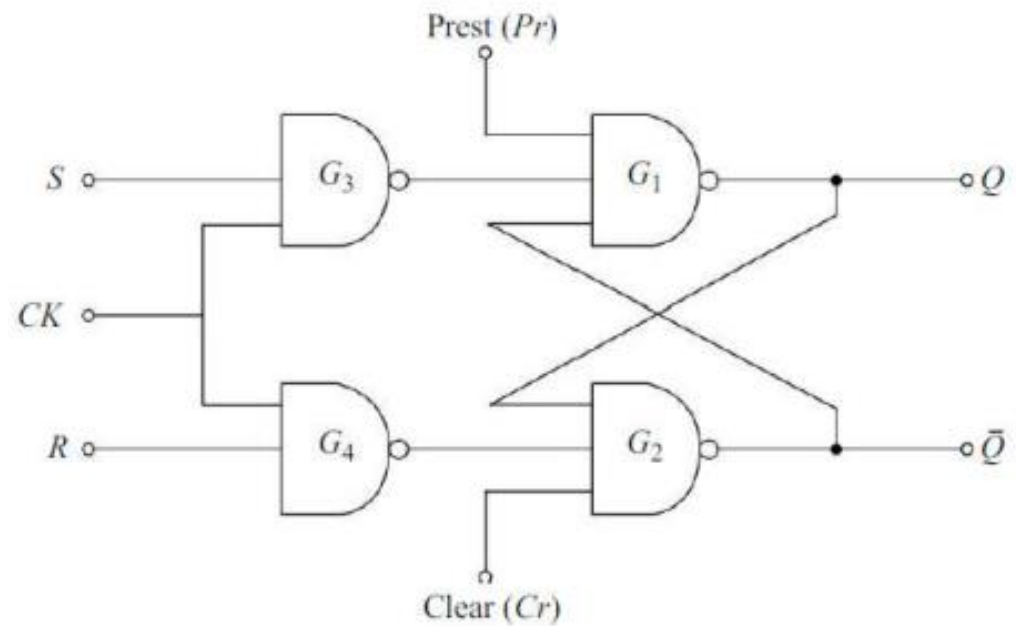
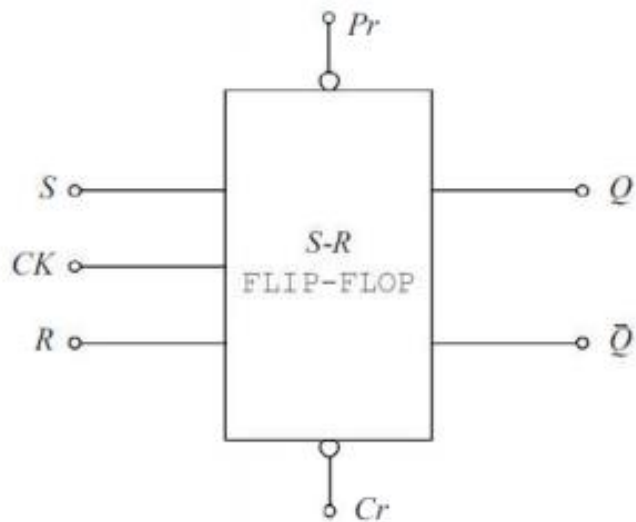
J	K	Clk	$\overline{\text{PRE}}$	$\overline{\text{CLR}}$	Q
0	0	↓	1	1	Q (no change)
0	1	↓	1	1	0 (Synch reset)
1	0	↓	1	1	1 (Synch set)
1	1	↓	1	1	$\overline{Q}$ (Synch toggle)
x	x	x	1	1	Q (no change)
x	x	x	1	0	0 (asynch clear)
x	x	x	0	1	1 (asynch preset)
x	x	x	0	0	(Invalid)



# Digital Logic Circuits



## SR Flip Flop

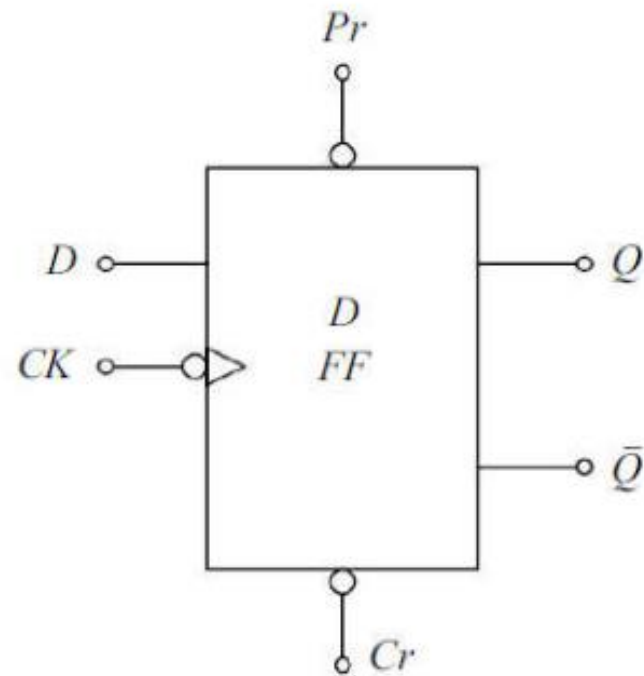
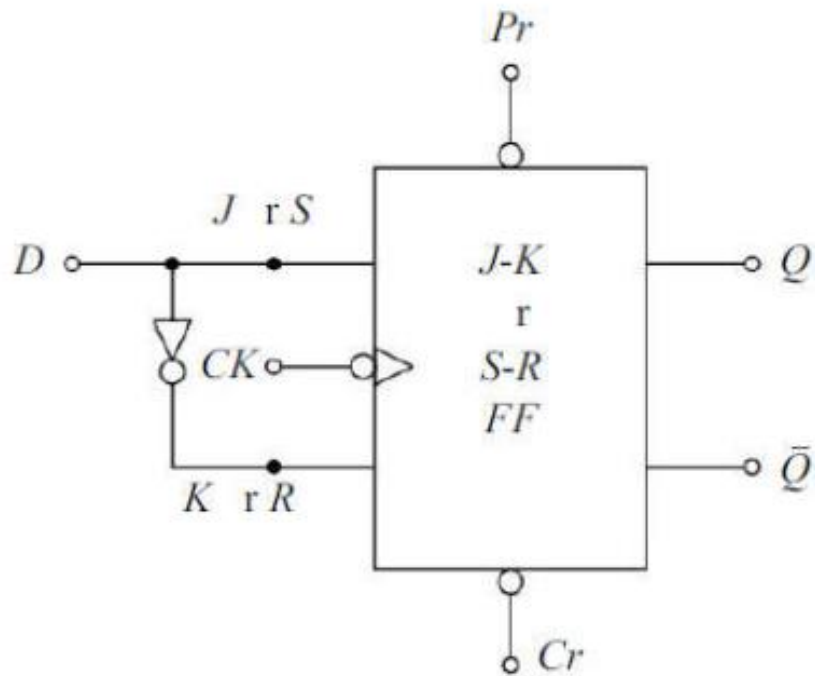




# Digital Logic Circuits



## D Flip Flop

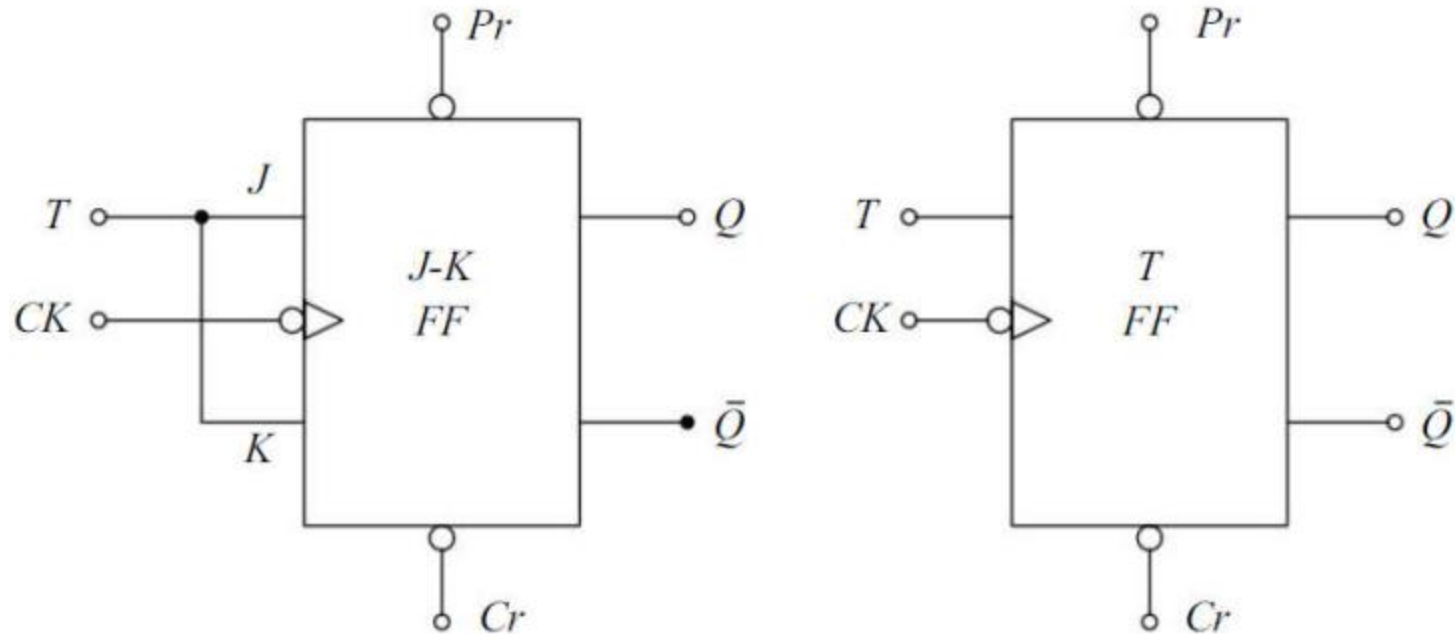




# Digital Logic Circuits



## T Flip Flop



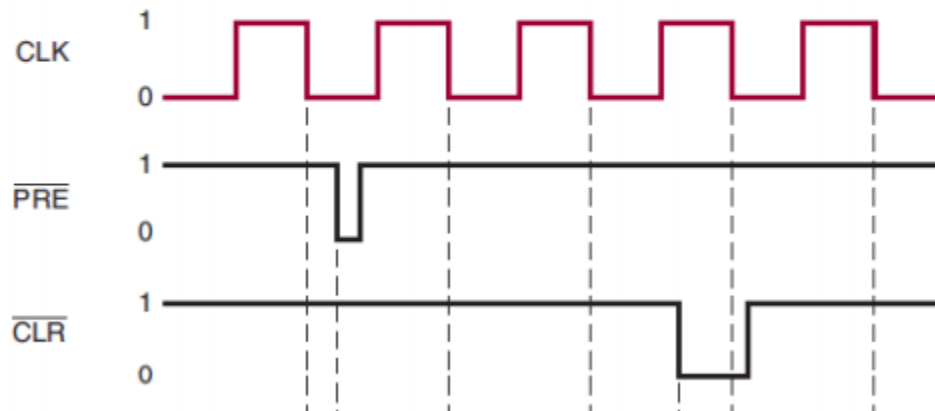
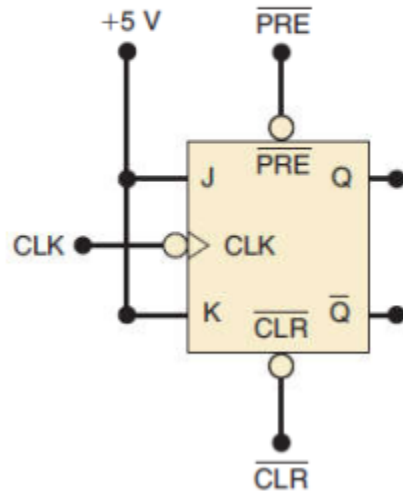


# Digital Logic Circuits



## T Flip Flop from JK Flip Flop

Assume  $Q=1$ , Initially

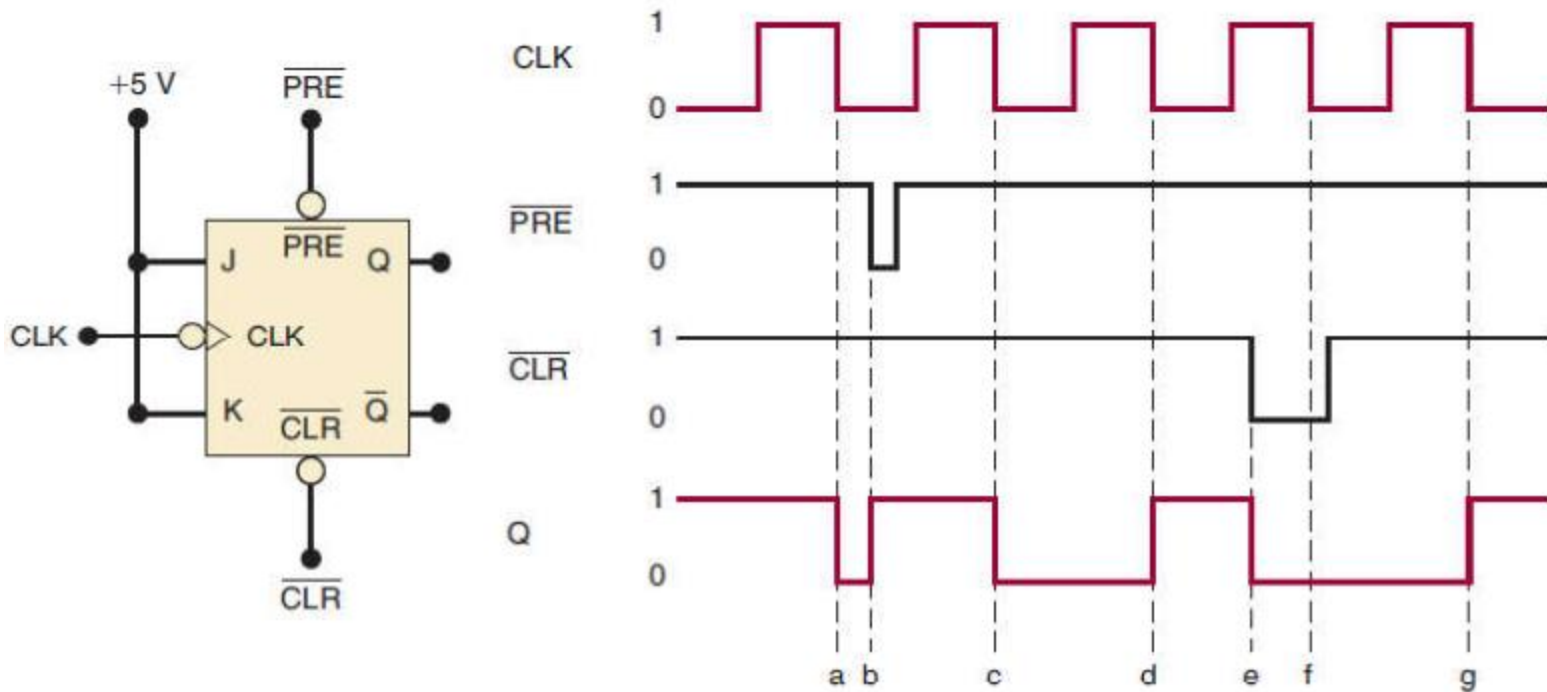




# Digital Logic Circuits



## Example

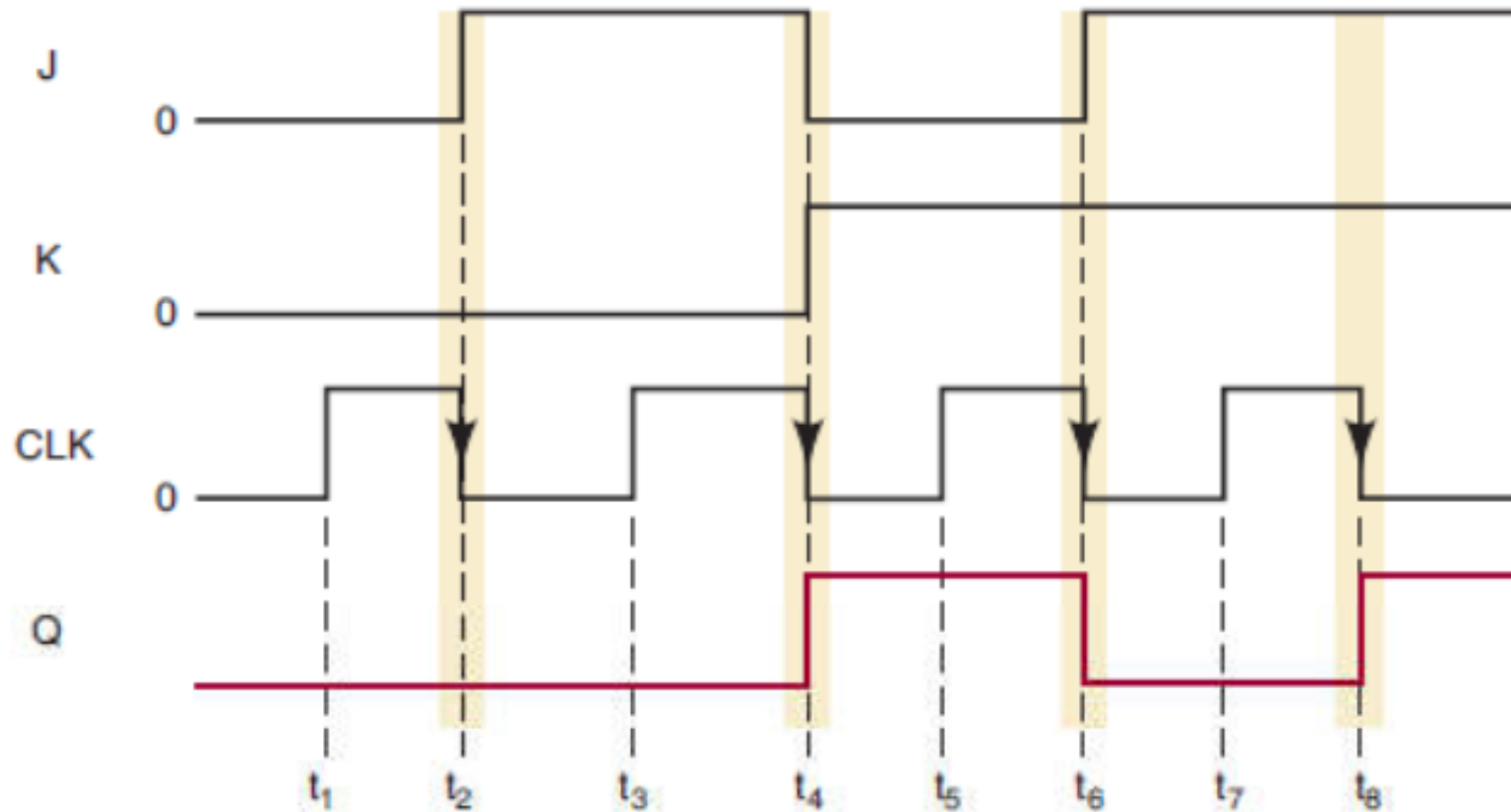




# Digital Logic Circuits



## Effect of Propagation Delays



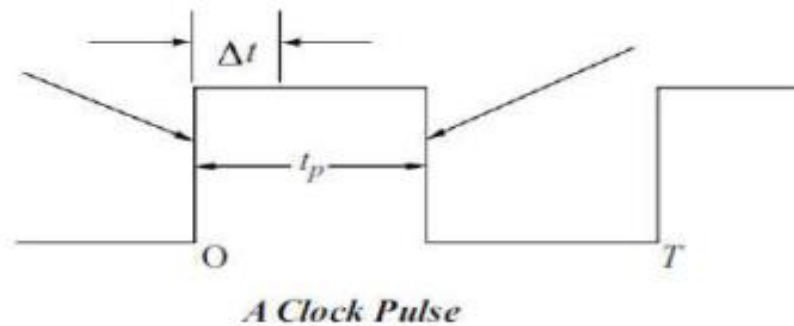
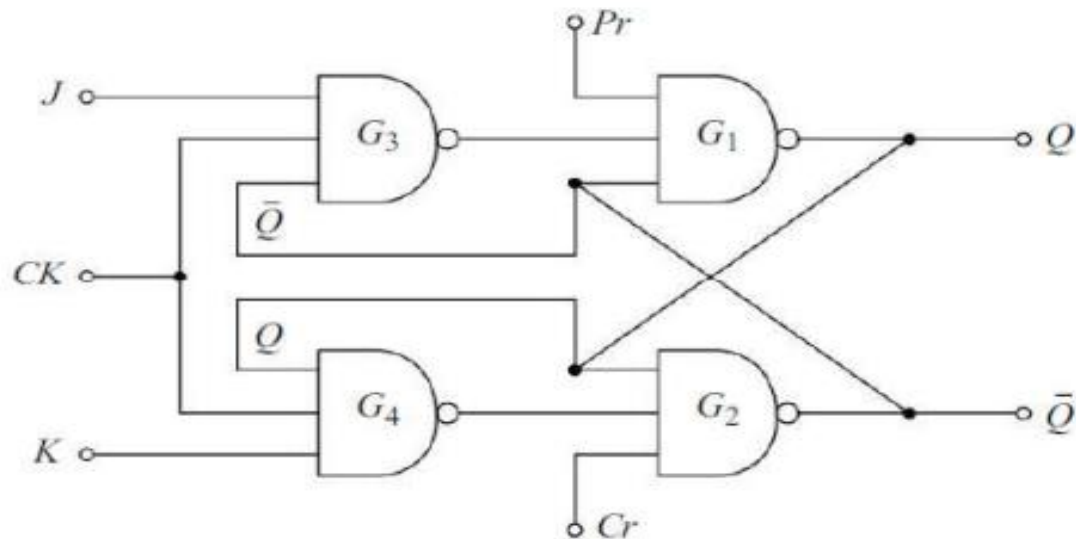




# Digital Logic Circuits



## Race Around Condition





# Digital Logic Circuits



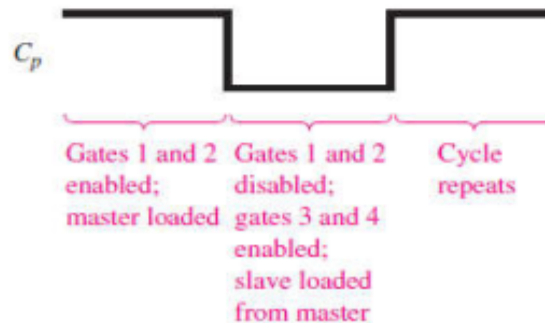
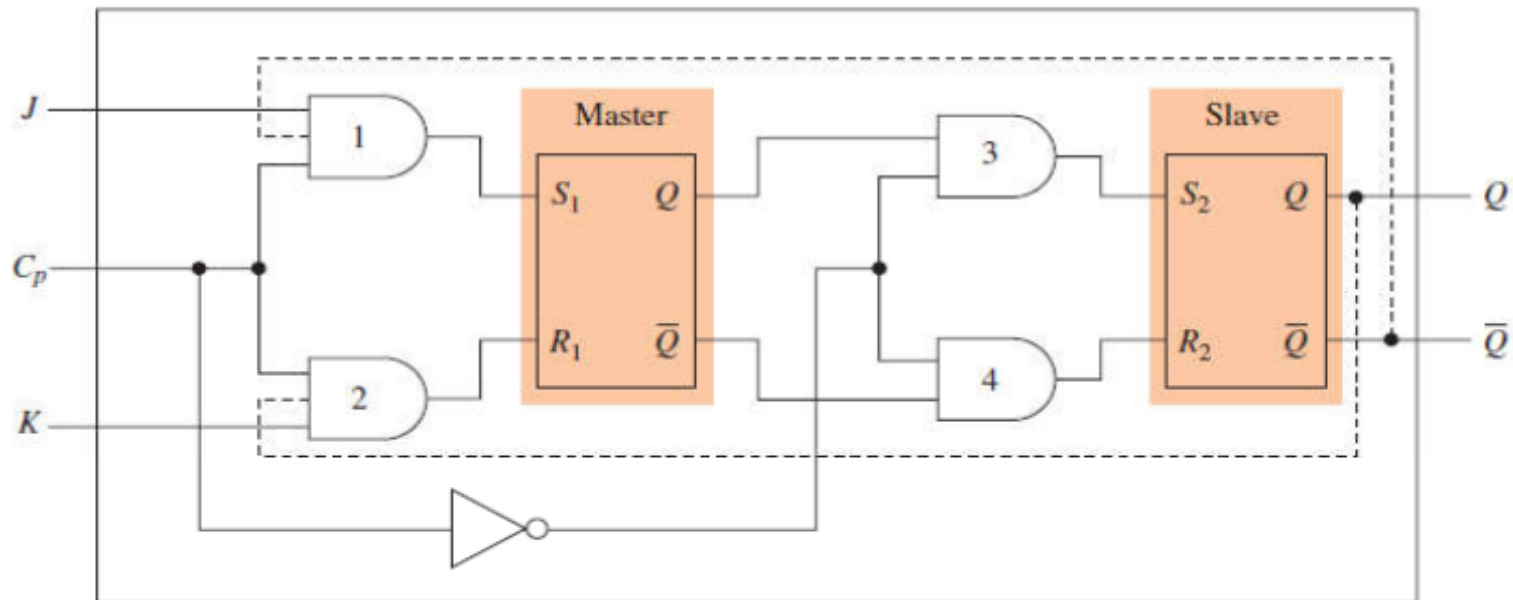
## Elimination of Race Around Condition

$$t_p < \Delta t < T$$

- ☐ Pulse width should be less than Propagation Delay
- ☐ Use of Master Slave Configuration

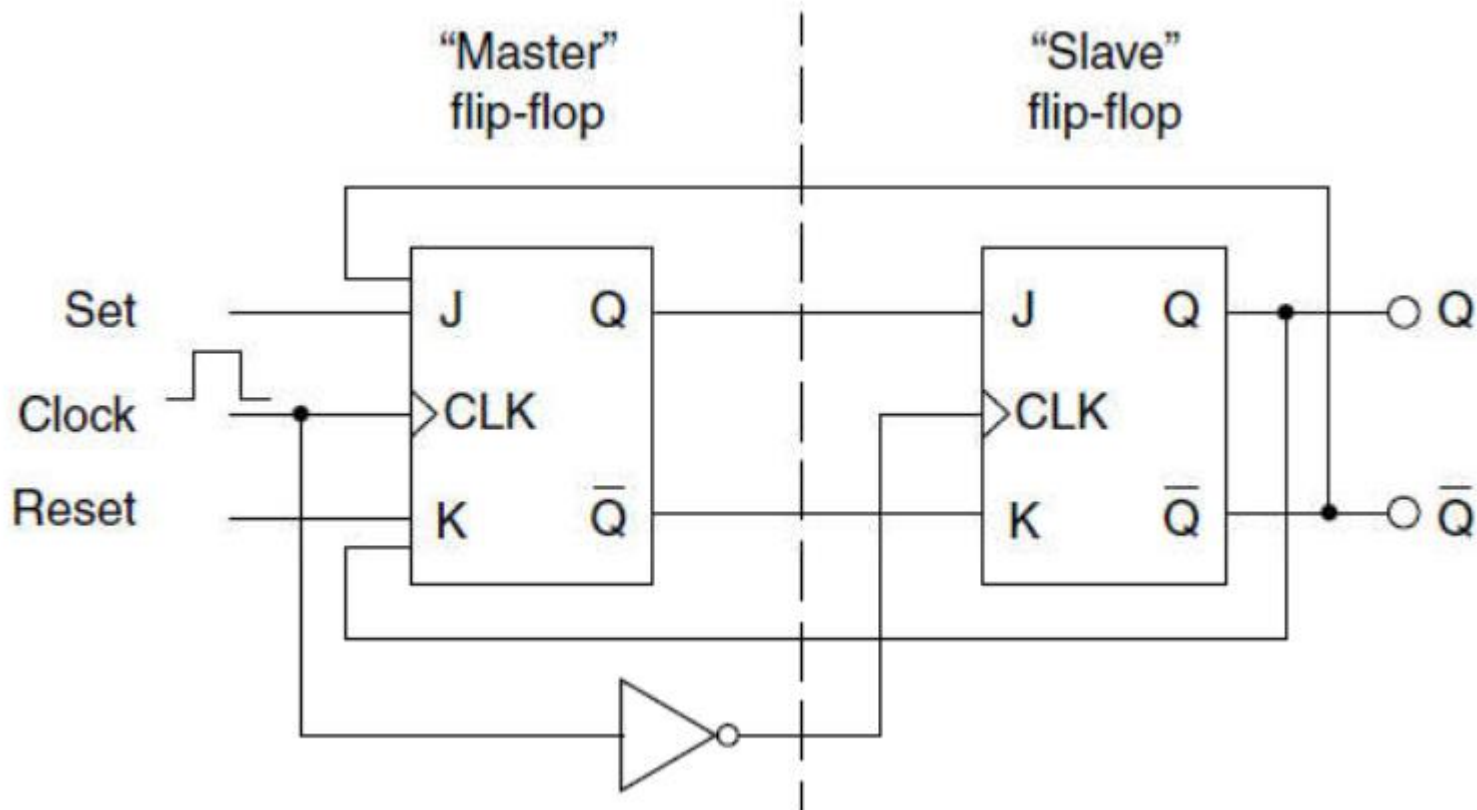


## Master Slave Arrangement





# Digital Logic Circuits

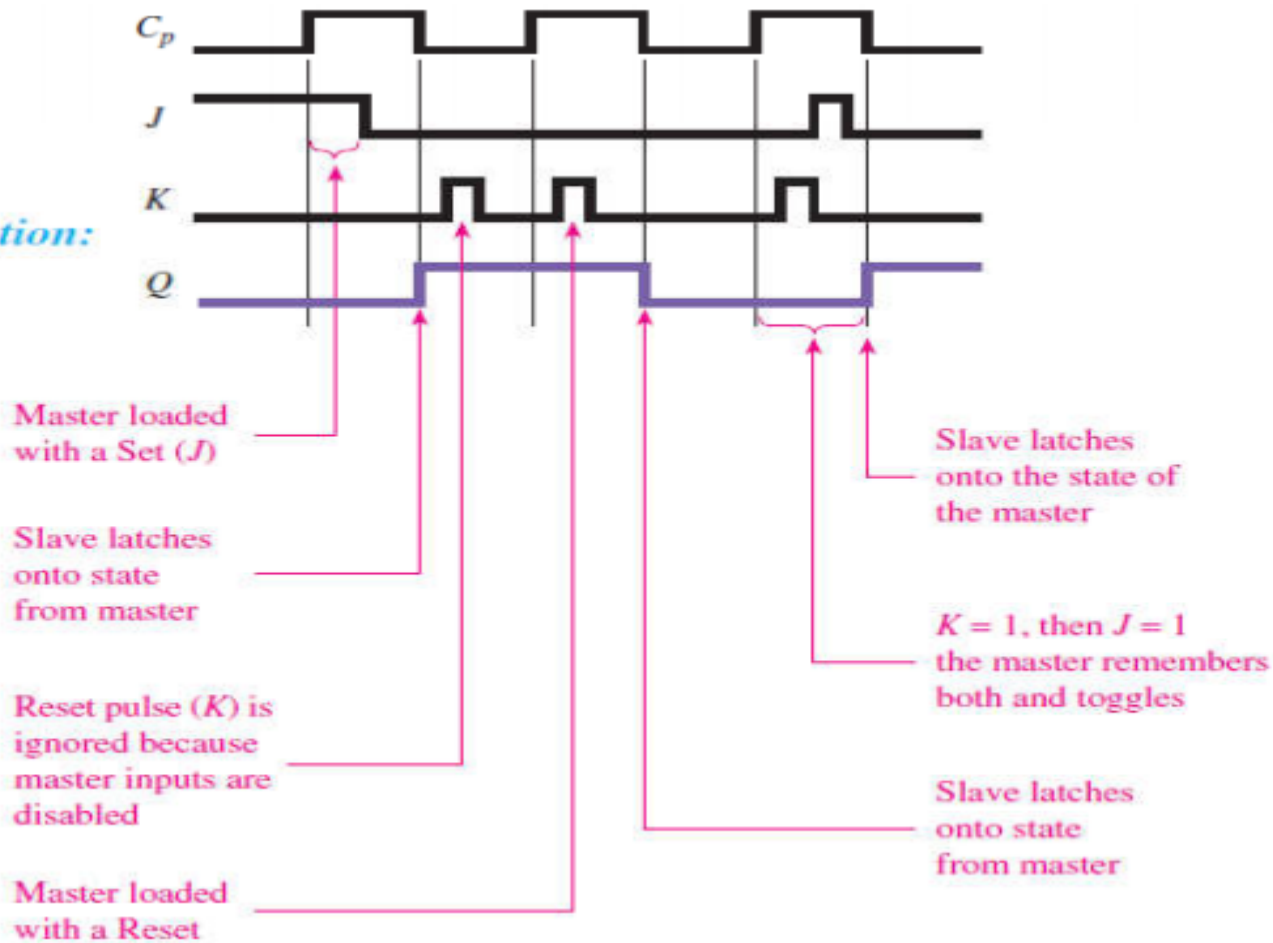




# Digital Logic Circuits



*Solution:*





# Digital Logic Circuits



## Excitation Tables

S	R	Present state $Q_n$	Next state $Q_{n+1}$
0	0	0	0
0	0	1	1
0	1	0	0
0	1	1	0
1	0	0	1
1	0	1	1
1	1	0	X
1	1	1	X

*Truth table of SR flip flop*

} Invalid states

$Q_n$	$Q_{n+1}$	S	R
0	0	0	X
0	1	1	0
1	0	0	1
1	1	X	0

*Excitation table of SR flip flop*

D	Present state $Q_n$	Next state $Q_{n+1}$
0	0	0
0	1	0
1	0	1
1	1	1

*Truth table of D flip flop*

$Q_n$	$Q_{n+1}$	D
0	0	0
0	1	1
1	0	0
1	1	1

*Excitation table of D flip flop*



# Digital Logic Circuits



J	K	Present state $Q_n$	Next state $Q_{n+1}$
0	0	0	0
0	0	1	1
0	1	0	0
0	1	1	0
1	0	0	1
1	0	1	1
1	1	0	1
1	1	1	0

*Truth table of JK flip flop*

$Q_n$	$Q_{n+1}$	J	K
0	0	0	X
0	1	1	X
1	0	X	1
1	1	X	0

*Excitation table of JK flip flop*

T	Present state $Q_n$	Next state $Q_{n+1}$
0	0	0
0	1	1
1	0	1
1	1	0

*Truth table of T flip flop*

$Q_n$	$Q_{n+1}$	T
0	0	0
0	1	1
1	0	1
1	1	0

*Excitation table of T flip flop*



# Digital Logic Circuits



Present State	Next State	<i>S-R</i>	<i>FF</i>	<i>J-K</i>	<i>FF</i>	<i>T-FF</i>	<i>D-FF</i>
		$S_n$	$R_n$	$J_n$	$K_n$		
0	0	0	×	0	×	0	0
0	1	1	0	1	×	1	1
1	0	0	1	×	1	1	0
1	1	×	0	×	0	0	1





# Digital Logic Circuits



## Steps for converting one flip-flop to the other:

- Consider the **characteristic table** of desired flip-flop.
- Fill the excitation values inputs of given flip-flop for each combination of present state and next state.
- Get the simplified expressions for each excitation input. If necessary, use K-maps for simplifying.
- Draw the circuit diagram of desired flip-flop according to the simplified expressions using given flip-flop and necessary logic gates.



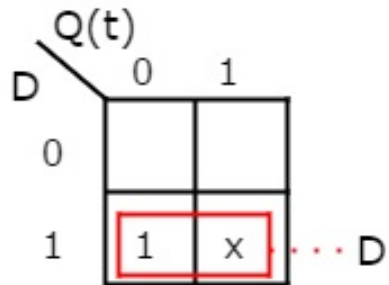
# Digital Logic Circuits



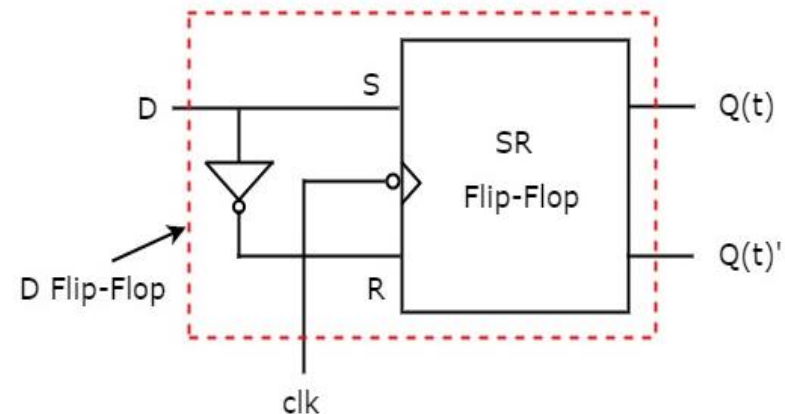
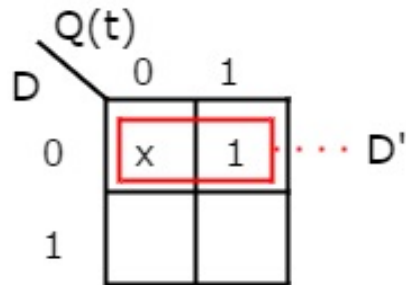
## SR flip-flop to D flip-flop conversion

D flip-flop input	Present State	Next State	SR flip-flop inputs	
D	$Q_t$	$Q_{t+1}$	S	R
0	0	0	0	x
0	1	0	0	1
1	0	1	1	0
1	1	1	x	0

K-Map for S



K-Map for R



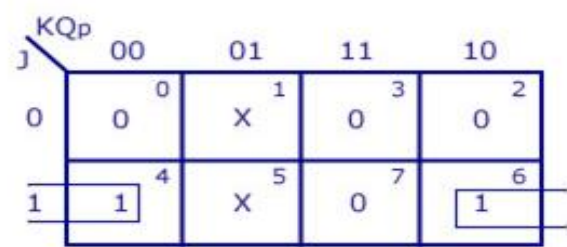
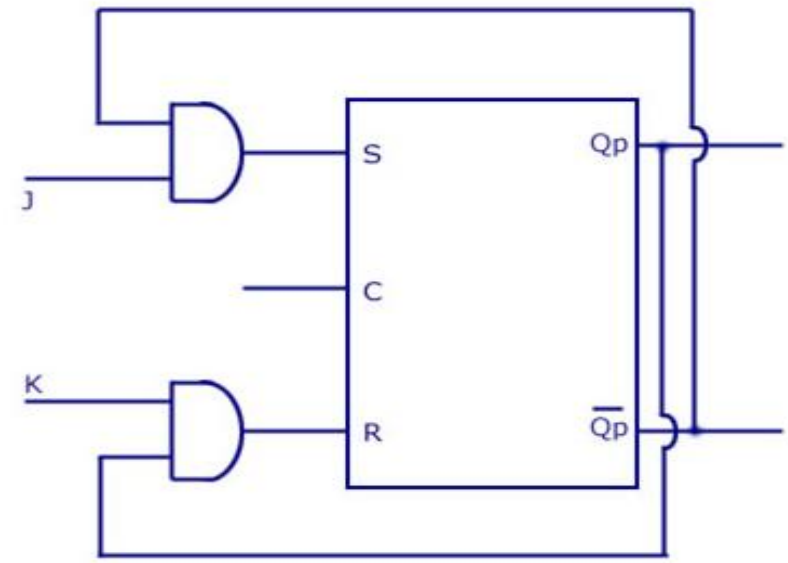


# SR to JK flip-flop

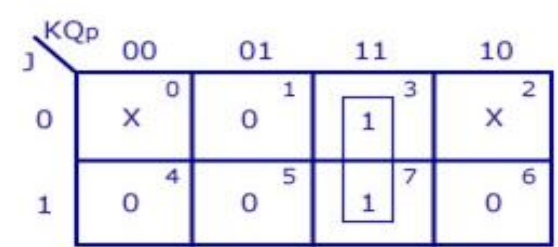
Conversion Table

J-K Inputs		Outputs		S-R Inputs	
J	K	Qp	Qp+1	S	R
0	0	0	0	0	X
0	0	1	1	X	0
0	1	0	0	0	X
0	1	1	0	0	1
1	0	0	1	1	0
1	0	1	1	X	0
1	1	0	1	1	0
1	1	1	0	0	1

Logic Diagram



$S = \bar{J}Q_p$



$R = KQ_p$

K-Map



- JK to SR flip-flop
- JK to D FF
- JK to T FF
- SR to D FF
- SR to T FF
- SR to JK
- D to SR FF
- D to JK FF
- D to T FF
- T to SR FF
- T to JK FF
- T to D FF