

# Slicing Java Programs

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**Abstract**—The software industry is growing very rapidly and the programs written by the developers are quite large having thousands and lacs of lines and hence to analyze the impact of a line of a code and debugging it, in such a large program would be a very tedious task. However, the tedious task can become easier if instead of thousands of lines, consisting of some lines that is of no use in reference to the variable we are analysing. Program Slicing is defined as retrieving statements as a slice of program that may potentially affect the value of the variable that is of interest at a particular time in a program. This project aims at developing a Java dynamic slicer which would support various functionalities of Java language.

## I. INTRODUCTION

As mentioned above, program slicing is retrieving instructions that affect a variable of interest at a particular time in the program. There are two types of slicing, the first being static and the other being dynamic. Static slicing does not take user input into consideration while dynamic slicing considers user input in order to compute a program slice. Also, the slicing methods can be implemented by maintaining some kind of dependency graph or by using certain graph-less techniques. We have focused on the graph-based algorithms for dynamic slicing in this project.

Slicing a program is defined in terms of a slicing criterion which includes the following things:

- The variable of interest
- The line number in the program
- User input for the variables in the program

Dynamic slicing is more helpful in debugging a variable than static slicing as static slicing includes all the instructions that might not be executed for a particular user input while the dynamic slices only contains executed instructions. Due to this reason, implementing dynamic slicing is a more tedious job and requires additional efforts since apart from the dependencies, one needs to also find the statements that have been executed for a user input.

As Java is one of the primary languages used in the software industry, we chose to implement a dynamic slicer which works for Java programs.

## II. RELATED WORK

The section describes the research papers that we reviewed which gave us the idea of what program slicing is and different types of algorithms that can be implemented for dynamic slicing a program.

Frank Tip in his research paper [2] explained about different types of dependencies that needs to be considered while creating a dependency graph. The research paper also discusses the applications of program slicing.

Hiralal and Joseph in their research paper [1] explained the idea of dynamic slicing by explaining the idea of PDG and static slicing and proposed different possible implementations of dynamic slicing. The research paper also evaluates the output slices computed via different algorithms and describes the advantages and disadvantages of a particular algorithm.

Matthew Bridges in his research paper [3] explained different kind of dependency graphs and also described slicing algorithms for parallel programs. The research paper also presented a graph based technique to handle the functional calls present in a program.

## III. BASIC CONSTRUCTS

### A. Basic Block

A basic block in a program is some set of consecutive statements such that there are no multiple entry or exit points. Conditional statements like if-else and loops in standard programming languages can not be a part of basic block since they have multiple exit points. Basic block can consist of a single instruction or may have multiple instructions. For the algorithm, we have considered basic blocks to have only one instruction.

### B. Control Flow Graph

A control flow graph is useful for showing the direction of flow of the program. It is a directed graph whose vertexes are basic blocks and the edges represent control flow between the vertex. The control flow edge represents that there exists at-least one execution path from x to y.

### C. Program Dependence Graph

Program dependence graph(PDG) is a directed graph with nodes as statements and edges as data dependencies and control dependencies.

### D. System Dependence Graph

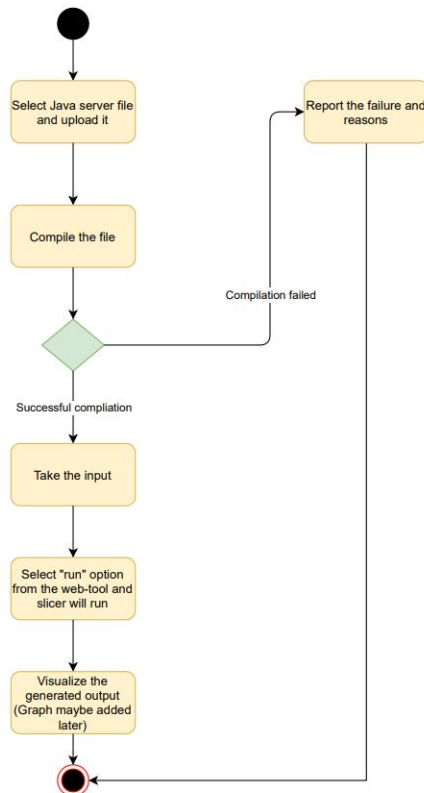
System Dependence Graph are different PDGs for different procedures connected with the help of edges and nodes at calling location.

## IV. UML DIAGRAMS

### A. User Stories

- As a user, I want a tool to slice a java code so that I can debug a particular variable
- As a user, I want a dynamic slicer, so that I can find dependencies of a particular variable
- As a user, I want to see a dependency graph, so that I can visualize the slice in a better way
- As a user, I want a tool in which I can upload the Java program, so that i
- As a user, I want a tool in which I can see the code after uploading, so that I can ensure that I have uploaded correct file

### B. Activity Diagram



The above figure shows the Activity Diagram representation of the dynamic slicer tool.

## V. LOGIC AND IMPLEMENTATION

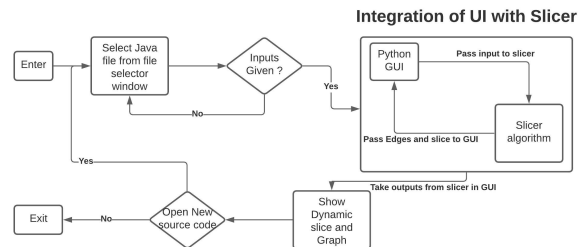
We can think of this problem as (i) Constructing a dependency graph (ii) Using a graph reachability algorithm on the dependency graph to compute the dynamic slice. Thus, first of all, we need to implement a code parser, then find out the line numbers of the instructions that will actually be executed depending upon the user inputs. Once the dependency graph has been created, the second part is relatively easier to implement.

### A. Code Parser

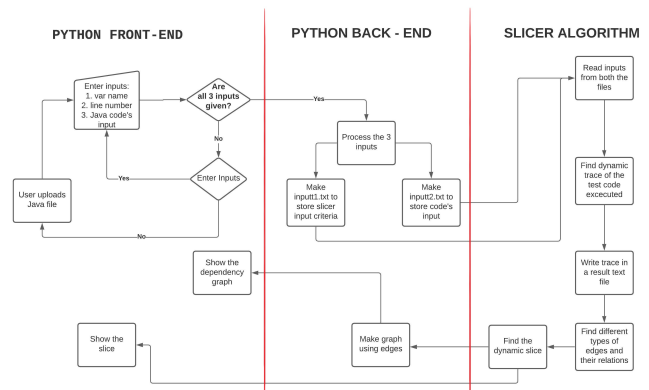
The most important part of slicers is to implement a code parser that can parse the Java keywords. Now, the role of the parser is to execute source code line-wise and since we want a dynamic slicer, while parsing the code we need to store the line numbers of the instructions or the instructions that have been executed after user inputs the variables. Also, Java being a quite wide-spread language, we decided the keywords which we want our slicer to handle. The list of keywords and functionalities that the slicer can successfully handle are as below:

- For loop
- While loop
- If else
- Try catch block
- Return statements
- Data Types (int, float, double, string, void, long)
- Scanner class
- Methods : Public static methods (void and int)
- Threading : Basic methods (object.start(), run method, thread.getid())
- API calls
- Function calls
- URL Connection
- Connection Request Method
- Iterators
- Comments
- Arithmetic operations
- String operations
- Assignment operations

### B. Schematic diagram



### C. Block diagram



#### D. Logic

The main logic of implementation starts when user uploads Java source code and the algorithm takes the source code and modifies the source code which will be needed to trace back the lines which will be executed in terms of dynamic slicing. After this process is done the algorithm executes the updated source code only if system supports the Java i.e. Java compiler is a prerequisite else the algorithm stops. Since in order to calculate the dynamic slice, there is a need that algorithm should first go through the whole source code and so the next step is to parse source code starting from first line. Moreover, Since this is an algorithm of Dynamic slicing, there is a need of system input to the source code because depending upon the system inputs some instructions of code may or may not get executed. Like, if there are conditional statements in the code, then either if or else if part of the program will get executed. So on the basis of system inputs and instructions the algorithm will create different vertexes and different kinds of edges between dependent vertexes based upon the relations between them. When the parsing of code till slicing line number is completed then the next step of algorithm is to create a SDG, so that algorithm can start slicing on this graph.

The user needs to input 3 things in order to execute a slicer:

- Source code of Java program
- Slicing criterion
- User inputs to the variables

When the algorithm is parsing the code, it will only parse the code till the slicing criteria mentioned in the input. While parsing the code, the algorithm stores different kind of dependencies between the statements. The algorithm generates SDG which has:

- Nodes: Instructions in the source code. Remember, for the simplicity of the algorithm, we kept only one instruction per basic block
- Edges: Different types of dependencies between the nodes

Some additional nodes need to be created in order to handle functional calls. These nodes are based on the way function or method is declared and called. The four additional types of nodes required for handling functional calls are as below:

- 1) Actual in-nodes: for all function arguments
- 2) Actual out-nodes : for the function arguments (passed by reference)
- 3) Formal in-nodes : at called procedure node for all function parameter
- 4) Formal out-nodes : for the function parameters passed by reference

To understand slicing of functional calls in a better way, consider the below example:

```
Function definition:
int sum(int x,int y)
{
    int k=x+y;
    return k;
}
```

```
Function call:
int z=sum(a,b);
```

The different types of nodes created are as follows:

- Actual out nodes:  $a=x_{out}$ ,  $b=y_{out}$
- Formal out nodes:  $x_{out}=x$ ,  $y_{out}=y$
- Actual in nodes:  $a_{in}=a$ ,  $b_{in}=b$
- Formal in nodes:  $x=a_{in}$ ,  $y=b_{in}$

The different type of dependency edges required to capture all the dependencies are as follows:

- 1) Control Dependence Edge : Edge from node A to node B states that execution of node B is controlled by node A
- 2) Data Dependence Edge : Edge from node A to node B with respect to some variable  $v$  states that value of  $v$  in node B is transmitted by node A
- 3) Parameter-in Edge : Edge between actual-in and formal-in nodes, representing the functional call
- 4) Parameter-out Edge : Edge between actual-out and formal-out nodes, representing the functional call
- 5) Transitive Dependence : This edge links between actual-out and actual-in nodes
- 6) Affect-return Edge : This edge is created between the call node X present in call site which is expecting a return value and the actual-in node
- 7) Call Edge : A call edge is to a caller X from a call site node Y

The algorithm tries to approach this slicing problem in two passes. However, in terms of computer vocabulary we can classify this algorithm under the topic of reachability of graphs. This approach can be viewed as modified version of DFS. During the first phase of the traversal, the slicing algorithm just as in DFS visits and then marks different nodes that are directly or indirectly or transitively connected to the node N of the slicing criteria as well as procedure Q of the slicing criteria or to the procedures that directly or indirectly or transitively calls the procedure Q. Just as in DFS, the algorithm reaches up till its maximum height (or reaches down till its maximum depth) and then iterates up, this algorithm behaves the same way and traverses up and never traverses down into the called procedure Q.

The algorithm that runs slicer operates with different types of edges as shown above, however data dependence edge and control dependence edge are being added only till the scope of the variable i.e. where it was last defined or where it was last used or the node and its enclosing node.

The whole logic can be summarized in a very simple manner. The first phase of the algorithm remembers and keeps the track of the nodes visited while traversing upwards and during the second pass all the types of edges given above are considered and system dependence graph is constructed. The last part of the algorithm merges the nodes from each phase to get the final state of SDG obtained from the slice. And hence, the algorithm terminates when it reaches the line number mentioned in the slicing criteria and gives the relevant set of nodes affecting that particular line.

### E. Pseudocode

Input: P : a program

Output: System Dependence Graph for P

- 1) Go through the source code line by line and parse the lines and depending upon different keywords create different vertices for each line
- 2) Store defined and used variables on that line in that line's vertex
- 3) Create Data dependence edge from used variable's vertex to where that used variable is last defined before the used variable's line
- 4) Create Control dependence edge from current vertex to its enclosing scope vertex
- 5) On the procedure definition line, create formal-in vertices for all procedure parameters, formal-out vertices for all procedure parameters which are passed by reference and procedure vertex
- 6) On the procedure call line create call site vertex, actual-in vertices for all procedure arguments and actual-out vertices for all procedure arguments which are passed by reference
- 7) Create a call edge from the call site vertex to its corresponding procedure vertex
- 8) Create parameter-in edge for all actual-in vertex at call site between actual-in vertex to its corresponding formal-in vertex
- 9) Create parameter-out edge for all formal-out vertex between formal-out vertex to its corresponding actual-out vertex
- 10) If there exist intraslice-path from the formal-out vertex to formal-in vertex then create transitive dependence edge from an actual-in vertex to an actual-out vertex
- 11) If there exist intraslice-path from the formal-out vertex to formal-in vertex then create affect-return edge from an actual-in vertex to the call site vertex
- 12) Create return-link edge for each return site in the called procedure Q from the return vertex in Q to each call site vertex that calls Q

The slicer works in two phases. The phases are described below in the pseudocode :

- 1) Take the source code and augment it by adding lines to get the execution trace and then compile that augmented source code
- 2) Go through the execution trace generated in above step and call construct\_SDG function by passing current executed source line
- 3) Repeat the above step until there are lines left in the execution trace
- 4) Now process the generated graph from the above steps in 2 phases
- 5) Phase1
  - Push the slicing vertex in the queue
  - Now repeat below steps till queue is not empty
  - Push the queue's front vertex's parent, parameter in edge, calling edge, transitive edge, and affect return

edge in the back of the queue

- Pop the first element of queue

#### 6) Phase 2

- Push all the visited vertex till this point in the queue
- Now repeat below steps till queue is not empty
- Push the queue's front vertex's parent, parameter out edge, return link edge, transitive edge, and affect return edge in the back of the queue
- Pop the first element of queue

#### 7) Return all the visited vertices

### F. Implementation

The algorithm for the slicer has been implemented in C++. The following is the step wise implementation of the algorithm:

- 1) When the user executes the slicer code, the slicer code uses system call named system() to execute the java source code. The java source code should be named as source.java and should contain only one class named source.
- 2) Now, the slicer parses the source code and dynamically adds few lines to original source code and created a new code in file named "Outputnn.java". The new lines are written above each line of original source code with sole purpose of redirecting the line numbers to the new text file. While parsing this file, dependencies are stored with the help of data structures, which would help in creating system dependence graph
- 3) This file starts getting executed and creates a new file named "resultt.txt" which contains the line numbers of the statements that got executed.
- 4) The slicer runs the modified version of graph reachability algorithm (BFS) in order to find the dynamic slice of the variable of interest at particular line number. The dynamic slice is calculated on the basis of dependencies between the line numbers. An array is maintained which maps line numbers to the instructions. With the help of this array, the actual dynamic slice is obtained.
- 5) The final step of the slicer is to create different files for different types of dependencies. This is so that system dependence graph can be created and visualized.

All the files mentioned above are automatically deleted by the code itself once the system dependence graph has been created. Several containers and data structures need to be maintained. They are as follows:

- A map mapping line numbers to their nodes in the graph
- A container to store all the definition nodes of the variables
- A container to store all the function nodes
- A container to store all the return statements
- A list of inbuilt datatypes that the slicer will be able to handle
- A stack for maintaining scope of variables
- A stack for evaluating control dependencies

- An array to map line number to their respective instructions
- An array to store the hierarchy of conditional statements

### G. Integrating back-end with GUI

- For designing of GUI, we have used Tkinter, it is basically a Python binding to the Tk GUI toolkit and is a standard GUI toolkit in Python. There are 3 files needed for the implementation which are as follows:
  - Source code (Java file)
  - Slicer (C++ implementation)
  - Python GUI (Using Tkinter)
- On running the GUI, it launches a dialogue box which first checks if Java compiler is installed in the system or not, if it is not installed then the slicer can't be functional, hence it reaches at the dead-end. However, if Java compiler is available in the system then on clicking the "Select File" button, the user will be given the choice to select any Java file from the system and on selecting the file a new window frame is invoked which gives the code preview of the file selected and options to write variable name and standard inputs.

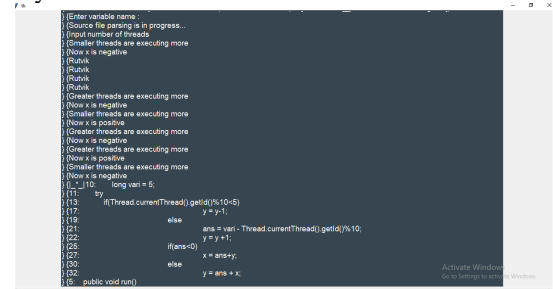


- Select the line for which we want to compute the slice and writing the variable name for dynamic slicing along with the "stdin"



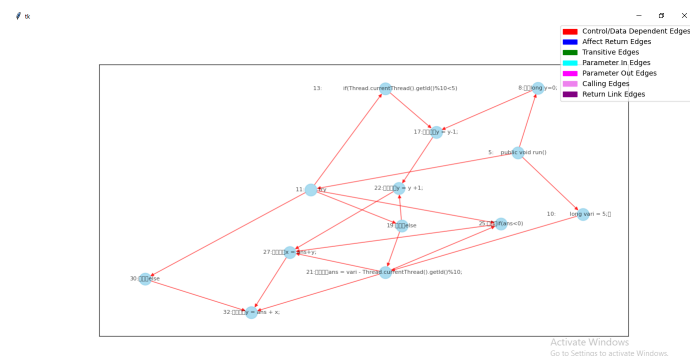
- The slicer running in the back-end of the GUI will give two output windows:

### – Dynamic slice



The above image shows an example of output window of dynamic slice obtained after running the dynamic slicer on one of the examples mentioned in this report.

- Dependency Graph: Dependency graph is created from the different files that were created when the slicer executed the source code. For visualizing graph, we have used networkx library of python to create a directed graph. The graph uses different colours for edges of different dependencies so that dependencies can be visualized properly from it.



- Also, there is an option available named "Copy Slice" which copies the output slice to clipboard.

## VI. EXAMPLE OF SIMPLE JAVA FUNCTIONALITIES

### A. Source Code

### B. Slice Criterion

Input var : y

Input line : 42

Code Input :

- 1
- 2
- 3
- 4

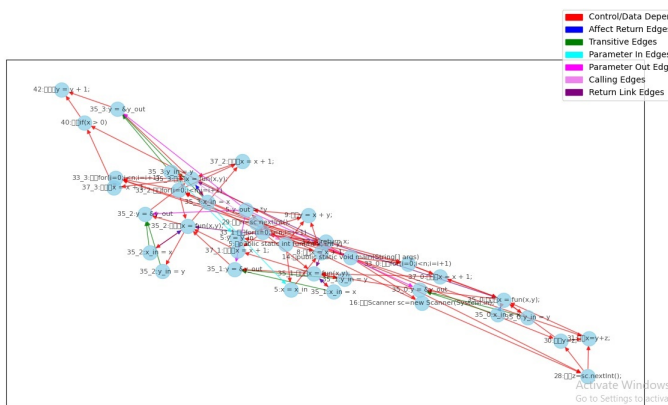
### C. Slice and Dependency graph

```
{ | * | 12: return x;
} { 14: public static void main(String[] args)
} { 16: Scanner sc=new Scanner(System.in);
} { 28: z=sc.nextInt();
} { 29: n=sc.nextInt();
} { 30: y=z;
} { 31: x=y+z;
```

```

} {33_0: for(i=0;i<n;i=i+1)
} {33_1: for(i=0;i<n;i=i+1)
} {33_2: for(i=0;i<n;i=i+1)
} {33_3: for(i=0;i<n;i=i+1)
} {35_0:y = &y_out
} {35_0: x = fun(x,y);
} {35_0:y_in = y
} {35_0:x_in = x
} {35_1:x_in = x
} {35_1:y = &y_out
} {35_1: x = fun(x,y);
} {35_1:y_in = y
} {35_2:y = &y_out
} {35_2: x = fun(x,y);
} {35_2:y_in = y
} {35_2:x_in = x
} {35_3:y = &y_out
} {35_3:y_in = y
} {35_3: x = fun(x,y);
} {35_3:x_in = x
} {37_0: x = x + 1;
} {37_1: x = x + 1;
} {37_2: x = x + 1;
} {37_3: x = x + 1;
} {40: if(x > 0)
} {42: y = y + 1;
} {5:x = x_in
} {5:y_out = *y
} {5: public static int fun(int x, int y)
} {5:y = y_in
} {8: x = x + 1;
} {9: y = x + y;
}

```



#### D. Explanation

- Since this is an algorithm for dynamic slicing, the output would only contain instructions that were actually executed after the user input. Since we chose line number to be 42, the statements before the line number would only be considered. Now execution of line number 42 is control dependent on line number 40 i.e. will depend on the value of x.

- Now, the statement on line 40 is data dependent on line number 37. The value of x on line number 37 is data dependent on the value of x obtained on line number 35.
- The execution of line number 35 is dependent on line number 33. Hence, there is control dependency between line number 33 and 35. Thus, the execution of line number 35 is dependent on the value of n.
- The instruction on line number 35 is data dependent on the value of x obtained on line number 31. which is in turn is data dependent on line number 30 for value of variable 'y'. The value of y on line number 30 is data dependent on value of 'z' on line number 28 that is being scanned. The for loop on line number 33 is data dependent on value of 'n' and hence is data dependent on line number 29.
- Also, the value of 'x' at line number 35 is dependent on the value that the function fun(x,y) returns.
- The statements y\_in=y and x\_in in output slice represent the actual in nodes and the statement y=&y\_out represent the actual out nodes as explained earlier in the logic section.
- The line numbers like 33\_0 present in the output slice represents the first iteration of loop at line number 33.

### VII. EXAMPLE OF THREADED JAVA PROGRAM

#### A. Source Code

```

1)import java.io.*;
2)import java.util.*;
3)class MultithreadingDemo extends Thread
4){
5)public void run()
6){
7)long x=0;
8)long y=0;
9)long ans=0;
10)long vari = 5;
11)try
12){
13)if(Thread.currentThread().
    getId()%10<5)
14){
15)ans = vari +
    Thread.currentThread().getId()%10;
16) x = x+1;
17) y = y-1;
18) }
19) else
20) {
21) ans = vari -
    Thread.currentThread().getId()%10;
22) y = y +1;
23) x = x-1;
24) }
25) if(ans<0)
26) {
27) x = ans+y;

```

```

28) System.out.println("Greater threads
    are executing more");
29) }
30) else
31) {
32) y = ans + x;
33) System.out.println("Smaller threads
    are executing more");
34) }
35) if(x + y < 0)
36) {
37) x = x + y;
38) x = -x;
39) System.out.println("Now x is positive");
40) }
41) else
42) {
43) x = x + y;
44) System.out.println("Now x is negative");
45) }
46) }
47) catch (Exception e)
48) {
49) // Throwing an exception
50) System.out.println("Exception is caught")
51) }
52) }
53) }
54)
55) // Main Class
56) public class source
57) {
58) public static void main(String[] args)
59) {
60) System.out.println("Input number
    of threads");
61) int n;
62) Scanner sc = new Scanner(System.in);
63) n = sc.nextInt();
64) for (int i = 0; i < n; i++)
65) {
66) MultithreadingDemo object =
    new MultithreadingDemo();
67) object.start();
68) }
69) for(int i=0;i<4;i++)
70) {
71) System.out.println("Hiii");
72) }
73) }
74) }

```

### B. Slice Criterion

Input var : y  
Input line : 43  
Code Input :

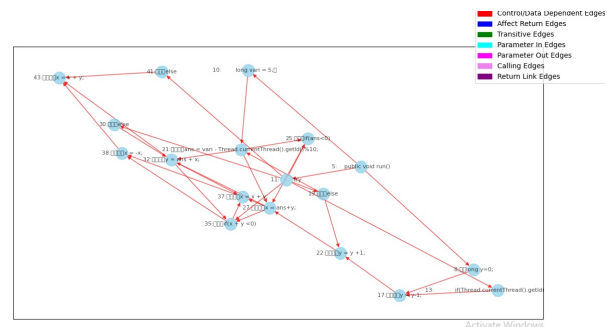
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### C. Slice and Dependency graph

```

{|*|10: long vari = 5;
} {11: try
} {13: if(Thread.currentThread().
    getId()%10<5)
} {17: y = y-1;
} {19: else
} {21: ans = vari -
    Thread.currentThread().getId()%10;
} {22: y = y +1;
} {25: if(ans<0)
} {27: x = ans+y;
} {30: else
} {32: y = ans + x;
} {35: if(x + y <0)
} {37: x = x + y;
} {38: x = -x;
} {41: else
} {43: x = x + y;
} {5: public void run()
} {8: long y=0;
}

```



### D. Explanation

- The execution of statement on line number 43 is dependent on the values of x and y in the conditional statement on line number 35.
- The values of x and y depends on the value of ans due to conditional statement present on line number 25.
- The value of x on line number 43 is data dependent on statement on line number 22.
- The value of ans on line number 25 depends on statement on line number 21. There is data dependency between both the statements.
- The execution of line number 21 depends upon the execution of line number 13 which means there is control dependency between line 13 and line 21
- The value of ans variable on line number 15 depends on the value of variable "vari" which is defined on line number 5 and hence there is data dependency between line number 5 and line number 13.
- Line number 13 executes only when try block gets executed and hence there is control dependency between line number 13 and line number 11

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## VIII. TESTING

We started adding functionalities to the slicer one by one and tested the previous functionality before adding the new one. The testing was done manually. We first added the support for datatypes and scanner class in our slicer and tested it for various user inputs as well as different slice criteria for different programs. After implementing the basic functionalities, we tested it on several programs and then the support for API and functional calls were added. The above mentioned examples are some of the source codes that we used, after the slicer was ready, when we tested at the final stage.

## IX. FUTURE WORK

As mentioned earlier, Java is quite a large language and hence Java has so many functionalities that can be added. The slicer will become more and more useful as support for additional functionalities are added. Some of the functionalities that can be added is support for object oriented concepts like inheritance, abstract classes, polymorphism etc. Also, functionalities such as JDBC can also be added so that the dynamic slicer becomes more useful to the developers out there.

The another part that can be added to the slicer is implementing a static slicer for the same functionalities and test both static and dynamic slicers for same program and compare the efficiencies of both the slicers. Efficiency means comparing number of instructions in the program slice. Also, graphless algorithms can be implemented and similarly efficiency comparison can be done.

## X. CONCLUSIONS

The project developed a tool for calculating dynamic slicing for Java programs. An algorithm for dynamic slicer was implemented and some of the functionalities of the Java code were added. The tool also shows dependency graph which can be helpful to the user in visualizing the slice in a better way. The Dynamic slicer would help a user in debugging as well as testing programs.

## ACKNOWLEDGMENT

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