RZ/A2M Group DRP Library User's Manual and Functional Design Specifications First Edition (Rev. 1.00)

Find Contours Crop

September 24, 2019					
Renesas Electronics					
Approved by	Examined by	Author			



RZ/A2M Group

DRP Custom Library User's Manual

FindContoursCrop

All information contained in these materials, including products and product specifications, represents information on the product at the time of publication and is subject to change by Renesas Electronics Corp. without notice. Please review the latest information published by Renesas Electronics Corp. through various means, including the Renesas Electronics Corp. website (http://www.renesas.com).

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
 In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.
- 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

The reserved addresses are provided for the possible future expansion of functions. Do not access
these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

— When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

Before changing from one product to another, i.e. to a product with a different part number, confirm that the change will not lead to problems.

The characteristics of Microprocessing unit or Microcontroller unit products in the same group but having a different part number may differ in terms of the internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

How to Use This Manual

1. Purpose and Target Readers

This manual is intended to provide the user with an understanding of the functions of the DRP library and how to utilize them. It is aimed at users designing application systems making use of the DRP library. In order to use this manual, you will need a basic knowledge of programming languages and microprocessors.

Particular attention should be paid to the precautionary notes when using the manual. These notes occur within the body of the text, at the end of each section.

The revision history summarizes the locations of revisions and additions. It does not list all revisions. Refer to the text of the manual for details.

Contents

1. Introduction	6
1.1 Summary	ϵ
1. Introduction 1.1 Summary 1.2 Functions	7
2. Operation Conditions	8
3. File Structure	9
4. DRP Library Reference	10
4.1 How to Read the DRP Library Reference4.2 Feature Detection	
4.2 Feature Detection	11
4.2.1 FindContoursCrop	
5. Using the DRP Library	
6. Reference Documents	20

RZ/A2M Group

DRP Library User's Manual

1. Introduction

1.1 Summary

This manual describes the functions and usage of the DRP library, which run on the dynamically reconfigurable processor (DRP) of RZ/A2M Group Microprocessors.

The DRP can perform various functions according to user's setting. In this document, the function performed by DRP is called "circuit", and the data representing circuit information is called "configuration data". Writing of the circuit to DRP can be performed by loading the configuration data using DRP Driver*1. DRP Library is a collection of configuration data with various functions, mainly image processing.

Note 1. For details of DRP Driver, refer to "RZ/A2M Group DRP Driver User's Manual (R01US0355)".

1.2 Functions

The functions of the configuration data contained in the DRP library are listed below.

Table 1.1 DRP Library Functions

Category	Function Name	Outline	Page
Feature Detection	FindContoursCrop	Detects contours in the image and calculates its bounding rectangle within a specified crop window. The shapes and boxes can be output directly into the video ram by a debugging interface. Various filter operations allow the limiting of the created data.	11

2. Operation Conditions

The DRP library operates under the conditions listed below.

Table 2.1 Operation Conditions

Item	Description
Microprocessor	RZ/A2M Group Microprocessors*1
	• R7S921051VCBG
	• R7S921052VCBG
	• R7S921053VCBG

Note 1. The DRP library operates on RZ/A2M Group Microprocessors equipped with a DRP function module. It will not operate on RZ/A2M Group Microprocessors without a DRP function module.

This library was confirmed to operate in the following development environment:

Renesas e² studio 7.5.0

The following toolchain is compatible:

GCC ARM Embedded Toolchain 6-2017-q2-update

3. File Structure

Figure 3.1 shows the file structure of configuration data and header files in the DRP library.

```
r_drp_find_contours_crop FindContoursCrop

+asm

| + r_drp_find_contours_crop_t2.asm
|
+dat
| + r_drp_find_contours_crop_t2.dat
|
+inc
| + r_drp_find_contours_crop_x_t2.h
| + r_drp_find_contours_crop_x_t2.h

+ toc
+ <this document>
```

Figure 3.1 File Structure

4. DRP Library Reference

4.1 How to Read the DRP Library Reference

In this section the specifications of the configuration data contained in the DRP library are presented in the format shown below.

Function	name* ¹
Function outline	
Configuration data file	The name of the configuration data file. Use the DRP Driver's R_DK2_Load() function to load the data in the DRP.
Supported version	Lists the version of the configuration data that operates under present specification. Use the DRP Driver's R_DK2_GetInfo() function to get the version.
Configuration data size (byte)	Lists the size of the configuration data. Lists all versions, if there are different versions.
Header file	The name of the header file for using the configuration data. Use #include "header file" to include the file.
Parameter	Lists the parameters required by the circuit. Parameters are passed from the CPU to the DRP by means of the DRP driver's R_DK2_Start() function. Parameters are defined as a structure within the header file. Before running the circuit, set the parameters on the CPU side. The data type defined in stdint.h is used.
	Also, the area where parameters are stored and the area indicated by parameters representing addresses such as 'src' and 'dst' must be located in physical memory. *2
I/O details	Lists the details of the data specified by the parameters. Unless otherwise indicated, the same address may be specified for the input buffer address and output buffer address.
Number of tiles	The number of tiles used by the circuit. The DRP has 6 tiles. The DRP Driver's R_DK2_Load() function is used to assign circuits to tiles.
Segmented processing	Indicates that the function can be processed in parallel by multiple circuits. In parallel processing, the input image is divided up in the vertical direction and processed accordingly. The segmented processing can be executed by utilizing the 6 tiles of DRP and loading multiple configuration data of 3 tiles or less. For details on loading multiple configuration data of 3 tiles or less into DRP, see the explanation of R_DK2_Load () function in "RZ/A2M Group DRP Driver User's Manual".

Example: A case where the input image is divided into three portions in the vertical direction



Description	Describes the specifications of the configuration data.
Note	Additional notes appear here.

Note 1. The function name of configuration data is a character string that can be obtained from the configuration data by using the DRP Driver's R_DK2_GetInfo() function.

Note 2. If the values of physical memory in the area of parameters and input/output data of the circuit are incorrect because the values are in the Cortex-A9 cache, etc., the circuit does not work properly. It must be necessary to clean the cache before calling the DRP driver's R_DK2_Start() function or to allocate the parameters and input/output data of circuit to a non-cached area.

For information on using the API functions of the DRP Driver, refer to "RZ/A2M Group DRP Driver User's Manual (R01US0355)".

4.2 Feature Detection

4.2.1 FindContoursCrop

FindContoursCrop

Detects contours in the image and calculates its bounding rectangle within a specified crop window. The shapes and boxes can be output directly into the video ram by a debugging interface. Various filter operations allow the limiting of the created data.

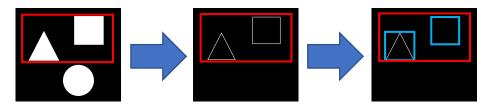
operations allo	w the limiting of th	ne created da	ata.	
Configuration	data file		r_drp_fin	d_contours_crop_t2.dat
Supported vers	sion		0.90	
Configuration data size (byte)			250336	
Header file				d_contours_crop_x_t2.h
	0: :		(r_drp_fi	nd_contours_crop.h)
Parameter	Structure name			
	r_drp_find_conto			
		er name	Туре	Description
	src		uint32_t	Input image address
	dst_rect		uint32_t	Output data (rectangle information) address
	dst_region	dst_region		Output data (region information) address
	width		uint16_t	Input image width (pixels)
	height		uint16_t	Input image height (pixels)
	work		uint32_t	Work area address
	dst_rect_size	Э	uint32_t	Maximum output number of Rectangle Information (0 to 20,000) (When set to 0, no output)
	dst_region_si		uint32_t	Maximum output number of Region Information (0 to 500,000) Specify the upper limit of the total of region information to be output, not the number per contour (When set to 0, no output)
	threshold_wi	dthOrMin	uint16_t	Width threshold of rectangle to be detected (1 to width)
	threshold_heightOrMa.		uint16_t	Height threshold of rectangle to be detected (1 to height)
			uint16_t	Output filter min contour points
	x_crop		uint16_t	Cropping window x-position
	y_crop		uint16_t	Cropping window y-position
	width_crop			Cropping window width
	height_crop			Cropping window height
	mode		uint16_t uint8_t	Output mode and filter control
	dst_rgbDebu	ıg	uint32_t	Output data (debug drawing specified by dmode) address
	dmode		uint8_t	Debug mode output control
I/O details	Input image	Address: Width (pixe Height (pix Format:	els):	Specified by src. Specified by width. (16 to 1280, integer multiple of 8) Specified by height. (8 to 960) Binary image (1 byte per pixel), or 8-bits grayscale (1 byte per pixel) Refer to the description for details. (width) × (height) × 1 byte
Crop window	Position:	x_crop		x_crop+width_crop <= width
· · · · · · · · · · · · · · · ·	pixel exact	y_crop		y_crop+height_crop <= height
	(no multiple of 8 pixels	width_crop height_cro		5 <= width_crop <= width 5 <= height_crop <=height
	required)			

	Output data (Rectangle	Address:	Specified by dst_rect (Specify an address that differs from src.)
	Information)	Format:	From the top address, specifications are made in the following order.
			Upper-left corner x coordinate of Bounding rectangle (2 bytes) Upper-left corner y coordinate of Bounding rectangle
			(2 bytes) Bounding rectangle width (2 bytes)
			Bounding rectangle height (2 bytes) Count of region information (4 bytes) Start address of region information (4 bytes)
		End Data:	Refer to the description for details. End of rectangle information. All fields are 0 (16 bytes)
		Data size:	Refer to the description for details. (Count of rectangles detected + 1) × 16 bytes
	Output data (Region		"+ 1" means the size of End Data The maximum size is (dst_rect_size) × 16 bytes
		Address:	Specified by dst_region (Specify an address that differs from src.)
	Information)	Format:	From the top address, specifications are made in the following order.
			x coordinate of one pixel constituting the contour (2 bytes) y coordinate of one pixel constituting the contour (2 bytes) Refer to the description for details.
		Data size:	(The total of pixels constituting every contour) × 4 bytes The maximum size is (dst_region_size) × 4 bytes
	Work area	Address: Data size: Description	Specified by work. ((width) × (height) × 1 / 4) + 8 byte The area used to store data during FindContoursCrop processing.
Number of tiles	2	2 30011711011	a.ca acces to core data daining i maccined to proceeding.
Segmented processing	Not supported.		

Description

This function performs FindFontoursCrop processing of the image at the address specified by src and outputs the bounding rectangle information of detected contours to the address specified by dst_rect, and the pixel coordinate constituting detected contours to the address specified by dst_region.

The red box in the left image (input image) specifies the crop window in which the FindFontoursCrop will be processed. FindContoursCrop detects two contours within the crop window (middle image). The right image shows the found contours and the surrounding boxes(blue).



A simplified representation of detection of rectangle in the input image

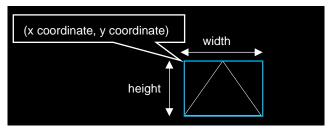
"Rectangle Information"

This function outputs the bounding rectangle information of detected contours in input image and the corresponding Region Information address and count as shown below. After outputs this data set for the number of detected contours, this function outputs the End Data means end of data. Keep reading the Rectangle Information until you find the End Data to obtain all the Rectangle Information. Also, you can obtain the corresponding Region Information using the Region Information count and address.



2 bytes	2 bytes	2 bytes	2 bytes	4 byte	S	4 bytes
x coordinate	y coordinate	width	height	Region Infor count		Region Information address
x coordinate	y coordinate	width height		Region Information count		Region Information address
Rectangle Information of contour-2 End Data						
0x0000	0x0000	0x0000	0x0000	0x00000	000	0x00000000

Rectangle Information



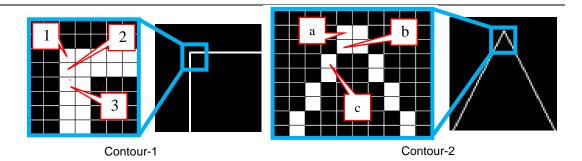
Description of Rectangle Information

"Region Information"

This function outputs (x, y) coordinate of all pixels constituting contours every contour as shown below. This coordinate is expressed in the coordinate system has upper-left corner pixel is (0, 0) in input image. If dst_region_size==0 then the "region information address" will be 0, the "region information count" always shows the number of region elements.

2 bytes	2 bytes						
x coordinate	y coordinate	x coordinate	y coordinate	x coordinate	y coordinate	x coordinate	y coordinate
· · · ·					<u> </u>		
1			2			Information of	Contour-1
x coordinate	y coordinate	x coordinate	y coordinate	x coordinate	y coordinate	x coordinate	y coordinate
	<u></u>						
			b · · ·		Region	Information of	Contour-2

Region Information



If output data count reaches the value set in dst_rect_size or dst_region_size, the data output of the one that reached the upper limit stops, but the other data output doesn't stop. Moreover, if Both data count reaches upper limit, both data output stop, then DRP terminates.

If the Rectangle Information output count reaches upper limit before output the End Data, The End Data is not output.

This function supposes binary image as input image format.

When input 8-bit grayscale, this function treats pixels with a pixel value of 1 or more as pixels with a pixel value of 1. Format should be white on black background.

The mode control allows to filter Rectangle Information and Region Information so that only relevant figures will be used for output generation. For aspect ratio (mode = 011, 100 and 101) a support function aspectfloat4contourfixedint(float) is available to create the required int value.

Mode	0000RFFF	Filter definition register
	R	origin of output coordinates
	0	coordinates are relative to src picture
	1	coordinates are relative to crop window
	FFF	filter mode
	000	boxWidth >= threshold_widthOrMin &&
		boxHeight > threshold_heightOrMax
	001	regionCnt > threshold_region
	010	boxWidth >= threshold_widthOrMin &&
		boxHeight > threshold_heightOrMax &&
		regionCnt > threshold_region
	011	boxWidth/boxHeight*256 >= threshold_widthOrMin &&
		boxWidth/boxHeight*256 <= threshold_heightOrMax &&
		regionCnt >= threshold_region
	100	boxWidth/boxHeight*256 >= threshold_widthOrMin &&
		regionCnt >= threshold_region
	101	boxWidth/boxHeight*256 <= threshold_heightOrMax &&
		regionCnt >= threshold_region
	110	undefined
	111	undefined

The processing performs by the function is equivalent to that of the OpenCV cv::findcontours function with the specifying of CV_RETR_LIST for mode and CV_CHAIN_APPROX_NONE for method. However, this function output is unique format.

Reference URL: https://opencv.org/

The crop window and always output of the "region information count" and the filter operations are an add on and not part of the cv::findcontours function, so in case opency should be used several functions have to be combined to get the same behavior.

This function allows the same address to be specified for both src and work. However, input image is broken because this function writes out data at the area specified by work during processing.

The function reports in addition the error status in the first box record

Condition: x_coordinate== y_coordinate== width == height == 0 && ((count &0x07) != 0)

count & 0x01 → Error: window out of right border count & 0x02 → Error: window out of bottom border count & 0x04 → Error: crop window box to small

The debug interface allows the output of the input pictures (src), found boxes and shapes. The target address is specified by dst_rgbDebug address. Thr the input grey picture will be converted into an RGB picture by copying the grey value int R, G and B channel. The crop window will be drawn in blue color. The found region boxes in red and the shape pixel in green.

Dmode	WCBP000A	debug mode register
	W	draw cropping window
	0	off
	1	on
	С	draw contour data stored in dst_region
	0	off
	1	on
	В	draw bounding box
	0	off
	1	on
	Р	Copy src picture
	0	off
	1	on
	Α	output format
	0	RGB (24bit)
	1	ARGB (32bit) – A channel will be set to 0

Note Please take care to keep the crop Window within the allowed range within the input picture.

Note

This function output size is depending of input image structure. Please allocate sufficient memory area for dst_rect and dst_region to avoid the memory broken by referring Rectangle Information and Region Information of I/O details and setting appropriate values to dst_rect_size and dst_region_size

15

5. Using the DRP Library

To use this library, it is necessary to initialize the DRP, load configuration data, etc. Also, since the parameters are different for each configuration data, set the parameters based on the specification of the configuration data to be used. For application example of DRP library, refer to "RZ/A2M Group 2D Barcode Application Note (R01AN4503)".

Usage example:

```
#include " r_drp_find_contours_crop_x_t2.h"
#define FIND CONTOURS NUM (150)
// variable declaration
uint8 t *output bufadr;
int32_t ret_val;
static uint8_t drp_lib_id[R_DK2_TILE_NUM] = {0};
static volatile uint8_t drp_lib_status[R_DK2_TILE_NUM] = {DRP_NOT_FINISH};
static uint8_t frame_RAM_A[R_BCD_CAMERA_HEIGHT * R_BCD_CAMERA_WIDTH]
                attribute ((section("ImageWork RAM"))); /* canny edge picture */
                       contours_rect_adr[FIND_CONTOURS_NUM + 1]
static contours_rect_t
                         _attribute__ ((section("Uncache_IRAM")));
static contours region t contours region adr[FIND CONTOURS NUM + 1]
                          _attribute__ ((section("Uncache_IRAM")));
static contours rect t
                       cropped_contours_rect_adr[FIND_CONTOURS_NUM + 1]
                         __attribute__ ((section("Uncache_IRAM")));
static contours_region_t cropped_contours_region_adr[FIND_CONTOURS_NUM + 1]
                         _attribute__ ((section("Uncache_IRAM")));
static r_drp_find_contours_crop_t param_find_contours_crop
                        attribute ((section("Uncache IRAM")));
static void cb drp finish(uint8 t id)
   uint32 t tile no;
   /* Change the operation state of the DRP library notified by
      the argument to finish */
   for (tile_no = 0; tile_no < R_DK2_TILE_NUM; tile_no++)</pre>
   {
       if (drp_lib_id[tile_no] == id)
       {
           drp lib status[tile no] = DRP FINISH;
           break;
       }
   return;
}
* End of function cb drp finish
                            *******************
```

```
/* Load DRP Library
/* tile 0 |
/*
                           + */
  +
/* tile 1 |
                           | */
/*
                           + */
/* tile 2 |
                           | */
/* +----+ */
                           | */
/* tile 3 |
/* + FindContoursCrop
                           + */
/* tile 4 |
                           | */
/* +-----+ */
/* tile 5 |
                           | */
·
/********************************/
/* Load DRP Library FindContoursCrop */
ret_val = R_DK2_Load(&g_drp_lib_find_contours_crop_t2[0],
                 R DK2 TILE 3,
                 R DK2 TILE PATTERN 3 2 1, NULL,
                  &cb drp finish, &drp lib id[0]);
DRP DRV ASSERT(ret val);
/*################################
/* Activate DRP Lib FindContoursCrop */
/*##################################
ret val = R DK2 Activate(drp lib id[TILE 3], 0);
DRP_DRV_ASSERT(ret_val);
/* Set R_DK2_Start function parameters for FindContourCrop */
/* input image*/
param_find_contours_crop.src = (uint32_t)&frame_RAM_A[0]; /* Address of image 1-Layer*/
                R_MMU_VAtoPA((uint32_t)param_find_contours_crop.src,
                &(param find contours crop.src ));
/* Address of rectangle output array*/
param_find_contours_crop.dst_rect = (uint32_t)&contours_rect_adr[0];
R_MMU_VAtoPA((uint32_t)param_find_contours_crop.dst_rect,
                 &(param_find_contours_crop.dst_rect ));
/* max number of rectangles to be generated */
param find contours crop.dst rect size = FIND CONTOURS NUM;
/* Set Input-Image size */
/* The horizontal size (pixels) of image */
param_find_contours_crop.width = R_BCD_CAMERA_WIDTH;
/* The vertical size (pixels) of image */
param find contours crop.height = R BCD CAMERA HEIGHT;
```

```
/* Address of work area; minimum size = width * height / 4 + 8 */
param find contours crop.work = (uint32 t)&work2[0];
R_MMU_VAtoPA((uint32_t)param_find_contours_crop.work,
                       &(param_find_contours_crop.work ));
/* Address of region information */
param find contours crop.dst region = (uint32 t)&contours region adr[0];
R MMU VAtoPA((uint32 t)param find contours crop.dst region,
                       &(param find contours crop.dst region ));
param find contours crop.dst region size
                                                   = 0; /* 0: no region output */
/* Threshold of width or min value
param find contours crop.threshold widthOrMin = aspectfloat4contourfixedint(3.1);
/* Threshold of height or max value
param find contours crop.threshold heightOrMax = aspectfloat4contourfixedint(5.9);
/* Crop window x position
param_find_contours_crop.x_crop
                                                    = 4;
/* Crop window y position
param_find_contours_crop.y_crop
/* Crop window width (min 3) */
param_find_contours_crop.width_crop
                                                   = R BCD CAMERA WIDTH-8;
/* Crop window height (min 3) */
param find contours crop.height crop
                                                   = R BCD CAMERA HEIGHT-8;
// Filter mode setting
/* 0000RFFF (bit field)
   R - origin of output coordinates
/*
                0 - off (coordinates are relative to <u>src</u> picture)
                1 - on (coordinates relative to crop window upper left (0 0))
      - filter for box/region found
              000 - boxWidth
                                       >= threshold widthOrMin &&
                   boxHeight
                                       >= threshold_heightOrMax
              001 - regionCnt
                                       >= threshold region
              010 - boxWidth
                                       >= threshold widthOrMin &&
                   boxHeight
                                       >= threshold_heightOrMax &&
                   regionCnt
                                       >= threshold_region
              011 - boxWidth/boxHeight*256 >= threshold_widthOrMin &&
                   boxWidth/boxHeight*256 <= threshold_heightOrMax &&</pre>
                   regionCnt
                                       >= threshold region
              100 - boxWidth/boxHeight*256 >= threshold_widthOrMin &&
                   regionCnt
                                      >= threshold region
              101 - boxWidth/boxHeight*256 <= threshold_heightOrMax &&</pre>
                   regionCnt
                                       >= threshold_region
              110 - reserved
              111 - reserved
param find contours crop.mode
                                                    = 0b00000011;
// debug mode setting
/* WCBP000A (bit field)
  W - draw cropping window
                                                  -> dst rgbDebug(RGB/ARGB)
                0 - off, 1 -on
   C - draw contour data stored in dst_region into
                                                  -> dst_rgbDebug(RGB/ARGB)
                0 - off, 1 -on
                                                  -> dst_rgbDebug(RGB/ARGB)
   B - boundingBox draw bounding box into
                0 - off, 1 -on
   P - debug
                                                  -> dst rgbDebug(RGB/ARGB)
                  copy picture <u>src</u>
                0 - off, 1 -on
   A - output format for debug
                                                  -> dst rgbDebug(RGB/ARGB)
                0 - RGB (24bit), 1 -ARGB(32bit) A channel set to 0
param find contours crop.dmode
                                                    = 0b00000001;
```

```
/* Threshold contour count (number of found contour pixel) (output box is created only
if the surrounding shape has more than 50 pixel) */
param_find_contours_crop.threshold_region
/* Output address for RGB/LRGB picture
                                                             */
/* debug bounding box(blue), found region(red), found pixel(green)
                                                             */
                                                             */
/* set to null if not used
/* Size is same as "width" * "height" of "src" * [3,4]
                                                             */
param find contours crop.dst rgbDebug
/* Initialize variables to be used in termination judgment of the DRP library */
drp_lib_status[TILE_3] = DRP_NOT_FINISH;
/* Start DRP Library FindContoursCrop */
ret_val = R_DK2_Start(drp_lib_id[TILE_3], (void *)&param_find_contours_crop,
                                    sizeof(r drp find contours crop t));
DRP_DRV_ASSERT(ret_val);
/*************/
/* Wait until FindContoursCrop finished */
while (drp_lib_status[TILE_3] == DRP_NOT_FINISH);
. . . . .
// clean up
/* Unload DRP library FindContoursCrop */
ret_val = R_DK2_Unload(drp_lib_id[TILE_3], &drp_lib_id[TILE_3]);
DRP DRV ASSERT(ret val);
```

6. Reference Documents

User's Manual: Hardware

RZ/A2M Group User's Manual: Hardware (R01UH0746)

(Download the latest version of the update or news from the Renesas Electronics website.)

User's Manual: Software

RZ/A2M Group DRP Driver User's Manual (R01US0355)

(Download the latest version of the update or news from the Renesas Electronics website.)

RZ/A2M Group 2D Barcode Sample Program Application Note (R01AN4503)

(Download the latest version of the update or news from the Renesas Electronics website.)

User's Manual: Development environment

For the Renesas Electronics integrated development environment (e² studio), visit the Renesas Electronics website to download the latest version.

Technical Update/Technical News

(Download the latest version of the update or news from the Renesas Electronics website.)

Revision History	RZ/A2M Group DRP Library User's Manual
------------------	--

Rev.	Date	Description		
		Page	Summary	
1.00	Sep 24, 2019	_	First Edition issued	

RZ/A2M Group DRP Custom Library User's Manual

Publication Date: Rev.1.00 Sept. 24, 2019

Published by: Renesas Electronics Corporation

RZ/A2M Group

