

Feedforward Neural Network Study Notes

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Part1: The equations of backpropagation

Equation 1: The error vector in the output layer

$$\delta^L = \nabla_a C \odot \sigma'(z^L)$$

Equation 2: The relationship of error between two consecutive layer

$$\delta^l = ((w^{l+1})^T \delta^{l+1}) \odot \sigma'(z^l)$$

Equation 3: The derivative of cost function of biases

$$\frac{dC}{db^l} = \delta^l$$

Equation 4: The derivative of cost function of weights

$$\frac{dC}{dw_{kj}^l} = \delta_k^l a_j^{l-1}$$

Part2: Proof of Backpropagate Formulas

(1) Equation 1

$$\begin{aligned}\delta_j^L &= \frac{dC}{dz_j^L} \\ &= \sum_k \frac{dC}{da_k^L} \times \frac{da_k^L}{dz_j^L}\end{aligned}$$

Only when $k=j$, the second term could be non-zero

$$\begin{aligned}&= \frac{dC}{da_j^L} \times \frac{da_j^L}{dz_j^L} \\ &= \frac{dC}{da_j^L} \sigma'(z_j^L)\end{aligned}$$

The vectorized expression is: $\delta^L = \nabla_a C \odot \sigma'(z^L)$

(2) Equation 2

$$\delta^l = ((w^{l+1})^T \delta^{l+1}) \odot \sigma'(z^l)$$

First, pull out a single element of the matrix calculation.

$$\delta_j^l = \sum_k (w_{kj}^{l+1} \delta_k^{l+1}) \sigma'(z_j^l)$$

Second, expand the left side.

$$\begin{aligned}\delta_j^l &= \frac{dC}{dz^{l+1}} \times \frac{dz^{l+1}}{dz_j^l} \\ &= \sum_k \frac{dC}{dz_k^{l+1}} \times \frac{dz_k^{l+1}}{dz_j^l} \\ &= \sum_k \delta_k^{l+1} \times \frac{dz_k^{l+1}}{da_j^l} \times \frac{da_j^l}{dz_j^l} \\ &= \sum_k \delta_k^{l+1} \times w_{kj}^{l+1} \times \sigma'(z_j^l)\end{aligned}$$

(3) Equation 3

$$\begin{aligned}\frac{dC}{db^l} &= \frac{dC}{dz^l} \times \frac{dz^l}{db^l} \\ &= \frac{dC}{dz^l} \\ &= \delta^l\end{aligned}$$

(4) Equation 4

$$\frac{dC}{dw_{kj}^l} = \sum_i \frac{dC}{dz_i^l} \times \frac{dz_i^l}{dw_{kj}^l}$$

Only when $i=k$, the second term could be non-zero

$$\begin{aligned} &= \frac{dC}{dz_k^l} \times \frac{dz_k^l}{dw_{kj}^l} \\ &= \delta_k^l \times a_j^{l-1} \end{aligned}$$

Part3: Implementation in Python

In following code, `L` stands for last layer, `l` stands for second to last layer

(1) Equation 1

$$\delta^L = \nabla_a C \odot \sigma'(z^L)$$

```
delta_L = cost_derivative(output, y) * sigmoid_prime(z_L)
```

(2) Equation 2

$$\delta^l = ((w^{l+1})^T \delta^{l+1}) \odot \sigma'(z^l)$$

```
delta_l = np.dot(weights_L.transpose(), delta_L) *
sigmoid_prime(z_l)
```

(3) Equation 3

$$\frac{dC}{db^l} = \delta^l$$

```
nabla_bias = delta_L # Just use the result of previous 2 equation
```

(4) Equation 4

$$\frac{dC}{dw_{kj}^l} = \delta_k^l a_j^{l-1}$$

```
nabla_weight = np.dot(delta_L, sigmoid(z_l).transpose())
```

```
# Helper functions

def cost_derivative(out_put, y):
    return out_put - y

def sigmoid(z):
    return 1.0/(1.0 + np.exp(-z))

def sigmoid_prime(z):
    return sigmoid(z) * (1-sigmoid(z))
```