Terms of Reference

A MOTION DETECTION DEVICE FOR SKATEBOARDS – WITH PAIRING MOBILE APPLICATION

SOFTWARE ENGINERING PROJECT

CM0645: INDIVIDUAL PROJECT

PROJECT AUTHOR: RYAN BAKER

STUDENT ID: W13012372

COURSE: COMPUTER SCIENCE

PROJECT SUPERVISOR: DAVID KENDALL

SECOND MARKER:

Contents

Project Title	2
Project Background	2
Why this project?	2
What issues will I face?	3
Proposed Work	4
The Placement of & Sourcing the Microcontroller	4
Create the Initial Embedded System & Capture Test Data	5
Give the Microcontroller Bluetooth Capability	5
Create the Mobile Application Gateway	6
Presenting the Captured Data	7
Project Aims	8
Project Objectives	8
a. Learning Objectives	9
Skills Required	9
Bibliography	11
Resources	11
Hardware	11
Software	11
Report Structure & Contents	12
Title Page	12
Contents Page	12
Abstract	12
Introduction	12
Analysis	12
Synthesis	13
Evaluation	14
Conclusions & Recommendations	14
List of Appendices	14
Marking Scheme	15
Project Type	15
Project Report	15
Product	15

Project Title

A Motion Detection Device for Skateboards - with pairing Mobile Application.

Project Background

Why this project?

The aim of this project is to create a motion detection device using a microcontroller that can be attached to a skateboard to record when skate tricks are performed.

The initial motivation of this project was the interest I had in doing and embedded systems project as the general theme for my final year project at university. The topic of embedded systems is something I find particularly interesting. With the amount of smart home technologies cropping up these days (*Gartner is predicting a typical family home could contain more than 500 smart devices by 2022, but right now, most consumers see smart home as a nebulous term without a clear value proposition.* - Gartner 2015) and the ease in which to get user friendly hardware someone like myself can use, I wanted to create one of my own.

With this in mind I looked into how I could create something I could use alongside my hobbies. At the time when I was thinking about a 'Smart' device I could make I had just started taking up skateboarding.

From here I wondered if you could use a device to record the distance you have travelled on skateboard, however when it comes to being 'good' at skating it is not down to the distance you have travelled but down to tricks you can perform.

I then started to think about a way of being able to digitally record when a trick has been performed. Which then led me to conclusion that by using a microcontroller as a motion detector you should be able to distinguish each trick due different changes on all 3 axes' (X, Y and Z).

With the world of Skateboarding not really incorporating technology so far in its lifespan I thought that this would be a good opportunity so see if I could pioneer something myself that would be a use to the community as a whole if they wanted to use it.

Primarily this project is aimed at developing something for intermediate to advanced skateboarders so that they can record and look at the tricks they have performed over the course of a day skating

for example the data could also be used in such a way to record how many tricks a skater has performed over the course of a month or a year. This is something that hasn't yet been created, I wondered why this hadn't been tried yet but couldn't think of a reason why as the logic behind detecting a trick using a motion detector seems sound.

However, this technology could be useful for Skateboarders regardless of their ability and could actually be of more use to beginners if I developed this project on further to use the data of the motion detector to suggest what the skateboarder needs to do in order to land the trick they are trying to perform.

Following on from this I could expand on the product that completes the initial objectives for this project and use the technology I develop to improve it so that it can use the data to monitor the form of the trick (how well it is executed). This would be something that could be very useful for skateboarding competitions as it will help judges to recognise how well a trick was performed. With skateboarding being accepted into the Olympics as a sport for Tokyo 2020 this kind of technology would be potentially sought after.

What issues will I face?

There are several issues that are presented to me be taking on this project. Firstly, I will need to find a place on the skateboard where the microcontroller can go without disrupting the users skating.

The point of doing this project without taking this into consideration would be flawed, having the microcontroller in a bad position could limit skateboarder's ability to do certain tricks. I couldn't place the microcontroller on the top of the board as it would make feet positioning difficult which is a major part of performing skateboarding tricks.

This means that the microcontroller has to go on the bottom of the board, as a result I will have to face the issue of choosing a place on the bottom of the board to put the microcontroller which will firstly protect it from damage on impact of landing tricks but also placed in such a position that all grind tricks can be performed without a problem for the skater.

Another issue as well as a main objective within this project is determining the approach for detecting when tricks are performed. I know that each trick you can perform causes the board to move in a different way and knowing this means in theory it will provide different values when being monitored by a motion detector.

The problem is that different gradients and different surfaces will cause the motion detector to be at potentially different starting positions each time a trick is performed. I will have to find a way of creating the program in such a way where this does not matter and the trick can be picked up regardless of its starting position.

The requirements needed of the embedded system that I will create generates issues that I will have to overcome in order to complete this project. A common issue with embedded systems is concurrency. This is something that I will definitely have to look at as I have hardware components on the board running concurrently.

The microcontroller will have to read the data from the motion detection components as well as maintaining a connection to the mobile device and posting the data to it. This will happen concurrently so I will have to look at solutions to prevent problems such as deadlock and starvation occurring. (Due to the constrains of embedded hardware and use cases of embedded systems, specific concurrency solutions are required. — Schramm & Sabo 2008) This means I will have to evaluate several different approaches specifically to creating concurrent systems and choose which one I will implement based on the specification I set out for the embedded system.

Other common embedded systems I will have to overcome include: making my system reliable, predictable and suited for a real – time environment. These issues will be discussed thoroughly in the Literature review I have to write as part of my project analysis section.

Proposed Work

The Placement of & Sourcing the Microcontroller

Before I can begin the development section of this project I need to source an appropriate microcontroller based on two major factors:

- Having all the components I need for the motion detection and communication to a mobile phone. (Accelerometer and/or Gyroscope as well as a Bluetooth Module)
- Being as small as possible so that it is not taking up too much room on the bottom of the skateboard.

I will then decide where the microcontroller will be placed on the bottom of the skateboard which subsequently will give me my size specification needed for the microcontroller, leaving me with the task of finding a board of the specified size with all the relevant components I need.

Create the Initial Embedded System & Capture Test Data

The main challenge of this project is to establish how I will distinguish each skate trick as and when it is performed. This will be done by creating an embedded system to analyse data generated by either an accelerometer, gyroscope or both working together in tandem. I will collect the test data using an open source program called Processing (*Processing is a flexible software sketchbook and a language for learning how to code within the context of the visual arts.* — Processing Website 2016) This software will draw a graph in real time based on the position of my microcontroller using data produced by the relevant components.

For this initial test I will be using a serial connection between the PC and microcontroller as this will be the simplest way to get my microcontroller hooked up to the Processing application to start recording data. I will place the microcontroller connected to the PC on a skateboard. Once the device is attached to the skateboard I will replicated the movements of the skateboard performing certain tricks. By doing this I will be able to observe, via the graph drawn by Processing in real time, how the movement caused by each trick affects the data values given by the motion detection components.

By analysing this data, I will be able to come up with an approach for processing the data when it is posted online so that it can be converted from raw data into a representation of this data in a form of what tricks have been performed and how many times they were performed later on in the project.

By carrying out this section of the project I will be able to evaluate how difficult the project will be too complete.

Give the Microcontroller Bluetooth Capability

Once I am satisfied with the data I have collected, and analysed it enough to come up with a solution to the problem of distinguishing and recording a skate trick, I will take on the task of getting the microcontroller connected to a smartphone device via Bluetooth. This will entail adding to the initial

embedded system so that it can use the on-board Bluetooth module to make itself available for connection to a mobile device.

How this will be done will depend on the Microcontroller that I purchase, some microcontrollers already have applications for Android and iOS devices that can be used to control components such as the on-board LED's. Although I will not be using the LED's specificity in this project it will give me a good framework for establishing the Bluetooth connection as I can look at the source code for these applications and see how the connection is made.

As a result of this section of work I will have a basis for the mobile application needed for my gateway from the microcontroller to the internet. However, for this section the application will be very basic and its only real function at this point will be to establish a connection from the microcontroller to the mobile device so that I can start working on sending the data from the board back to phone to then be pushed onto the internet.

During this phase of the development I will study the Bluetooth stack protocol so I have a solid understanding of its workings so I can identify any issues that may occur using Bluetooth for the wireless technology involved in this project.

Create the Mobile Application Gateway

During this phase of the development I will develop the protocol by which the data will be sent from the microcontroller to the mobile device. Initially I will store the data received by the application into the mobile phones memory so I can view it. From here I will be able to see whether the data is being transmitted to the phone correctly and consistently. It will also show me if there are any differences in the data captured by the board when it is used properly to perform skate tricks rather than just emulating them myself.

Once I am happy with the way the data is being sent from the board to the phone when properly performing the tricks, I will then create an online database for this data to transferred into. This will require me setting up the database in way dedicated to receiving raw accelerometer or gyroscope readings.

When this database is then set up I will create a method within the mobile application that will post up the data receives from the board up to the internet and store it in the database I create on the

web. If an internet connection is not available at the time of data capture, then the data will be saved into the phones memory so that it can then be posted online when a connection becomes available.

Presenting the Captured Data

The final phase of development work to be carried out for this project will be creating a form of web based application that will use the data that is stored in the online database. The web application will be used by the user to view the data that is stored and present in a friendlier way than just raw accelerometer or gyroscope data readings.

To do this I will use the methods created as a result of the data analysis carried out in the second section to distinguish between each trick and create a method or algorithm to translate the recorded data into presentable values such as "Kick Flip" or "Pop – Shuvit". To do this I am planning on creating a system in PHP, this system will contain a method which will have a way of processing the case of each individual trick for example it could look something like this:

Pseudo code:

I will use this sort of method so the application will be able to handle different tricks performed on the skateboard. Once I am satisfied that the method can interpret the data properly it is time to design the user interface, this will require me to brush up on some basic UI and UX skills learnt in my previous 2 years of university. I would like the development of this project to be of use to other people as well so making this web based application well designed is important.

Project Aims

This project has 2 aims:

- 1. To investigate whether a motion detector can be used to record and define Skateboarding tricks as and when they are performed.
- 2. To create a mobile phone application which can receive data from a paired microcomputer that is attached to a Skateboard via Bluetooth. This application will display the data it receives in a user friendly manner.

Project Objectives

- 1. To write a literature review on the issues presented to me by creating an embedded system and what solutions I can use to overcome these problems.
- 2. To establish a method for how I can distinguish between different skateboarding tricks using the accelerometer & gyroscope.
- 3. Gather a thorough set of requirements to specify what the application and microcontroller are able to do when working in tandem.
- 4. To create an embedded system which can use a microcontroller to produce readings of raw data.
- 5. To establish a wireless protocol by which I can communicate this raw data produced by the microcontroller to a mobile phone.
- 6. Design user interfaces for all of the mobile application's use case scenarios based on the requirements I capture.
- 7. To create an application for mobile phone's which uses the data received wirelessly from the microcontroller and presents this to users in an interactive way based on the requirements I capture.
- 8. Evaluate the microcontroller's ability to be used as a device to detect when skateboarding tricks have been performed.
- 9. Evaluate the performance of the application created to pair with the microcontroller and use the data it receives from it to present it user interactively.
- 10. Evaluate my performance during the course of developing this product and project as a whole including coding, time management skills and ability to work according to a schedule.

a. Learning Objectives

- 11. Investigate and understand what makes for good UI and UX then apply this to my mobile application development process.
- 12. To learn and understand how to transmit information wirelessly via Bluetooth and how to establish secure and reliable protocols for doing this.

Skills Required

Skill	Level of experience	Do I need to Improve	How will I improve
	with this skill	this Skill?	this skill?
Researching for	Moderate	Yes	Read up on research
relevant literature			methods as well as
			working on the search
			criteria that I use to
			find references.
Requirements	High	No	
Gathering			
Data Analysis	Moderate	Yes	I have to look at trends
			previously when
			studying subjects such
			as statistics. I will
			improve this technique
			solely by gathering
			data for my project
			and looking at it and
			Trying to determine
			what is means.
Creation of embedded	High	Yes	I am comfortable with
systems			the workings of
			embedded systems
			although I do believe I
			need to improve on
			this further for this
			project.

Mobile Application	Moderate	Yes	I will improve this skill
Development			through dedicating
			time to studying the
			development of mobile
			applications and apply
			this to my project.
Project / Time	High	No	Even though I am
Management			already competent in
			this skill, I believe I will
			improve even further
			as I have never had to
			manage a project of
			this scale.
Working with wireless	Low	Yes	I have never worked
communication			with wireless
			communication before
			in any sense so this will
			be a whole new
			experience for me. I
			will learn this through
			studying methods of
			transferring data
			online and reading
			literature. I will also be
			able to reference the
			microcontrollers
			function library's for
			wireless components.
Evaluation Skills	High	No	

Bibliography

[1] - iControl. (2015). 2015 State of the Smart Home Report. 2015. (Introduction), pg2.

[2] - Schramm, N & Sabo, A. (2008). Concurrent Programming Method for Embedded

Systems. International Symposium of Hungarian Researchers on Computational Intelligence and

Informatics. 9 (Abstract), 369.

[3] - Processing. (2004). Home Page. Available: https://processing.org/. Last accessed 24th Sep 2016.

Resources

Hardware

- A Microcontroller to be used as a motion detector
- A laptop to install the IDE on for programming the application and embedded system
- Android phone to install & test the application on
- A skateboard to attach the microcontroller to

Software

- Eclipse IDE for mobile application development
- Processing an application that will draw graphs based on the position of the microcontroller
- The Arduino development environment for writing the embedded system
- MS Office suite for creating all relevant documents
- MS Project for creating my project plan
- Adobe Illustrator for designing the application screens

Report Structure & Contents

Title Page

Contents Page

Abstract

The abstract will outline the project as whole. It will briefly mention the aims of this project and what work I have carried out in order to meet these aims. I will mention the methodology approach to the project and briefly mention the end result of the project.

Introduction

This section will discuss the reasoning for carrying out the project and outline the approach I will take for the development and what deliverables I will satisfy. The introduction will also outline what the other sections of the report will include.

Analysis

This section will be made up of 2 chapters. The first will be a literature review which will discuss the key issues I will face during the development of this project and evaluate the solutions to these problems in a critical way.

Literature Review

Within my literature review I will discuss 2 topics relevant to the work I am carrying out for this project. (Covers Objective 1).

The Embedded System Design Challenge

In this section of the literature review I will discuss the main challenges and choices that need to be made when creating embedded systems. I will evaluate the different approaches for concurrency, scheduling etc. and explain the choices of methods I am going to use.

Pattern Recognition with Digital Signal Processing

I also discuss pattern recognition with digital signal processing evaluating the techniques I have available to me and which one will be best suited to the work needed for my project. (Detecting the skateboard tricks).

Requirements Commentary

The second chapter of this section will be discussion of the project requirements justifying where necessary and explaining how I captured the requirements. (Covers Objective 3).

Methodology Approach

I will discuss my methodology approach for this project comparing different approaches you can take and explaining why the approach I decided to take was the correct one for the development of this project.

Hardware Justification

I will discuss the different hardware components I had to acquire for this project, what factors led me to this choice and also how the hardware I choose satisfied those factors.

Synthesis

Deliverables Commentary

In this section I will be discussing why the deliverables of project are required for its completion.

Skate Trick Detection Analysis

A commentary/ explanation of the process I went through to coin a method to detect when skateboarding tricks have been performed. (Covers Objective 2).

Analysis Models

This section will include content such as my class diagrams and use case diagrams. I will be commenting on these explain certain points when needed.

Design Work

This section will include all the design work that I carry out for the project, it will include the designs of the mobile application interface as well as the designs for the web application if that is the way I choose to present the data to the user. (Covers Objectives 6 and 11).

Coding Work

This section will be split into a commentary of the 3 pieces of coding work done for this project. The embedded system for the microcontroller, the application for the android device web based application that will present the data. (Covers Objectives 4, 5, 7 and 12).

Test Plan & Results

I will describe my test plan in this section and show the results giving comment on if that is happening is what I expected and highlighting any issues discovered over the different testing phases.

Evaluation

Product Evaluation

I will evaluate the product that I end up with at the end of the project against the requirements I laid out for it and what deliverables where expected. I will talk about areas that the product excels in and areas that it might have quite been such as a success. (Covers Objectives 8 and 9).

Project Development Evaluation

In this section I will be evaluating my own performance throughout the development of this project. Commenting on aspects such as time management, workload balancing and the improvement of my skillset. (Covers Objective 10).

Conclusions & Recommendations

I will conclude the project summarising the findings and explaining what I could have done differently or better if I had more time to spend on the project.

List of Appendices

- 1. Terms of Reference Document
- 2. Risk Assessment Form
- 3. Ethics Form
- 4. Test data from motion detector

Marking Scheme

Project Type

This project is a Software Engineering Project the marking scheme is as follows:

Software Engineering Project:

Report 40%
Product 50%
Viva 10%
Total 100%

Project Report

Report:

Abstract & Introduction 5%
Analysis 30%
Synthesis 30%
Evaluation & Conclusions 30%
Presentation 5%
Total 100%

Covered by the following deliverables:

- Project Report
- Skate Trick Analysis Graphs

Product

Product:

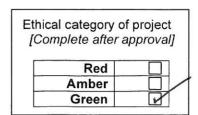
Fitness for Purpose 40%
Build Quality 60%
Total 100%

Viva:

Presentation / Demonstration 50%
Discussion 50%
Total 100%

Covered by the following deliverables:

- Bluetooth enabled microcontroller for data capture
- Mobile Application for receiving captured data and recognising patterns
- Web Based Application for viewing data





Department of Computer Science and Digital Technologies

UNDERGRADUATE COMPUTING PROJECTS: ETHICS REGISTRATION AND APPROVAL FORM

Section One: Registration [To be completed by student]

Title of research project/dissertation	Motion Delection & Analysis for Shale brichs.
Researcher's name	Ryan Baker
Programme of study	Computer Science
Academic Year	2016/17
Module code	CM0645
Supervisor's name	David Kendall
Second marker's name	Longzhi Yang
Start Date of Project	19 109 1 7016
Brief outline of research topic:	
To develop a syste	en which can delect
	using a microcontracter
and mobile application	n to interpet what
frichs have been per	

Short description of pr	oposed research methods	including identi	fication of part	icipants:	
I will be knough be	researching at books.	moinly	online	and	

Ethical considerations in the research project	YES	NO
Does your research involve an external organisation or partner?		Y /
2. Does your research involve human participants?		Ø
3. If yes to Q.2, will you inform the participants about the research?	Z	1
4. Will you obtain their consent using the standard consent form?	J.Z	D.
5. Is any deception involved?		Y
6. Do any participants constitute a 'vulnerable group'?		
(refer to definition of Vulnerable People)		
7. Will the research involve the following information?		
Commercially sensitive		Ø,
Personally sensitive		9
Politically sensitive		V
Legally sensitive		Q,
8. Is the research likely to have any significant environmental impacts?		4
9. Are there likely to be any risks for the participants in your research?	.0	
10. Are there likely to be any risks for you in conducting the research?	Ø,	
11. If yes [to 5, 6, 7, 8, 9 or 10 above] have you identified steps to address the issues and mitigate any risks to participants, yourself or the environment?	ব	

		7-2								
		lain how any i risks or adver			bove will b	e addre	ssed and wh	nat steps	will be taken	
Who	in t	esting	sha	le 1	richs	S	their	def	ection	
		wea								
as	a	helem	el,	knee	pads	and	elb.	on p	ads.	
	<u>.</u>					au e				-

Ethical category of research project

Based on the above Ethical Considerations and with reference to the University's Ethical Scrutiny Risk Assessment tool identify the Ethical category of your research project (refer to http://www.northumbria.ac.uk/static/5007/respdf/riskassesmenttool for further guidance):

[Please tick as appropriate]

Red	T' d I	vulnerable participants; human tissue; sensitive data; risks to participants & researchers etc.
Amber		human participants requiring informed consent; commercially sensitive information etc.
Green	1	no participants involved; secondary data only; no sensitive data

0.00	
	thics Policy and Procedures and confirm that the issues arise under items 5, 6, 7, 8, 9 or 10 [above] Inch these issues in the research.
Researcher's signature	10111 12016
Date	10/11/2016
to a reviewer as follows: Green risk - may be approved by Supervisor Amber risk - to be submitted for approval by one	Principal Supervisor or Module Tutor and allocated e independent reviewer (second marker) dependent members of Faculty Research Ethics

Section Two: Approval

Supervisor/Module Tutor's name confirming ethical risk status	David Kendal					
Ethical approval [Please tick as appropriate]						
Green - Ethical approval is given without co	☐ ☐					
Amber – (to be approved by one independe given with the following conditions:						
Information to be provided to all par Participant consent to be obtain						
procedures • Data to be stored and destroyed sec	erwise in accordance with Hair control					
guidelinesAdherence to Data Protection Act						
 Anonymity to be offered to participal Commercial confidentiality to be pro Software vulnerabilities, exploits, ha published without prior 'responsible 	vided to organisations(s) zardous software etc. not to be					
Other (please state):						
Red - Project is referred to FREC for approv Please e-mail the submission to <u>PGR Facult</u>	ral.by two independent reviewers ty <u>Support</u>					
Name & role of reviewer 1:						
Signature						
Date						
Name & role of reviewer 2:						
Signature						
Date						
Outcome of Review						
Approved.						