COMP 3804 — Assignment 2

Due: Thursday February 16, 23:59.

Assignment Policy:

• Your assignment must be submitted as one single PDF file through Brightspace.

Use the following format to name your file:

LastName_StudentId_a2.pdf

- Late assignments will not be accepted. I will not reply to emails of the type "my internet connection broke down at 23:57" or "my scanner stopped working at 23:58", or "my dog ate my laptop charger".
- You are encouraged to collaborate on assignments, but at the level of discussion only. When writing your solutions, you must do so in your own words.
- Past experience has shown conclusively that those who do not put adequate effort into the assignments do not learn the material and have a probability near 1 of doing poorly on the exams.
- When writing your solutions, you must follow the guidelines below.
 - You must justify your answers.
 - The answers should be concise, clear and neat.
 - When presenting proofs, every step should be justified.

Question 1: Write your name and student number.

Solution: Ryan Lo (101117765)

Question 2: You are given k sorted lists L_1, L_2, \ldots, L_k of numbers. Let n denote the total length of all these lists.

Describe an algorithm that returns one list containing all these n numbers in sorted order. The running time of your algorithm must be $O(n \log k)$.

Explain why your algorithm is correct and why the running time is $O(n \log k)$. Hint: If k = 2, this should look familiar.

Solution:

Algorithm:

First start by creating a min-heap of size k.

For each list L_i we can insert the first element of L_i into the min-heap.

While the min-heap is not empty:

We remove the smallest element from the min-heap

Take that element and add it to the output list

Finally return the output list

Correctness:

For k = 2, the algorithm is just a standard merge sort, which is proved to be correct. Assume now that in the algorithm we have is correct for k-1 lists. We no consider having k lists, so L_1, L_2, \ldots, L_k . We can now pair up each lists into k/2 pairs and merge them together into a single sorted list using the algorithm for two lists as stated above which is correct. If k is even then the lists are paired evenly and works out perfectly, if k is odd then we have a left over list which we can just merge with the main list. After everything is finished we get a single sorted list that contains all n elements from the k amount of lists and therefore is correct.

Question 3: This is a long question. Don't be intimidated! As always, for each part in this question, you must justify your answer.

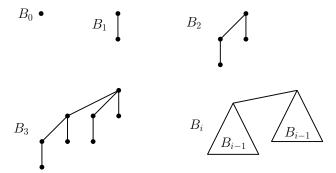
Professor Justin Bieber needs a data structure that maintains a collection A, B, C, \ldots of sets under the following operations:

- 1. MAXIMUM(X): return the largest element in the set X.
- 2. INSERT(X, y): add the number y to the set X.
- 3. ExtractMax(X): delete and return the largest element in the set X.
- 4. Combine (X, Y): take the union $X \cup Y$ of the sets X and Y, and call the resulting set X.

Professor Bieber knows how to support the first three operations: Store each set X in a max-heap. The fourth operation seems to be more problematic, because we have to take two max-heaps and combine them into one max-heap.

To support all four operations, Professor Bieber has invented the following sequence B_0, B_1, B_2, \ldots of trees, which are now universally known as *Bieber trees*:

- 1. B_0 is a tree with one node.
- 2. For each $i \geq 1$, the tree B_i is obtained as follows: Take two copies of B_{i-1} and make the root of one copy a child of the root of the other copy.



Question 3.1: Let $i \geq 0$. How many nodes does the tree B_i have?

Solution:

The tree is doubling in nodes every time. Therefore the tree B_i has 2^i nodes.

Question 3.2: Let $i \geq 0$. What is the height of the tree B_i ?

Solution:

The height of the tree increases every time. Therefore the height of the tree B_i is i+1.

Question 3.3: Let $i \geq 1$. Prove that the subtrees of the root of B_i are the Bieber trees $B_0, B_1, \ldots, B_{i-1}$.

Solution:

We will prove this by induction that the subtrees of the root of B_i are Bieber trees. Base Case:

When i = 0, the root of B_0 is just a single node. The only subtree of the root is the root itself, so the subtree is the Bieber tree which is B_0 .

Inductive Case:

We assume that the subtrees of the root of B_i are Bieber trees $B_0, B_1, \ldots, B_{i-1}$. Now we want to show the the subtress of the root of $B_i + 1$ are Bieber trees B_0, B_1, \ldots, B_i . From the definition of a Bieber tree, the Bieber tree $B_i + 1$ is formed by taking two copies of B_i and then attaching the root of one to the root of the other. Therefore the tree contains a subtree that is a Bieber tree. The Bieber tree $B_i + 1$ contains 2 instances of the Bieber subtree B_i ,

one rooted at the root and the second one which is the root itself. The subtrees B_i rooted at the root of the $B_i + 1$ tree are copies of B_i which by the inductive hypothesis, they are the Bieber trees $B_0, B_1, \ldots, B_{i-1}$.

Let X be a set of n numbers, assume that $n \geq 1$, and let

$$n = (b_m, b_{m-1}, \dots, b_1, b_0)$$

be the binary representation of n. Note that $b_m = 1$ and

$$n = \sum_{i=0}^{m} b_i \cdot 2^i.$$

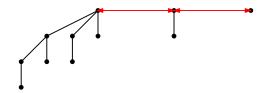
The Bieber max-heap for the set X is obtained as follows:

1. Partition the set X, arbitrarily, into subsets such that for each i for which $b_i = 1$, there is exactly one subset of size 2^i .

For example, if $n = 11 = 2^3 + 2^1 + 2^0$, the set X is partitioned into three subsets: one of size 2^3 , one of size 2^1 , and one of size 2^0 .

- 2. Each subset of size 2^i is stored in a Bieber tree B_i . Each node in B_i stores one element of the subset. Each node in B_i has pointers to its parent and all its children. There is a pointer to the root of B_i .
- 3. Each Bieber tree has the property that the value stored at a node is larger than the values stored at any of its children.
- 4. The roots of all these Bieber trees are connected using a doubly-linked list.

The figure below gives an example when n = 11.



Question 3.4: Let X be a non-empty set of numbers, and assume that this set is stored in a Bieber max-heap. Describe an algorithm that implements the operation MAXIMUM(X) in $O(\log |X|)$ time.

Solution:

Algorithm:

Start by following through the doubly linked-list to find the maximum element. Then compare the current maximum value with each root. Update the maximum if the value is

larger. Continue traversing till the very end. Return the maximum value found. It will take O(log|X|) to traverse through the Bieber tree.

Question 3.5: Let X and Y be two sets of numbers, and assume that both sets have the same size 2^i . A Bieber max-heap for X consists of one single Bieber tree B_i . Similarly, a Bieber max-heap for Y consists of one single Bieber tree B_i . Describe an algorithm that implements the operation COMBINE(X,Y) in O(1) time.

Solution:

To combine two Bieber max-heaps we can make the root of the Bieber tree for Y a child of the root of the Bieber tree for X. Since each of the values is stored at a node that is larger than the values stored at any of its children it follows the Bieber max-heap.

Algorithm:

First we attach the root of the Bieber tree for Y to the root of the Bieber tree for X Next we update the connects of the roots for X and Y

This operation would take constant time.

Question 3.6: Let X and Y be two non-empty sets of numbers, and assume that X is stored in a Bieber max-heap and Y is stored in a Bieber max-heap. Describe an algorithm that implements the operation Combine(X,Y) in $O(\log |X| + \log |Y|)$ time.

Hint: This operation computes one Bieber max-heap storing the union $X \cup Y$. If you take the sum of two integers, both given in binary, then you go through the bits from right to left and keep track of a carry bit.

Solution:

Algorithm:

First, we want to merge X and Y using the union of both of them $X \cup Y$ and we will label this new set Z. Next we need to create a new Bieber tree for the set Z, we do this by spliting the $B_i - 1$ into 2 copies until Z becomes a Bieber tree. Then we update the doubly linked list of the Bieber trees to add in the new root Finally, we do a Bieber max-heapify on the Bieber tree to keep the Bieber max heap property.

First step takes O(|X|+|Y|), second step takes O(|Z|) time to get the Bieber tree, third step takes O(1) time because it's just linked list pointer upates and last step takes O(|Z|) time to heapify the tree.

The total time complexity of the whole operation is O(log|X| + log|Y|) time.

Question 3.7: Let X be a non-empty set of numbers, and assume that this set is stored in a Bieber max-heap. Describe an algorithm that implements the operation INSERT(X, y) in $O(\log |X|)$ time.

Note that this operation computes a Bieber max-heap for the set $X \cup \{y\}$.

Solution:

Algorithm:

If y is greater than the value that is in the root of the Bieber tree then create a new Bieber tree $B_i + 1$ with y as the root and make the new tree a child of of it. Otherwise, make a new node with y and add it to the existing Bieber tree. If we were to traverse through, the worst case would be O(log|X|) time.

Question 3.8: Let X be a non-empty set of numbers, and assume that this set is stored in a Bieber max-heap. Describe an algorithm that implements the operation ExtractMax(X) in $O(\log |X|)$ time.

Note that this operation computes a Bieber max-heap for the set $X \setminus \{y\}$, where y is the largest number in X.

Solution:

Algorithm:

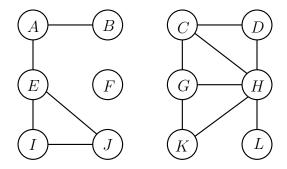
To start we extract the maximum value from the root of the Bieber tree. Next we have to rebuild the remaining Bieber trees. To do this we have to repeatly merge the Bieber trees together until it becomes one connected tree. The time complexity for the whole algorithm takes $O(\log |X|)$ time to perform, there is going to be at most $\log |X|$ levels.

Question 3.9: Let X be a non-empty set of numbers, and assume that this set is stored in a Bieber max-heap. How would you extend this data structure such that the operation MAXIMUM(X) only takes O(1) time, whereas the running times for the other operations COMBINE, INSERT, and EXTRACTMAX remain as above?

Solution:

An easy and simple way to extend this data structure such that the operation of MAX-IMUM(X) only takes O(1) time is to add and maintain an extra pointer to the maximum element in the heap. Whenever we run combine the we can just compare the two maximums between the two heaps and update the pointer to the new maximum. Running insert we just compare the newly inserted element with the current maximum and update if needed. For extract maximum, we can just return the maximum that the pointer is pointing to then remove it from the heap. Finding the new maximum element and assigning the pointer to it will take only O(log|X|) when does not hinder the performance. With that the new MAXIMUM(X) will be O(1) with changing the runtime of the other operations.

Question 4: Consider the following undirected graph:



Draw the DFS-forest obtained by running algorithm DFS on this graph. The pseudocode is given at the end of this assignment. Algorithm DFS uses algorithm EXPLORE as a subroutine; the pseudocode for this subroutine is also given at the end of this assignment.

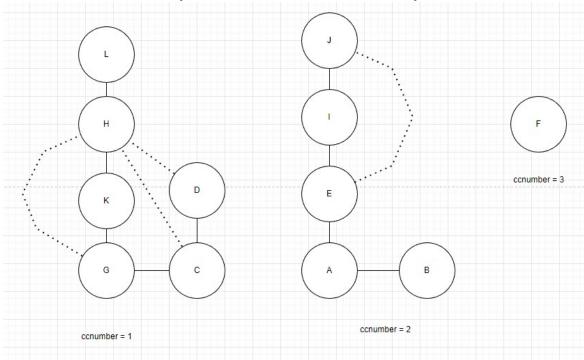
In the forest, draw each tree edge as a solid edge, and draw each back edge as a dotted edge.

Whenever there is a choice of vertices, pick the one that is alphabetically last.

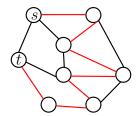
Solution:

Reverse alphabetical order:

Assuming it is stored as: [L, K, J, I, H, G, F, E, D, C, B, A]



Question 5: Tyler is not only your friendly TA, he is also the inventor of Tyler paths and Tyler cycles in graphs: A *Tyler path* in an undirected graph is a path that contains every vertex exactly once. In the figure below, you see a Tyler path in red. A *Tyler cycle* is a cycle that contains every vertex exactly once. In the figure below, if you add the black edge $\{s,t\}$ to the red Tyler path, then you obtain a Tyler cycle.



If G = (V, E) is an undirected graph, then the graph G^3 is defined as follows:

- 1. The vertex set of G^3 is equal to V.
- 2. For any two distinct vertices u and v in V, $\{u, v\}$ is an edge in G^3 if and only if there is a path in G between u and v consisting of at most three edges.

Question 5.1: Describe a recursive algorithm TylerPath that has the following specification:

Algorithm TylerPath(T, u, v):

Input: A tree T with at least two vertices; two distinct vertices u and v in T such that $\{u, v\}$ is an edge in T.

Output: A Tyler path in T^3 that starts at vertex u and ends at vertex v.

Hint: You do not have to analyze the running time. The base case is easy. Now assume that T has at least three vertices. If you remove the edge $\{u, v\}$ from T, then you obtain two trees T_u (containing u) and T_v (containing v).

1. One of these two trees, say, T_u , may consist of the single vertex u. How does your recursive algorithm proceed?

Solution:

The case where T_u consist of a single vertex u, in this case the edge u, v is the Tyler path from u to v. The other case where the edge u, v is in the other tree, the Tyler path from u to v is the path that consists of u, the edge u, v and a Tyler path from v to a node in T_v .

2. If each of T_u and T_v has at least two vertices, how does your recursive algorithm proceed?

Solution:

If T_u and T_v both has at least 2 vertices, we can first take T_u and find the Tyler path from u to another vertex in T_u which we can call x. Now we can take T_v and then find the Tyler path from v to another vertex in T_v which we can label as y. Now we can take both the Tyler paths in T_u and T_v which we just found and insert an edge from x to y we can get a Tyler path from T_u to T_v .

Question 5.2: Prove the following lemma:

Tuttle's Lemma: For every tree T that has at least three vertices, the graph T^3 contains a Tyler cycle.

Solution:

Base Case: If T has 3 vertices, the Tyler path is the path that just contains all three vertices.

Inductive Case: We now assume that T has at least four vertices. Say we have two trees T_u and T_v , and we remove the edge u, v, and we have a vertex x that is connected to both u and v. We can add the path from v to the vertex x. With that the graph T still contains a path from v to x and a path from x to u. It connects all the vertices creating a Tyler cycle. Therefore it contains a Tyler cycle.

Question 5.3: Prove the following theorem:

Tuttle's Theorem: For every connected undirected graph G that has at least three vertices, the graph G^3 contains a Tyler cycle.

Solution:

Base Case: If T has 3 vertices, the Tyler cycle is the cycle that just contains all three vertices.

Inductive Case: Assume that the graph G has at least four vertices. Since the graph is connected there is a path P where it starts at a vertex u and goes around and visits all vertices in the connected part then returns back to the vertex u. The Tyler cycle still contains all vertices in the cycle so therefore it is still a Tyler cycle.

```
Algorithm DFS(G):
for each vertex u
do visited(u) = false
endfor;
cc = 0;
for each vertex v
do if visited(v) = false
   then cc = cc + 1
        Explore(v)
   endif
endfor
Algorithm Explore(v):
visited(v) = true;
ccnumber(v) = cc;
for each edge \{v, u\}
do if visited(u) = false
   then Explore(u)
   endif
endfor
```