

 $S_{oldsymbol{
ho}oldsymbol{
ho}oldsymbol{
ho}}$

 \sim

 \sim

Нίρ

Speed

Contact Lidar <u>1</u>

TPG+SBB Bid

TPG+SBB Act

Hull Ang.

Hip 1

Hip 1

Probability of Observation Index per Instruction



Lidar

Sin /

Lidar

Lidar

Lidar

Lidar

Lidar

Lidar

- 0.02

0.00