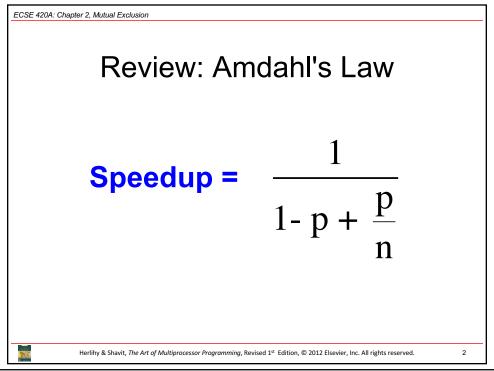
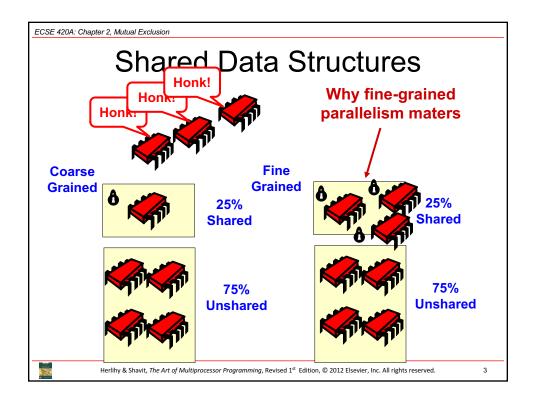
Chapter 2
Mutual Exclusion

Chapter 1
Mutual Exclusion

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Example Synchronization Paradigms

Mutual exclusion

ECSE 420A: Chapter 2, Mutual Exclusion

- Readers-Writers
- Producer-Consumer

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Mutual Exclusion



- We will clarify our understanding of mutual exclusion
- We will also show how to reason about various properties in an asynchronous concurrent setting



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ECSE 420A: Chapter 2, Mutual Exclusion

Mutual Exclusion



In his 1965 paper E. W. Dijkstra wrote:

"Given in this paper is a solution to a problem which, to the knowledge of the author, has been an open question since at least 1962, irrespective of the solvability. [...] Although the setting of the problem might seem somewhat academic at first, the author trusts that anyone familiar with the logical problems that arise in computer coupling will appreciate the significance of the fact that this problem indeed can be solved."



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Mutual Exclusion



- Formal problem definitions
- Solutions for 2 threads
- Solutions for *n* threads
- Fair solutions
- Inherent costs



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Warning

- You will never use these protocols
 - Get over it
- · You are advised to understand them
 - The same issues show up everywhere
 - Except hidden and more complex



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Why is Concurrent Programming so Hard?

- Try preparing a seven-course banquet
 - By yourself
 - With one friend
 - With twenty-seven friends ...
- · Before we can talk about programs
 - Need a language
 - Describing time and concurrency



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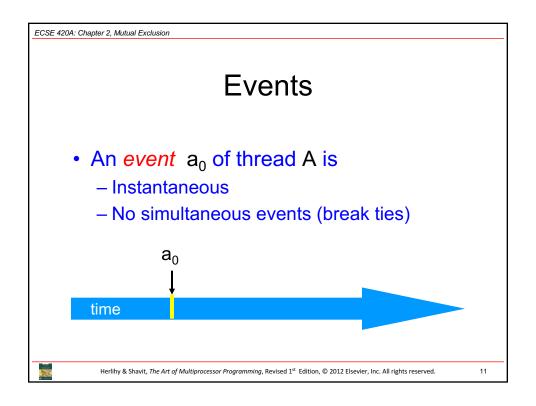
Time

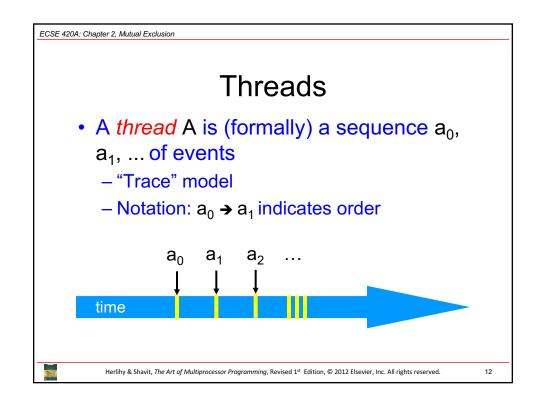
- "Absolute, true and mathematical time, of itself and from its own nature, flows equably without relation to anything external." (Isaac Newton, 1689)
- "Time is what keeps everything from happening at once." (Ray Cummings, 1922)

time



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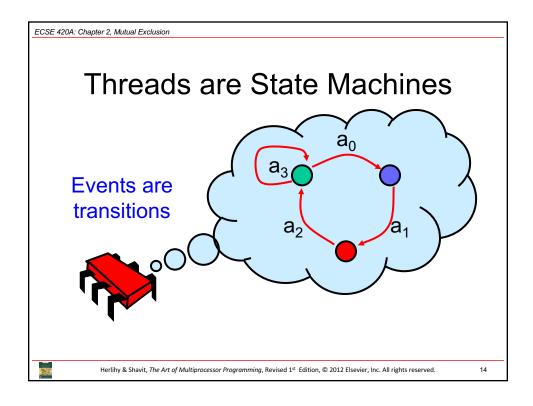


Example Thread Events

- Assign to shared variable
- · Assign to local variable
- · Invoke method
- · Return from method
- Lots of other things ...



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States

• Thread State

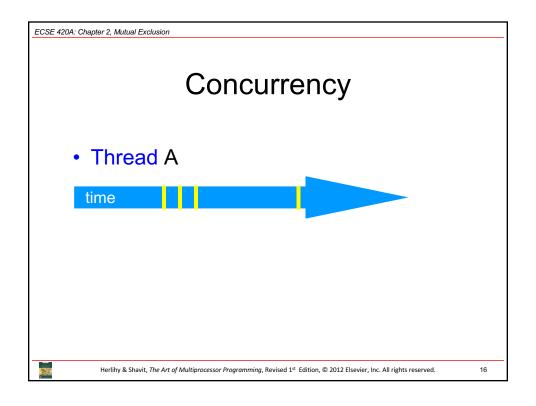
- Program counter

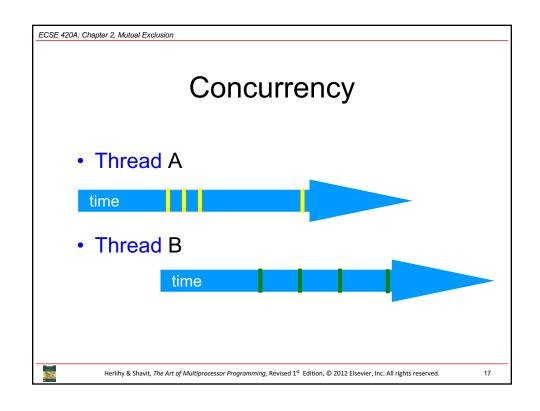
- Local variables

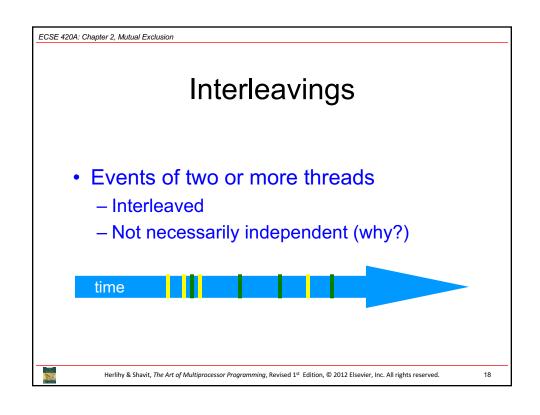
• System state

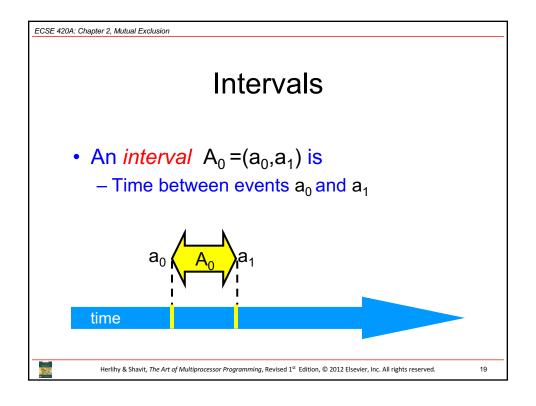
- Object fields (shared variables)

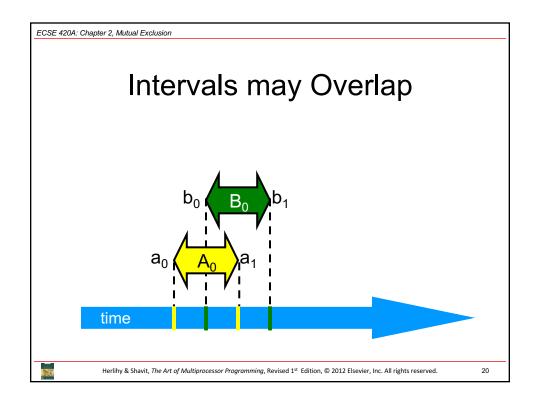
- Union of thread states

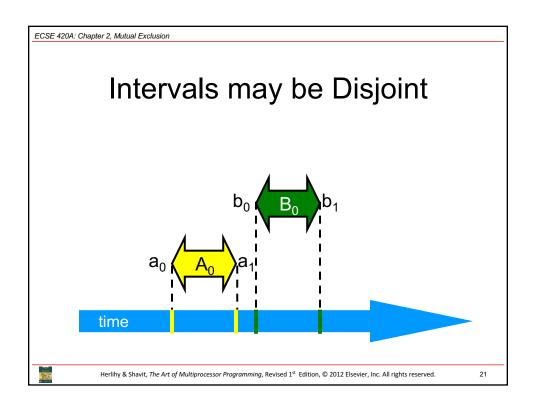


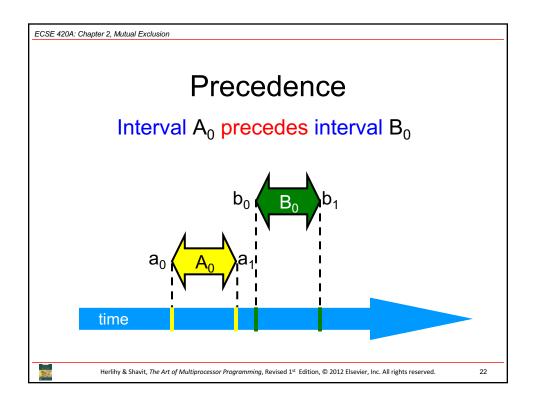




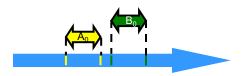








Precedence



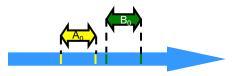
- Notation: A₀ → B₀
- Formally,
 - End event of A₀ before start event of B₀
 - Also called "happens before" or "precedes"

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Precedence Ordering

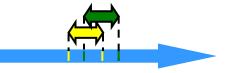


- Remark: A₀ → B₀ is just like saying
 - $-1066 AD \rightarrow 1492 AD$
 - Middle Ages → Renaissance,
- · Oh wait,
 - what about this week vs this month?

1

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Precedence Ordering



- Never true that A → A
- If A →B then not true that B →A
- If A →B & B →C then A →C
- Funny thing: A →B & B →A might both be false!



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Partial Orders

(review)

- Irreflexive:
 - Never true that A → A
- Antisymmetric:
 - If A → B then not true that B → A
- Transitive:
 - If A → B & B → C then A → C

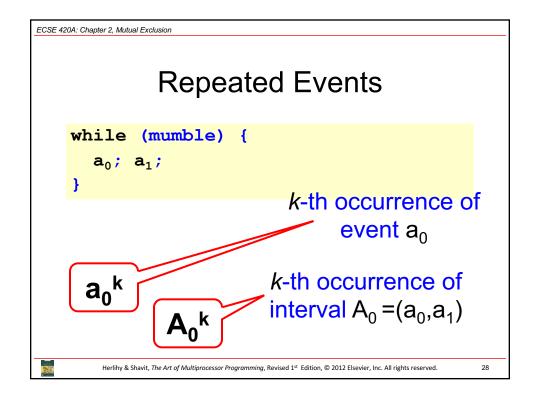


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Total Orders
(review)

• Also
— Irreflexive
— Antisymmetric
— Transitive

• Except that for every distinct A, B,
— Either A → B or B → A



```
Implementing a Counter

public class Counter {
    private long value;

public long getAndIncrement() {
    temp = value;
    value = temp + 1;
    return temp
}

Make these steps
}

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```

```
Locks (Mutual Exclusion)

public interface Lock {

public void lock();

public void unlock();
}

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```

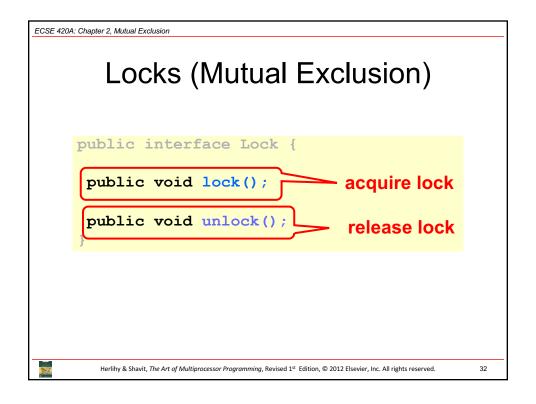
```
Locks (Mutual Exclusion)

public interface Lock {

public void lock();

public void unlock();
}

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```



```
ECSE 420A: Chapter 2, Mutual Exclusion
                        Using Locks
     public class Counter {
        private long value;
        private Lock lock;
                                     //to protect critical section
        public long getAndIncrement() {
         lock.lock();
                                            //enter critical section
         try {
           int temp = value;
                                          //in critical section
          value = value + 1;
         } finally {
            lock.unlock();
                                          //leave critical section
         return temp;
        }}
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```

Using Locks

public class Counter {
 private long value;
 private Lock lock;
 public long getAndIncrement() {
 lock.lock();
 try {
 acquire Lock
 int temp = value;
 value = value + 1;
 } finally {
 lock.unlock();
 }
 return temp;
 }}

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```
ECSE 420A: Chapter 2, Mutual Exclusion
                         Using Locks
      public class Counter {
         private long value;
        private Lock lock;
         public long getAndIncrement() {
          lock.lock();
          try {
           int temp = value;
           value = value + 1;
          } finally {
                                              Release lock
             lock.unlock();
                                            (no matter what)
          return temp;
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```

```
Using Locks

public class Counter {
    private long value;
    private Lock lock;
    public long getAndIncrement() {
        lock.lock();
        try {
            int temp = value;
            value = value + 1;
        } rinally {
            lock.unlock();
        }
        return temp;
        }}

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```

Mutual Exclusion

Let CS_i^k
 ⇔ be thread i's k-th critical section execution



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Mutual Exclusion

- Let CS_i^k
 ⇔ be thread i's k-th critical section execution



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Mutual Exclusion

- Let CS_i^k
 ⇔ be thread i's k-th critical section execution
- And $CS_{j}^{m} \iff$ be j's m-th execution
- Then either
 - $-\Leftrightarrow \Leftrightarrow \text{or} \Leftrightarrow \Leftrightarrow$

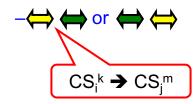
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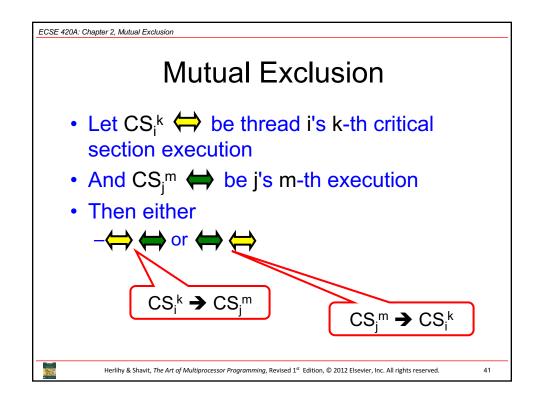
Mutual Exclusion

- Let CS_i^k
 ⇔ be thread i's k-th critical section execution
- And $CS_{j}^{m} \iff$ be j's m-th execution
- · Then either



-

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Starvation-Free



- If some thread calls lock()
 - It will eventually return
- Individual threads make progress



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ECSE 420A: Chapter 2, Mutual Exclusion

Two-Thread vs *n*-Thread Solutions

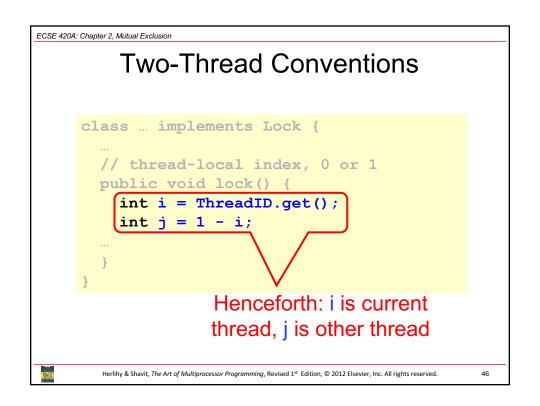
- · 2-thread solutions first
 - Illustrate most basic ideas
 - Fits on one slide
- Then *n*-thread solutions



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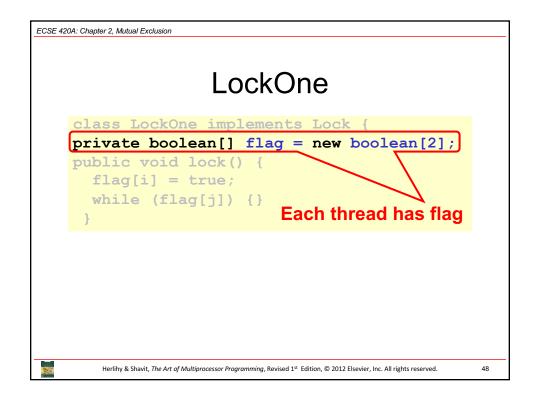
```
Two-Thread Conventions

class ... implements Lock {
    ...
    // thread-local index, 0 or 1
    public void lock() {
        int i = ThreadID.get();
        int j = 1 - i;
    ...
    }
}
```



```
LockOne

class LockOne implements Lock {
  private boolean[] flag = new boolean[2];
  public void lock() {
    flag[i] = true;
    while (flag[j]) {}
  }
}
```



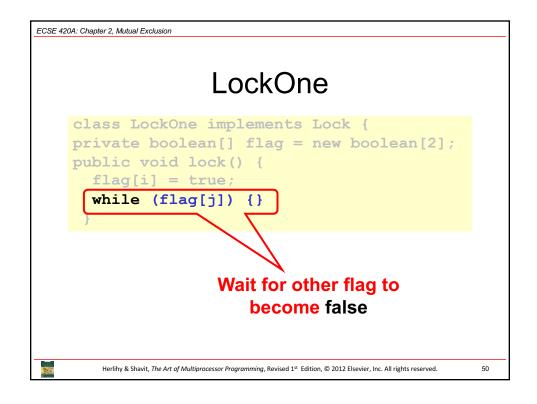
```
LockOne

class LockOne implements Lock {
    private boolean[] flag = new boolean[2];
    public void lock() {
        flag[i] = true;
        while (flag[j]) {}
    }

Set my flag

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```



LockOne Satisfies Mutual Exclusion

- Assume CS_A^j overlaps CS_B^k
- · Consider each thread's last
 - $-(j^{th}$ and $k^{th})$ read and write ...
 - in lock () before entering
- Derive a contradiction



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From the Code

- write_A(flag[A]=true) → read_A(flag[B]==false) → CS_A
- write_B(flag[B]=true) → read_B(flag[A]==false) → CS_B

```
class LockOne implements Lock {
...
public void lock() {
  flag[i] = true;
  while (flag[j]) {}
}
```

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From the Assumption

- read_A(flag[B]==false) → write_B(flag[B]=true)
- read_B(flag[A]==false) → write_A(flag[A]=true)



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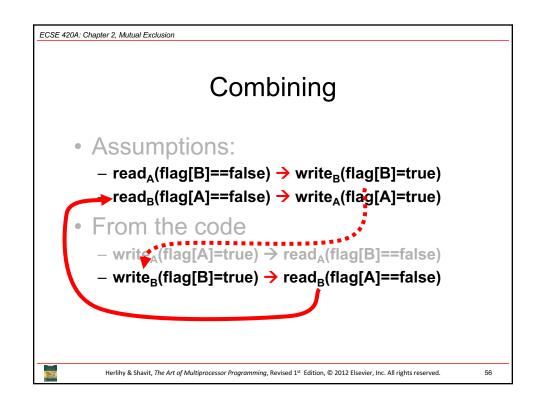
ECSE 420A: Chapter 2, Mutual Exclusion

Combining

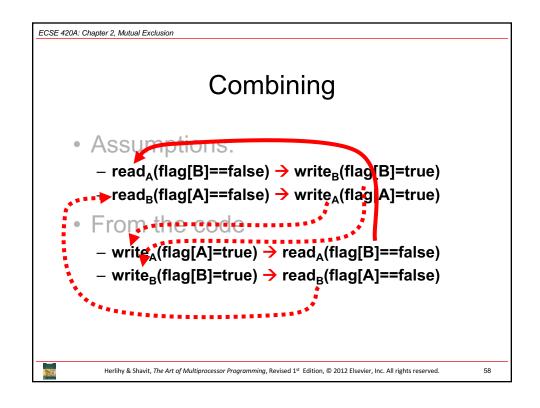
- Assumptions:
 - $read_A(flag[B]==false)$ → write_B(flag[B]=true)
 - $read_B(flag[A]==false)$ → write_A(flag[A]=true)
- From the code
 - write_A(flag[A]=true) → read_A(flag[B]==false)
 - write_B(flag[B]=true) → read_B(flag[A]==false)



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```
Combining \\ \bullet Assumptions: \\ - read_A(flag[B]==false) \rightarrow write_B(flag[B]=true) \\ - read_B(flag[A]==false) \rightarrow write_A(flag[A]=true) \\ \hline \bullet From the code \\ - write_A(flag[A]=true) \rightarrow read_A(flag[B]==false) \\ - write_B(flag[B]=true) \rightarrow read_B(flag[A]==false) \\ \hline \bullet Herlihy \& Shavit, \textit{The Art of Multiprocessor Programming, Revised 1st Edition, © 2012 Elsevier, Inc. All rights reserved.}
```



```
Combining

• Assumptions.

- read_A(flag[B]==false) > write_B(flag[B]=true)

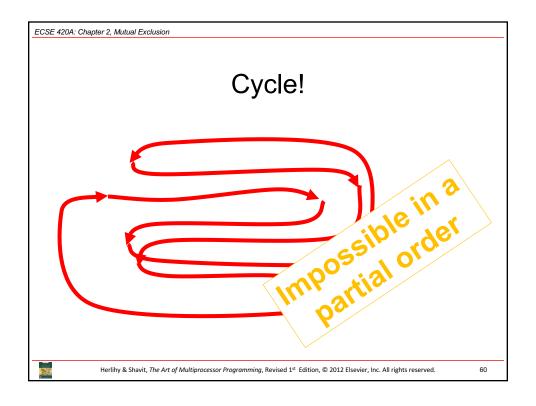
- read_B(flag[A]==false) > write_A(flag A]=true)

• From the code

- write_A(flag[A]=true) > read_A(flag[B]==false)

- write_B(flag[B]=true) > read_B(flag[A]==false)

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```



Deadlock Freedom

- LockOne Fails deadlock-freedom
 - Concurrent execution can deadlock

```
flag[i] = true; flag[j] = true;
while (flag[j]){} while (flag[i]){}
```

- Sequential executions OK



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LockTwo

```
public class LockTwo implements Lock {
  private int victim;
  public void lock() {
    victim = i;
    while (victim == i) {};
}

public void unlock() {}
}
```

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```
LockTwo

public class LockTwo implements Lock {
    private int victim;
    public void lock() {
        victim = i;
        while (victim == i) {};
    }

public void unlock() {
}

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```

```
LockTwo

public class Lock2 implements Lock {
    private int victim;
    public void lock() {
        victim = i;
        while (victim == i) {};
    }

public void unlock() {}

Public void unlock() {}

Public void interview () {}

Public void int
```

LockTwo Claims

• Satisfies mutual exclusion

- If thread i in CS

- Then victim == j

- Cannot be both 0 and 1

• Not deadlock free

- Sequential execution deadlocks

- Concurrent execution does not

Peterson's Algorithm

```
public void lock() {
  flag[i] = true;
  victim = i;
  while (flag[j] && victim == i) {};
}
public void unlock() {
  flag[i] = false;
}
```

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Peterson's Algorithm

Announce I'm interested

```
public void lock()
flag[i] = true;
victim = i;
while (flag[j] && victim == i) {};
}
public void unlock() {
 flag[i] = false;
}
```

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```
Peterson's Algorithm

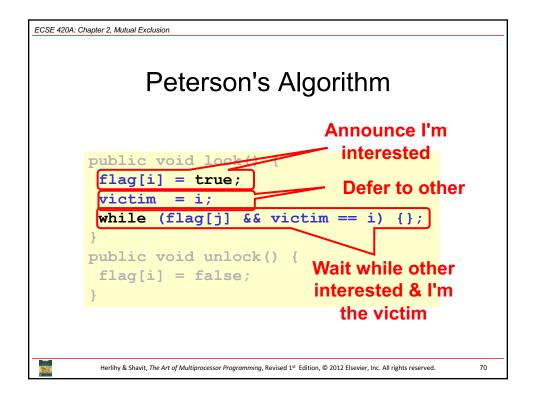
Announce I'm interested flag[i] = true;

victim = i;

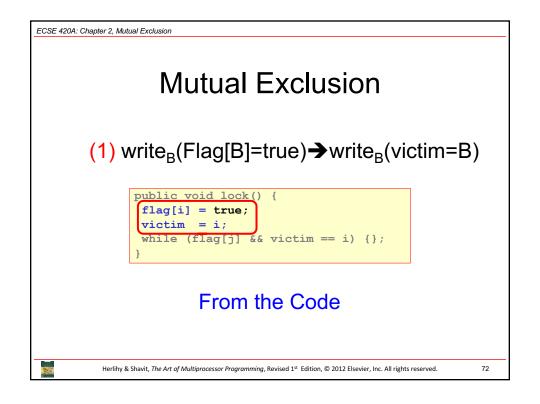
while (flag[j] && victim == i) {};

public void unlock() {
 flag[i] = false;
}

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```



```
ECSE 420A: Chapter 2, Mutual Exclusion
             Peterson's Algorithm
                                  Announce I'm
                                    interested
      public void lock
       flag[i] = true;
                                     Defer to other
                        && victim == i) {};
       while (flag[j]
      public void unlock() {
                                 Wait while other
       flag[i] = false;
                                 interested & I'm
                 No longer
                                    the victim
                interested
```



Also from the Code

(2) write_A(victim=A)→read_A(flag[B])
→read_A(victim)

```
public void lock() {
  flag[i] = true:
  victim = i;
  while (flag[j] && victim == i) {};
}
```



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Assumption

(3) write_B(victim=B) \rightarrow write_A(victim=A)

W.L.O.G. assume A is the last thread to write **victim**



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Combining Observations

- (1) write_B(flag[B]=true) \rightarrow write_B(victim=B)
- (3) write_B(victim=B) \rightarrow write_A(victim=A)
- (2) write_A(victim=A)→read_A(flag[B])
 → read_A(victim)

.

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ECSE 420A: Chapter 2, Mutual Exclusion

Combining Observations

- (1) write_B(flag[B]=true)→
- (3) write_B(victim=B)→
- (2) write_A(victim=A)→read_A(flag[B])
 → read_A(victim)

-

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```
Combining Observations

(1) write<sub>B</sub>(flag[B]=true)→

(3) write<sub>B</sub>(victim=B)→

(2) write<sub>A</sub>(victim=A)→read<sub>A</sub>(flag[B])

→ read<sub>A</sub>(victim)

A read flag[B] == true and victim == A, so it could not have entered the CS (QED)

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```

Deadlock Free

public void lock() {
...
 while (flag[j] && victim == i) {};

• Thread blocked
 - only at while loop
 - only if other's flag is true
 - only if it is the victim
• Solo: other's flag is false
• Both: one or the other not the victim

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Starvation Free

 Thread i blocked only if j repeatedly re-enters so that

```
flag[j] == true and
victim == i
```

- When j re-enters
 - it sets victim to j.
 - So i gets in

```
public void lock() {
   flag[i] = true;
   victim = i;
   while (flag[j] && victim == i) {};
}

public void unlock() {
   flag[i] = false;
}
```



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ECSE 420A: Chapter 2, Mutual Exclusion

The Filter Algorithm for *n*Threads

There are *n*-1 "waiting rooms" called levels

- · At each level
 - At least one enters level
 - At least one blocked if many try



Only one thread makes it through



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```
Filter

class Filter implements Lock {
   int[] level; // level[i] for thread i
   int[] victim; // victim[L] for level L

public Filter(int n) {
   level = new int[n];
   victim = new int[n];
   for (int i = 1; i < n; i++) {
      level[i] = 0;
   }}

...
}

Thread 2 at level 4

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```

```
Filter

class Filter implements Lock {

...

public void lock() {

for (int L = 1; L < n; L++) {

level[i] = L;

victim[L] = i;

while ((∃ k != i level[k] >= L) &&

victim[L] == i ) {};

}

public void unlock() {

level[i] = 0;

}}
```

```
Filter

class Filter implements Lock {
...

proble void lock() {
    for (int L = 1; L < n; L++) {
        level[i] = L;
        victim[L] = i;
        while ((∃ k != i) level[k] >= L) &&
            victim[L] == i) {};
    }
    public void release(int i) {
        level[i] = 0;
    }

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```

```
Filter

class Filter implements Lock {

...

public void lock() {

for (int L = 1; L < n; L++) {

level[i] = L;

victim[L] |

while ((∃ k != i) | xel[k] >= L) &&

victim[L] == i) | Announce

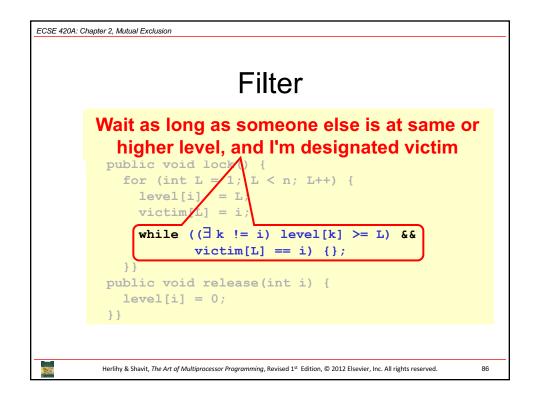
}

public void release(int i) intention to enter

level[i] = 0; | level L

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```

```
ECSE 420A: Chapter 2, Mutual Exclusion
                           Filter
       class Filter implements Lock {
         int level[n];
         int victim[n];
         public void lock() {
           for (int L = 1; L < n; L++) {
             level[i] = L;
             victim[L] = i;
                              () level[k] >= L) &&
                                == i) {};
           } }
                                         Give priority to
         public void release(int i)
           level[i] = 0;
                                         anyone but me
```



```
Filter

class Filter implements Lock {
   int level[n];
   int victim[n];
   public void lock() {
     for (int L = 1; L < n; L++) {
        level[i] = L;
        victim[L] = i;

   while ((∃ k != i) level[k] >= L) &&
        victim[L] == i) {};

Thread enters level L when it completes the loop

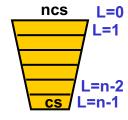
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```

Claim

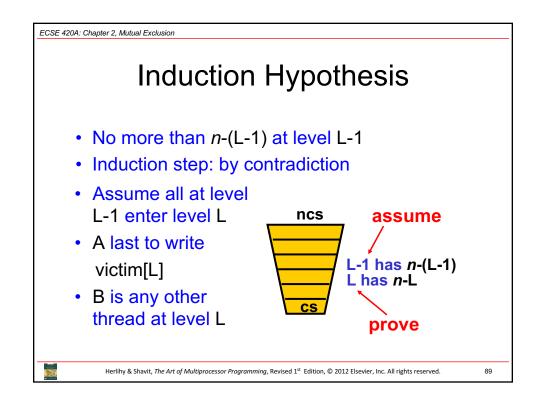
• Start at level L=0

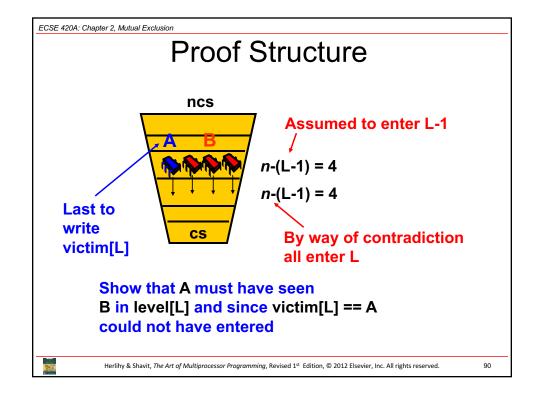
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- At most n-L threads enter level L
- Mutual exclusion at level L=n-1



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Just Like Peterson

(1) write_B(level[B]=L) \rightarrow write_B(victim[L]=B)

```
public void lock() {
  for (int L = 1; L < n; L++) {
    level[i] = L;
    victim[L] = i;
    while ((∃ k != i) level[k] >= L)
          && victim[L] == i) {};
}
```

From the Code



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From the Code

(2) write_A(victim[L]=A)→read_A(level[B]) →read_A(victim[L])

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By Assumption

(3) $write_B(victim[L]=B) \rightarrow write_A(victim[L]=A)$

By assumption, A is the last thread to write **victim[L]**



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Combining Observations

- (1) write_B(level[B]=L) \rightarrow write_B(victim[L]=B)
- (3) write_B(victim[L]=B) \rightarrow write_A(victim[L]=A)
- (2) write_A(victim[L]=A)→read_A(level[B])
 →read_A(victim[L])



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Combining Observations

- (1) write_B(level[B]=L)→
- (3) write_B(victim[L]=B) \rightarrow write_A(victim[L]=A)
- (2) → read_A(level[B])
 → read_A(victim[L])

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Combining Observations

- (1) write_B(level[B]=L)→
- (3) write_B(victim[L]=B) \rightarrow write_A(victim[L]=A)

 $read_{A}(level[B])$ $read_{A}(victim[L])$

A read level[B] ≥ L, and victim[L] = A, so it could not have entered level L!

.

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No Starvation

- Filter Lock satisfies properties:
 - Just like Peterson Alg at any level
 - So no one starves
- But what about fairness?
 - Threads can be overtaken by others



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Bounded Waiting

- Want stronger fairness guarantees
- Thread not "overtaken" too much
- If A starts before B, then A enters before B?
- But what does "start" mean?
- Need to adjust definitions



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Bounded Waiting

- Divide lock () method into 2 parts:
 - Doorway interval:
 - Written DA
 - · always finishes in finite steps
 - Waiting interval:
 - Written WA
 - may take unbounded steps



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gc

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r-Bounded Waiting

- For threads A and B:
 - $If D_A^k \rightarrow D_B^j$
 - A's k-th doorway precedes B's j-th doorway
 - Then CS_A^k → CS_B^{j+r}
 - A's k-th critical section precedes B's j+r-th critical section
 - · B cannot overtake A more than r times
- First-come-first-served → r = 0



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What is "r" for Peterson's Algorithm?

```
public void lock() {
  flag[i] = true;
  victim = i;
  while (flag[j] && victim == i) {};
}
public void unlock() {
  flag[i] = false;
}
```

Answer: r = 0



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What is "r" for the Filter Algorithm?

Answer: there is no value of "r"



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First-Come-First-Served

- For threads A and B:
 - $\text{If } D_A^k \rightarrow D_B^j$
 - A's k-th doorway precedes B's j-th doorway
 - Then CS_A^k → CS_B^j
 - A's k-th critical section precedes B's j-th critical section
 - · B cannot overtake A



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Fairness

- Filter Lock satisfies properties:
 - No one starves
 - But very weak fairness
 - Can be overtaken arbitrary # of times
 - So being fair is stronger than avoiding starvation
 - And filter is pretty lame…



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Bakery Algorithm

- Provides First-Come-First-Served for n threads
- · How?
 - Take a "number"
 - Wait until lower numbers have been served
- Lexicographic order
 - -(a,i) > (b,j)
 - If a > b, or a = b and i > j



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Bakery Algorithm

```
class Bakery implements Lock {
  boolean[] flag;
  Label[] label;
public Bakery (int n) {
  flag = new boolean[n];
  label = new Label[n];
  for (int i = 0; i < n; i++) {
    flag[i] = false; label[i] = 0;
  }
}</pre>
```

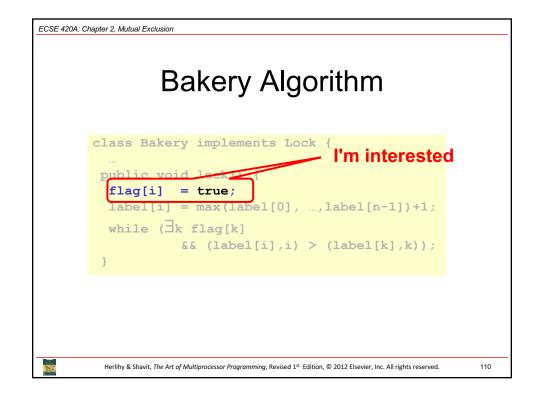
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```
Bakery Algorithm

class Bakery implements Lock {
boolean[] flag;
Label[] label;
public Bakery (int n) {
  flag = new boolean[n];
  label = new Label[n];
  for (int i = 0; i < n; i++) {
    flag[i] = false; label[i] = 0;
  }
}

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```



```
Bakery Algorithm

Take increasing label (read labels in some arbitrary public void lock() {

In some arbitrary order)

Iabel[i] = true:

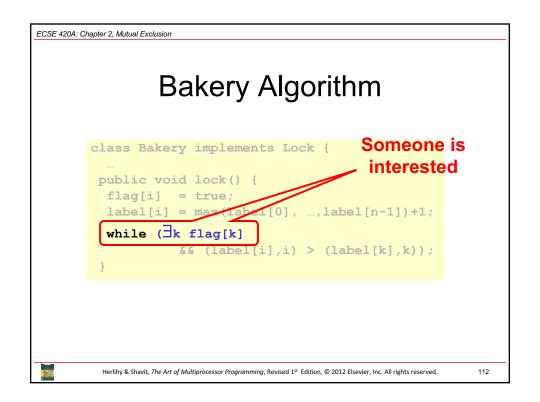
Iabel[i] = max(label[0], ...,label[n-1])+1;

While (∃k flag[k]

&& (label[i],i) > (label[k],k));

}

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```



```
Bakery Algorithm

class Bakery implements Lock {
  boolean flag[n];
  int label[n];
  interested ...

public void lock() {
  flag[i] = true;
  label[i] = max(abel[i], ..., label[n-1])+1;
  while (∃k flag[k])

... whose (label,i) in
  lexicographic order is lower

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```

```
Bakery Algorithm

class Bakery implements Lock {

...

public void unlock() {
 flag[i] = false;
 }
}

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```

```
Bakery Algorithm

class Bakery implements Lock {
    No longer interested

public void flag[i] = false;
}

labels are always increasing

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```

No Deadlock

• There is always one thread with earliest label
• Ties are impossible (why?)

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First-Come-First-Served

class Bakery implements Lock {

label[i] = max(label[0],

&& (label[i],i) > (label[k],k));

public void lock() {
 flag[i] = true;

while $(\exists k \text{ flag}[k]$

- If D_A → D_B then
 - A's label is smaller
- And:
 - write_A(label[A]) →
 - read_B(label[A]) →
 - write_B(label[B]) → read_B(flag[A])
- So B sees
 - smaller label for A
 - locked out while flag[A] is true



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Mutual Exclusion

- Suppose A and B in CS together
- Suppose A has earlier label
- When B entered, it must have seen
 - flag[A] is false, or
 - label[A] > label[B]

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Mutual Exclusion

- · Labels are strictly increasing so
- B must have seen flag[A] == false



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Mutual Exclusion

- · Labels are strictly increasing so
- B must have seen flag[A] == false
- Labeling_B → read_B(flag[A]) → write_A(flag[A]) → Labeling_A



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Mutual Exclusion

- · Labels are strictly increasing so
- B must have seen flag[A] == false
- Labeling_B → read_B(flag[A]) → write_A(flag[A]) → Labeling_A
- Which contradicts the assumption that A has an earlier label

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Bakery Y232K Bug

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Does Overflow Actually Matter?

- Yes
 - Y2K
 - 18 January 2038 (Unix time_t rollover)
 - 16-bit counters
- No
 - 64-bit counters
- Maybe
 - 32-bit counters

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Timestamps

- Label variable is really a timestamp
- · Need ability to
 - Read others' timestamps
 - Compare them
 - Generate a later timestamp
- Can we do this without overflow?



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The Good News

- One can construct a
 - Wait-free (no mutual exclusion)
 - Concurrent
 - Timestamping system
 - That never overflows



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Instead ...

- We construct a Sequential timestamping system
 - Same basic idea
 - But simpler
- As if we use mutex to read & write atomically
- No good for building locks
 - But useful anyway

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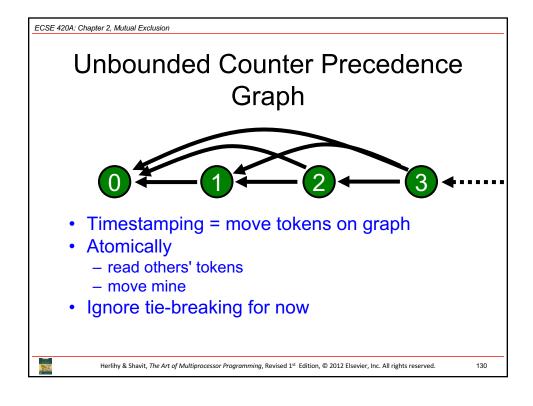
Precedence Graphs

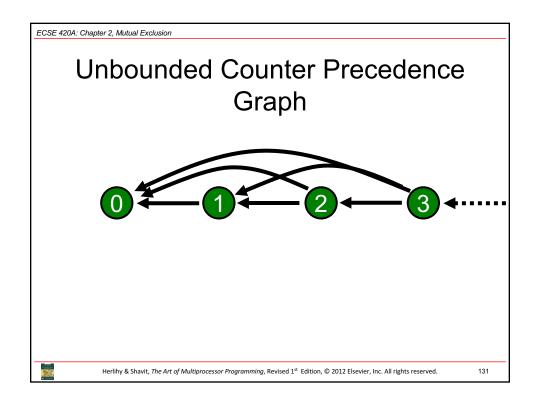
Timestamps form directed graph

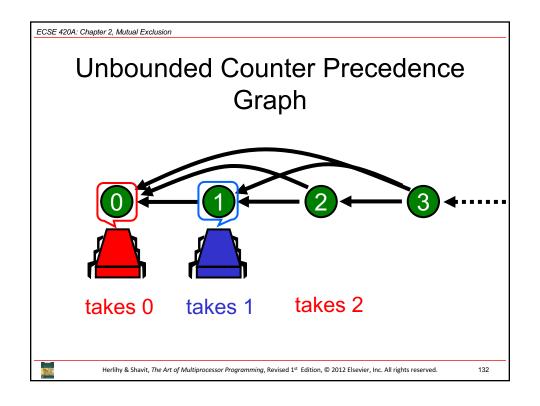
Edge x to y

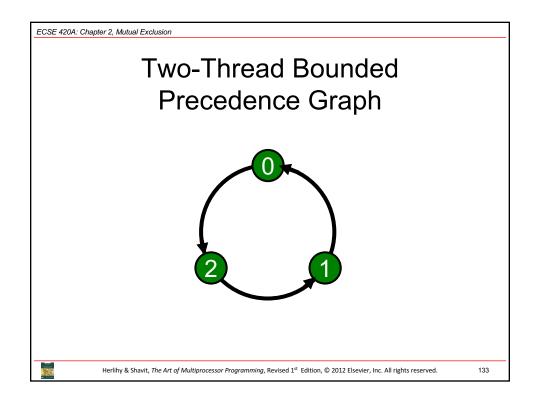
Means x is later timestamp

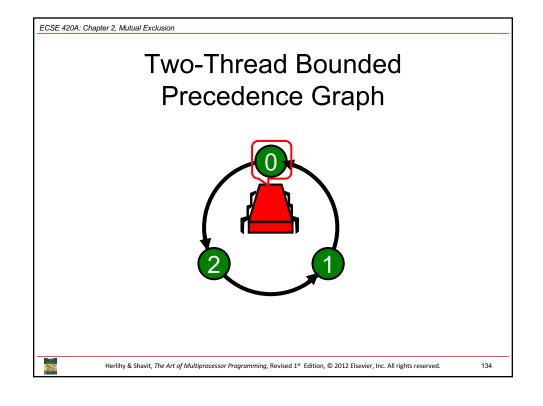
We say x dominates y

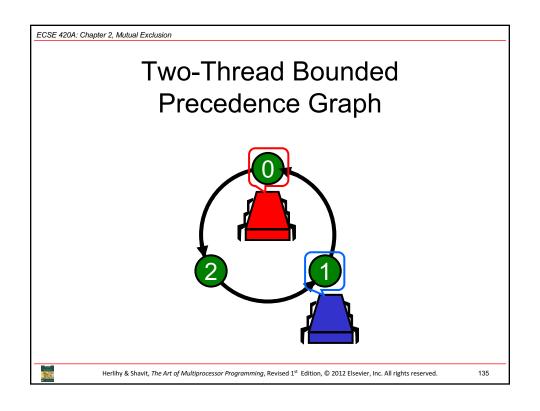


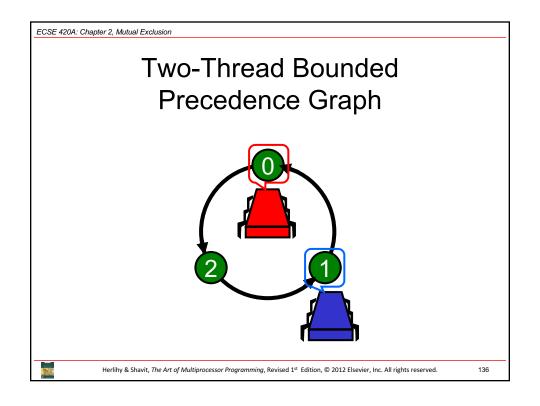


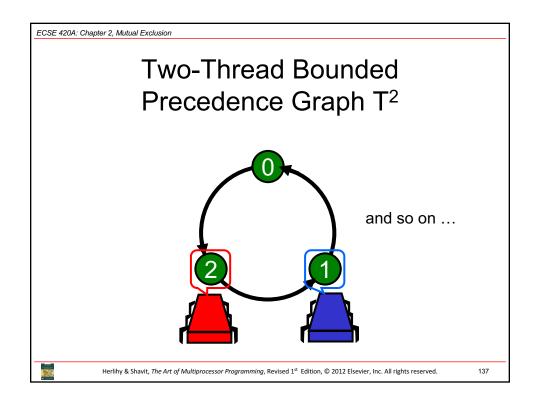


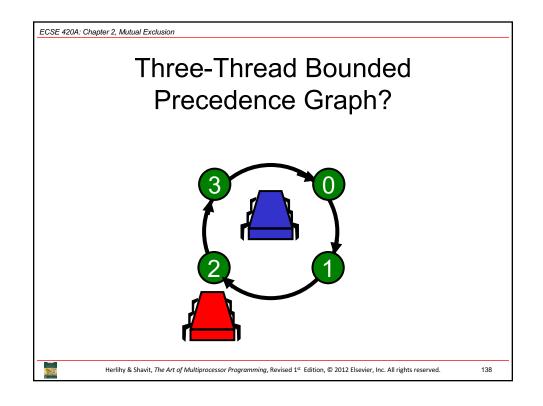


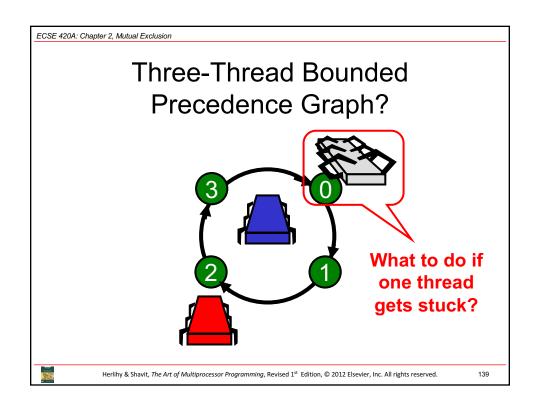


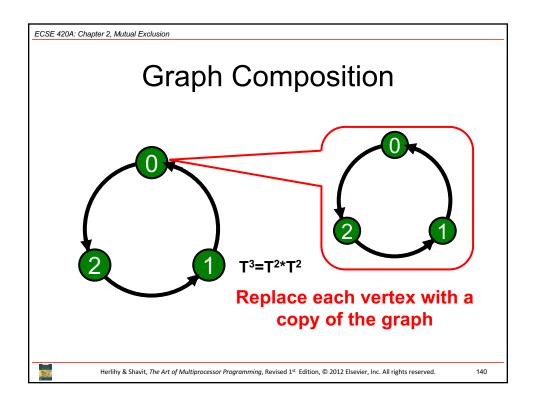


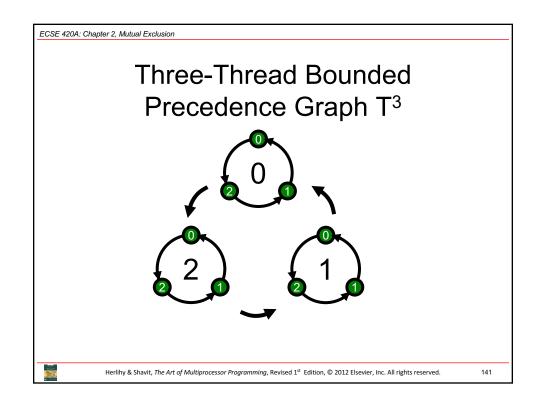


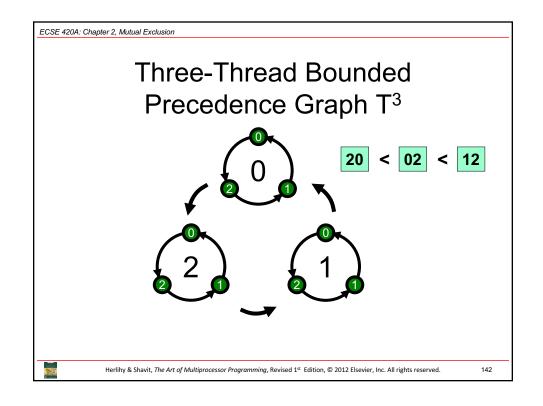


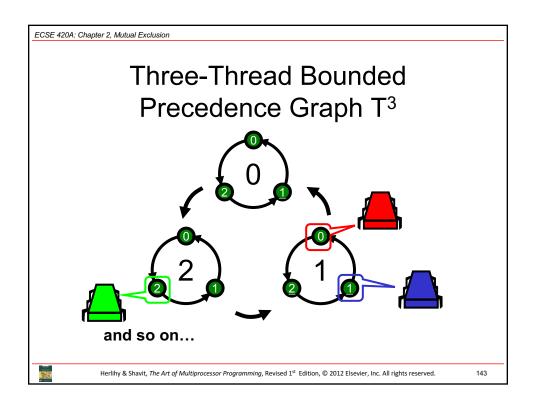


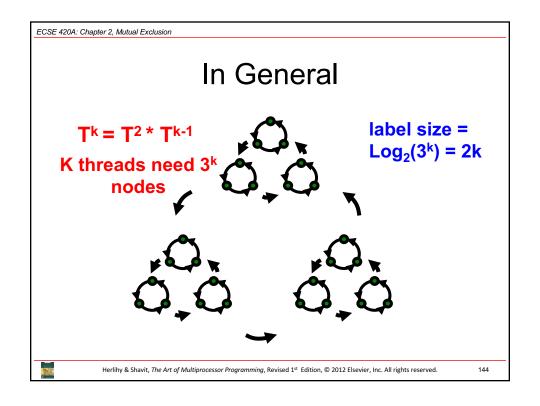












Deep Philosophical Question

- · The Bakery Algorithm is
 - Succinct,
 - Elegant, and
 - Fair.
- Q: So why isn't it practical?
- A: Well, you have to read N distinct variables



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ECSE 420A: Chapter 2, Mutual Exclusion

Shared Memory

- Shared read/write memory locations called Registers (historical reasons)
- Come in different flavors
 - Multi-Reader-Single-Writer (flag[])
 - Multi-Reader-Multi-Writer (victim[])
 - Not that interesting: SRMW and SRSW



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Theorem

At least N MRSW (multi-reader/single-writer) registers are needed to solve deadlock-free mutual exclusion.

N registers such as flag[]...



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ECSE 420A: Chapter 2, Mutual Exclusion

Proving Algorithmic Impossibility

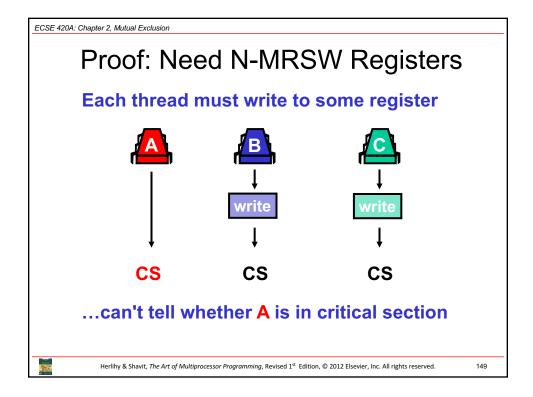
- •To show no algorithm exists:
 - assume by way of contradiction one does,
 - show a bad execution that violates properties:
 - in our case assume an alg for deadlock free mutual exclusion using < N registers



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Upper Bound

- Bakery algorithm
 - Uses **2N** MRSW registers
- So the bound is (pretty) tight
- But what if we use MRMW registers?
 - -Like victim[] ?



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Bad News Theorem

At least N MRMW multireader/multi-writer registers are needed to solve deadlock-free mutual exclusion.

(So multiple writers don't help)



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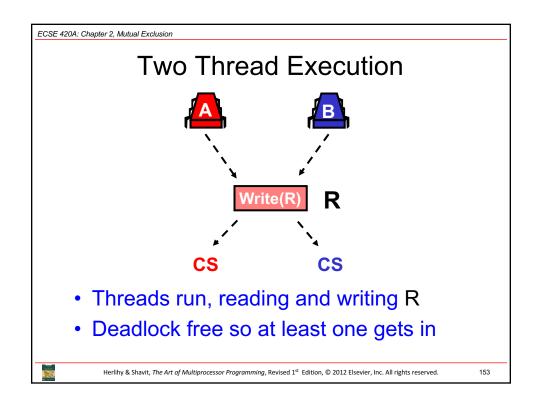
Theorem (For 2 Threads)

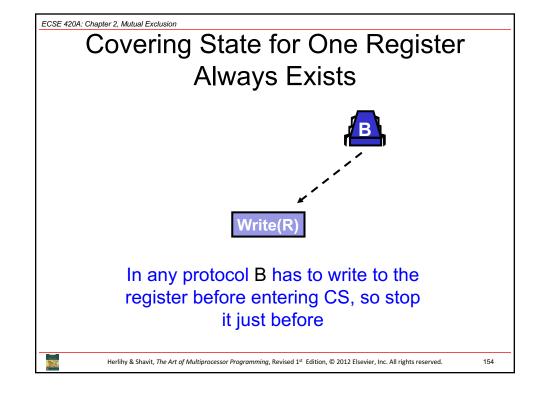
Theorem: Deadlock-free mutual exclusion for 2 threads requires at least 2 multi-reader multi-writer registers

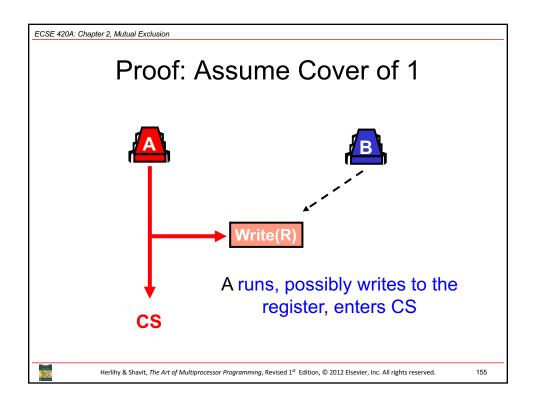
Proof: assume one register suffices and derive a contradiction

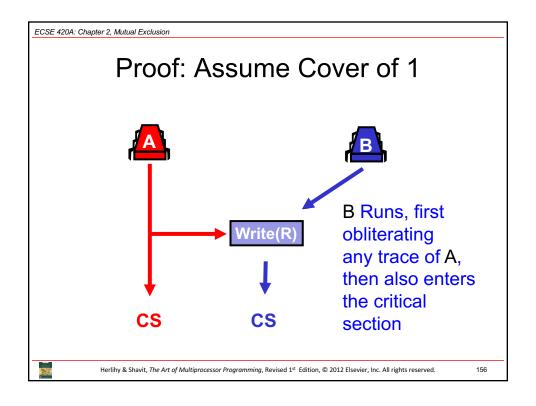


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Theorem

Deadlock-free mutual exclusion for 3 threads requires at least 3 multi-reader multi-writer registers



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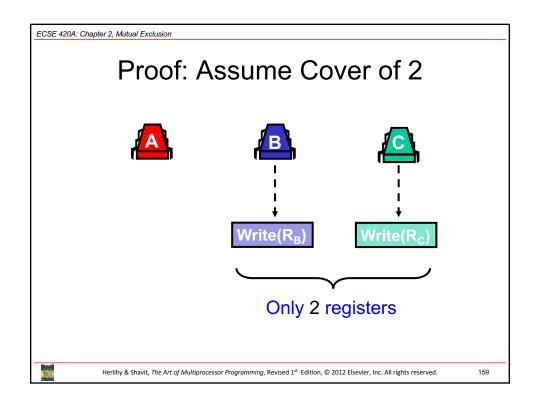
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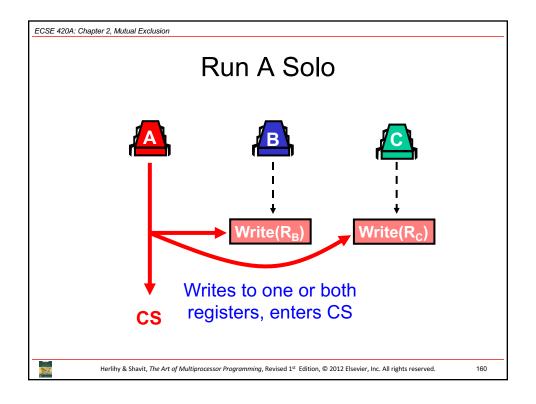
Theorem

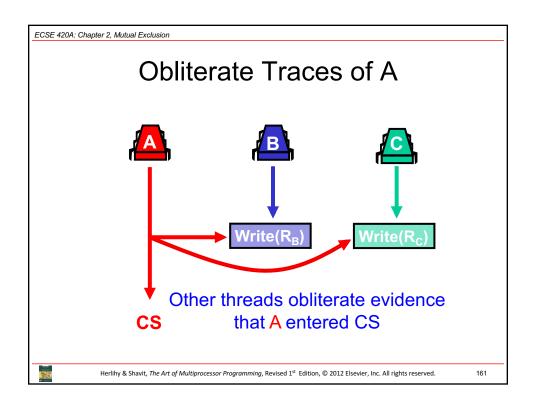
Deadlock-free mutual exclusion for *n* threads requires at least *n* multi-reader multi-writer registers

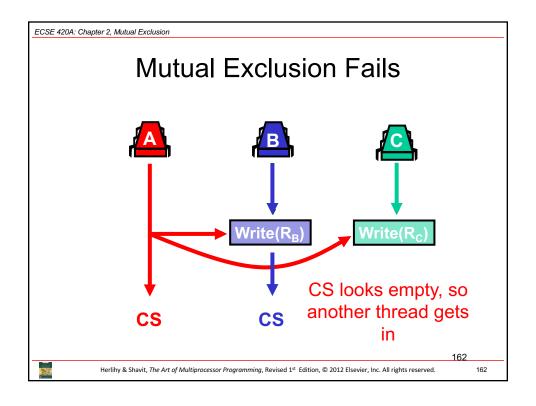


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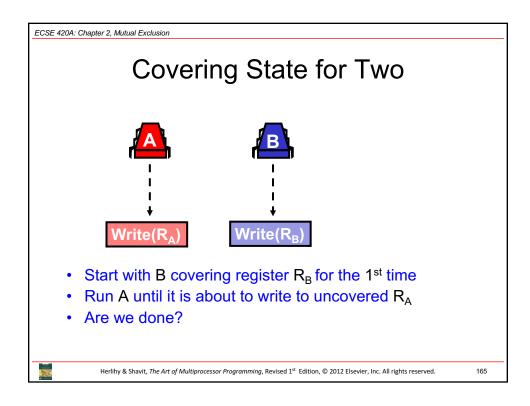
Proof Strategy

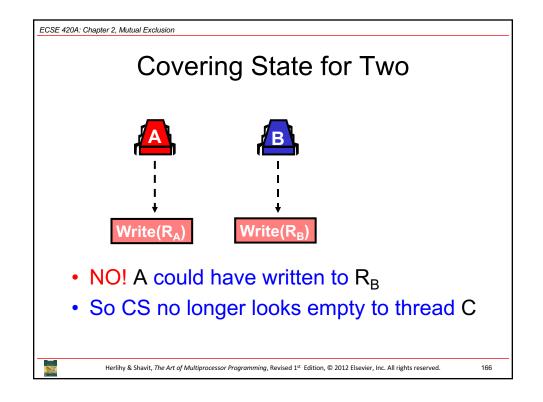
- Proved: a contradiction starting from a covering state for 2 registers
- Claim: a covering state for 2 registers is reachable from any state where CS is empty

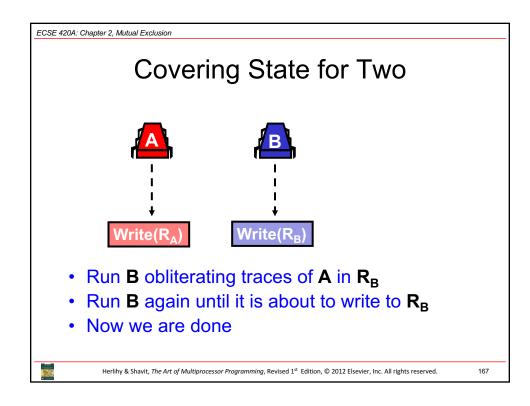
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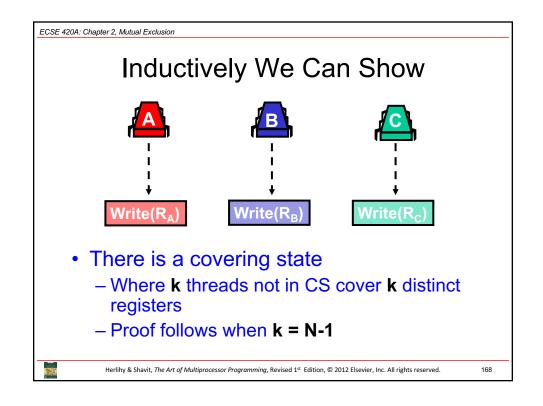
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Covering State for Two Write(R_A) • If we run B through CS 3 times, B must return twice to cover some register, say R_B Herlihy & Shavit, The Art of Multiprocessor Programming, Revised 1st Edition, © 2012 Elsevier, Inc. All rights reserved.









Summary of Lecture

- In the 1960's several incorrect solutions to starvation-free mutual exclusion using RW-registers were published...
- Today we know how to solve FIFO N thread mutual exclusion using 2N RW-Registers



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ECSE 420A: Chapter 2, Mutual Exclusion

Summary of Lecture

- N RW-Registers inefficient
 - Because writes "cover" older writes
- Need stronger hardware operations
 - that do not have the "covering problem"
- In next lectures understand what these operations are...



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