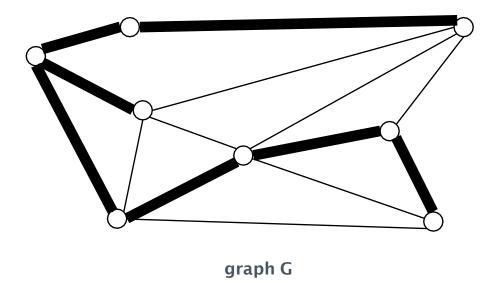
# CS2010: Data Structures and Algorithms II

Minimum Spanning Trees

Ivana.Dusparic@scss.tcd.ie

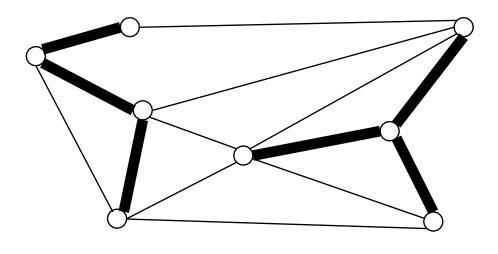
A spanning tree of G is a subgraph T that is:

- Connected.
- Acyclic.
- Includes all of the vertices.



Def. A spanning tree of *G* is a subgraph *T* that is:

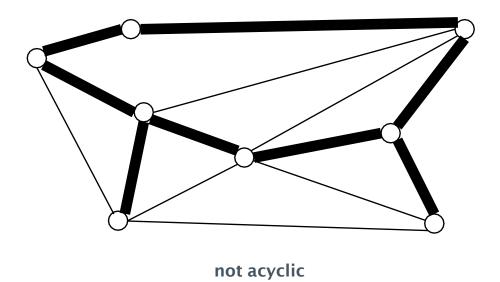
- Connected.
- Acyclic.
- Includes all of the vertices.



not connected

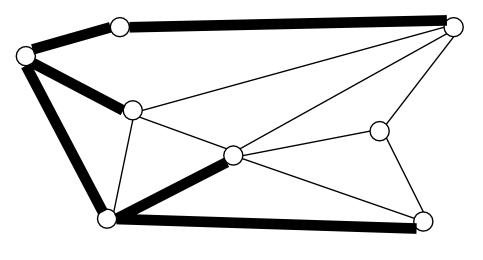
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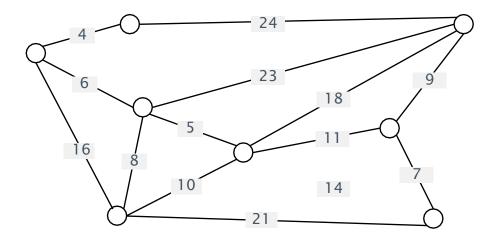


not spanning

### Minimum spanning tree

Given. Undirected graph *G* with positive edge weights (connected).

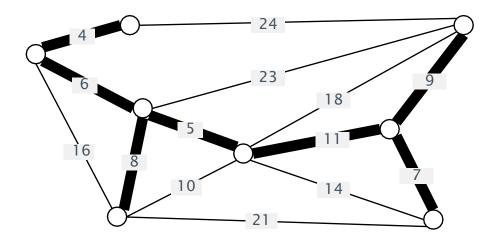
Goal. Find a min weight spanning tree.



edge-weighted graph G

### Minimum spanning tree

Given. Undirected graph *G* with positive edge weights (connected). Goal. Find a min weight spanning tree.



minimum spanning tree T  $(\cos t = 50 = 4 + 6 + 8 + 5 + 11 + 9 + 7)$ 

Brute force. Try all spanning trees?

### **Applications**

- Network design (communication, electrical, hydraulic, computer, road etc)
- > Clustering
- > Approximation algorithms (eg TSP)
- Many others classification in biology, sociology, face verification, hand writing detection etc

### MST question – Turning Point

- Let G be a connected, edge-weighted graph with V vertices and E edges. How many edges are in a minimum spanning tree of G?
  - V
  - -V-1
  - E
  - E-1

# Algorithms

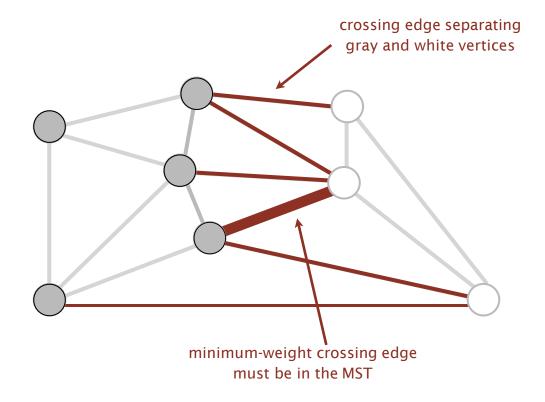
- > Greedy algorithms
  - Prim's
  - Kruskal's

### Cut property

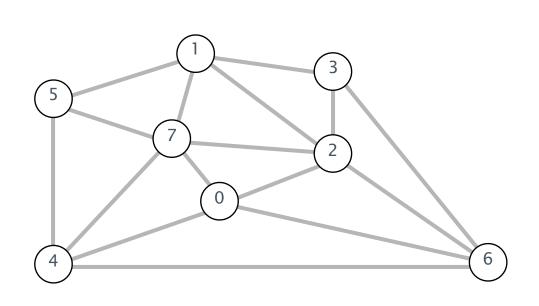
Def. A cut in a graph is a partition of its vertices into two (nonempty) sets.

Def. A crossing edge connects a vertex in one set with a vertex in the other.

Cut property. Given any cut, the crossing edge of min weight is in the MST.



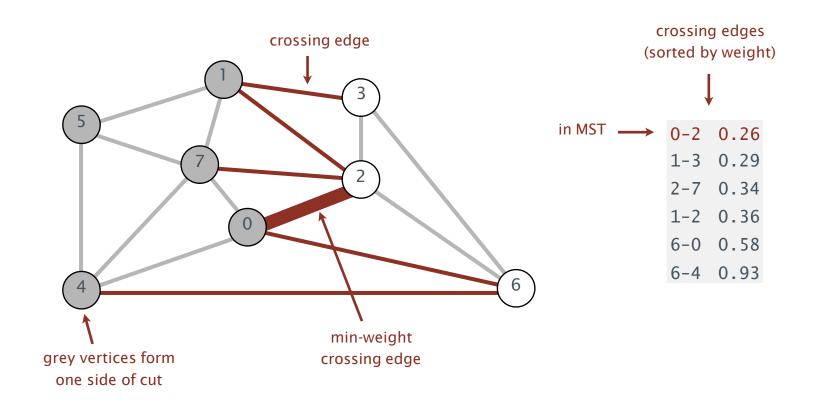
- Start with all edges colored gray.
- Find cut with no black crossing edges; color its min-weight edge black.
- Repeat until V-1 edges are colored black.



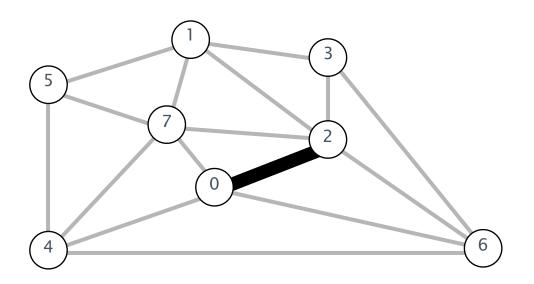
an edge-weighted graph

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2-3	0.17
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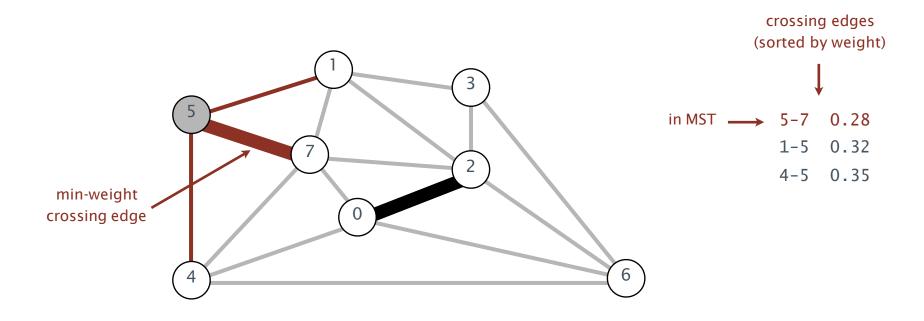


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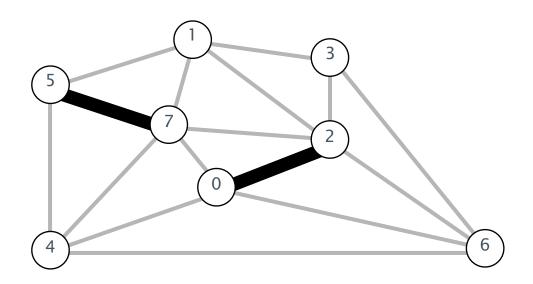


MST edges

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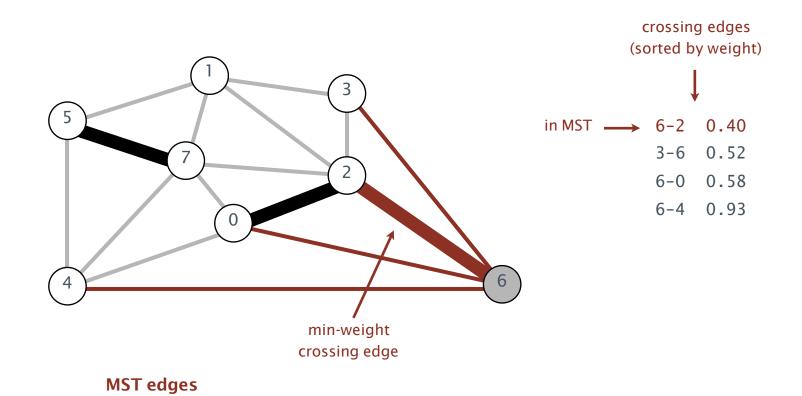
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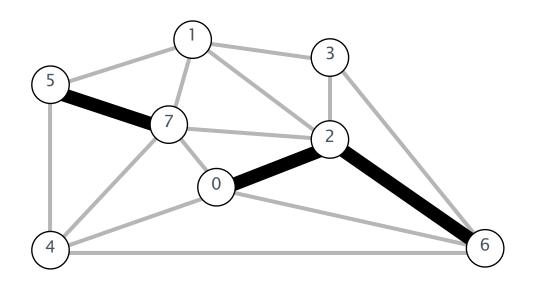
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0-2 5-7

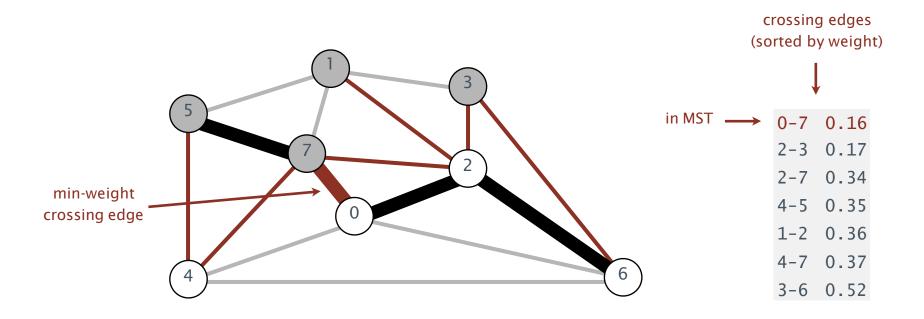


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#### MST edges

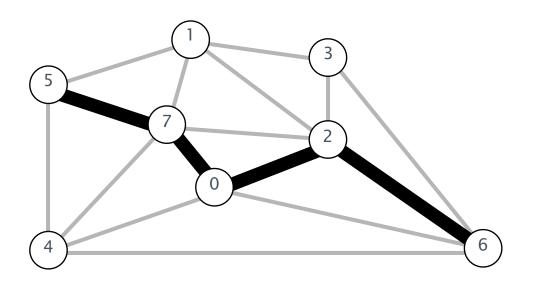
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MST edges

0-2 5-7 6-2

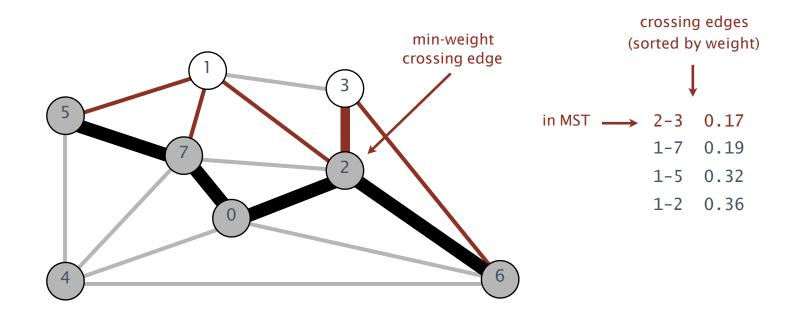
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#### MST edges

0-2 5-7 6-2 0-7

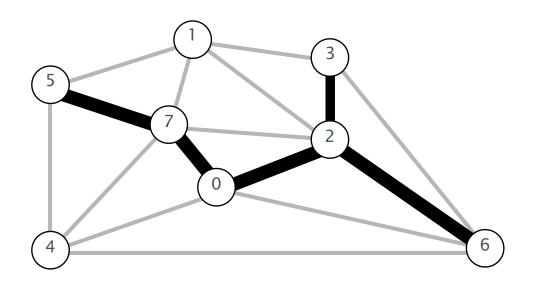
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#### **MST** edges

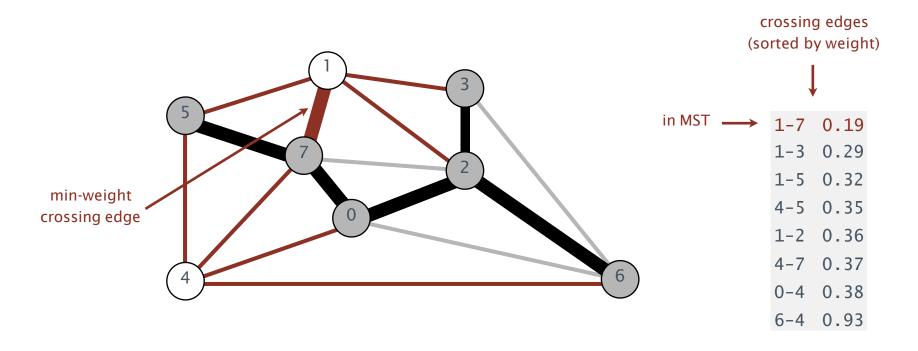
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#### MST edges

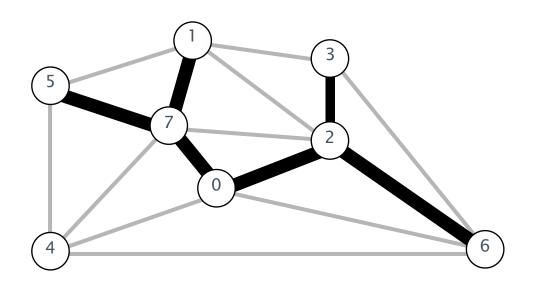
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#### **MST edges**

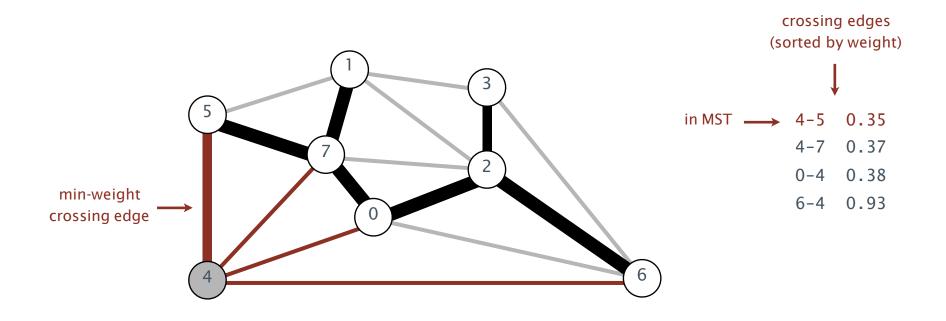
0-2 5-7 6-2 0-7 2-3

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#### MST edges

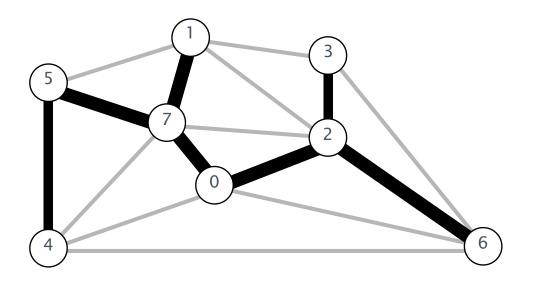
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#### **MST edges**

0-2 5-7 6-2 0-7 2-3 1-7

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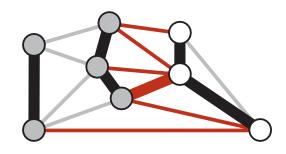
#### MST edges

Greedy MST algorithm: correctness proof

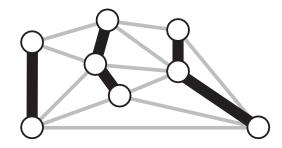
Proposition. The greedy algorithm computes the MST.

#### Pf.

- Any edge colored black is in the MST (via cut property).
- Fewer than V-1 black edges  $\Rightarrow$  cut with no black crossing edges. (consider cut whose vertices are any one connected component)



a cut with no black crossing edges



fewer than V-1 edges colored black

- Q. What if edge weights are not all distinct?
- A. Greedy MST algorithm still correct if equal weights are present! (our correctness proof fails, but that can be fixed)

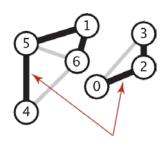


1	2	1.00
1	3	0.50
2	4	1.00
3	4	0.50



1	2	1.00
1	3	0.50
2	4	1.00
3	4	0.50

- Q. What if graph is not connected?
- A. Compute minimum spanning forest = MST of each component.



can independently compute MSTs of components

4	5	0.6
		1
4	6	0.6
		2
5	6	0.8
		8
1	5	0.1
		1
2	3	0.3
		5
0	3	0.6
1	6	0.1
		0
0	2	0.2
		2

### Greedy MST algorithm: efficient implementations

### Efficient implementations.

How to choose cut? How to find min-weight edge?

- Ex 1. Kruskal's algorithm.
- Ex 2. Prim's algorithm.
- Ex 3. Borüvka's algorithm.

# Weighted-edge graph API, Edge API

### Adjacency-lists graph representation (review): Java implementation

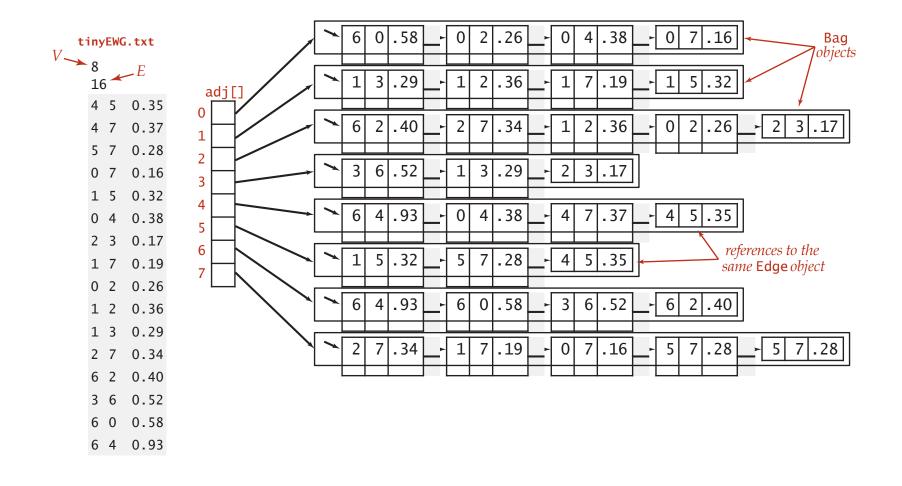
```
public class Graph
   private final int V;
                                                     adjacency lists
   private final Bag<Integer>[] adj;
   public Graph(int V)
                                                     create empty graph
                                                     with V vertices
      this.V = V;
      adj = (Bag<Integer>[]) new Bag[V];
      for (int v = 0; v < V; v++)
         adj[v] = new Bag<Integer>();
                                                     add edge v-w
   public void addEdge(int v, int w)
      adj[v].add(w);
      adj[w].add(v);
                                                     iterator for vertices
   public Iterable<Integer> adj(int v)
                                                     adjacent to v
   { return adj[v]; }
```

### Edge-weighted graph: adjacency-lists implementation

```
public class EdgeWeightedGraph
   private final int V;
                                                        same as Graph, but adjacency
   private final Bag<Edge>[] adj;
                                                        lists of Edges instead of integers
   public EdgeWeightedGraph(int V)
                                                        constructor
      this.V = V;
      adj = (Bag<Edge>[]) new Bag[V];
      for (int v = 0; v < V; v++)
         adj[v] = new Bag<Edge>();
   public void addEdge(Edge e)
      int v = e.either(), w = e.other(v);
                                                        add edge to both
      adj[v].add(e);
                                                        adjacency lists
      adj[w].add(e);
   public Iterable<Edge> adj(int v)
   { return adj[v]; }
```

Edge-weighted graph: adjacency-lists representation

Maintain vertex-indexed array of Edge lists.



### Edge-weighted graph API

public class	EdgeWeightedGraph	
	EdgeWeightedGraph(int V)	create an empty graph with V vertices
	EdgeWeightedGraph(In in)	create a graph from input stream
void	addEdge(Edge e)	add weighted edge e to this graph
Iterable <edge></edge>	adj(int v)	edges incident to v
Iterable <edge></edge>	edges()	all edges in this graph
int	V()	number of vertices
int	E()	number of edges
String	toString()	string representation

# Weighted Edge API

Edge abstraction needed for weighted edges.

```
public class Edge implements Comparable<Edge>

Edge(int v, int w, double weight) create a weighted edge v-w

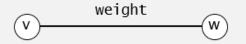
int either() either endpoint

int other(int v) the endpoint that's not v

int compareTo(Edge that) compare this edge to that edge

double weight() the weight

String toString() string representation
```



Idiom for processing an edge e: int v = e.either(), w = e.other(v);

### Weighted edge: Java implementation

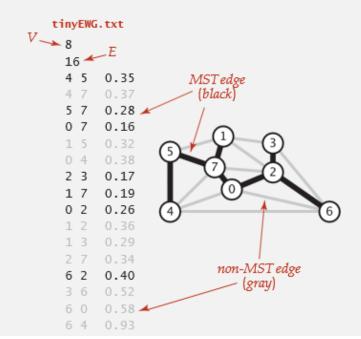
```
public class Edge implements Comparable<Edge>
   private final int v, w;
   private final double weight;
   public Edge(int v, int w, double weight)
                                                                  constructor
      this.v = v;
      this.w = w;
      this.weight = weight;
   public int either()
                                                                  either endpoint
   { return v; }
   public int other(int vertex)
      if (vertex == v) return w;
                                                                  other endpoint
      else return v;
   public int compareTo(Edge that)
              (this.weight < that.weight) return -1;</pre>
                                                                  compare edges by weight
      else if (this.weight > that.weight) return +1;
      else
                                            return 0;
```

## MST API

#### Minimum spanning tree API

#### Q. How to represent the MST?





% java MST tinyEWG.txt 0-7 0.16 1-7 0.19 0-2 0.26 2-3 0.17 5-7 0.28 4-5 0.35 6-2 0.40 1.81

#### Minimum spanning tree API

#### Q. How to represent the MST?

```
public class MST

MST(EdgeWeightedGraph G) constructor

Iterable<Edge> edges() edges in MST

double weight() weight of MST
```

```
public static void main(String[] args)
{
    In in = new In(args[0]);
    EdgeWeightedGraph G = new EdgeWeightedGraph(in);
    MST mst = new MST(G);
    for (Edge e : mst.edges())
        StdOut.println(e);
    StdOut.printf("%.2f\n", mst.weight());
}
```

```
% java MST tinyEWG.txt

0-7 0.16

1-7 0.19

0-2 0.26

2-3 0.17

5-7 0.28

4-5 0.35

6-2 0.40

1.81
```

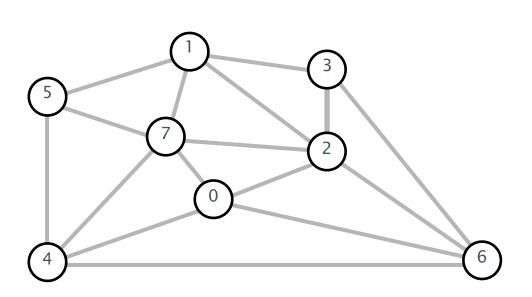
# Kruskal's algorithm

Consider edges in ascending order of weight.

Add next edge to tree T unless doing so would create a cycle.

graph edges sorted by weight

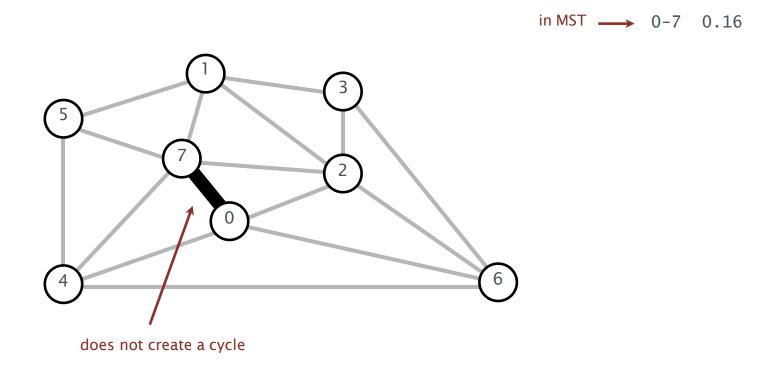




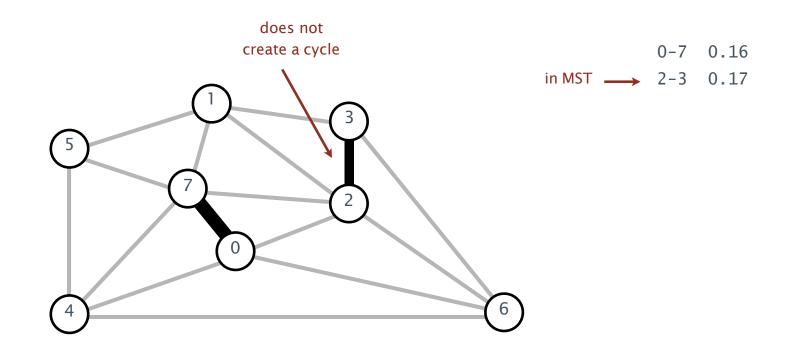
an edge-weighted graph

	<b>↓</b>
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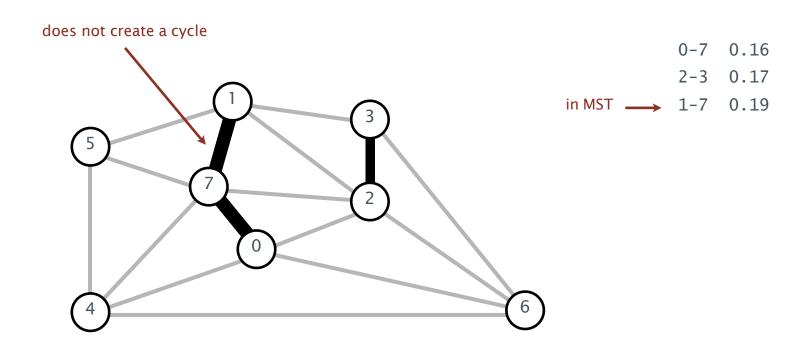
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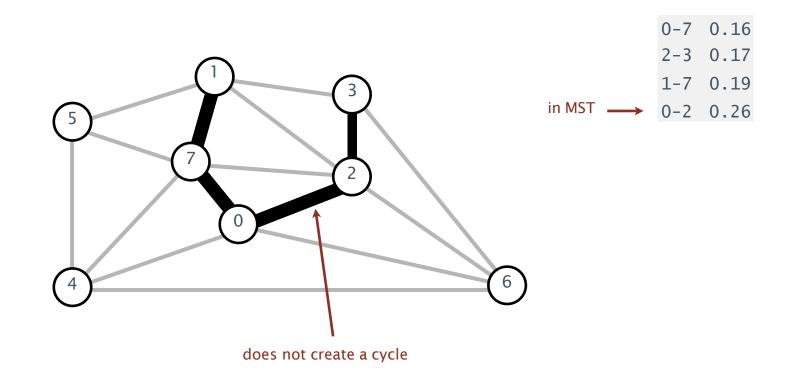
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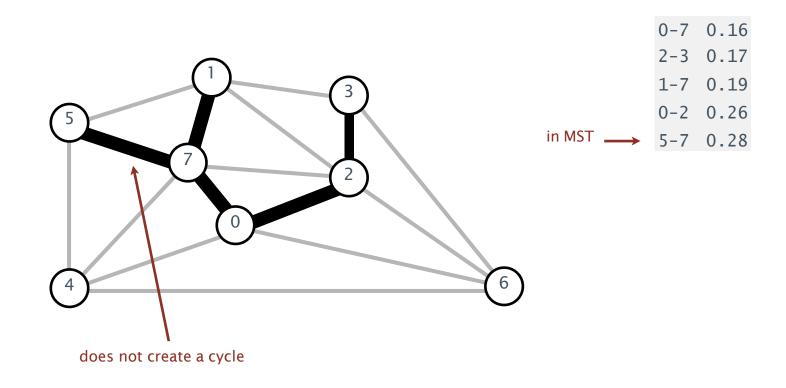
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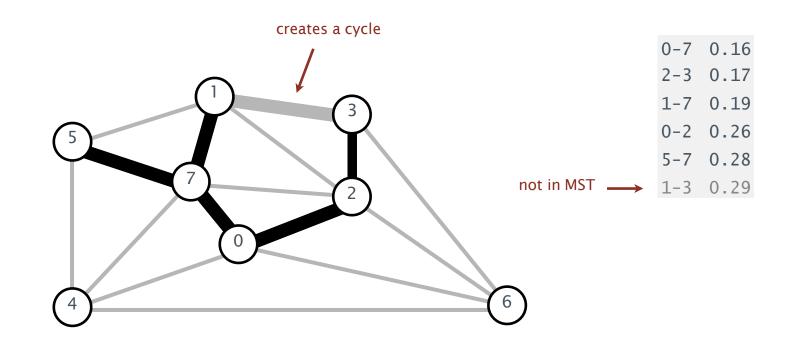
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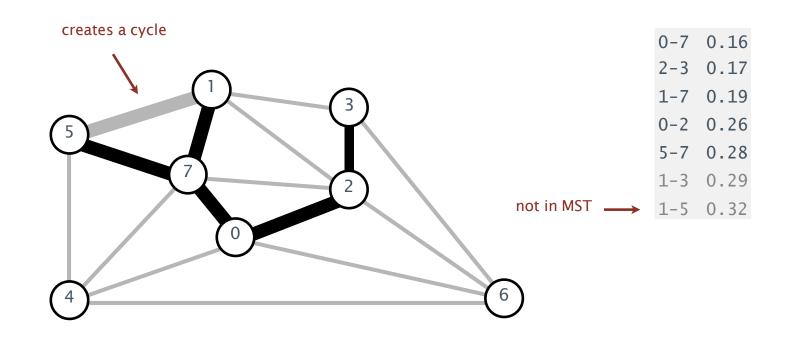
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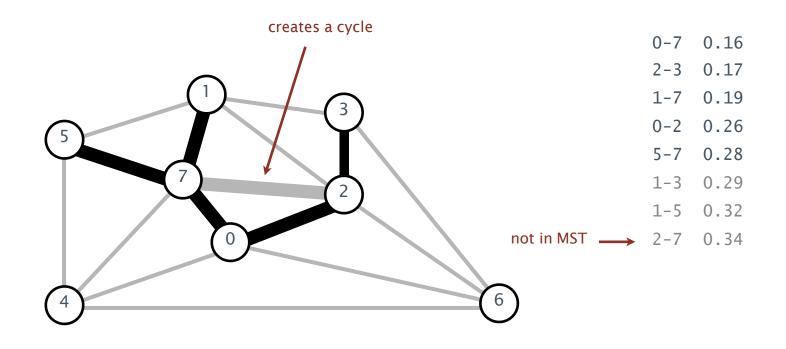
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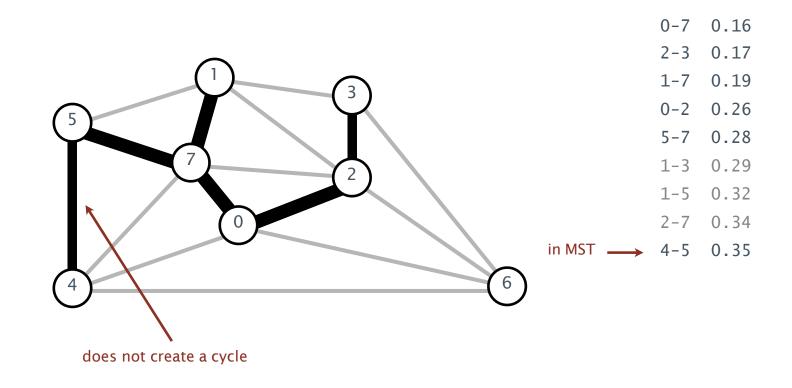
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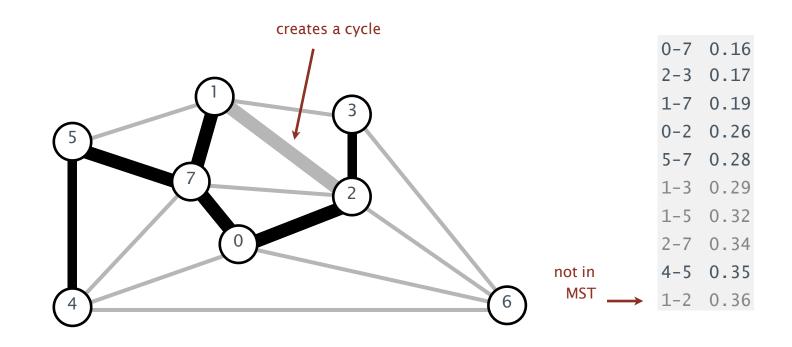
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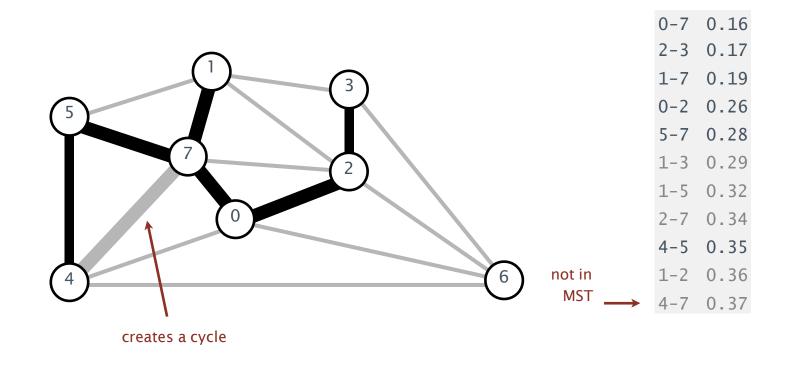
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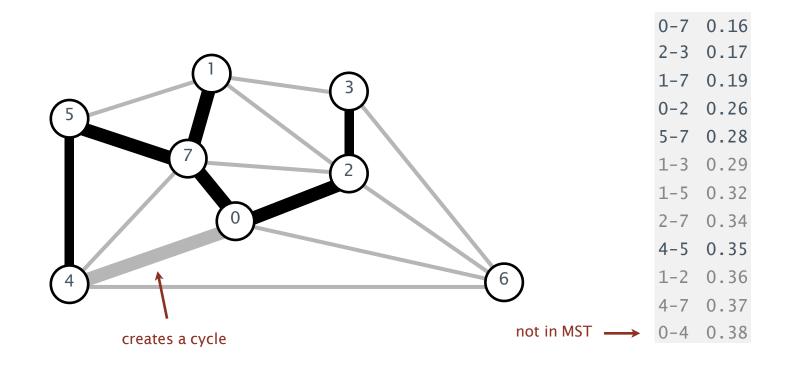
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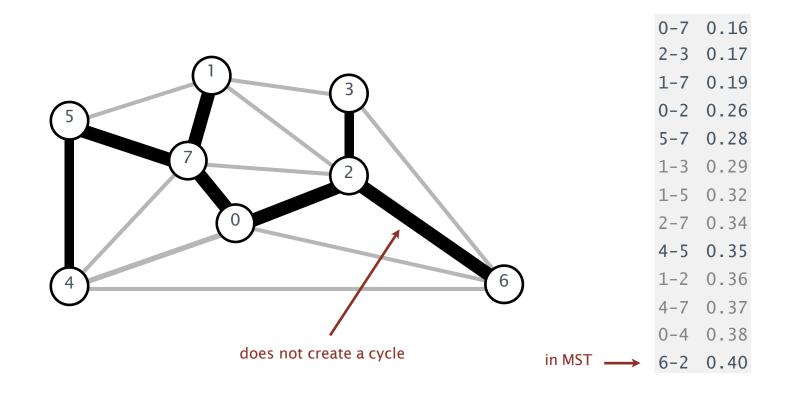
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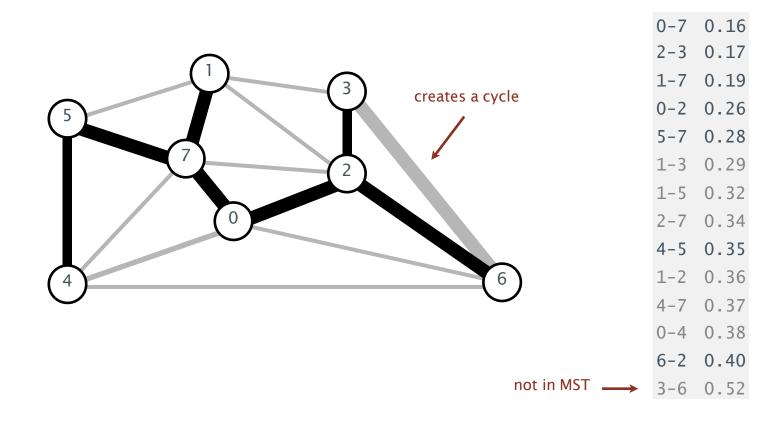
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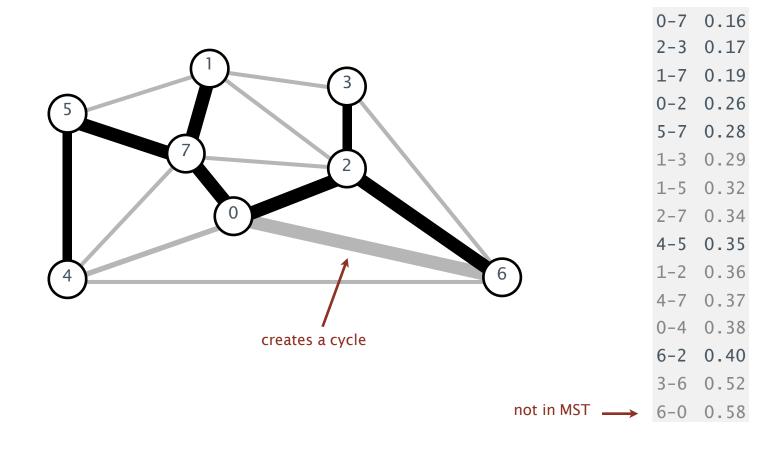
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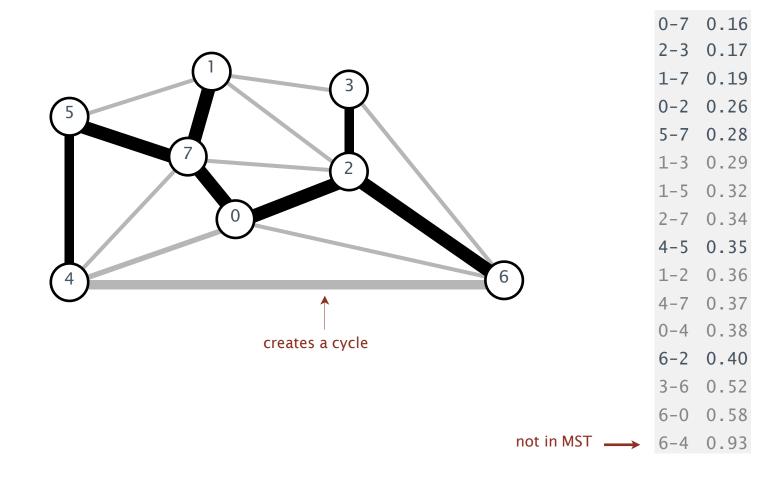
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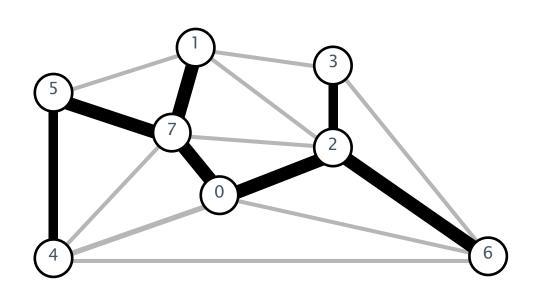


Consider edges in ascending order of weight.



Consider edges in ascending order of weight.

• Add next edge to tree *T* unless doing so would create a cycle.



a minimum spanning tree

0.16
0.17
0.19
0.26
0.28
0.29
0.32
0.34
0.34
0.34
0.34 0.35 0.36
0.34 0.35 0.36 0.37
0.34 0.35 0.36 0.37 0.38
0.34 0.35 0.36 0.37 0.38 0.40

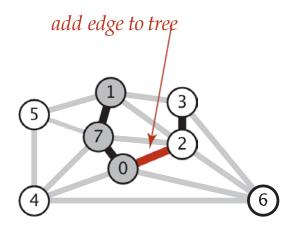
# Kruskal's progression visualisation

Kruskal's algorithm: correctness proof

Proposition. [Kruskal 1956] Kruskal's algorithm computes the MST.

Pf. Kruskal's algorithm is a special case of the greedy MST algorithm.

- Suppose Kruskal's algorithm colors the edge e = v w black.
- Cut = set of vertices connected to v in tree T.
- No crossing edge is black.
- No crossing edge has lower weight

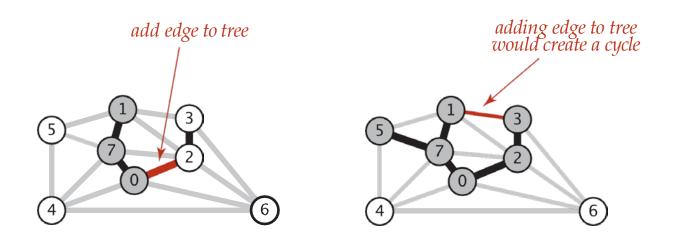


#### Kruskal's algorithm: implementation challenge

Challenge. Would adding edge v–w to tree T create a cycle? If not, add it.

#### How difficult?

- E+V
- V run DFS from v, check if w is reachable (T has at most V 1 edges)
- $\log V$
- $\log^* V$  — use the union-find data structure!
- 1

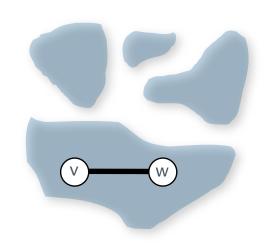


Kruskal's algorithm: implementation challenge

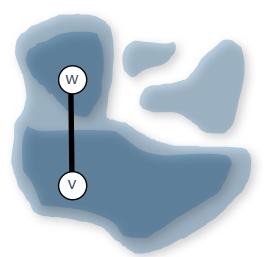
Challenge. Would adding edge v–w to tree T create a cycle? If not, add it.

Efficient solution. Use the union-find data structure.

- Maintain a set for each connected component in T.
- If v and w are in same set, then adding v–w would create a cycle.
- To add v–w to T, merge sets containing v and w.







Case 2: add v-w to T and merge sets containing v and w

#### Kruskal implementation

- > So what other data structures do we need?
  - Maintain the list of edges, ordered by weight, removing the lowest-weight edge when we add it to MST
  - List od edges and their weights added to the MST, to represent the MST (we'll need to iterate through them, and sum up their weight – to provide API required by MST)

#### Kruskal's algorithm: Java implementation

```
public class KruskalMST
   private Queue<Edge> mst = new Queue<Edge>();
   public KruskalMST(EdgeWeightedGraph G)
                                                                   build priority queue
                                                                   (or sort)
      MinPQ<Edge> pg = new MinPQ<Edge>(G.edges());
      UF uf = new UF(G.V());
      while (!pq.isEmpty() && mst.size() < G.V()-1)</pre>
         Edge e = pq.delMin();
                                                                   greedily add edges to MST
         int v = e.either(), w = e.other(v);
         if (!uf.connected(v, w))
                                                                   edge v-w does not create cycle
             uf.union(v, w);
                                                                   merge sets
             mst.enqueue(e);
                                                                   add edge to MST
   public Iterable<Edge> edges()
      return mst; }
```

#### Kruskal's algorithm: running time

Proposition. Kruskal's algorithm computes MST in time proportional to  $E \log E$  (in the worst case).

Pf.

operation	frequency	time per op
build pq	1	E
delete-min	E	$\log E$
union	V	$\log^* V^\dagger$
connected	E	$\log^* V^\dagger$

<sup>†</sup> amortized bound using weighted quick union with path compression

recall:  $log*V \le 5$  in this universe

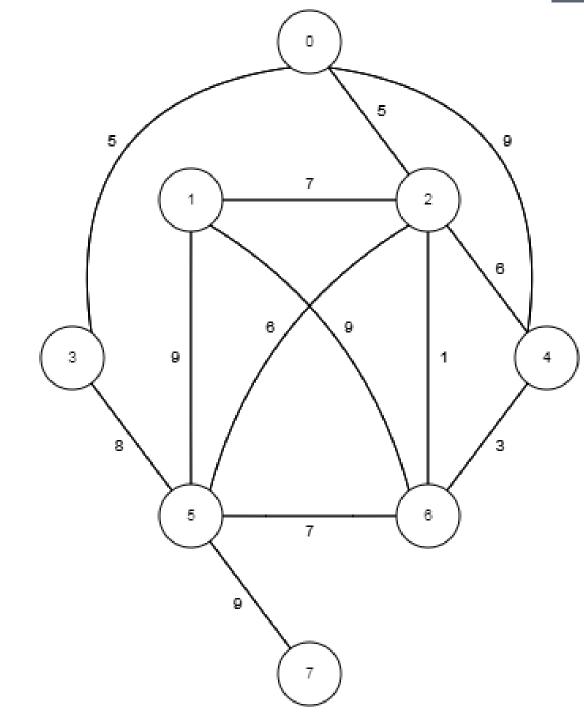


Remark. If edges are already sorted, order of growth is  $E \log^* V$ .

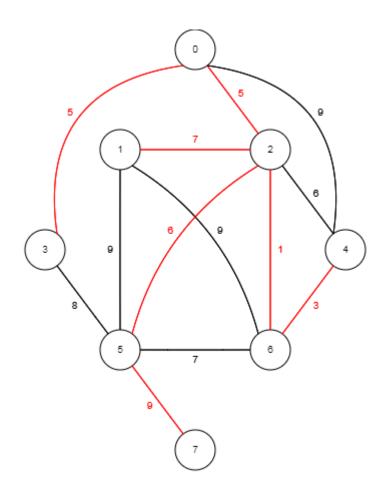
#### Kruskal's exercise

- Apply Kruskal's algorithm to find an MST of the following graph
- Provide trace of order in which edges are considered and added/discarded from being added to an MST

V	W	Weight	Added to MST?
2	6	1	yes
4	6	3	yes

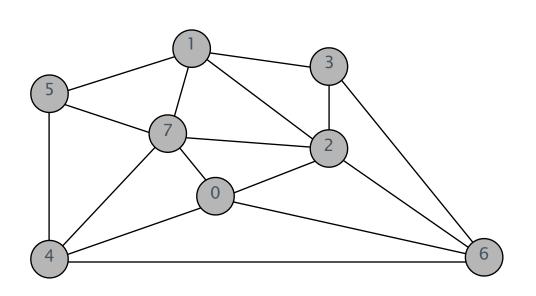


## Kruskal's algorithm exercise solution



# Prim's algorithm

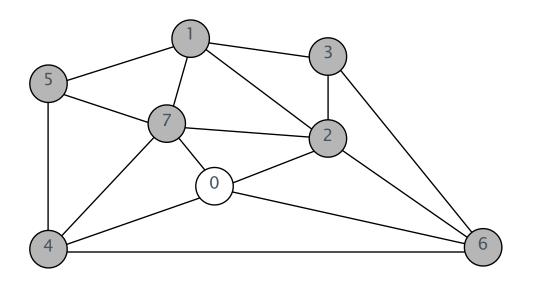
- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



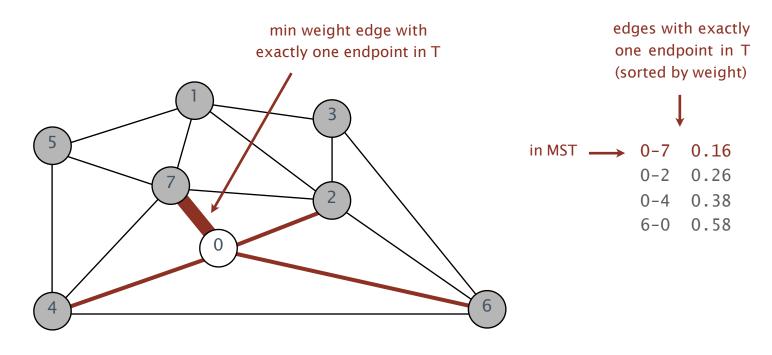
an edge-weighted graph

0-7	0.16
2-3	0.17
1-7	0.19
0-2	0.26
5-7	0.28
1-3	0.29
1-5	0.32
2-7	0.34
4-5	0.35
1-2	0.36
4-7	0.37
0-4	0.38
6-2	0.40
3-6	0.52
6-0	0.58
6-4	0.93

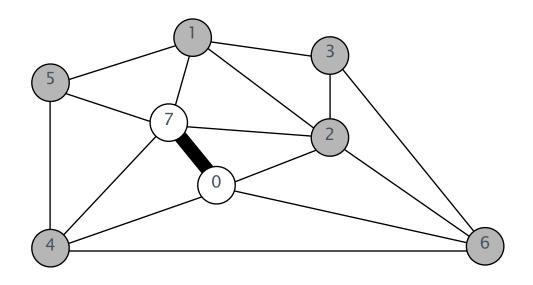
- Start with vertex 0 and greedily grow tree *T*.
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- Start with vertex 0 and greedily grow tree T.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.

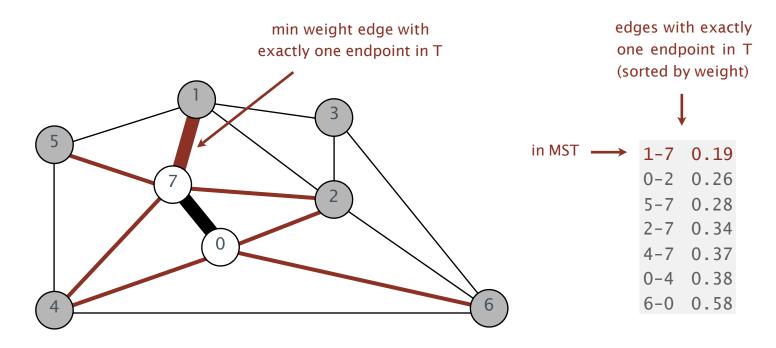


- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



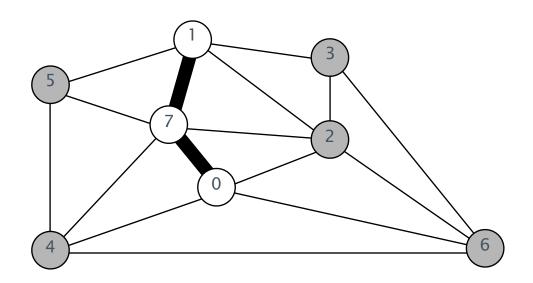
MST edges

- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



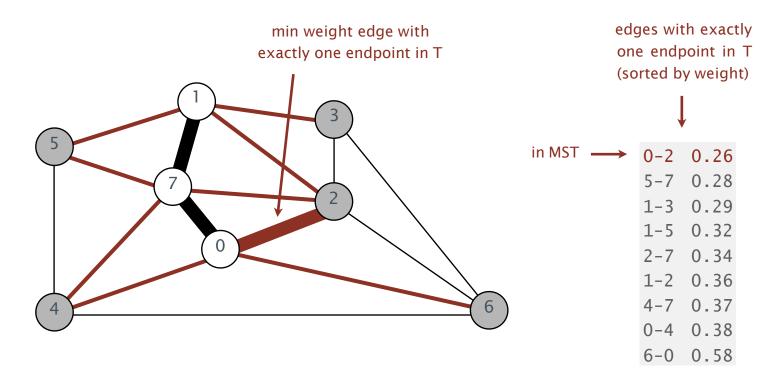
MST edges

- Start with vertex 0 and greedily grow tree *T*.
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- Repeat until V-1 edges.



MST edges

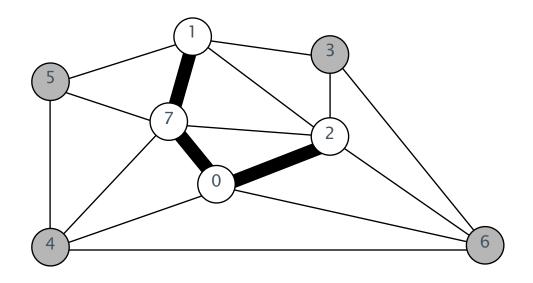
- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



MST edges

0-7 1-7

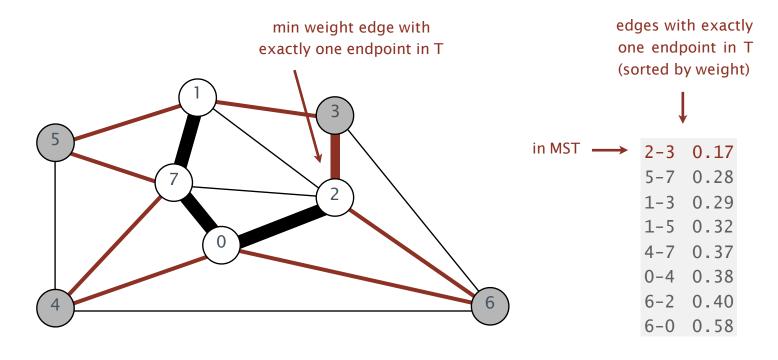
- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2

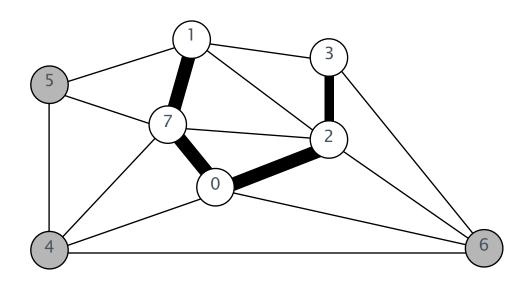
- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2

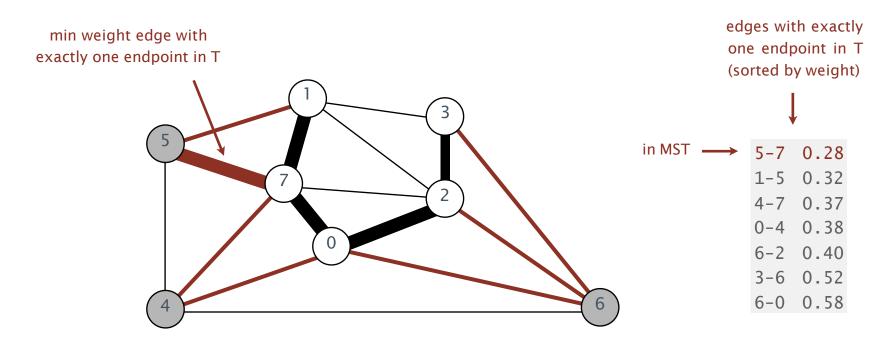
- Start with vertex 0 and greedily grow tree T.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2 2-3

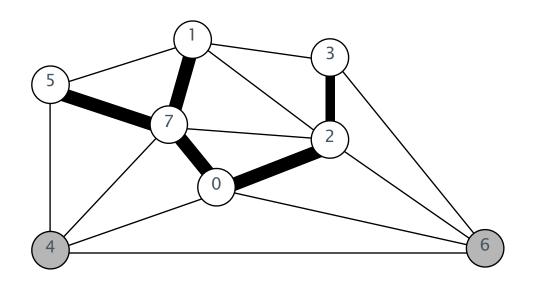
- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2 2-3

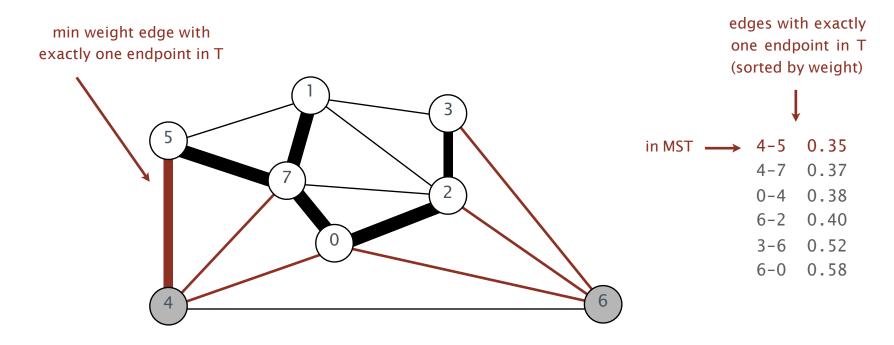
- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2 2-3 5-7

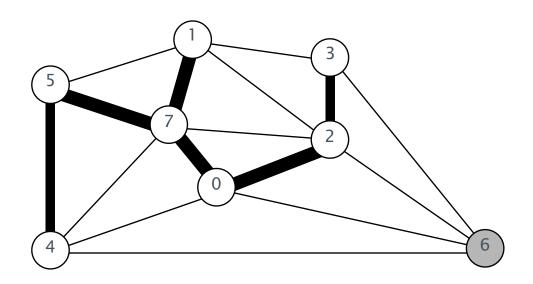
- Start with vertex 0 and greedily grow tree *T*.
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- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2 2-3 5-7

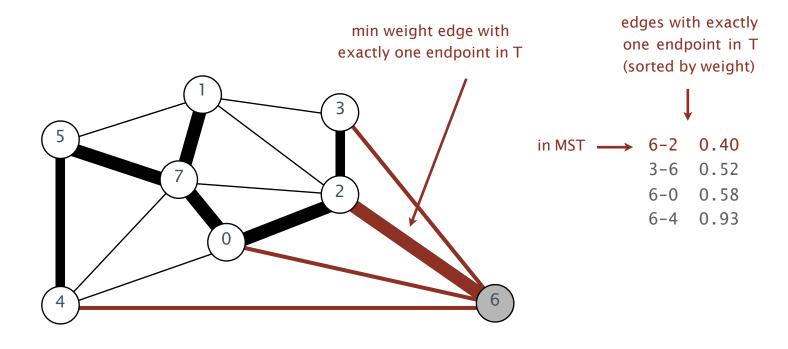
- Start with vertex 0 and greedily grow tree *T*.
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- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2 2-3 5-7 4-5

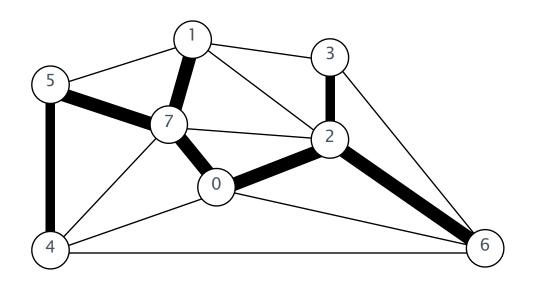
- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2 2-3 5-7 4-5

- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2 2-3 5-7 4-5 6-2

# Prim's algorithm visualisation

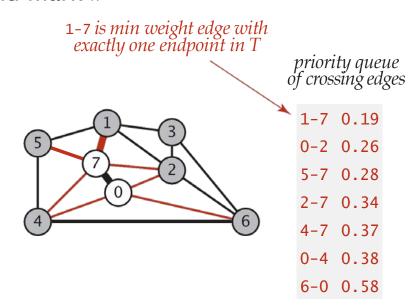
# Prim implementation

- > So what other data structures do we need?
  - Maintain the list of edges, ordered by weight, removing the lowest-weight edge when we add it to MST
    - > This list will be used slightly differently than in Kruskal not list of all edges, just those with exactly one end-point in current MST
    - > Lazy vs Eager implementation
  - List od edges and their weights added to the MST, to represent the MST (we'll need to iterate through them, and sum up their weight – to provide API required by MST)

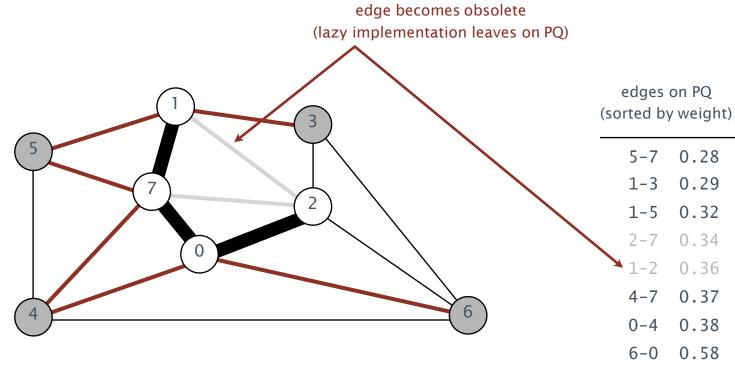
Challenge. Find the min weight edge with exactly one endpoint in T.

Lazy solution. Maintain a PQ of edges with (at least) one endpoint in T.

- Key = edge; priority = weight of edge.
- Delete-min to determine next edge e = v-w to add to T.
- Disregard if both endpoints *v* and *w* are marked (both in *T*).
- Otherwise, let w be the unmarked vertex (not in T):
  - add to PQ any edge incident to w (assuming other endpoint not in T)
  - add e to T and mark w



- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### MST edges

0-7 1-7 0-2

```
public class LazyPrimMST
   private boolean[] marked; // MST
                                       vertices
   private Queue<Edge> mst; // MST edges
   private MinPQ<Edge> pq; // PQ of edges
public LazyPrimMST(WeightedGraph G)
        pq = new MinPQ<Edge>();
        mst = new Queue<Edge>();
        marked = new boolean[G.V()];
                                                                       assume G is connected
        visit(G, 0);
        while (!pq.isEmpty() && mst.size() < G.V() - 1)</pre>
                                                                       repeatedly delete the
            Edge e = pq.delMin();
                                                                       min weight edge e = v-w from PQ
            int v = e.either(), w = e.other(v);
                                                                       ignore if both endpoints in T
            if (marked[v] && marked[w]) continue;
                                                                       add edge e to tree
            mst.enqueue(e);
            if (!marked[v]) visit(G, v);
                                                                       add v or w to tree
            if (!marked[w]) visit(G, w);
```

```
private void visit(WeightedGraph G, int v)
{
    marked[v] = true;
    for (Edge e : G.adj(v))
        if (!marked[e.other(v)])
            pq.insert(e);
}

public Iterable<Edge> mst()
{    return mst; }
add v to T

for each edge e = v-w, add to
PQ if w not already in T
```

Lazy Prim's algorithm: running time

Proposition. Lazy Prim's algorithm computes the MST in time proportional to  $E \log E$  and extra space proportional to E (in the worst case).

Pf.

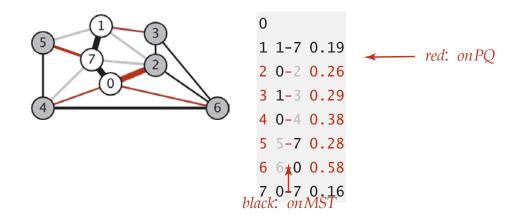
operation	frequency	binary heap	
delete min	E	$\log E$	
insert	E	$\log E$	

Challenge. Find min weight edge with exactly one endpoint in T.

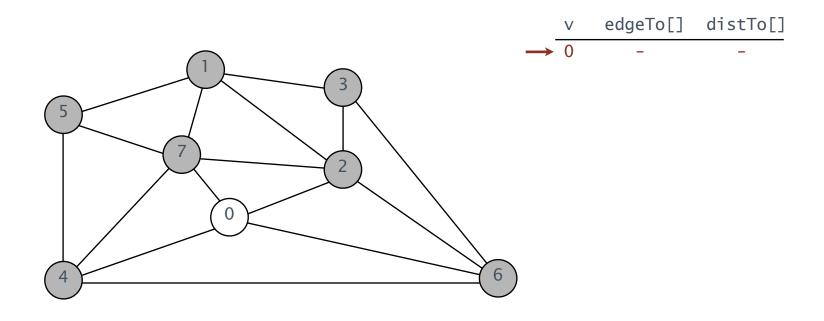
pq has at most one entry per vertex

Eager solution. Maintain a PQ of vertices connected by an edge to T, where priority of vertex v = weight of shortest edge connecting v to T.

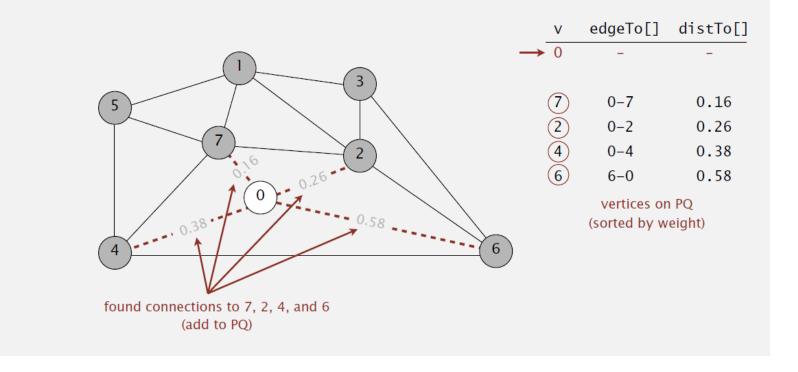
- Delete min vertex v and add its associated edge e = v w to T.
- Update PQ by considering all edges e = v-x incident to v
  - ignore if *x* is already in *T*
  - add *x* to PQ if not already on it
  - decrease priority of x if v-x becomes shortest edge connecting x to T



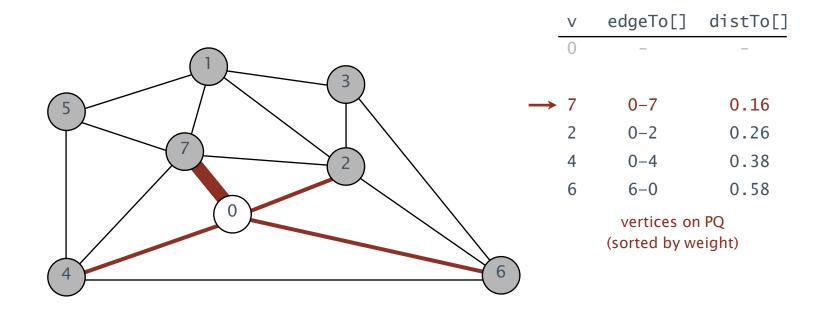
- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



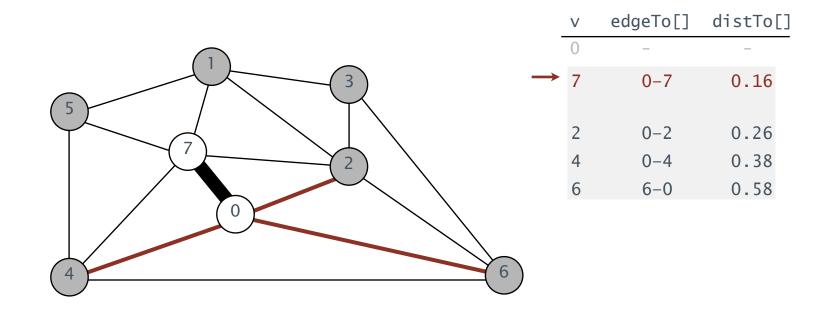
- Start with vertex 0 and greedily grow tree T.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.

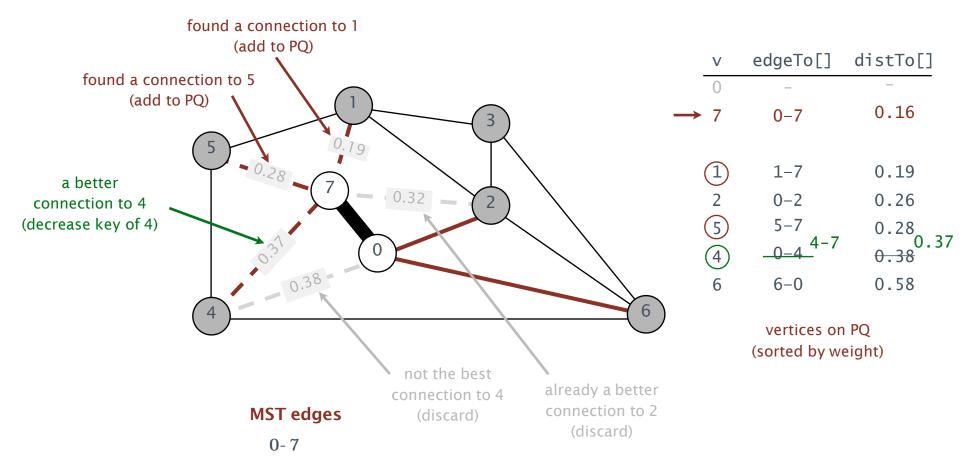


- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



MST edges

- Start with vertex 0 and greedily grow tree *T*.
- Add to T the min weight edge with exactly one endpoint in T.
- Repeat until V-1 edges.



### Indexed priority queue

Associate an index between 0 and N-1 with each key in a priority queue.

- Supports insert and delete-the-minimum.
- Supports decrease-key given the index of the key.

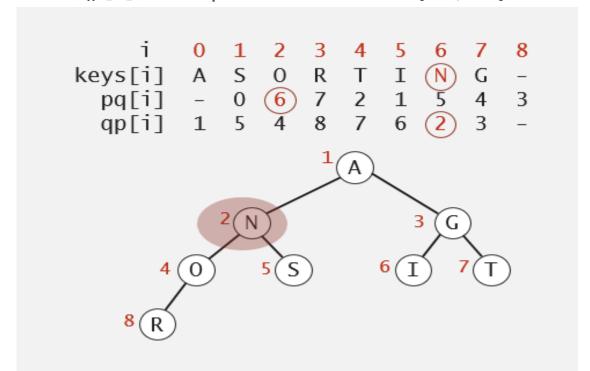
public class IndexMinPQ<Key extends Comparable<Key>>

```
create indexed
           IndexMinPQ(int N)
                                                            priority queue with
                                                            indices 0, 1, ..., N –
   void insert(int i, Key key)
                                                         associate key with index i
   void
           decreaseKey(int i, Key key)
                                                   decrease the key associated with index i
boolean contains(int i)
                                                     is i an index on the priority queue?
                                                      remove a minimal key and
           delMin()
     int
                                                                  return its
                                                                  associated index
boolean isEmpty()
                                                        is the priority queue empty?
     int size()
                                                    number of keys in the priority queue
```

### Indexed priority queue implementation

### Binary heap implementation. [see Section 2.4 of textbook]

- Start with same code as MinPQ.
- Maintain parallel arrays keys[], pq[], and qp[] so that:
  - keys[i] is the priority of i
  - pq[i] is the index of the key in heap position i
  - qp[i] is the heap position of the key with index i
- Use swim(qp[i]) to implement decreaseKey(i, key).



Prim's algorithm: which priority queue?

Depends on PQ implementation: Vinsert, V delete-min, E decrease-key.

PQ implementation	insert	delete-min	decrease-key	total
unordered array	1	V	1	$V^2$
binary heap	$\log V$	$\log V$	$\log V$	$E \log V$
d-way heap	$\log_d V$	$d \log_d V$	$\log_d V$	$E \log_{E/V} V$
Fibonacci heap	1 †	$\log V^{\dagger}$	1†	$E + V \log V$

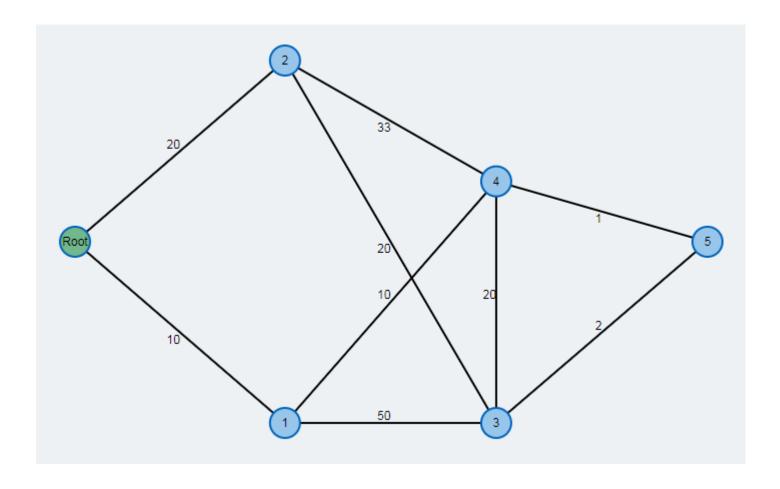
† amortized

### Bottom line.

- Array implementation optimal for dense graphs.
- Binary heap much faster for sparse graphs.
- 4-way heap worth the trouble in performance-critical situations.
- Fibonacci heap best in theory, but not worth implementing.

# Prim's algorithm exercise- Turning Point

- Starting from root (0)
- show order in which edges are added to mst
- Status of queue of vertices with edgeTo and distance values



# MST for Digraphs?

> Equivalent for digraphs is "minimum spanning arborescence" which will produce a tree where every vertex can be reached from a single vertex (panning arborescence of minimum weight, optimum branching)

MST for Digraphs?

# Greedy Algorithms

- > Applicable to optimisation problems
- > Constructs a solution through a sequence of steps, each expanding on the partially constructed solution obtained so far, until a complete solution is built
- > On each step, a choice is made which is:
  - 1. Feasible has to satisfy problem constraints
  - 2. Locally optimal it has to be the best local choice among all feasible choices
  - 3. Irrevocable once made, it cannot be changed on subsequent steps of the algorithm
- Greedily takes the best current option, in the hope it will add up to the overall best option
  - in some problems it does, in some it doesn't, but approximation might be good enough
- > Dijsktra's shortest path algorithm is also greedy