#### Assignment 1 Project Report

#### **Background**

The purpose of this programming exercise is to familiarize us with calling and running new processes and threads. In order to complete the assignment, we must fork a child process and run test programs inside of it. The assignment's goal is to expose us with operating system and kernel interaction and editing, as well as moving between user mode and kernel mode. The Ubuntu Version I use is version **16.04.7 LTS** and Kernel Version used is **Linux 5.10.147**.

#### Problem 1

In order to complete Task 1, we must use the fork() function in user mode to establish a child process that will run a separate program while the parent process waits for it to finish. This task's design and execution are both rather simple. We distinguish the parent and child processes once fork() is invoked using their process identifiers. The return value from fork() can be used for this. Following that, it just involves invoking execve() on the specified executable to start the child process.

```
if(identifier != -1){
   if(identifier == 0){
    int n;
    char *arg[argc];

   n = 0;
   while(n<argc-1){
        arg[n] = argv[n+1];
        n++;
   }

   arg[argc-1] = NULL;
   printf("This is child process, the PID = %d\n", getpid());
   printf("Child start to execute test program:\n");
   execve(arg[0], arg, NULL);
}</pre>
```

Figure 1.1 Example for getpid() and execve()

We instruct the parent process to wait until the child process has finished executing before proceeding while the child process is active. The wait() and waitpid() external function routines can be used for this. The child process will send a SIGCHLD signal to indicate its termination. The parent process will then proceed to output processing after receiving this and print out various outputs based on the exit signal received from the child process. This is assisted by the family of functions WIFEXITED(stat), WTERMSIG(stat), and WIFSTOPPED (stat).

```
else{
  printf("This is parent process, the PID = %d\n", getpid());
  waitpid(identifier, &stat, WUNTRACED);
  /* wait for child process terminates */
  printf("Receiving SIGCHLD Signal For Parent Process");

  if(WIFEXITED(stat)){
    printf("Normal termination with EXIT status = %d\n", WEXITSTATUS(stat));
  }
  else if(WIFSIGNALED(stat)){
    if(WIFERMSIG(stat) == 1){
        printf("Child Process Receive SIGHUP Signal \n");
        printf("Child Process Is Hung Up \n");
    }
}
```

Figure 1.2 Parent Process with WIFEXITED and WTERMSIG

#### **Problem 2**

The main difference between job 2 and task 1 is that task 2 is carried out in kernel mode as opposed to user mode. This makes the work more complex since we must examine kernel function calls and modify them to export some of their functions. This entails updating the kernel version and compiling and recompiling the kernel in order to correctly handle some essential function calls.

#### **Problem 2 Process**

Create a thread to start building task. To create a thread we use a function called kthread\_create(). We then use a straightforward approach by attempting to fork a child process, similar to job 1. It turned out to be more difficult to complete in kernel mode because we had to call kernel\_clone(), which is located in /kernel/fork.c, to complete the task, as opposed to the simple fork() function in user mode. The settings that will be used to create kernel clone are passed as parameters to the kernel clone() function in the form of a struct object called kernel clone args. Things like its flags, stack size, exit signal, etc. are included in this. In a manner similar to the user mode fork() function, it will output the pid of the child upon success. After calling kerne\_clone function we will run exec\_process() to tell the kernel\_clone() function about the stack information that the should run. Throughout the exec\_process() we will utilize the external function that we imported which is do\_execve(). This function do\_execve() is the kernel version of execve(). This function is located in the /fs/exec.c. There will also be a getname\_kernel() function which is located in /fs/namei.c which is called to get the path of executable before it given ti do\_execve() and if it succed it will return a ) value. We must additionally instruct the parent process to hold off until the child process has finished

running. This is accomplished through the use of the do wait() method from kernel/exit.c in the custom wait process() function. A struct object called wait opts that is comparable to kernel clone() is passed into the do wait() function. The outcomes of the child process's exit signal can then be obtained by accessing the wait opts structure. The status member inside the wait opts structure is where this is primarily accessed. Similar to task 1, we process this member to obtain the appropriate exit signals we seek, which subsequently direct our programs' output.

```
// Exec Process
int exec_process(void){
  int res;
  const char file_location[] = "/home/vagrant/csc3150/Assignment1_119010507/source/program1/abort";
  struct filename *exec_file = getname_kernel(file_location);
  res = do_execve(exec_file, NULL, NULL);
  if(!res){
    return 0;
  } else{
    do_exit(res);
  }
}
```

Figure 2.1 Code for Exec\_process function using do\_execve()

# **Environment Set up**

The kernel needs to be updated because it was no longer appropriate for the job. This entails installing a 5.10.x Linux kernel version that is downloaded to our machine as a tar or zip file. After extracting the tar or zip file, we use a variety of make calls to compile the kernel including make mrproper, clean, etc. To be able to compile the kernel, we must first install the appropriate development tools. In order to install our upgraded kernel, we then moved and copied the .config() file from /boot to our new kernel directory. Then, by using the make clean command, we must clean up our old kernel installation. The prior built and compiled modules from our old kernel version are erased as a result. After cleaning the old kernel, we then configure the menu with make menuconfig and a GUI will pop up.

After everything is finished, we proceed with make bzImage to build kernel images and install all the modules. After the installation process is done the kernel will reboot automatically. In besides installing the kernel, we must export various functions from the kernel function calls in order to use them correctly in problem 2. In the paragraph before, each function call included a specific file

location specification. They must be exported using EXPORT SYMBOL (). We rebuild the kernel after exporting these methods, reboot once more, and then move on to problem 2. Furthermore, in order to use these functions, we must first import it with the extern tag in problem 2.

# **Project Summary and Learning**

The assignment provided us with knowledge about the internal dynamics of several of the user mode function calls that we frequently use when programming. Additionally, this project demonstrated to us how the operating system controls several processes. The biggest difficulty is creating the ideal environment for our software before we even begin to create it. I picked up how to assemble a kernel and add and remove modules from a kernel during this procedure. After completing the two jobs, I have a clearer idea of the process. I also learn how the child process runs the program and how the parent process receives the message from its child process when I experiment with various test programs in task 1. Additionally, task 2 involves changing the kernel, and in order to do this effectively, we must read a few references.

# **OUTPUT SAMPLE**

#### **Problem 1 Result Output**

**Abort** Alarm

#### Bus

# vagrant@csc3150:~/csc3150/Assignment\_1\_119010507/source/program1\$ ./program1 ./alarm Fork Process Begin This is parent process, the PID = 1873 This is child process, the PID = 1874 Child start to execute test program: ---------------------------------This is the SIGALRM program Receiving SIGCHLD Signal For Parent ProcessChild Process Receive SIGALRM Signal Child Process Is Alarmed Execution Failed

#### **Floating**

# Hang up

#### **Illegal Instr**

#### **Interrupt**

# 

#### Kill

#### **Normal**

#### Pipe

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#### Quit

#### Stop

#### **Segment Fault**

Execution Failed

#### **Terminate**

#### **Trap**

#### **Problem 2 Result Output**

#### Abort

```
[ 6970.543531] [program2] : Module_init
[ 6970.543533] [program2] : Module_init create kthread start
[ 6970.543773] [program2] : The child process has pid = 7544
[ 6970.543774] [program2] : This is the parent process, pid = 7543
[ 6970.543775] [program2] : child process
[ 6970.649503] [program2] : get SIGABRT signal
[ 6970.649504] [program2] : The return signal is 6
```

# Bus

```
[ 7100.083826] [program2] : Module_init
[ 7100.083827] [program2] : Module_init create kthread start
[ 7100.083962] [program2] : The child process has pid = 8200
[ 7100.083963] [program2] : This is the parent process, pid = 8199
[ 7100.083964] [program2] : child process
[ 7100.189687] [program2] : get SIGBUS signal
[ 7100.189704] [program2] : The return signal is 7
```

#### Alarm

```
[ 6888.717554] [program2] : Module_init
[ 6888.717558] [program2] : Module_init create kthread start
[ 6888.717869] [program2] : The child process has pid = 6827
[ 6888.717871] [program2] : This is the parent process, pid = 6826
[ 6888.717872] [program2] : child process
[ 6890.719308] [program2] : get SIGALRM signal
[ 6890.719312] [program2] : The return signal is 14
```

## **Floating**

```
[ 7181.544354] [program2] : Module_init
[ 7181.544357] [program2] : Module_init create kthread start
[ 7181.544636] [program2] : The child process has pid = 8878
[ 7181.544638] [program2] : This is the parent process, pid = 8877
[ 7181.544639] [program2] : child process
[ 7181.655722] [program2] : get SIGFPE signal
[ 7181.655738] [program2] : The return signal is 8
```

# Assignment 1 CSC 3150 **Hang Up**

```
[ 7273.499897] [program2] : Module_init
[ 7273.499899] [program2] : Module_init create kthread start
[ 7273.500381] [program2] : The child process has pid = 9936
[ 7273.500383] [program2] : This is the parent process, pid = 9935
[ 7273.500383] [program2] : child process
[ 7273.500786] [program2] : get SIGHUP signal
[ 7273.500788] [program2] : The return signal is 1
```

#### **Illegal Instr**

```
[ 7399.584501] [program2] : Module_init
[ 7399.584503] [program2] : Module_init create kthread start
[ 7399.584613] [program2] : The child process has pid = 11194
[ 7399.584614] [program2] : This is the parent process, pid = 11193
[ 7399.584615] [program2] : child process
[ 7399.688525] [program2] : get SIGILL signal
[ 7399.688527] [program2] : The return signal is 4
```

# Interrupt

```
[ 7465.849911] [program2] : Module_init
[ 7465.849913] [program2] : Module_init create kthread start
[ 7465.850154] [program2] : The child process has pid = 11836
[ 7465.850155] [program2] : This is the parent process, pid = 11835
[ 7465.850156] [program2] : child process
[ 7465.850712] [program2] : get SIGINT signal
[ 7465.850714] [program2] : The return signal is 2
```

# 7560.962275] [program2] : get SIGKILL signal 7560.962277] [program2] : The return signal is 9

7560.961954] [program2] : child process

7560.961212] [program2] : Module\_init

#### Normal

```
[ 7619.238589] [program2] : Module_init
[ 7619.238591] [program2] : Module_init create kthread start
[ 7619.238843] [program2] : The child process has pid = 12707
[ 7619.238844] [program2] : This is the parent process, pid = 12706
[ 7619.238845] [program2] : child process
[ 7619.239897] [program2] : normal termination
[ 7619.239899] [program2] : The return signal is 0
```

#### **Pipe**

Kill

7560.961214] [program2] : Module\_init create kthread start

7560.961952] [program2] : The child process has pid = 12311

7560.961953] [program2] : This is the parent process, pid = 12309

```
[ 7681.108237] [program2] : Module_init
[ 7681.108239] [program2] : Module_init create kthread start
[ 7681.108413] [program2] : The child process has pid = 13103
[ 7681.108414] [program2] : This is the parent process, pid = 13102
[ 7681.108415] [program2] : child process
[ 7681.109024] [program2] : get SIGPIPE signal
[ 7681.109025] [program2] : The return signal is 13
```

#### Quit

```
[ 7813.991880] [program2] : Module_init
[ 7813.991881] [program2] : Module_init create kthread start
[ 7813.992440] [program2] : The child process has pid = 13538
[ 7813.992441] [program2] : This is the parent process, pid = 13536
[ 7813.992442] [program2] : child process
[ 7814.096788] [program2] : get SIGQUIT signal
[ 7814.096790] [program2] : The return signal is 3
```

#### **Segment Fault**

```
[ 7933.859304] [program2] : Module_init
[ 7933.859306] [program2] : Module_init create kthread start
[ 7933.859607] [program2] : The child process has pid = 13949
[ 7933.859608] [program2] : This is the parent process, pid = 13948
[ 7933.859609] [program2] : child process
[ 7933.973521] [program2] : get SIGSEGV signal
[ 7933.973523] [program2] : The return signal is 11
```

#### Stop

```
[ 8062.161372] [program2] : Module_init
[ 8062.161374] [program2] : Module_init create kthread start
[ 8062.161604] [program2] : The child process has pid = 14361
[ 8062.161605] [program2] : This is the parent process, pid = 14360
[ 8062.161606] [program2] : child process
[ 8062.162823] [program2] : get SIGSTOP signal
[ 8062.162825] [program2] : The return signal is 19
```

#### **Terminate**

```
[ 8116.455716] [program2] : Module_init
[ 8116.455717] [program2] : Module_init create kthread start
[ 8116.456154] [program2] : The child process has pid = 14748
[ 8116.456155] [program2] : This is the parent process, pid = 14746
[ 8116.456156] [program2] : child process
[ 8116.456431] [program2] : get SIGTERM signal
[ 8116.456432] [program2] : The return signal is 15
```

#### Trap

```
[ 8168.070234] [program2] : Module_init
[ 8168.070236] [program2] : Module_init create kthread start
[ 8168.070380] [program2] : The child process has pid = 15170
[ 8168.070381] [program2] : This is the parent process, pid = 15169
[ 8168.070382] [program2] : child process
[ 8168.176642] [program2] : get SIGTRAP signal
[ 8168.176644] [program2] : The return signal is 5
```