# Ryan DuToit

# **Education**

## University of Minnesota

Minneapolis, MN

PhD in Computer Science, 3.6 GPA

2013 - Present

2009-2013

Selected coursework: Computational Geometry, Computer Vision, Estimation and Detection, Estimation in Robotics, Matrix Theory, Optimization, Probability Theory

Drake University Des Moines, IA

Bachelors of Science, summa cum laude, 3.9 GPA Majors: Computer Science, Mathematics, and Physics

Majors: Computer Science, Mathematics, and Physics

# **Experience**

## MARS Lab, University of Minnesota

Minneapolis, MN

Research Assistant

2013 - Present

Development of real-time, vision-inertial localization and mapping algorithms for mobile devices (cell phones, tablets, wearables). Consistent and efficient 3D map-based localization.

Drake University Des Moines, IA

Research Assistant

2011 - 2013

Developed computer simulations modeling an  $H_2^+$  ion within strong laser fields. Produced highly efficient, parallel code, employing FORTRAN and MPI.

Programming Intern 2010 - 2013

Designed, developed, and tested web-server and iOS software for Drake University employees and students.

Auburn University Auburn, AL

Undergraduate Researcher

2012

Studied and developed methods for unmanned aerial vehicle collision avoidance. Implemented algorithms in Robot Operating System.

# **Honors and Awards**

University of Minnesota, Dept. of CSE: Ph.D. Candidate Travel Award	2016
Drake University, Dept. of Physics & Astronomy: Helmick Senior Scholar	2013
Drake University, Dept. of Physics & Astronomy: Physics Prize Scholarship	2009 - 2013

#### Skills

o C/C++	<ul><li>MATLAB</li></ul>	<ul><li>Java</li></ul>
<ul> <li>Android</li> </ul>	o iOS	<ul><li>Linux</li></ul>
<ul> <li>Sensor Fusion</li> </ul>	<ul><li>SLAM</li></ul>	<ul> <li>Computer Vision</li> </ul>

# **Journal Publications**

- [J3] C.X. Guo, K. Sartipi, R.C. DuToit, G.A. Georgiou, R. Li, J. O'Leary, E.D. Nerurkar, J.A. Hesch, and S.I. Roumeliotis, "Resource-Aware Large-Scale Cooperative 3D Mapping using Multiple Mobile Devices", *IEEE Transactions on Robotics*, submitted May 2016.
- [J2] G. Xiaoxu, R.C. DuToit, and K. Bartschat, "Photoionization of the  $H_2^+$  ion by ultrashort elliptically polarized laser pulses", *Physical Review A* 87(5), May 2013
- [J1] G. Xiaoxu, E. Secor, R.C. DuToit, and K. Bartschat, "Diffraction patterns in the ionization of the heteronuclear  $HeH_2^+$  ion by attosecond x-ray radiation", *Physical Review A* 86(5), October 2012

## **Conference Publications**

- [C4] R.C. DuToit, J.A. Hesch, E.D. Nerurkar, and S.I. Roumeliotis, "Consistent Map-based 3D Localization on Mobile Devices", pre-print, arXiv:1604.08087, Apr 27, 2016,
- [C3] C.X. Guo, K. Sartipi, R.C. DuToit, G.A. Georgiou, R. Li, J. O'Leary, E.D. Nerurkar, J.A. Hesch, and S.I. Roumeliotis, "Large-Scale Cooperative 3D Visual-Inertial Mapping in a Manhattan World", IEEE International Conference on Robotics and Automation (ICRA'16), Stockholm, Sweden, May 16 21, 2016.
- [C2] C.X. Guo, D.G. Kottas, R.C. DuToit, A. Ahmed, R. Li, and S.I. Roumeliotis, "Efficient Visual-Inertial Navigation using a Rolling-Shutter Camera with Inaccurate Timestamps", Robotics: Science and Systems (RSS'14), Berkeley, CA, July 12 16, 2014.
- [C1] D.G. Kottas, R.C. DuToit, A. Ahmed, C.X. Guo, G. Georgiou, R. Li, and S.I. Roumeliotis, "A Resource-aware Vision-aided Inertial Navigation System for Wearable and Portable Computers", Workshop: Long Term Autonomy, IEEE International Conference on Robotics and Automation (ICRA'14), Hong Kong, China, May 31 June 5, 2014.

## **Conference Presentations**

- [P3] R.C. Dutoit, G. Georgios, C.X. Guo, K. Wu, and S.I. Roumeliotis, "Vision-Aided Inertial Navigation for Virtual Reality Applications", *IEEE Conference on Computer Vision and Pattern Recognition (CVPR'16) Live Demo, Las Vegas, NV, June 27 30, 2016.*
- [P2] C.X. Guo, R.C. DuToit, K. Sartipi, J. O'leary, R. Li, G. Georgios, E.D. Nerurkar, J.A. Hesch, S.I. Roumeliotis, "Resource-Aware Large-Scale Cooperative 3D Mapping from Multiple Cell Phones", IEEE International Conference on Robotics and Automation (ICRA'15) Late Breaking Result Poster, Seattle, WA, May 27 29, 2015.
- [P1] R.C. DuToit, G. Xiaoxu, and K. Bartschat, "The Hydrogen Molecular Ion in an Intense Elliptically Polarized XUV Laser Pulse", APS Division of Laser Science, Symposium on Undergraduate Research, Rochester, NY, October 15, 2012.

## **Academic Service**

Journal Paper Reviewer: IEEE Transactions on Robotics

Conference Paper Reviewer: IEEE International Conference on Robotics and Automation