

6.1.7

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$$K_{false} = K_{true}$$

$$\frac{1}{2}mv_f^2 = mc^2(\gamma - 1)$$

$$\frac{1}{2}v_f^2 = c^2(\gamma - 1)$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v_t^2}{c^2}}}$$

$$\frac{1}{2}v_f^2 = c^2 \left(\frac{1}{\sqrt{1 - \frac{v_t^2}{c^2}}} - 1 \right)$$

$$\frac{c^2}{\sqrt{1 - \frac{v_t^2}{c^2}}} = \frac{v_f^2 + 2c^2}{2}$$

$$\sqrt{1 - \frac{v_t^2}{c^2}} = \frac{2c^2}{v_f^2 + 2c^2}$$

$$1 - \frac{v_t^2}{c^2} = \left(\frac{2c^2}{v_f^2 + 2c^2} \right)^2$$

$$\frac{v_t^2}{c^2} = 1 - \left(\frac{2c^2}{v_f^2 + 2c^2} \right)^2$$

$$v_t = c \sqrt{1 - \left(\frac{2c^2}{v_f^2 + 2c^2} \right)^2}$$

$$\begin{aligned}
& \left| \frac{v_f - v_t}{v_t} \right| \times 100 = E \\
& v_f > v_t \\
& \frac{v_f - v_t}{v_t} \times 100 = E \\
& \frac{v_f}{v_t} - 1 = \frac{E}{100} \\
& \frac{v_f}{v_t} = \frac{E}{100} + 1 \\
& \frac{v_f}{c\sqrt{1 - \left(\frac{2c^2}{v_f^2 + 2c^2}\right)^2}} = \frac{E}{100} + 1 \\
& \frac{v_f^2}{c^2 \left(\frac{v_f^4 + 4v_f^2c^2 + 4c^4}{v_f^4 + 4v_f^2c^2 + 4c^4} - \frac{4c^4}{v_f^4 + 4v_f^2c^2 + 4c^4} \right)} = \left(\frac{E}{100} + 1 \right)^2 \\
& \frac{v_f^6 + 4v_f^4c^2 + 4v_f^2c^4}{v_f^4 + 4v_f^2c^2} = c^2 \left(\frac{E}{100} + 1 \right)^2 \\
& \frac{v_f^4 + 4v_f^2c^2 + 4c^4}{v_f^2 + 4c^2} = c^2 \left(\frac{E}{100} + 1 \right)^2 \\
& \text{Define: } n = \left(\frac{E}{100} + 1 \right)^2 \\
& \frac{v_f^4 + 4v_f^2c^2 + 4c^4}{v_f^2 + 4c^2} = c^2 n \\
& v_f^4 + 4v_f^2c^2 + 4c^4 = v_f^2c^2n + 4c^4n \\
& v_f^4 + v_f^2c^2(4 - n) = 4c^4(n - 1) \\
& v_f^4 + v_f^2c^2(4 - n) + \frac{1}{4}c^4(4 - n)^2 = 4c^4(n - 1) + \frac{1}{4}c^4(4 - n)^2 \\
& (v_f^2 + \frac{1}{2}c^2[4 - n])^2 = c^4(4n - 4 + (4 - 2n + \frac{n^2}{4})) \\
& (v_f^2 + \frac{1}{2}c^2[4 - n])^2 = c^4 \left(\frac{n^2}{4} + 2n \right) \\
& v_f^2 + \frac{1}{2}c^2(4 - n) = c^2 \left(\frac{n^2}{4} + 2n \right)^{1/2} \\
& v_f^2 = c^2 \left(\frac{n^2}{4} + 2n \right)^{1/2} - \frac{1}{2}c^2(4 - n) \\
& v_f = c \left[\left(\frac{n^2}{4} + 2n \right)^{1/2} + \frac{n}{2} - 2 \right]^{1/2} \\
& v_f = \frac{c}{\sqrt{2}} \left[(n^2 + 8n)^{1/2} + n - 4 \right]^{1/2}
\end{aligned}$$