

Practical 5:

Object tracking with Kalman filter

Scripts to be modified:

`kalman_1_sensor.py` (2 points)

`practical_5.py` (1 point)

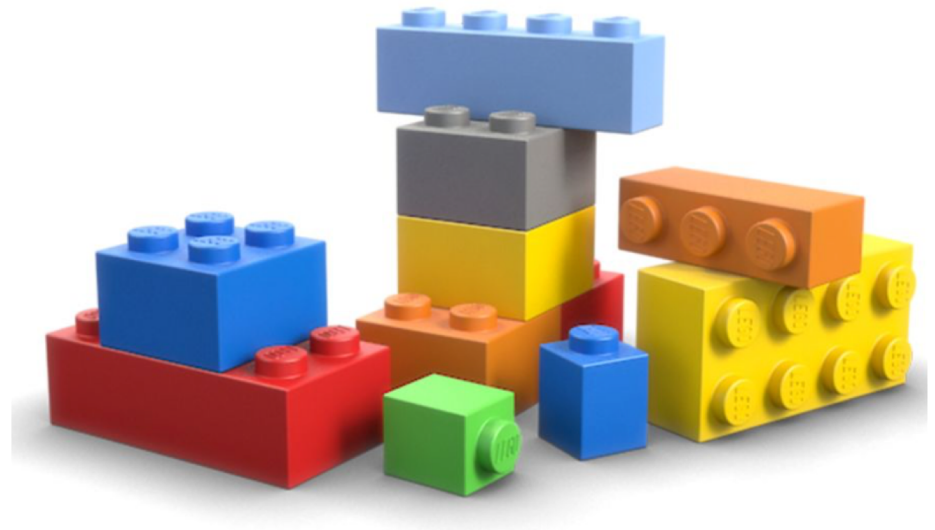
Your “LEGO bricks”:

`kalman_predict`

`object_detect`

`kalman_update`

Search for *****Task for you***** sections and fill the gaps to get correct implementations of Kalman-filter-based object tracking



Present your solutions in class
or
Upload modified Python code
to Dropbox by **Wed. Dec. 4, 11:59 pm**