# Ryan Sutherland

Sutherry@oregonstate.edu | 863-377-1825 | Robotics | LinkedIn

# **Skills**

Programming Python, C++, Java, MATLAB, C, Machine Learning Certificate, JavaScript

Electrical PCB Development, Soldering, Multimeter, Oscilliscope, Waveform Generator

Mechanical SolidWorks, Fusion360, Rapid Prototyping, Lathe, Milling Machine

# Technical Experience

#### Fuel Cell Defect Detection - Capstone

September 2022 - April 2023

- Responsible for creating an automated, AI powered system capable of classifying various defects found on fuel cells
- Developed a structure to introduce controlled lighting and surface conditions
- Utilized and implemented existing YOLO framework to classify and identify regions of defects

### UBC Biomedical Engineering Student Team (Co-Captain Projects)

September 2022 - August 2023

- Responsible for helping teams develop timelines and aid in project management.
- Communicating with faculty about reserving proper meeting and prototyping space.
- Developed various pipelines to streamline processes including: on-boarding, training and project proposals.

#### UBC Biomedical Engineering Student Team (SportsMed)

September 2021 - August 2023

- Founded SportsMed team to reimagine ways of treating and preventing common sports injuries
- Developing a core-activation device that informs users of ways to improve their posture and strength abdominal muscles
- Delegated research topics to team members and ensured constant communication between individuals

Can Collection Robot Summer 2021

- Designed robot using CAD, ensuring all components could effectively be integrated using assemblies
- Created custom PCBs for effective power distribution and signal management
- Created a state-machine that allowed all components of the robot to work together synchronously with precise timing for specific tasks
- Placed 3rd in competition

#### Plate Recognition Robot

Fall 2021

- Developed code for a robot in gazebo to drive a course and recognize car plates while avoiding obstacles
- Used a PID loop to effectively control sharp turns with minimal shaking afterwards
- Created a pedestrian/car avoidance system using image subtraction to identify movement
- Trained two neural networks using TensorFlow to identify letters and numbers

#### UBC Biomedical Engineering Student Team (MINT)

2019-2021

- Developed an electrode headset to read brain waves to enable individuals to perform day to day tasks through thought
- Designed a mechanical headset that was adaptable to all head sizes and integrable with headset electronics
- Prototyped headset using SolidWorks and rapid prototyping techniques
- Tested parts by ensuring that they fit on various head sizes and parts functioned cohesively with electrical aspects

#### **Autonomous Soccer Playing Robots**

2016-2018

- Designed and prototyped all aspects of the robot using Arduino coding and CAD
- Determined proper motherboard and motor shield need to function with components
- Fully soldered a breadboard ensuring proper power distribution to several components simultaneously
- Ensured effective integration of numerous components into a functioning and coherent system while limiting brownouts
- Represented Canada in WorldCup Junior, placing within the top 30% of all teams

# **Employment Experience**

#### Sparkmate, Paris, France

May 2023 - Present

- Joined a team of engineers to develop a wine fridge that could individually cool wine bottles to various temperatures
- Designed a custom PCB that could integrate 8 different compartments with various sensors and features
- Wrote C++ code to control the hardware of the system ensuring each compartment was held at the appropriate temperature
- Developed a python GUI to analyze, store, and plan testing of the device

#### TRAIN Fitness, Toronto, ON

May - December 2022

- Created an automated labeling system using computer vision techniques to increase data available for model training.
- Developed AI that could identify wrong form exercises with 98% accuracy.
- Interacted and parsed through large data files to extract vital information and pinpoint potential flaws in our database.
- Developed position estimation algorithm to identify users movement through space given sensors available on the watch.

# ConeTec, Burnaby, BC

January - April 2021

- Created precise SolidWorks drawings for use by machinists
- Designed custom PCB for accurately controlling motor outputs

# Education

#### Ph.D, Robotics, Oregon State University

2024-Present

Bachelor of Applied Science, Engineering Physics, The University of British Columbia

2019-2024

Cumalative Average 82.9%, Graduated with Distinction in the Co-Operative Education Program, Dean's Honour's List

## Interests

Lifesaving Certified to perform and teach lifesaving and swimming skills2016 - PresentMarksmanship Precision shooting of air rifles on the provincial stage2017 - 2019Pitcher/Second Baseman Newmarket Hawks A/AA Baseball (Provincial Champions)2017 - 2019