

# Non-Autonomous Ricker's Map in $\mathbb{R}^n$

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Using our results (O. Merino, M.R.S. Kulenovic) we can prove facts about the more robust **non-autonomous model**:

$$(x_{n+1}, y_{n+1}) = F_n(x_n, y_n) = (x_n e^{\rho_n - x_n - \alpha_n y_n}, y_n e^{s_n - \beta_n x_n - y_n})$$

where  $\rho_n \rightarrow \rho$ ,  $s_n \rightarrow s$ ,  $\alpha_n \rightarrow \alpha$ ,  $\beta_n \rightarrow \beta$ .

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- 10  $\mathbb{1}$  denotes the vector  $(1, 1, \dots, 1)$
- 11 A **Kolmogorov Map** is a map of the form  $F(x) = \text{diag}(x) G(x)$  where  $G: \mathbb{R}_+^n \rightarrow \text{int } \mathbb{R}_+^n$  is continuous.

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**note:** In 2 dimensions, the set  $Z_\ell^\circ$  is either  $\mathbb{X}^\circ$  or  $\mathbb{Y}^\circ$ .

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The map associated with the 2 dimensional Ricker's model is

$$F(x, y) = \left( x e^{\rho - x - \alpha y}, y e^{s - \beta x - y} \right)$$

which can be written as  $F(\mathbf{x}) = \text{diag}(\mathbf{x})G(\mathbf{x})$  where  $\mathbf{x} = (x, y)$  and  $G(x, y) = (e^{\rho - x - \alpha y}, e^{s - \beta x - y})$ .

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**1**  $F$  has up to 4 fixed points:  $o$ ,  $(\rho, 0)$ ,  $(0, s)$ , and  $\left( \frac{\rho - \alpha s}{1 - \alpha\beta}, \frac{s - \beta\rho}{1 - \alpha\beta} \right)$

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- 3 (Baigent et al.) If  $0 < \rho, s < 2$  and  $\alpha < \frac{\rho}{s} < \frac{1}{\beta}$  then the interior equilibrium exists and is globally asymptotically stable, while if either  $\alpha < \frac{\rho}{s}$  and  $\frac{\rho}{s} > \frac{1}{\beta}$  or  $\alpha > \frac{\rho}{s}$  and  $\frac{\rho}{s} < \frac{1}{\beta}$ , one of the axial points is globally attracting.

## Proposition 2

Assume  $0 < \rho, s < 1$  and  $G_t \rightrightarrows G$ . Then the following statements are true for the equation  $x_{t+1} = F_t(x_t)$  with  $F_t(\mathbf{x}) = \mathbf{x}G_t(\mathbf{x})$

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Let  $\phi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  defined by  $\phi(v) = ve^{c-v}$ , where  $0 < c < 1$  is fixed. Then  $\forall 0 < \varepsilon < 1 - c, \exists 0 < \varepsilon' < \varepsilon$  and  $\tau = \tau(\varepsilon) \in \mathbb{N}$  such that  $f^{\circ \tau}(\mathbb{R}_+) \subset [0, c + \varepsilon]$  and  $f([0, c + \varepsilon]) \subset [0, c + \varepsilon']$ .

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$\forall \varepsilon > 0$  s.t.  $p(\varepsilon) := (\rho + \varepsilon, s + \varepsilon) \ll 1, \exists \varepsilon' \in (0, \varepsilon)$  and  $\tau = \tau(\varepsilon) \in \mathbb{N}$  s.t.  $F^{\circ \tau}(\mathbb{R}_+^2) \subset [o, p(\varepsilon)]$  and  $F([o, p(\varepsilon)]) \subset [o, p(\varepsilon')]$



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To prove part (2) of Proposition 2, assume  $\alpha < \frac{\rho}{s} > \frac{1}{\beta}$ . Since  $s < \frac{\rho}{\alpha}$ , there exists  $\varepsilon > 0$  such that  $s + \varepsilon < \frac{\rho}{\alpha}$ . For this choice of  $\varepsilon$ , the conditions for theorem 2 have been met:

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✓
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- 4  $\exists r' \in \mathbb{R}^n$  s.t.  $o \ll r' \ll r$  and  $F([o, r]) \subset [o, r']$  ✓
- 5  $F_t([o, r]) \subset [o, r]$  ✓



## Proof of Part 3

To prove the third condition, notice  $\min\{\gamma_i : i \neq j\}$  has to be  $\gamma_2$  since  $i = 1, 2$  and  $j = 1$ . Hence, since  $s + \varepsilon < \frac{r}{\alpha}$ , we have

$$\gamma = \gamma_2 = \min\{e^{r-\alpha y} : y \in [o, p(\varepsilon)] \cap \mathbb{Y}^o\} > e^{r-\alpha(s+\varepsilon)} > 1$$

This completes the proof of part (2) of proposition 2.

Figure 1

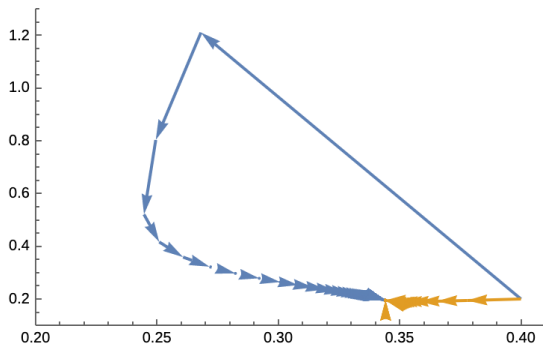


Figure: Ricker's map with  $\alpha = 2/7$ ,  $\beta = 3/7$ ,  $\rho = 2/5$ , and  $s = 12/35$ .

Rickers non-autonomous map with  $\alpha_n = \frac{2n^2}{7n^2+20}$ ,  $\beta_n = \frac{3n^8}{7n^8+2}$ ,  $\rho_n = \frac{2n^2}{5n^2+2}$ ,  
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Figure 2

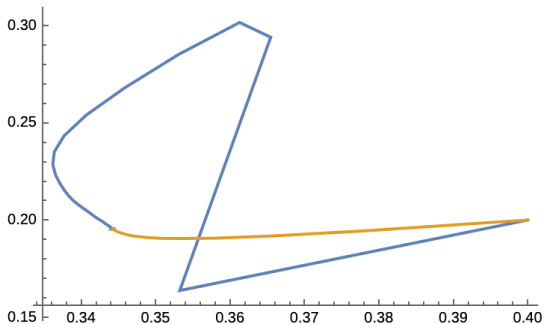


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Rickers non-autonomous map with  $\alpha_n = \frac{2n^2 + \cos(n)}{7n^2 + 20}$ ,  $\beta_n = \frac{3n^8}{7n^8 + 2\cos(n)}$ ,

$\rho_n = \frac{2e^{n^2} + \sin(n)}{5e^{n^2} + 2}$ , and  $s_n = \frac{12n^3 + 18n + 2\sin(n)}{35n^3 + 1}$



## Figure 2

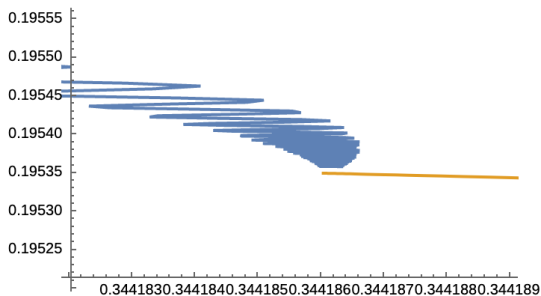


Figure: Figure 2 zoomed in on the positive equilibrium point.