

Ryan Taylor

Embedded Systems Engineer

Proficient in embedded systems with an emphasis in robotics. My areas of expertise are networks, controls, and autonomy.

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WORK EXPERIENCE

Controls Simulation Intern Rolls-Royce

05/2023 – 08/2023,

Indianapolis, Indiana

Achievements/Tasks

- Perform behavioral analysis on a legacy Simulink engine model and correlate its output data to validate its fidelity with modern engine simulations used by Rolls-Royce.
- Comprehensively understand the architecture of the AE3007N engine and how its electro-mechanical systems are emulated within the Simulink model.

Contact: David Halamka – david.halamka@rolls-royce.com

Electronics Development Intern Rolls-Royce

05/2022 – 08/2022,

Indianapolis, Indiana

Achievements/Tasks

- Administrated driver integration of an AVL dynamometer into the test stand control system in the Electric Power Lab to streamline testing operations and data acquisition.
- Modernized data aggregation systems by installing private git server and establishing autonomous routine to log changes in configuration files for test stands for auditing purposes.
- Characterized electronic equipment to verify that they operated within specified threshold values and performed diagnostic testing to identify flaws in the structural design of devices in the event of failure.

Contact: George Hutchins – george.hutchins@rolls-royce.com

LEADERSHIP ACTIVITIES

Drive Control and Electrical Team Co-Lead Vanderbilt Robotics Club

01/2021 – Present,

Nashville, Tennessee

Achievements/Tasks

- Revised and consolidated circuit topology of power management systems to drive robot on smaller chassis.
- Developed a navigational drive control algorithm by constructing local and global mapping using Intel RealSense cameras, LiDAR, and ROS2 architecture.

Electrical and Programming Team Co-Lead Vanderbilt Satellite Club

08/2021 – Present,

Nashville, Tennessee

Achievements/Tasks

- Launched weather balloon to test preliminary designs and operating conditions for PCB circuit, sensory devices, and communication systems.
- Designed communications interface to connect weather balloon with ground operations and implementing relevant software on Raspberry Pi to successfully broadcast sensory data with radio frequencies to ground with APRS.

SKILLS

C/C++

Julia

Python

Bash

Gatsby

Firebase

Circuitry

LTSpice

ROS2

Autodesk Inventor

MATLAB/Simulink

JavaScript

Radio Technicians License

Hardware

Firmware

PERSONAL PROJECTS

Laser Tracking Robot (08/2022 - 12/2022)

- Programmed a FreeNove robot to autonomously follow a laser, record its trajectory, and re-traverse the path it travels from its starting position.
- Designed software architecture using threads, task synchronization and communication, and motor control functions.

Maze Solving Robot (01/2021 - 05/2021)

- Encoded a Polulu 3Pi Robot to navigate and re-traverse a maze autonomously. Then calculate the optimal path and traverse the maze a second time without making redundant traversals.
- Designed a control loop that allows the robot to follow a black line using infrared sensors and course correct itself if it veers off the path and record its position as it traverses the maze.

Electric Longboard (06/2020 - Present)

- Designed and built a Dual-Motor Hub Electric Longboard
- Built schematic designs and the longboard from constituent components to successfully operate and drive from a bluetooth controller.
- Revised design by upgrading electric speed controller and battery to optimize motor performance and increase customization capabilities.

EDUCATION

B.E. Electrical and Computer Engineering Minor: Computer Science Vanderbilt University

08/2020 - 05/2024,

GPA: 3.44/4.00

Relevant Coursework

Embedded Systems

Microcontrollers

Electronics

Autonomous Vehicles

Microelectronics

Circuits

Intermediate Software Design

Digital Systems

Applied Statistical Machine Learning

Computer Networks

Awards

Cornelius Vanderbilt Scholar

Dean's List

Ron Brown Captain