

# Ryan Vu

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## Education

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| <b>California State Polytechnic University, Pomona (Cal Poly Pomona), B.S. Computer Science</b>  | Pomona, United States |
| <ul style="list-style-type: none"><li>• GPA: 3.97</li><li>• Leadership &amp; Activities: Vietnamese Student Association Intern (2024-2025) → VCN Director (2025–2026); Data Science &amp; AI Club; Competitive Club Tennis Team</li><li>• Coursework: Systems Programming, Data Structures and Advanced Programming, Computer Organization and Assembly Programming</li><li>• Expected Graduation: May, 2027</li></ul> |                       |

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## Engineering Experience

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| <b>Fire Detection and Suppression Team (Ground Control Systems),</b><br><i>Sponsored by Lockheed Martin</i>   | 02/2025 – present<br>Pomona, United States |
| <ul style="list-style-type: none"><li>• Built <b>C++/Qt/QML ground control system</b> for <b>real-time multi-UAV command &amp; control</b>, resilient telemetry in <b>back-end</b>, and scalable UI in <b>front-end</b>.</li><li>• <b>Collaborated</b> with the machine-learning team to integrate <b>live fire-detection video feeds</b>, aligning <b>interfaces</b> and <b>data contracts</b> for seamless ingest.</li><li>• Drove <b>multi-UAV state awareness</b> and <b>robust telemetry display</b> to maintain situational awareness over unreliable links</li></ul> |  |
| <b>Health Information Technician / Intern, Bach Diagnostics</b>   | 08/2020 – 08/2024<br>Irvine, California    |
| <ul style="list-style-type: none"><li>• <b>Automated workflows</b>, cutting per-claim handling time ~400% and saving 15–20 hrs/week.</li><li>• Optimized <b>Hamilton STAR robotics</b> platform throughput (2× improvement) and pipetting precision (+30%).</li><li>• Co-authored ADLM 2024 publication on <b>automation, robotics, and scientific computing</b>.</li></ul>   |  |
| <b>Software Lead, FIRST Robotics Competition Team 4322</b>  | 08/2020 – 05/2024<br>Orange, United States |
| <ul style="list-style-type: none"><li>• Directed subteam of 5–8; implemented <b>Agile workflows and technical mentorship</b>.</li><li>• Built <b>real-time telemetry, diagnostics, and autonomous control software</b>, reducing debugging time &gt;90%.</li><li>• Delivered <b>mission-critical robotics software</b> at 2024 World Championships with zero blocking faults.</li></ul>   |  |

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## Additional Experience

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| <b>Circulation Desk Student Assistant, California State Polytechnic University, Pomona</b>  | 08/2025 – Present<br>Pomona, California |
| <ul style="list-style-type: none"><li>• <b>Front-line customer service</b> in a <b>fast-paced</b> academic library; checked materials in/out using the <b>ALMA system</b> and supported <b>student &amp; faculty account inquiries</b>.</li></ul> |   |

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## Skills

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**Programming & Systems** — C++, Python, C, Java, JavaScript, Multithreading, Parallel Programming, Operating Systems, Computer Architecture, Algorithms, Data Structures, Firmware

**Tools & Frameworks** — Git, Linux, UNIX, Qt/QML, WPILib, TensorFlow, Pytorch, OpenCV, Docker, CI/CD

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## Awards & Publications

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| <b>Winner - FIRST Robotics Competition, Aerospace Valley Regional (2024)</b><br>Top placement among ~40+ teams.  | 2024 |
| <b>Automation for the Isolation of Peripheral Blood Mononuclear cells (PBMCs) with Hamilton Robotics for T-Spot Testing, Association for Diagnostics &amp; Laboratory Medicine</b> | 2024 |