

# Modeling Patterns for C Constructs

**A guide for generating popular C constructs from models using  
Real-Time Workshop® Embedded Coder™**

# Summary

- **This presentation is a reference guide for transitioning from hand coding in C to modeling with automatic code generation**
- **For a typical C pattern:**
  - Different modeling methodologies are illustrated using Simulink®, Stateflow®, and Embedded MATLAB™
  - Code from Real-Time-Workshop® Embedded Coder™ is shown
  - The mapping of the C construct to the model and its generated code is illustrated
  - All the steps involved in creating the model and generating the code are detailed in the notes page for each slide
- **Readers are encouraged to request or submit other patterns for future releases of this document by contacting:**
  - [arvind.jayaraman@mathworks.com](mailto:arvind.jayaraman@mathworks.com) or
  - [tom.erkkinen@mathworks.com](mailto:tom.erkkinen@mathworks.com)

## Caveats

- **This document does not cover every modeling method or C construct**
- **MathWorks Release R2008a is used and results may differ for other versions**
- **White-spaces in the generated code snippets have been changed in some cases for clarity**
- **Working knowledge of MATLAB and Simulink is helpful for readers but not required**

## Additional Resources

- **C/C++ Code Generation Web Videos**
  - [www.mathworks.com/products/rtwembedded/demos.html](http://www.mathworks.com/products/rtwembedded/demos.html)
- **HDL Code Generation Web Videos**
  - [www.mathworks.com/products/slhdlcoder/demos.html](http://www.mathworks.com/products/slhdlcoder/demos.html)
- **Fixed Point Code Generation Web Videos**
  - [www.mathworks.com/products/simfixed/demos.html](http://www.mathworks.com/products/simfixed/demos.html)
- **Fixed Point Modeling and Code Generation Tips**
  - [www.mathworks.com/matlabcentral/fileexchange/loadFile.do?objectId=19835](http://www.mathworks.com/matlabcentral/fileexchange/loadFile.do?objectId=19835)

# Index

- Standard Steps to prepare models
- Types, Operators and Expressions
- Control Flow
- Functions and Program Structure
- Structures
- Arrays and Pointers

# Types, Operators and Expressions

## C Pattern

Data Declaration

Data-Type Conversion

Type Qualifiers

Relational and Logical Operations

Bitwise Operations

# Control Flow

C Pattern
<a href="#"><u>If-Then-Else</u></a>
<a href="#"><u>Switch-Case</u></a>
<a href="#"><u>For-Loop</u></a>
<a href="#"><u>While-Loop</u></a>
<a href="#"><u>Do-While Loop</u></a>

# Functions & Program Structure

## C Pattern

### Functions

- void-void Functions
- Functions returning arguments
- Calling external C functions

### #define



# Structures

## C Pattern

[Typedef](#)

[Structures for Parameters](#)

[Structures for Signals](#)

[Nested Structures](#)

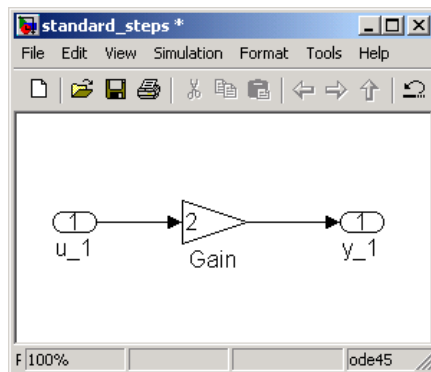
[Bit Fields](#)

# Arrays and Pointers

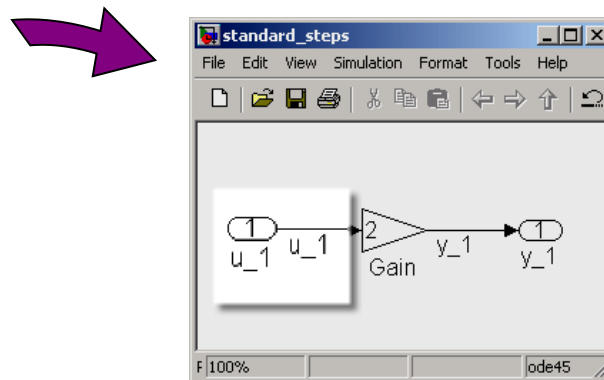
<b>C Pattern</b>
<u><a href="#">Arrays</a></u>
<u><a href="#">Pointers</a></u>

# Standard Steps adopted in this document to prepare models for Code Generation

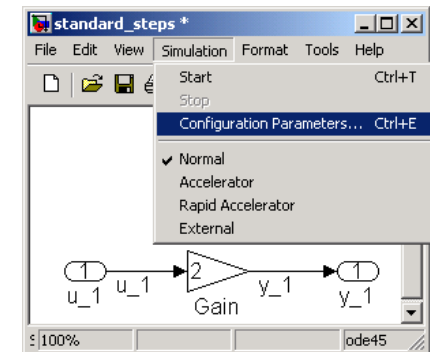
Create the model



Label Input/Output Signals  
as shown

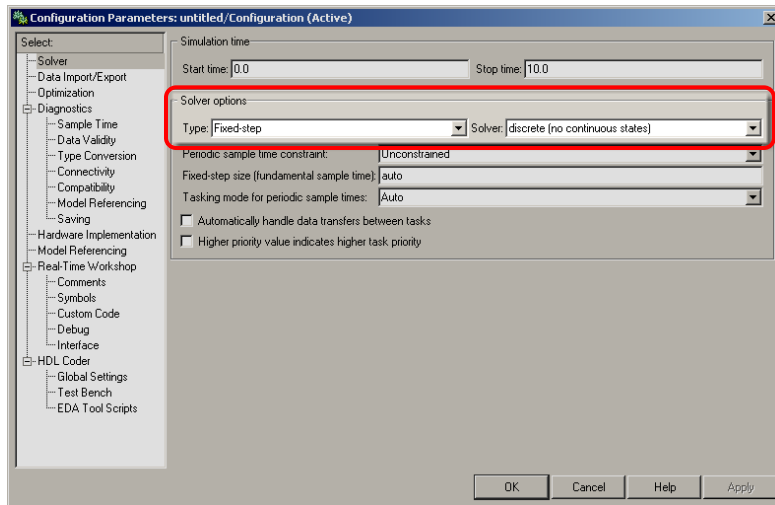


From the file menu choose  
'Simulation' and select  
'Configuration Parameters'

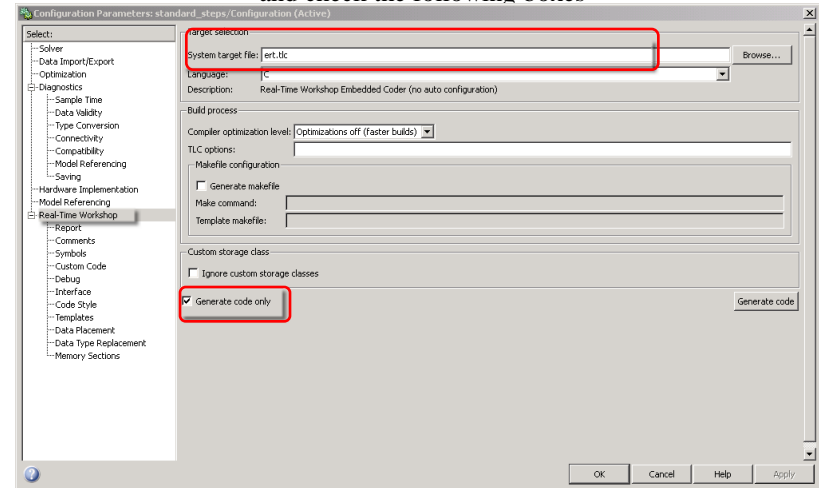


Select Configuration Parameters

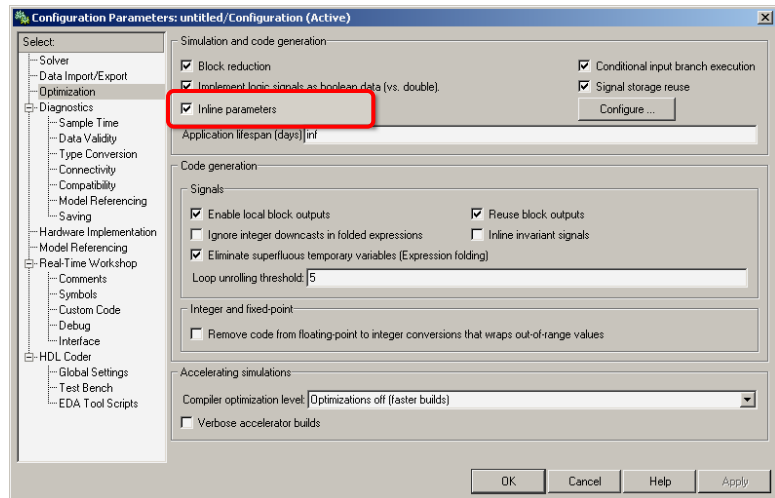
From the Solver Pane: Select Fixed Step discrete Solver



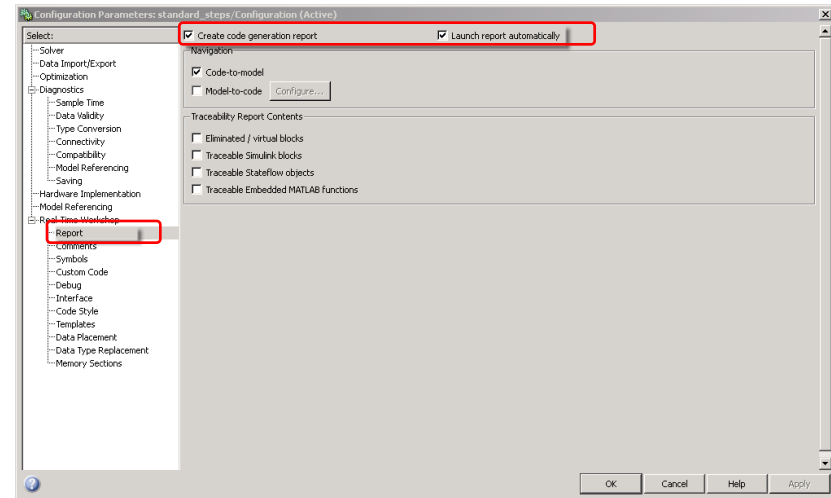
In the Real-Time Workshop Pane: Choose ert.tlc as System Target File and check the following boxes



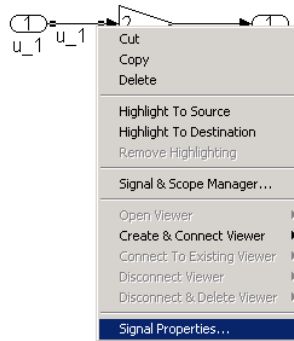
In the Optimization Pane: Select Inline Parameters



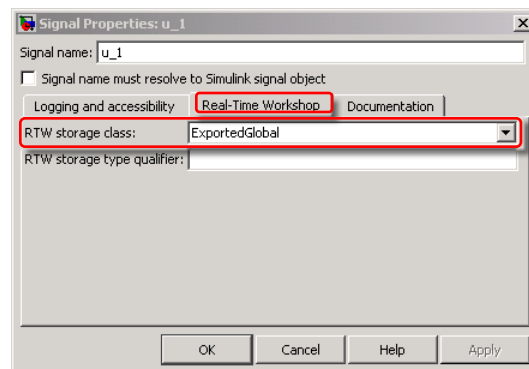
Enable code generation Report



Right Click on Signal Lines and  
Select “Signal Properties”



In the Real Time Workshop pane select the RTW storage class  
to be Exported Global



We are now ready to generate code !

# Glossary

- **CSC** : Custom Storage Class
- **Signal** : An entity whose value is expected to change during simulation. Generally a connecting wire that carries data is referred to as a 'signal'.
- **Parameter** : An entity whose value typically remains constant during simulation run-time. Constants, gains etc. are typical examples of parameters.
- **Simulink Data Object**: An entity that specify values, data types, tunability, value ranges, and other key attributes of block outputs and parameters.
- **Virtual Subsystem**: Virtual subsystems visually organize blocks but have no effect on the model's functional behavior.
- **Non-Virtual Subsystem**: A subsystem whose algorithm is executed atomically.
- **Non-Virtual Bus** : A Bus whose signals are copied/packed into a data-structure.

# C Code Pattern: Data Declaration

Code Pattern, Parameter	Code Pattern, Signal
<pre>int p_1 = 3 ;</pre> <p>Description: <i>The aim is to obtain declarations such as the ones above in the generated code. p_1 is a parameter that has a 32 bit integer data-type.</i></p>	<pre>int u_1 ;</pre> <p>Description: <i>u_1 is a signal that has an integer data-type. In this example the size of the data type int is 16 bits.</i></p>

## Data Declaration

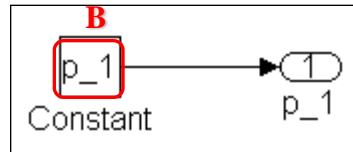
### C- Code Pattern, Parameter

**A** **B** **C**  
`int p_1 = 3;`

### Generated Code, Parameter

**A** **B** **C**  
`int32_T p_1 = 3;`

## Creation : Parameters



```
>> p_1 = mpt.Parameter
```

Current Directory		
Name	Value	Min
p_1	<1x1 mpt.Parameter>	

**mpt.Parameter: default**

**C** Value: 3  
**A** Data type: int32

Dimensions: [1 1] Complexity: real  
 Minimum: -Inf Maximum: Inf  
 Units:

Code generation options:  
 Storage class: Global (Custom)  
 Custom attributes:  
 Memory section: Default  
 Header file:  
 Owner:  
 Definition file:  
 Persistence level: 1  
 Alias:

Description:  
 p\_1 is an integer that stores the value 3.

OK Cancel Help Apply

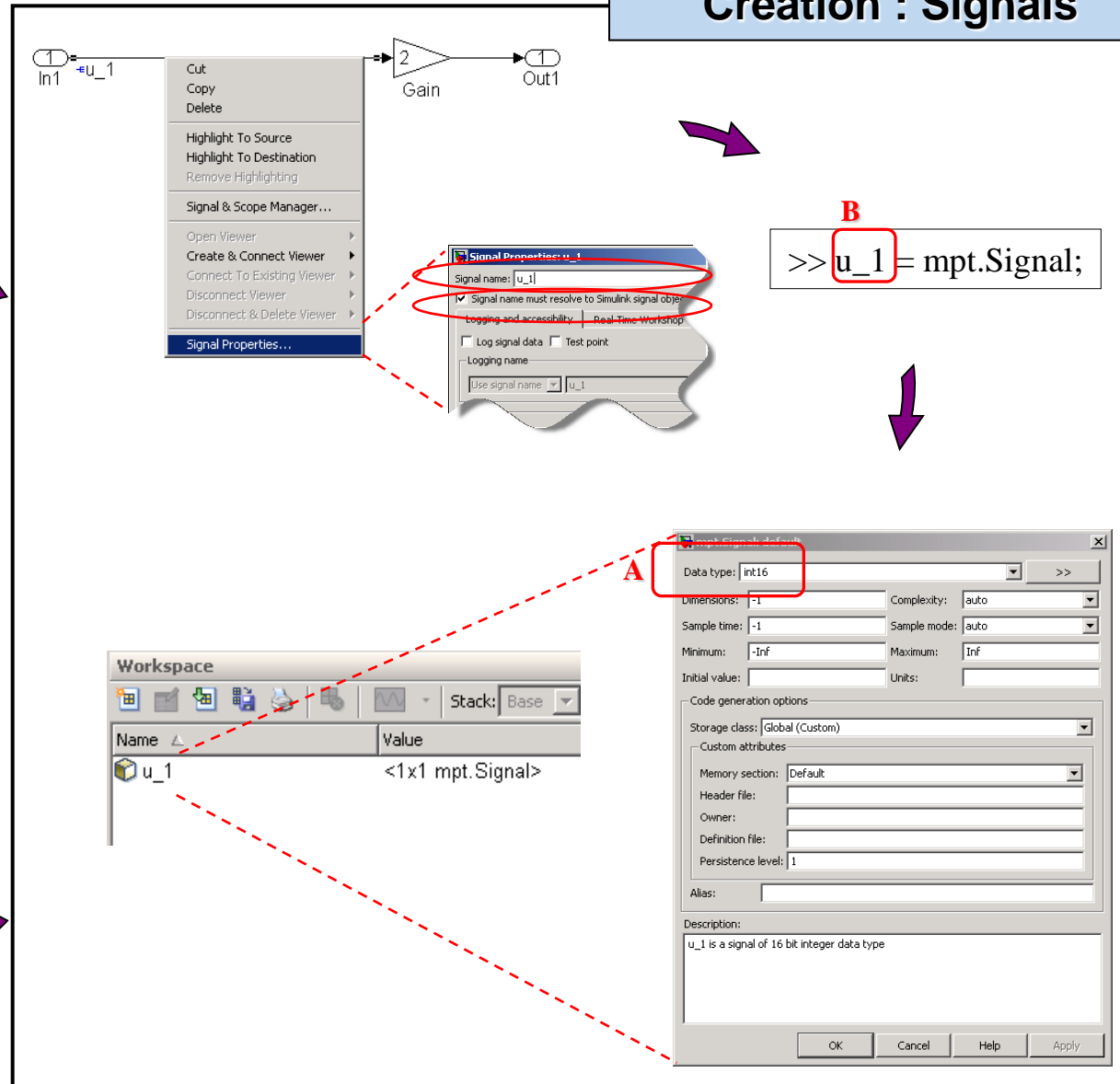


## Data Declaration

### C- Code Pattern, Signal

**A**  
`int` **B**  
`u_1;`

## Creation : Signals



### Generated Code, Signal

**A**  
`int16_T` **B**  
`u_1;`

# C Code Pattern: Data-Type Conversion

Code Pattern	Modeling Methodology
<pre>y_1 = (double) u_1 ;</pre> <p>Description: <i>u_1</i> is a 32 bit signed integer (int32). The typecasting operation converts an int32 to a double.</p>	1. Use Simulink Data-Type Conversion Block.
	2. Usage within Stateflow Chart
	3. Usage within Embedded MATLAB (EML) Block
	4. Other type conversion methods

# Type-Conversion

# Creation

SL SF EML

## C-Code Pattern

```
y_1 = (double)u_1 ;
```

## Generated Code

```
y_1 = (real_T)u_1 ;
```

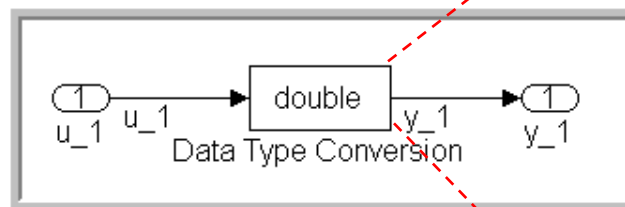
NOTE : real\_T is a Real-Time Workshop Embedded Coder Typedef for double.

rtwdemo\_typeconvsl.mdl

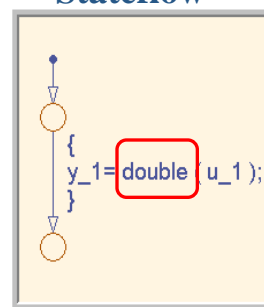
rtwdemo\_typeconvsf.mdl

rtwdemo\_typeconveml.mdl

## Simulink



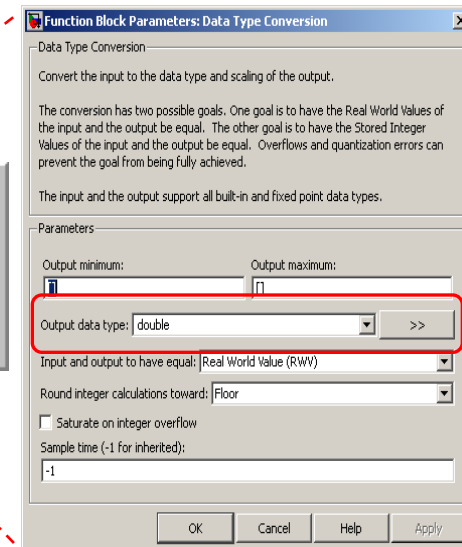
## Stateflow



## Embedded MATLAB Function

```
function y_1 = typeconv(u_1)
```

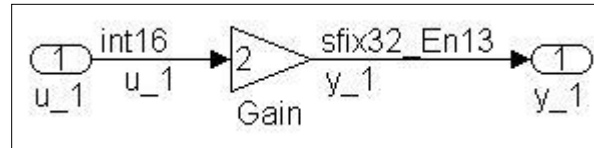
```
y_1 = double(u_1);
```



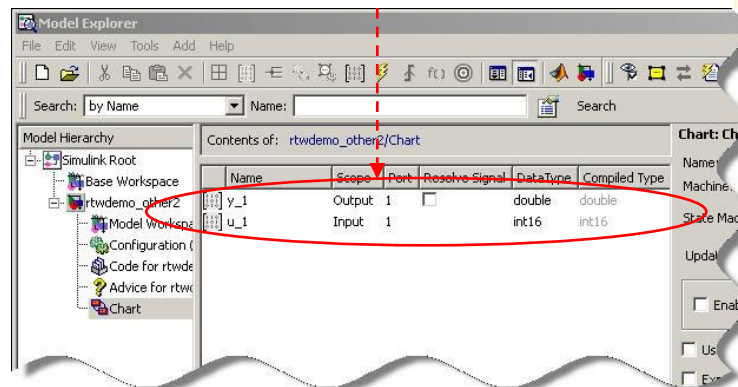
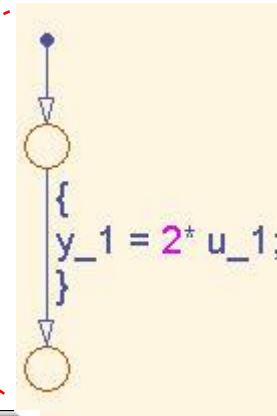
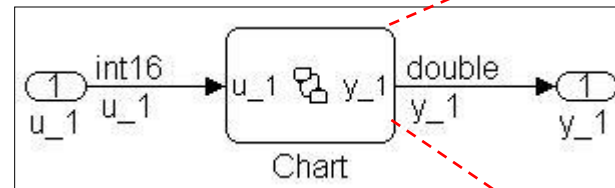
## Type-Conversion

## Other type-conversion mechanisms

**Example 1:**



**Example 2:**



rtwdemo\_other.mdl

rtwdemo\_other2.mdl

# C Code Pattern: Type Qualifiers

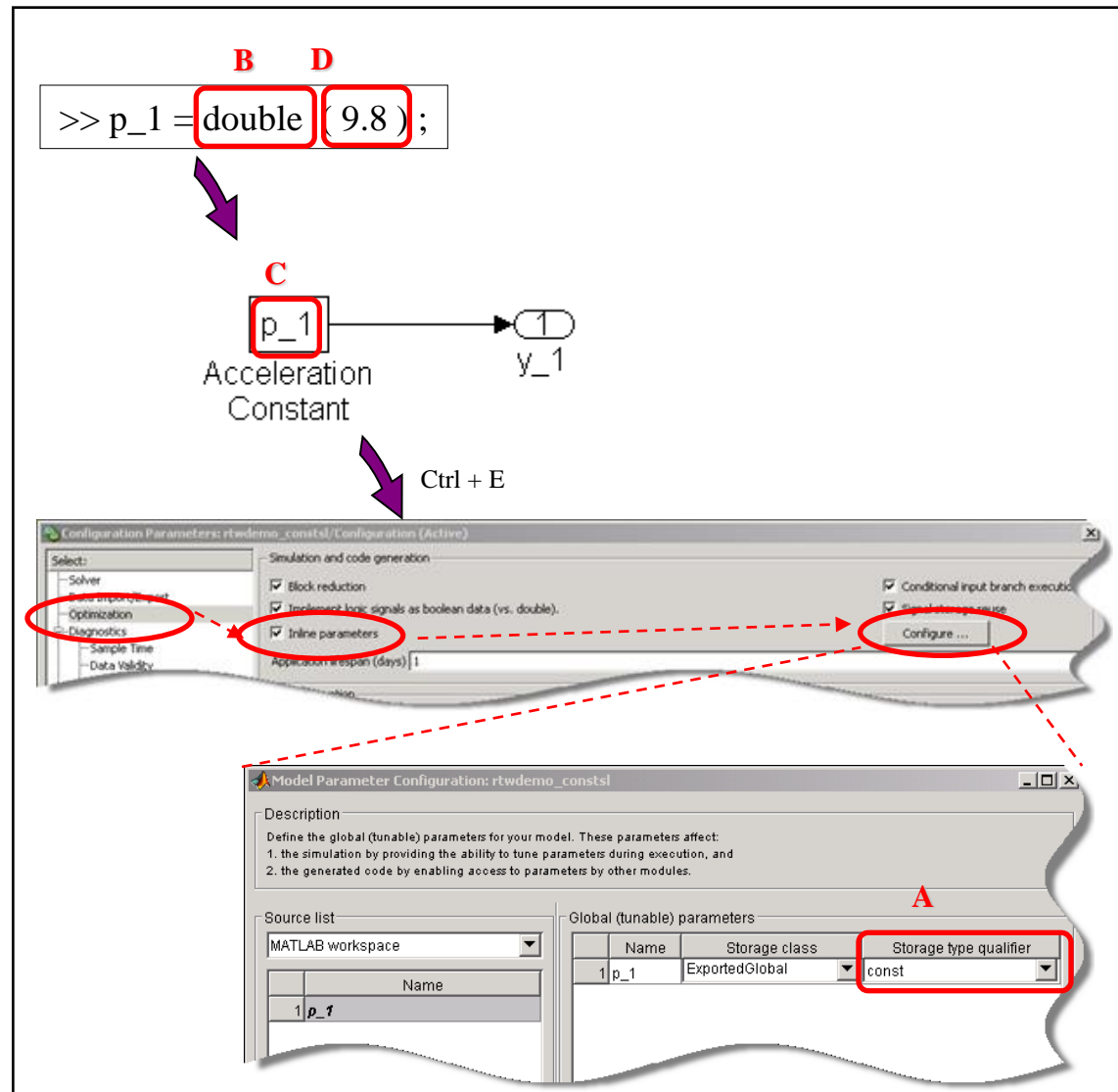
Code Pattern, Parameter	Modeling Methodology
<pre>const double p_1 = 9.8 ;</pre> <p><b>Description:</b> The aim is to obtain declarations such as the one above in the generated code. <i>p_1</i> is a constant parameter that has a double data-type.</p>	1. Create a parameter in the MATLAB workspace and make it tunable.
	2. Create a data Object and use the Const custom storage class.

## Type Qualifiers

## Tunable Parameters

### C- Code Pattern, Parameter

**A** **B** **C** **D**  
`const double p_1 = 9.8;`



### Generated Code, Parameter

**A** **B** **C** **D**  
`const real_T p_1 = 9.8;`



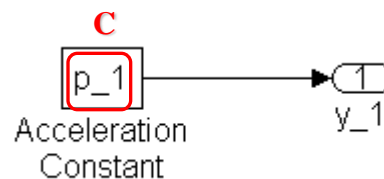
## Type Qualifiers

### C- Code Pattern, Parameter

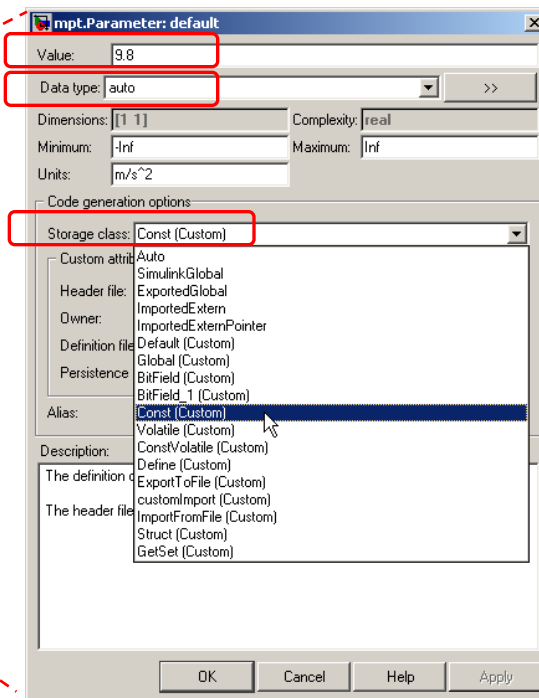
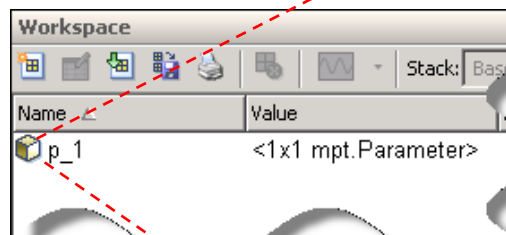
**A** **B** **C** **D**  
`const double p_1 = 9.8;`



## Simulink Data Object & CSC



`>> p_1 = mpt.Parameter`



### Generated Code, Parameter

**A** **B** **C** **D**  
`const real_T p_1 = 9.8;`



# C Code Pattern: Relational & logical Operators

Code Pattern, Relational Operator	Modeling Methodology
$y\_1 = (u\_1 > u\_2) ;$ <p>Description: <i>In this example a relational-operation is shown.</i></p>	1. Use Simulink Relational & Logical Operator Blocks.
	2. Usage within Stateflow Chart (primarily for transitions)
	3. Usage within Embedded MATLAB (EML) Block

Code Pattern, Logical Operator	Modeling Methodology
$y\_1 = ( u\_1 \parallel u\_2 );$ <p>Description: <i>u_1, u_2 are Booleans. In this example a logical-operation is shown.</i></p>	1. Use Simulink Relational & Logical Operator Blocks.
	2. Usage within Stateflow Chart (primarily for transitions)
	3. Usage within Embedded MATLAB (EML) Block



## Relational & Logical Operations

### C- Code Pattern, Relational Operator

$$y_1 = (u_1 \overset{\text{A}}{>} u_2);$$

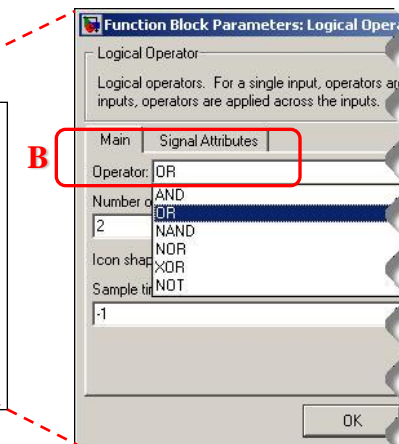
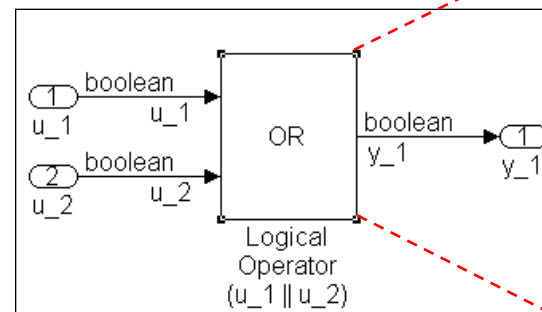
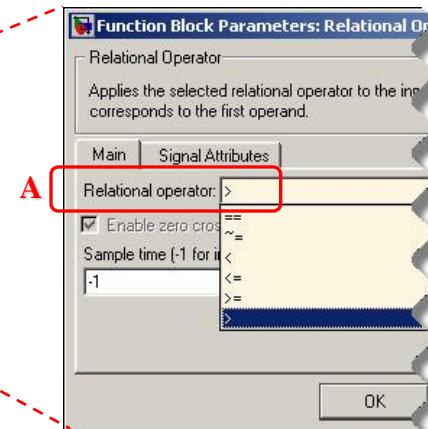
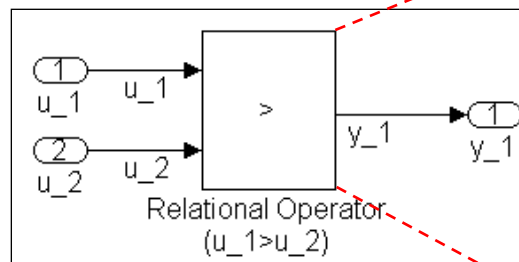
### C- Code Pattern, Logical Operator

$$y_1 = (u_1 \overset{\text{B}}{||} u_2);$$

### Generated Code, Relational Operator

$$y_1 = (u_1 \overset{\text{A}}{>} u_2);$$

### Generated Code, Logical Operator

$$y_1 = (u_1 \overset{\text{B}}{||} u_2);$$


# Creation

SL SF EML

## Relational & Logical Operations

### C- Code Pattern, Relational Operator

$$y\_1 = (u\_1 \overset{\text{A}}{>} u\_2);$$

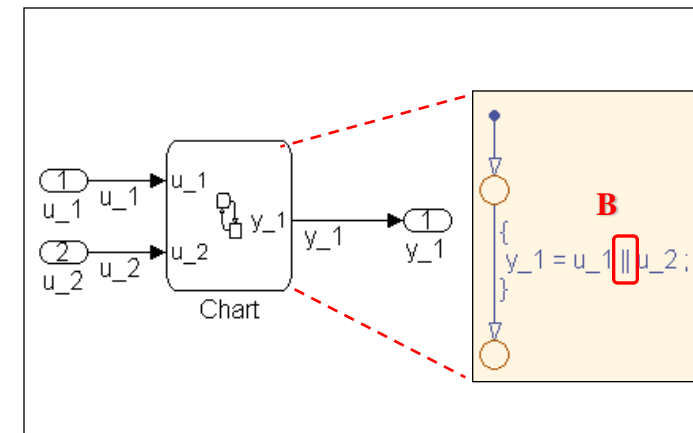
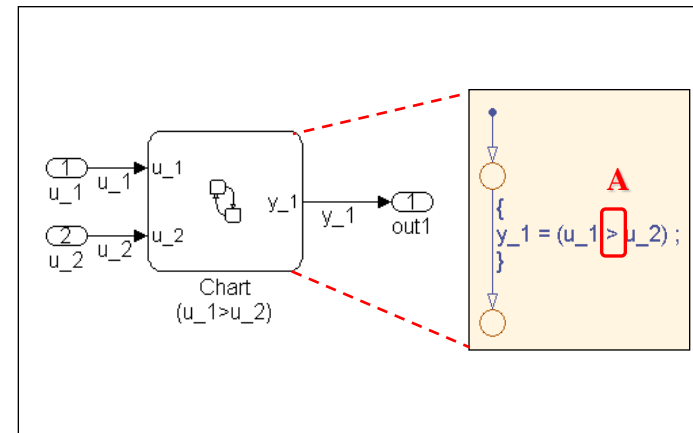
### C- Code Pattern, Logical Operator

$$y\_1 = (u\_1 \overset{\text{B}}{||} u\_2);$$

### Generated Code, Relational Operator

$$y\_1 = (u\_1 \overset{\text{A}}{>} u\_2);$$

### Generated Code, Logical Operator

$$y\_1 = (u\_1 \overset{\text{B}}{||} u\_2);$$


## Relational & Logical Operations

### C- Code Pattern, Relational Operator

$$y\_1 = (u\_1 \overset{\text{A}}{>} u\_2);$$

### C- Code Pattern, Logical Operator

$$y\_2 = (u\_1 \overset{\text{B}}{||} u\_2);$$

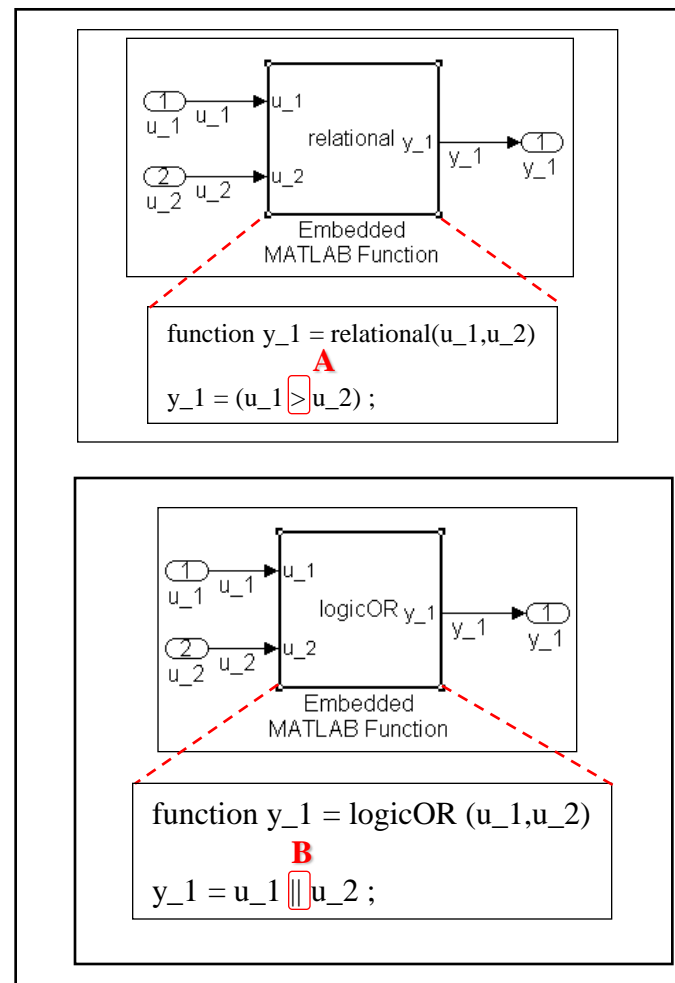
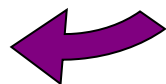
### Generated Code, Relational Operator

$$y\_1 = u\_1 \overset{\text{A}}{>} u\_2;$$

### Generated Code, Logical Operator

```
if ((!u_1) && (!u_2)) {
    y_1 = 0U;
} else {
    y_1 = 1U;
}
```

rtwdemo\_relationaleml.mdl  
rtwdemo\_logicalOREml.mdl



# C Code Pattern: Bitwise-Logic operations

Code Pattern, AND operation	Modeling Methodology
$y\_1 = u\_1 \& 0xD9 ;$  <i>Description: u_1 is an 8 bit unsigned integer. In this example, a Bitwise-logical operation with a bit-mask is shown</i>	1. Use Simulink Bitwise-Operator Block.
	2. Use Stateflow Chart
	3. Use Embedded MATLAB (EML) Block

Code Pattern, OR operation	Modeling Methodology
$y\_2 = u\_2   u\_3 ;$  <i>Description: u_2, u_3 are 8 bit unsigned integers. In this example a Bitwise-logical operation between two numbers is shown.</i>	1. Use Simulink Bitwise-Operator Block.
	2. Use Stateflow Chart
	3. Use Embedded MATLAB (EML) Block

# Bitwise-Logic

# Creation

SL SF EML

## C- Code Pattern, AND

$$y\_1 = u\_1 \overset{A}{\&} \overset{B}{0xD9};$$

## C- Code Pattern, OR

$$y\_2 = u\_2 \overset{C}{|} u\_3;$$

## Generated Code, AND

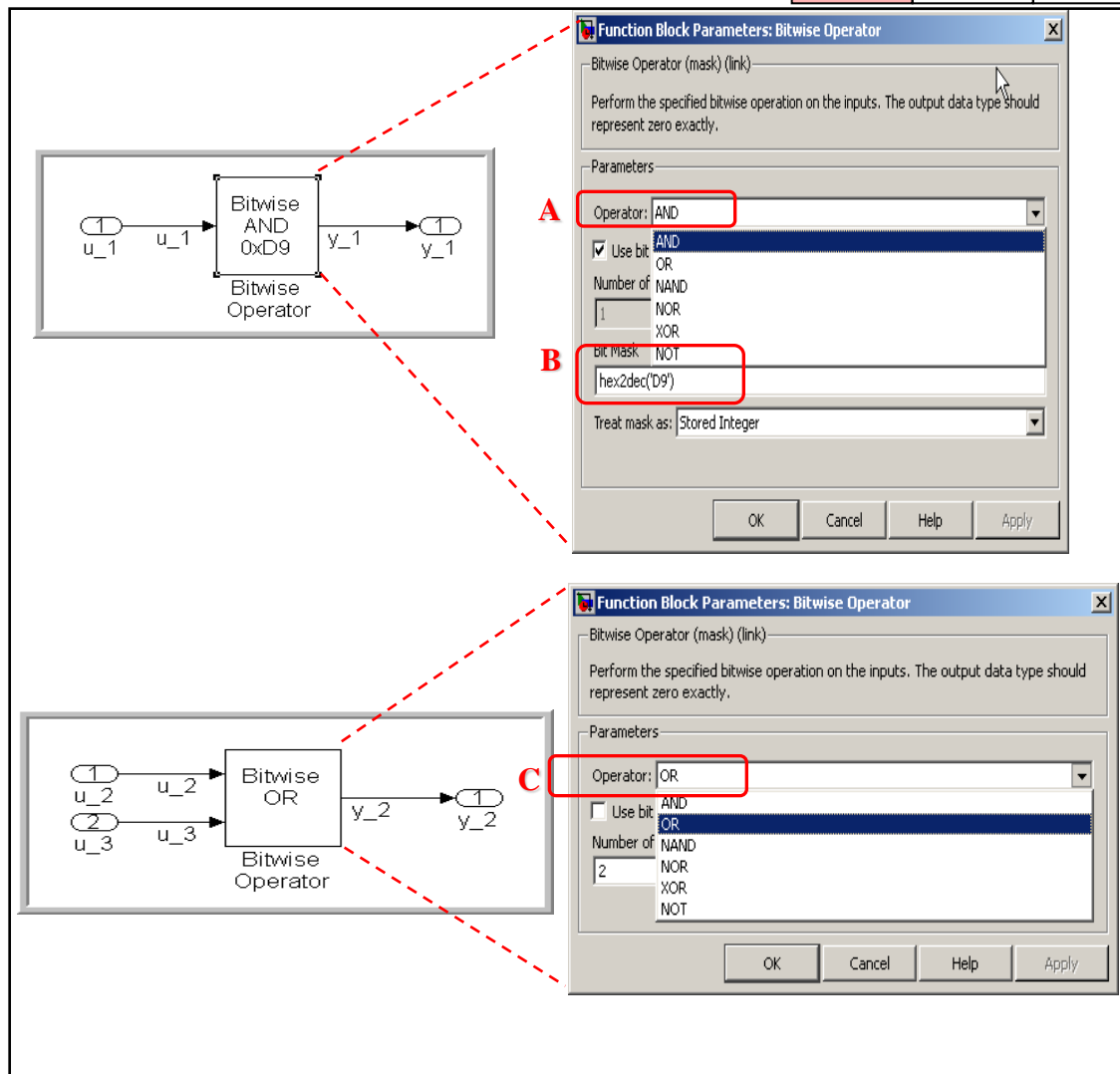
$$y\_1 = (\text{uint8\_T})(u\_1 \overset{A}{\&} \overset{B}{217U});$$

## Generated Code, OR

$$y\_2 = (\text{uint8\_T})(u\_2 \overset{C}{|} u\_3);$$

rtwdemo\_logicANDsl.mdl

rtwdemo\_logicORsl.mdl



## Bitwise-Logic

## Creation

SL SF EML

### C- Code Pattern, AND

$$y_1 = u_1 \text{ \textcolor{red}{A} } 0xD9;$$

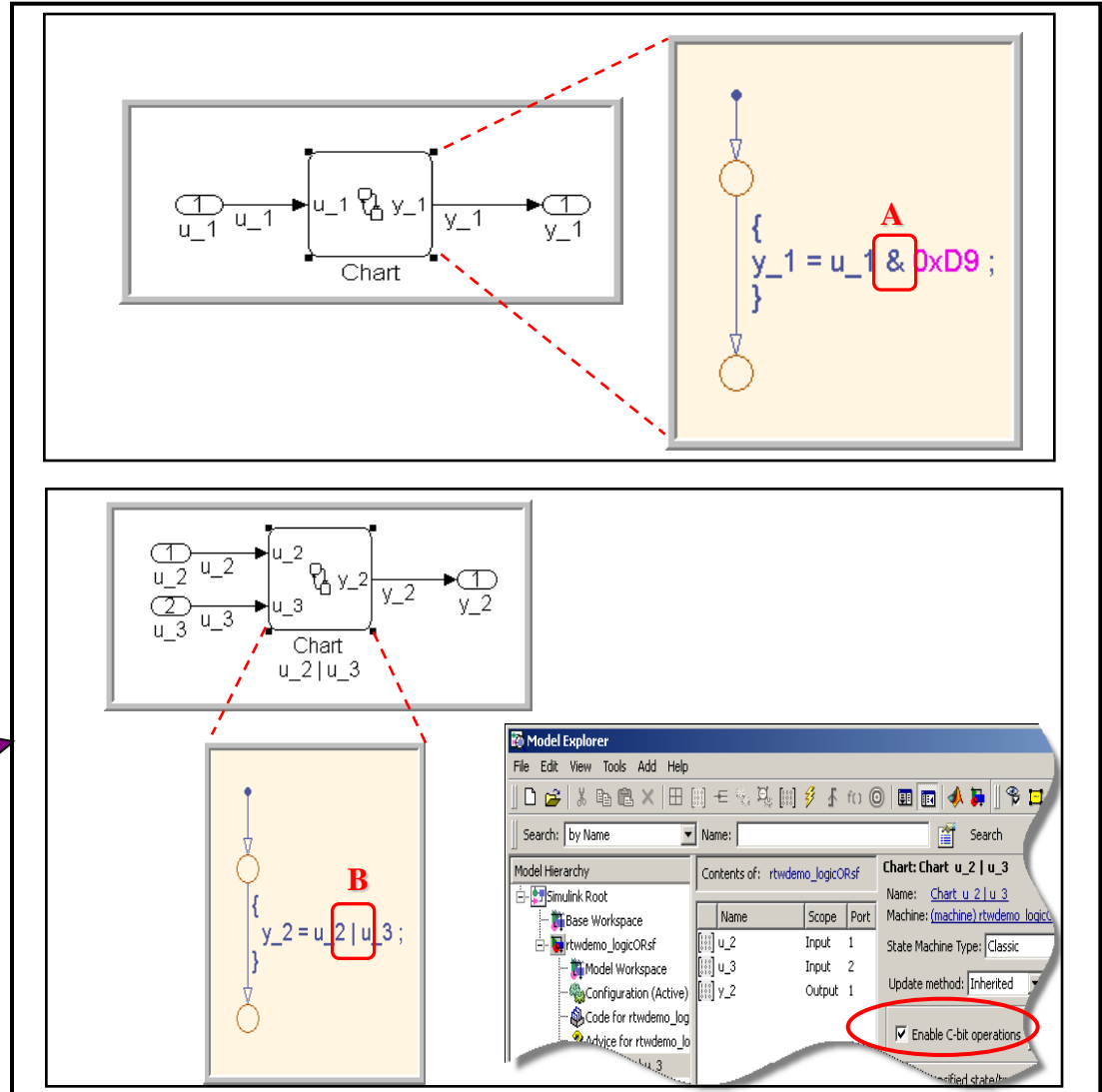
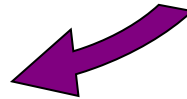

### C- Code Pattern, OR

$$y_2 = u_2 \text{ \textcolor{red}{B} } u_3;$$

### Generated Code, AND

$$y_1 = (\text{uint8\_T})(u_1 \text{ \textcolor{red}{A} } 0xD9);$$

### Generated Code, OR

$$y_2 = (\text{uint8\_T})(u_2 \text{ \textcolor{red}{B} } u_3);$$


rtwdemo\_logicANDsf.mdl  
rtwdemo\_logicORSf.mdl

## Bitwise-Logic

### C- Code Pattern, AND

$y_1 = u_1 \overset{\text{A}}{\&} 0xD9;$

### C- Code Pattern, OR

$y_2 = u_2 \overset{\text{B}}{|} u_3;$

### Generated Code, AND

$y_1 = (\text{uint8\_T})(u_1 \overset{\text{A}}{\&} 217);$

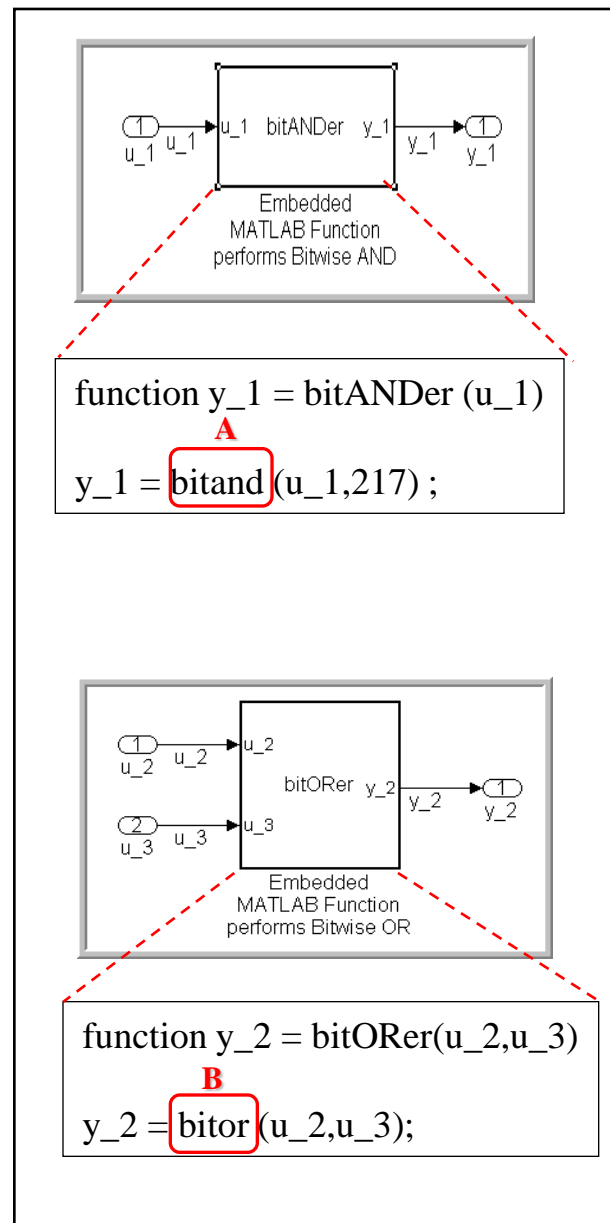
### Generated Code, OR

$y_2 = (\text{uint8\_T})(u_2 \overset{\text{B}}{|} u_3);$



rtwdemo\_logicANDeml.mdl

rtwdemo\_logicOREml.mdl



## Creation

SL	SF	EML
----	----	-----

# C Code Pattern: If-Then-Else

Code Pattern	Modeling Methodology
<pre> if (u_1 &gt; u_2) {     y_1 = u_1; } else {     y_1 = u_2; }         </pre>	1. Use Simulink Switch Block
	2. Use Stateflow Chart
	3. Use Embedded MATLAB (EML) Block



## If-Then-Else

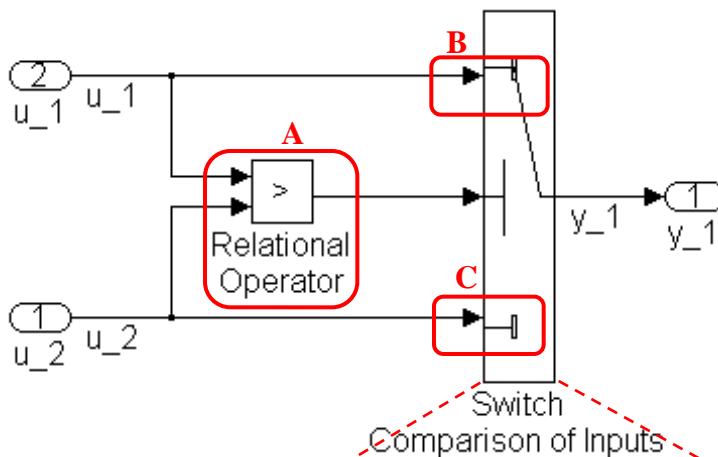
## Creation

SL SF EML

### C- Code Pattern

```

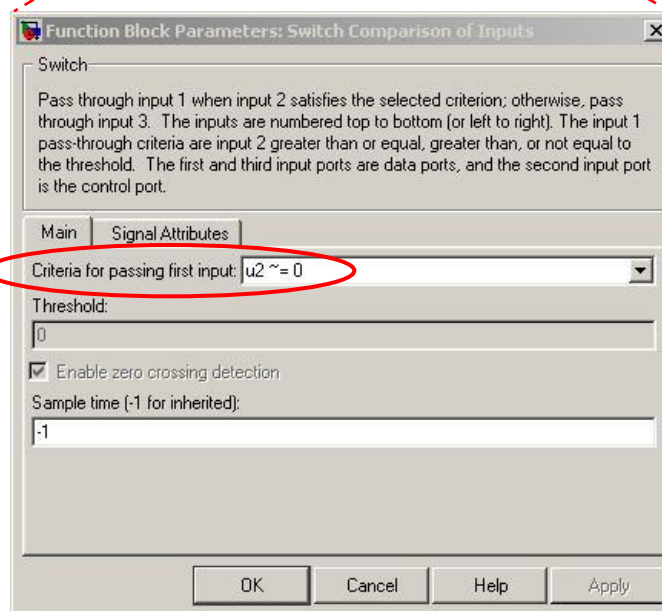
A if (u_1 > u_2)
{
B   y_1 = u_1;
}
else
{
C   y_1 = u_2;
}
    
```



### Generated ode

```

A if (u_1 > u_2)
{
B   y_1 = u_1;
}
else {
C   y_1 = u_2;
}
    
```



## If-Then-Else

## Creation

SL SF EML

### C- Code Pattern

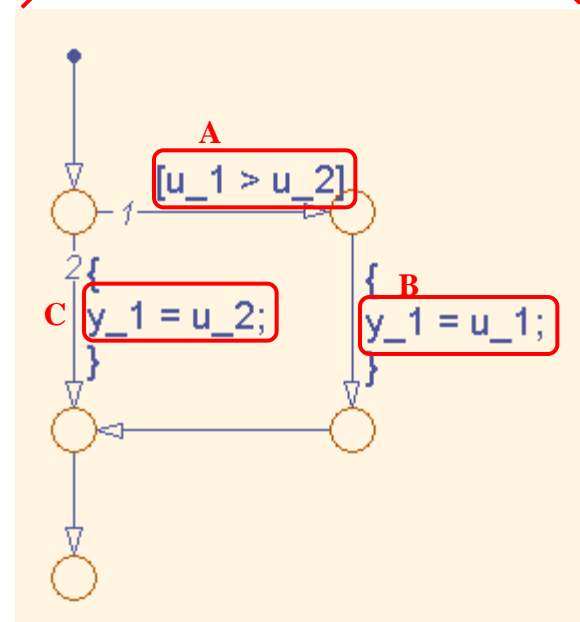
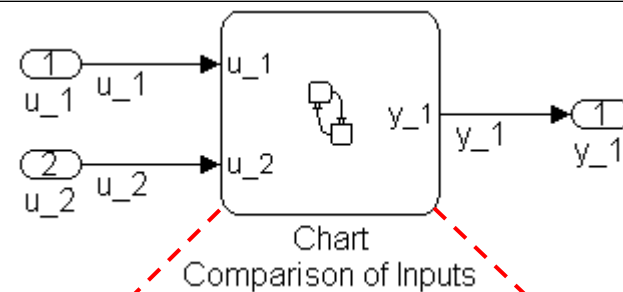
```

A if (u_1 > u_2)
{
B   y_1 = u_1;
}
else
{
C   y_1 = u_2;
}
    
```

### Generated Code

```

A if (u_1 > u_2)
{
B   y_1 = u_1;
}
else
{
C   y_1 = u_2;
}
    
```



## If-Then-Else

## Creation

SL	SF	EML
----	----	-----

### C- Code Pattern

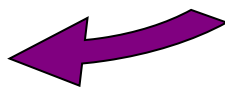
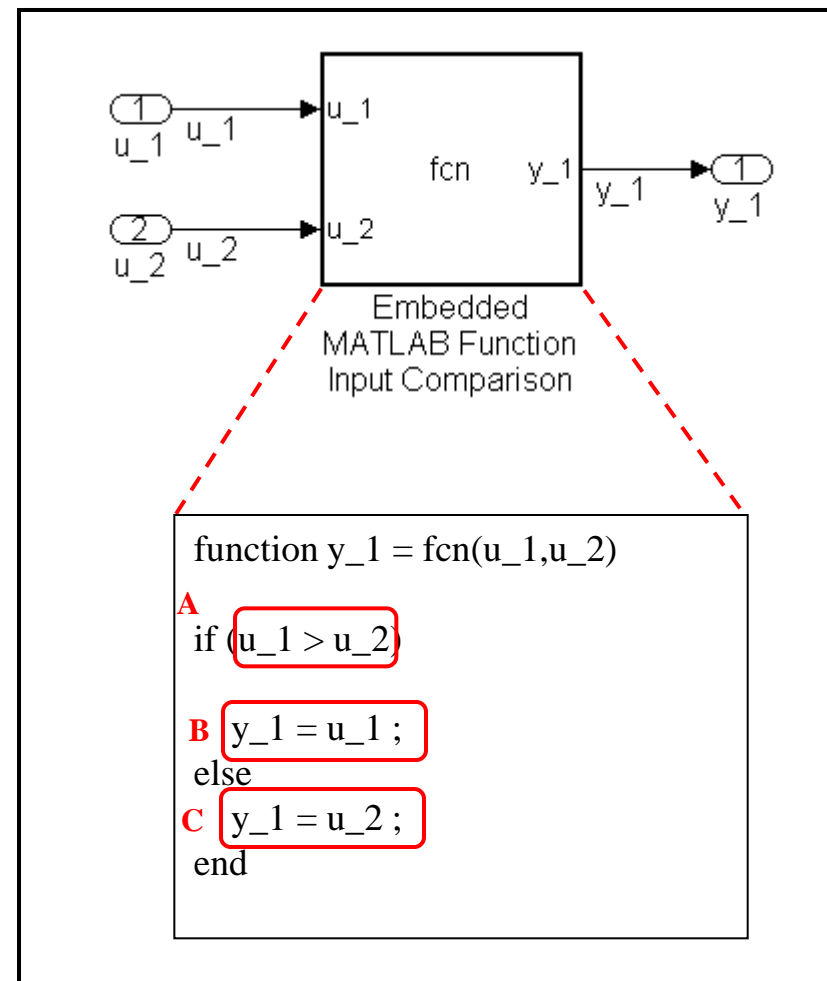
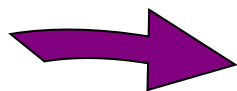
```

A if (u_1 > u_2)
{
B   y_1 = u_1;
}
else
{
C   y_1 = u_2;
}
    
```

### Generated Code

```

A if (u_1 > u_2)
{
B   y_1 = u_1;
}
else {
C   y_1 = u_2;
}
    
```



# C Code Pattern: Switch-Case

Code Pattern	Modeling Methodology
<pre> switch (u_1) {     case 2:         y_1 = u_2;         break;      case 3:         y_1 = u_3 ;         break;      default:         y_1 = u_4;         break;  }</pre>	1. Use Simulink Switch-Case Block
	2. Use Embedded MATLAB (EML) Block

## Switch-Case

# Creation

SL

EML

### C- Code Pattern

```
switch (u_1)
```

**A** case 2:

```
y_1 = u_2;
break;
```

```
case 3:
y_1 = u_3;
break;
```

**B** default:

```
y_1 = u_4;
break;
```

```
}
```

### Generated Code

```
switch (u_1) {
```

**A** case 2:

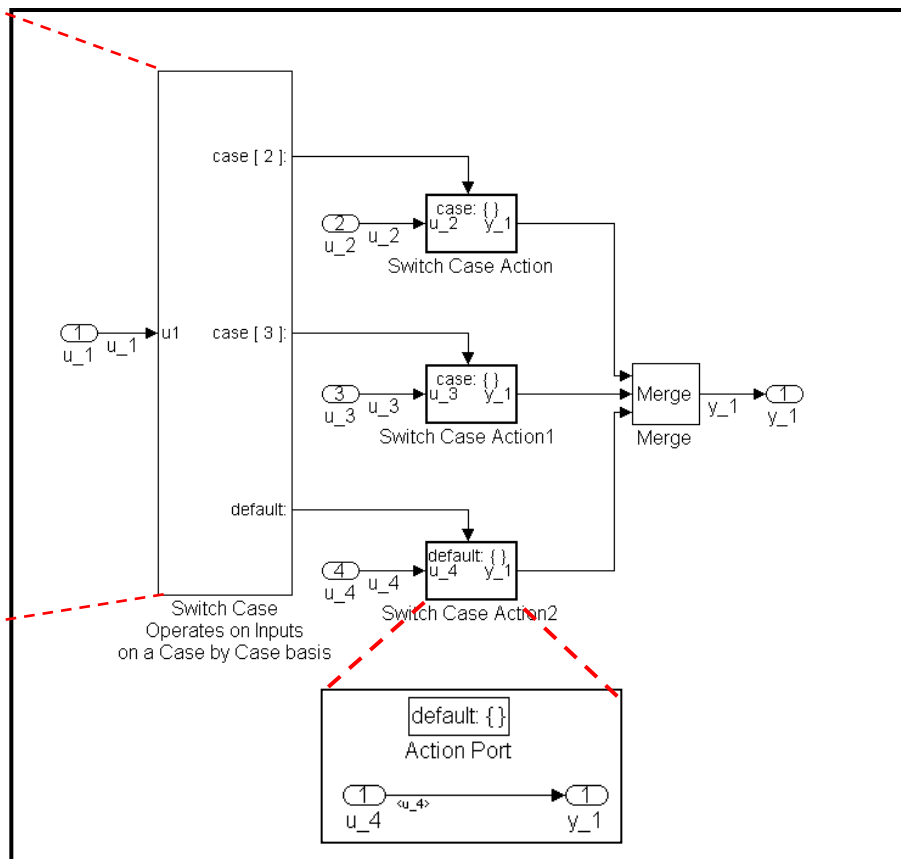
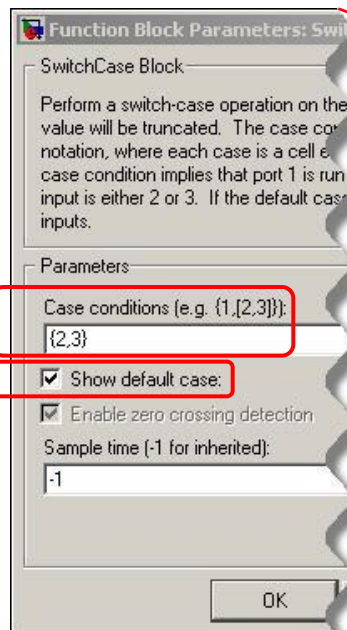
```
y_1 = u_2;
break;
```

```
case 3:
y_1 = u_3;
break;
```

**B** default:

```
y_1 = u_4;
break;
```

```
}
```



## Switch-Case

## Creation

SL

EML

### C- Code Pattern

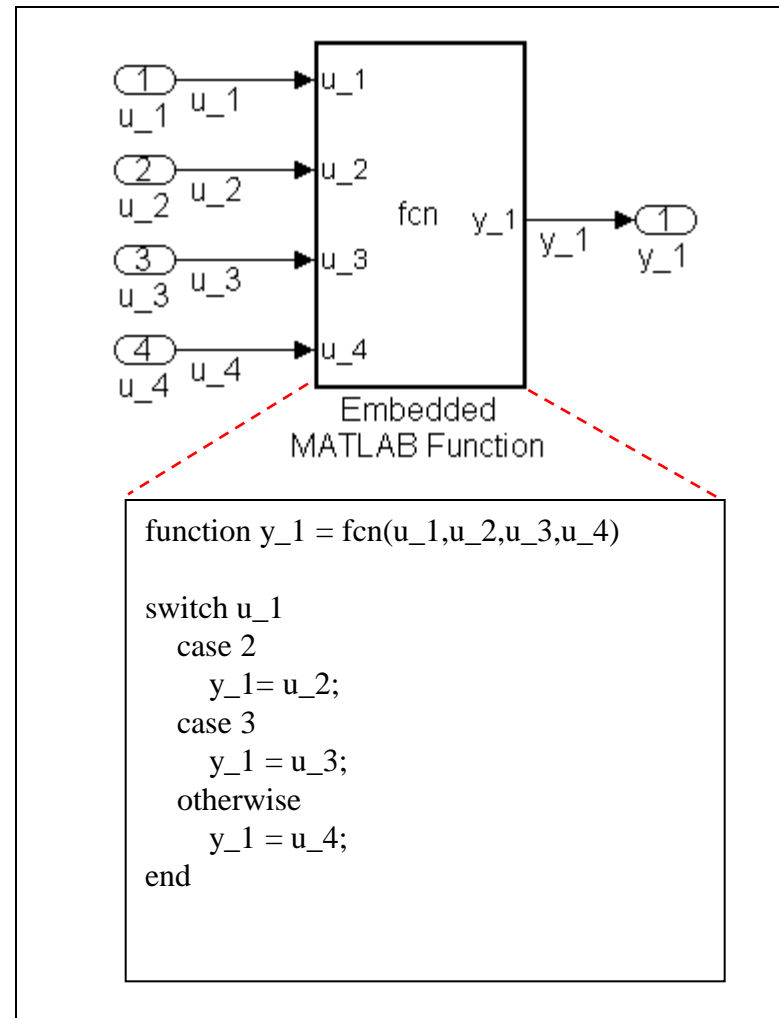
```
switch (u_1)
{
    case 2:
        y_1 = u_2;
        break;
    case 3:
        y_1 = u_3;
        break;
    default:
        y_1 = u_4;
        break;
}
```



### Generated Code

```
switch (u_1) {
    case 2U:
        y_1 = u_2;
        break;
    case 3U:
        y_1 = u_3;
        break;

    default:
        y_1 = u_4;
        break;
}
```



# C Code Pattern: For - Loop

Code Pattern	Modeling Methodology
<pre> y_1 = 0;  for(inx = 0; inx &lt; 10; inx++) {     y_1 = u_1 [ inx ] + y_1 ; } </pre> <p><i>Description: for-loop for summing up elements of an array. In this example, u_1 is a vector with dimension 10.</i></p>	1. Use Simulink For-Iterator Block
	2. Use Stateflow Chart
	3. Use Embedded MATLAB (EML) Block

## For-Loop

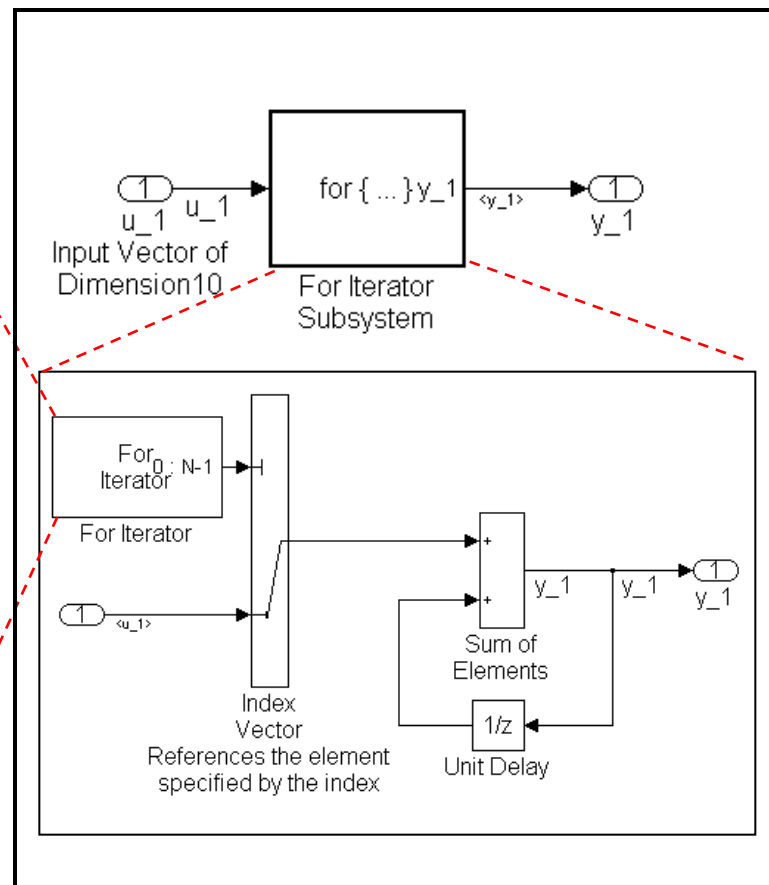
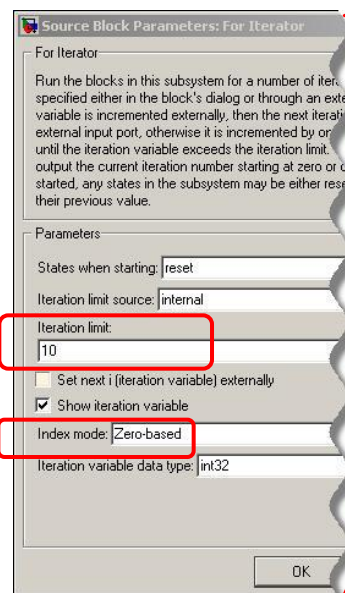
## Creation

SL SF EML

### C- Code Pattern

```

y_1 = 0;
for (A inx = 0; B inx < 10; inx++)
{
    y_1 = u_1 [ inx ] + y_1 ;
}
    
```



### Generated Code

```

x_1 = 0.0;
for (A s1_iter = 0; B s1_iter < 10; s1_iter++) {
    y_1 = u_1[s1_iter] + x_1;
    x_1 = y_1;
}
    
```



rtwdemo\_forsl.mdl



## For-Loop

## Creation

SL SF EML

### C- Code Pattern

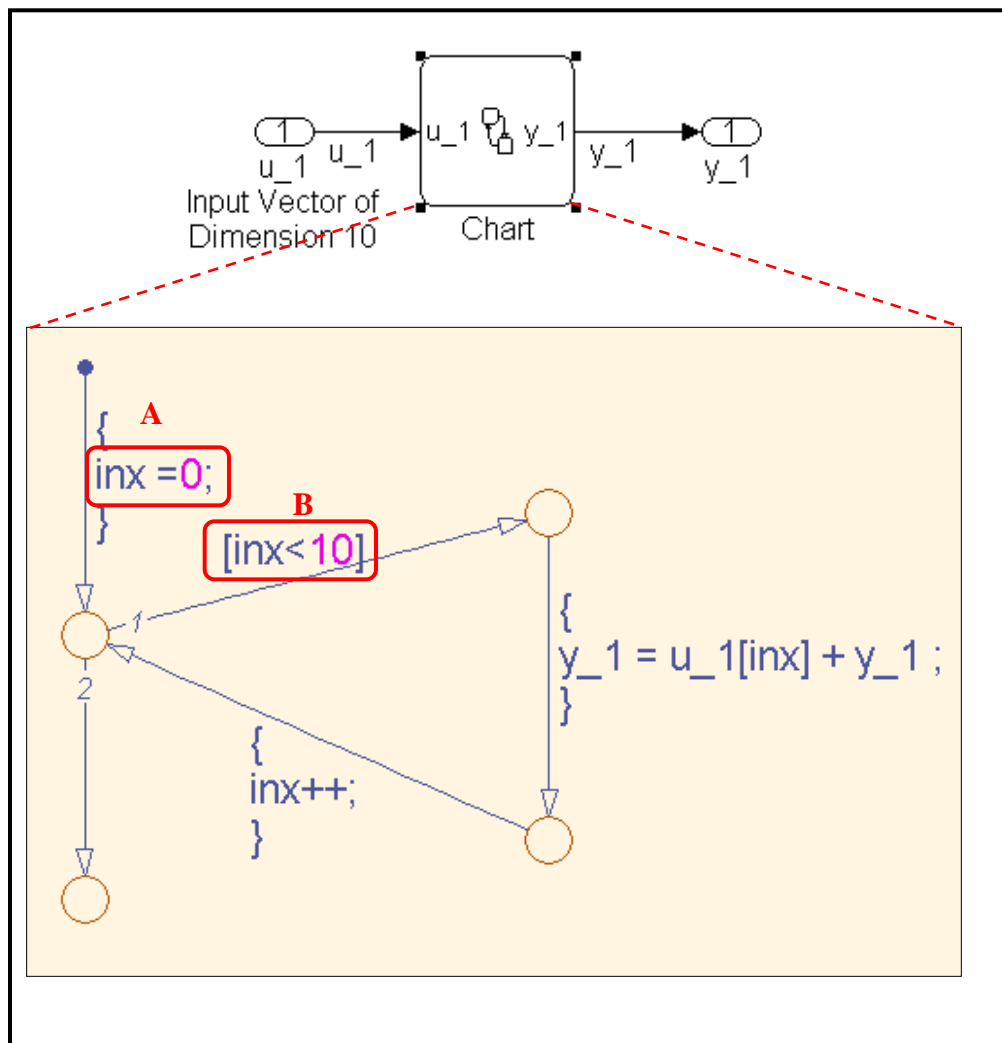
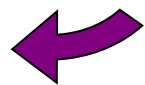
```

y_1 = 0;
for (A:inx = 0; B:inx < 10; inx++)
{
    y_1 = u_1 [ inx ] + y_1 ;
}
    
```

### Generated Code

```

for (A:sf_inx = 0; B:sf_inx < 10; sf_inx++)
{
    y_1 = u_1[sf_inx] + y_1;
}
    
```



## For-Loop

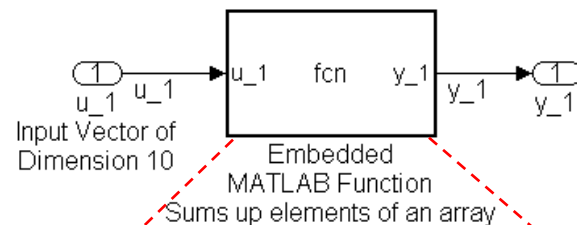
## Creation

SL | SF | EML

### C- Code Pattern

```

y_1 = 0;
for (inx = 0; inx < 10; inx++)
{
    y_1 = u_1 [ inx ] + y_1 ;
}
    
```

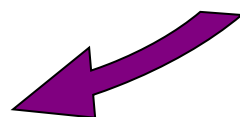


```

function y_1 = fcn(u_1)

y_1 = 0;

for inx=1:10
    y_1 = u_1(inx) + y_1 ;
end
    
```



### Generated Code

```

y_1 = 0.0;
for eml_inx = 0; eml_inx < 10; eml_inx++
{
    y_1 = u_1[eml_inx] + y_1;
}
    
```

rtwdemo\_forloopeml.mdl

NOTE: In M-Script, the index is One-based

# C Code Pattern: While - Loop

Code Pattern	Modeling Methodology
<pre>while( flag &amp;&amp; (num_iter&lt;=100) ) {     flag = func ( );     num_iter ++ ; }</pre> <p><i>Description: A while loop used to ensure that a function returns "TRUE". The Number of iterations allowed is fixed and set to 100</i></p>	1. Use Simulink While Block
	2. Use Stateflow Chart
	3. Use Embedded MATLAB (EML) Block

## While-Loop

# Creation

SL SF EML

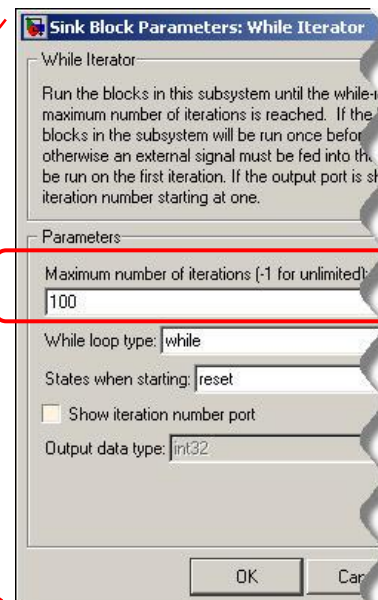
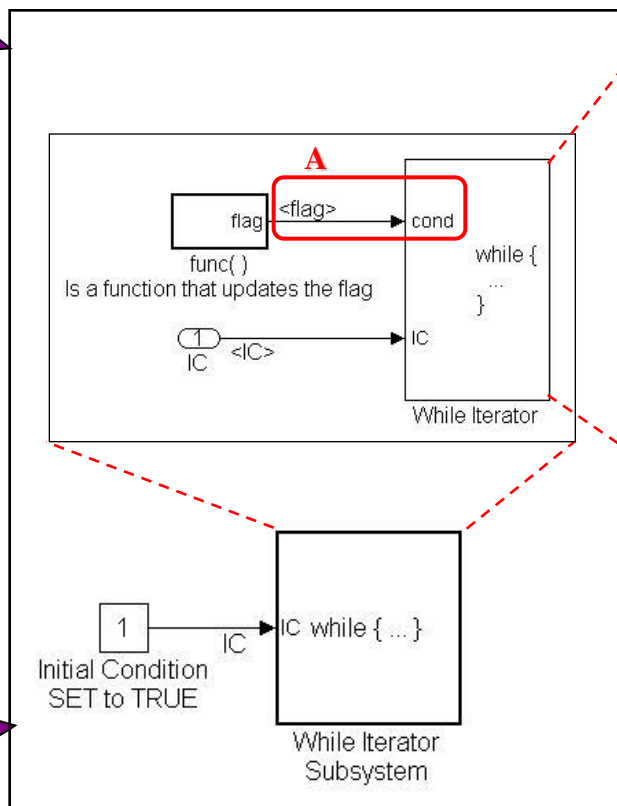
### C- Code Pattern

```
while ( A B )
{
    flag = func ( );
    num_iter ++;
}
```

### Generated Code

```
while ( A B )
{
    func();
    loopCond = flag;
    s1_iter++;
}
```

NOTE: 'flag' is a global variable updated by the function func ( )



rtwdemo\_whilesl.mdl

## While-Loop

## Creation

SL SF EML

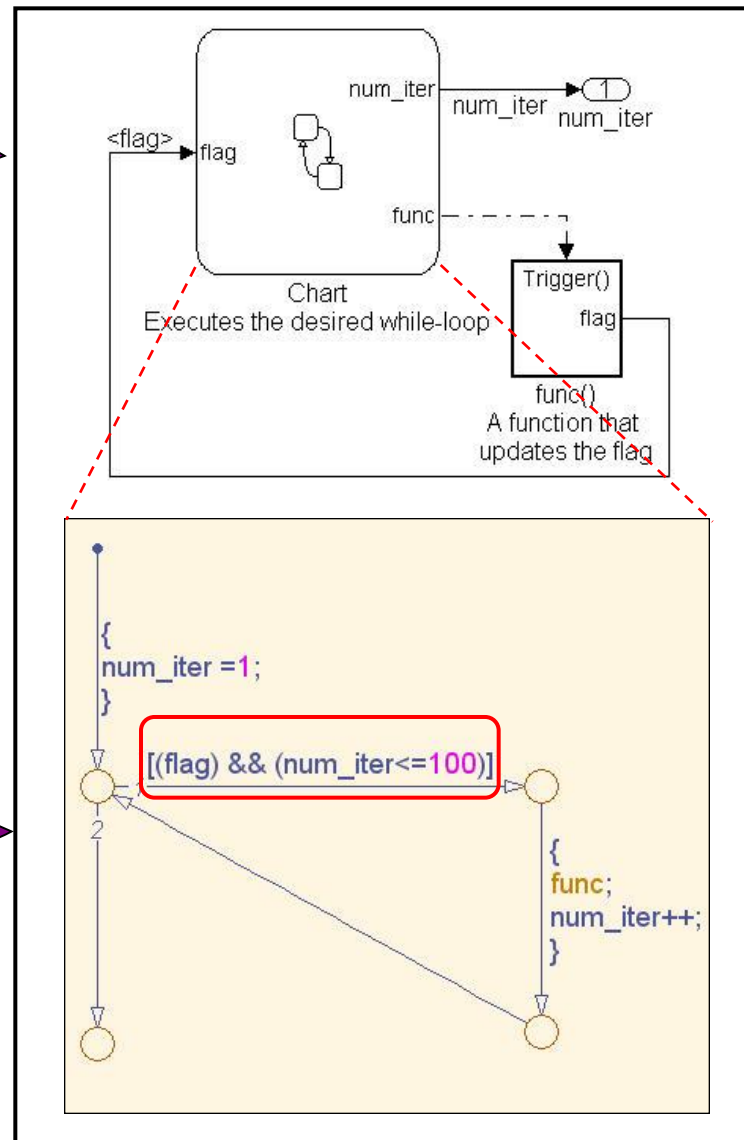
### C- Code Pattern

```
while ( flag && (num_iter <= 100) )
{
    flag = func ( );
    num_iter ++;
}
```

### Generated Code

```
while (flag && (num_iter <= 100))
{
    func();
    num_iter = num_iter + 1;
}
```

NOTE: 'flag' is a global variable updated by the function func ( )



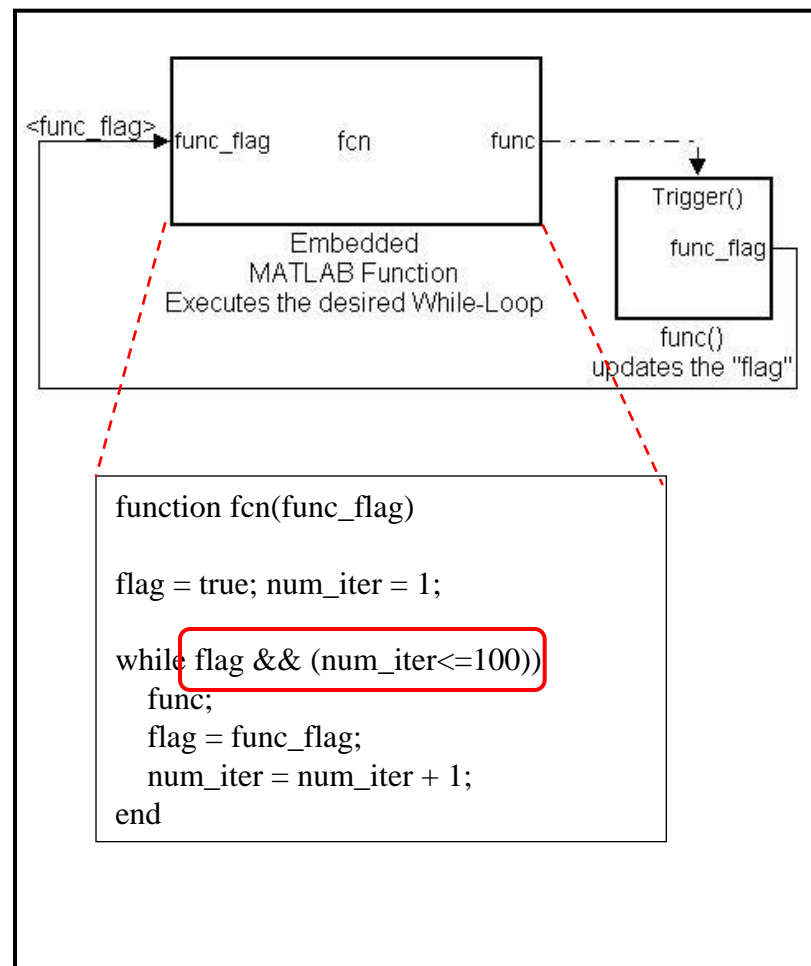
## While-Loop

## Creation

SL	SF	EML
----	----	-----

### C- Code Pattern

```
while ( flag && (num_iter <= 100) )
{
    flag = func ( );
    num_iter ++;
}
```



### Generated Code

```
for (eml_num_iter = 1; eml_flag && (eml_num_iter <= 100); eml_num_iter++)
{
    func();
    eml_flag = eml_func_flag;
}
```

NOTE: The function func ( ) updates the flag

# C Code Pattern: do-while Loop

Code Pattern	Modeling Methodology
<pre> num_iter = 1; do {     flag = func ( );     num_iter++; } while( flag &amp;&amp; (num_iter&lt;=100)) ; </pre> <p><i>Description: A do-while loop used to ensure that a function returns "TRUE". The Number of iterations allowed is fixed and set to 100.</i></p>	1. Use Simulink While Block
	2. Use Stateflow Chart

## do while loop

## Creation

SL

SF

### C- Code Pattern

```

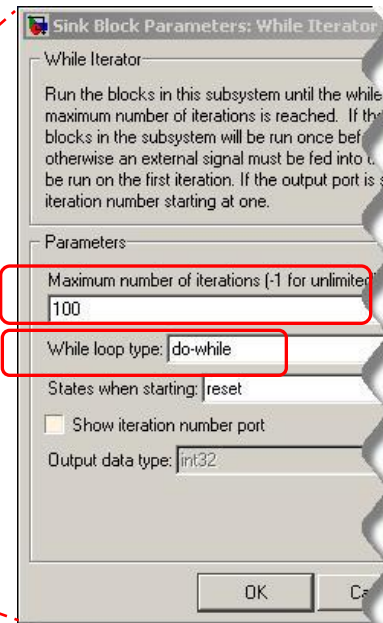
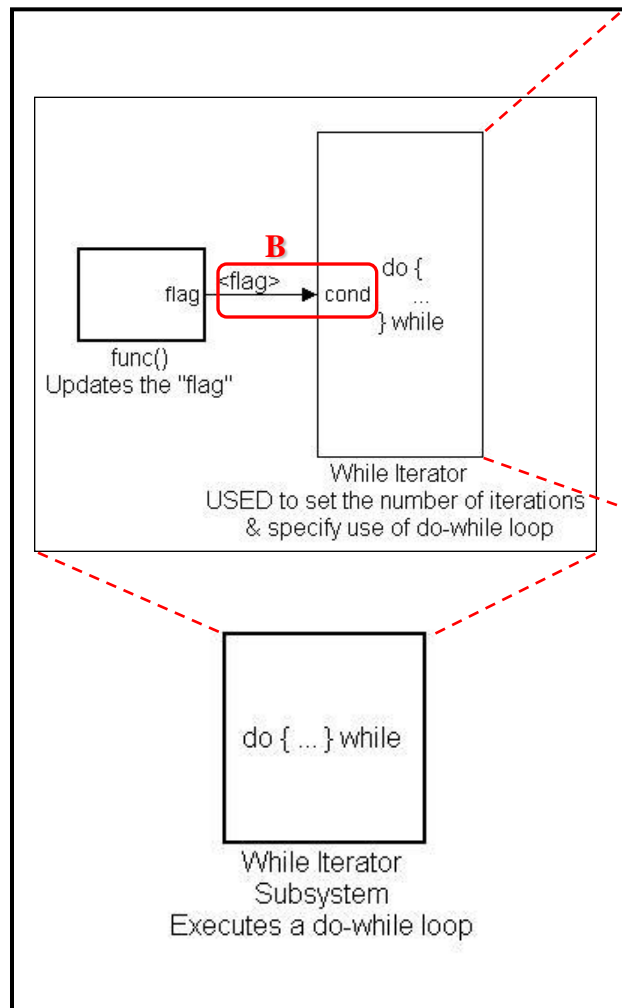
num_iter = 1;
A do {
    flag = func();
    num_iter++;
}
while B (flag && C (num_iter <= 100));
    
```

### Generated Code

```

s1_iter = 1;
A do {
    func();
    s1_iter++;
}
while B (flag && C (s1_iter <= 100));
    
```

NOTE: 'flag' is a global variable updated by the function func ( )



rtwdemo\_dowhiles1.mdl



# do while loop

# Creation

SL

SF

## C- Code Pattern

```

A
num_iter = 1;
do {
    B flag = func();
    num_iter++;
}
C while (flag && (num_iter <= 100));
    
```



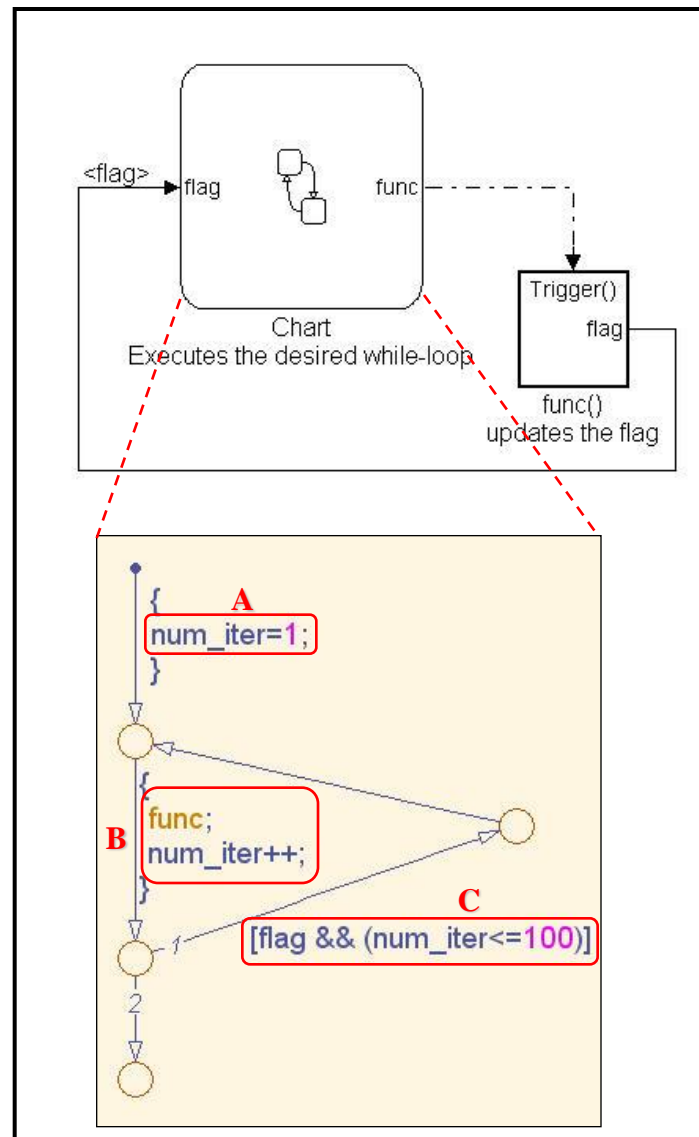
## Generated Code

```

A
sf_num_iter = 1;
do {
    B func();
    sf_num_iter++;
} while (C (flag && (sf_num_iter <= 100)));
    
```

NOTE: 'flag' is a global variable updated by the function func ( )

rtwdemo\_dowhilesf.mdl



# C Code Pattern: Functions

Code Pattern, void <fcn> (void)	Modeling Methodology
<pre>void adder (void) {     y_1 = u_1 + u_2; }</pre> <p><i>Description: Obtain functions in the generated code that operate on global variables. Here u_1, u_2 and y_1 are all global variables.</i></p>	<p>Create a subsystem and treat as atomic unit.</p>

## functions

## Creation with Atomic Subsystem

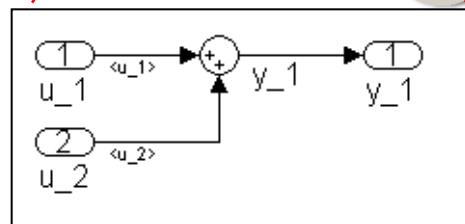
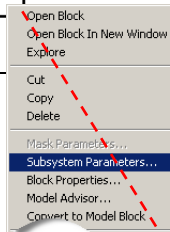
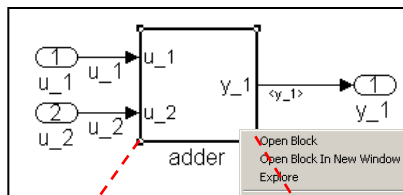
### C- Code Pattern

```
void adder (void)
{
    y_1 = u_1 + u_2;
}
```

### Generated Code

<function>.c

```
void adder(void)
{
    y_1 = u_1 + u_2;
}
```



**Function Block Parameters: adder**

Subsystem  
Select the settings for the subsystem block.

Parameters

Show port labels: FromPortIcon

Read/Write permissions: ReadWrite

Name of error callback function:

Permit hierarchical resolution: All

☒ Treat as atomic unit

☐ Minimize algebraic loop occurrences

Sample time (-1 for inherited): -1

Real-Time Workshop system code: Function

Real-Time Workshop function name options: User specified

Real-Time Workshop function name: adder

Real-Time Workshop file name options: User specified

Real-Time Workshop file name (no extension): adder

☐ Function with separate data

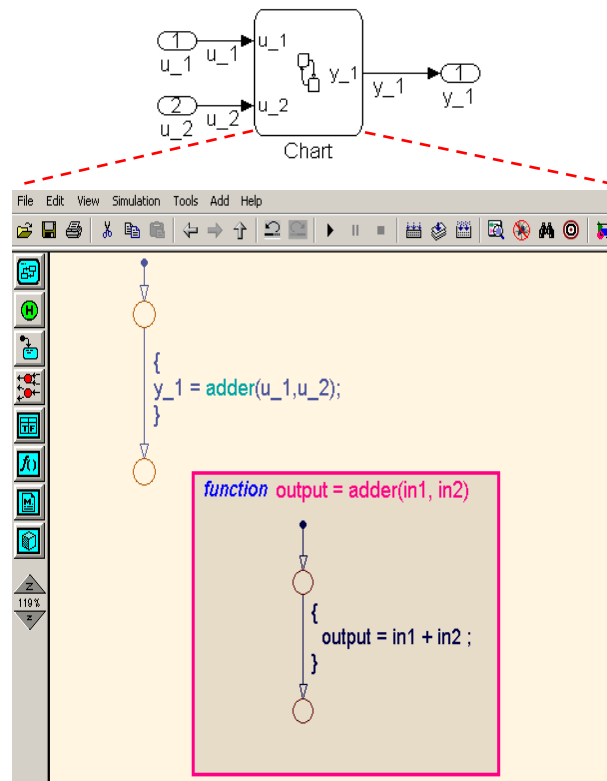
Memory section for initialize/terminate functions: Inherit from model

Memory section for execution functions: Inherit from model

OK Cancel Help Apply

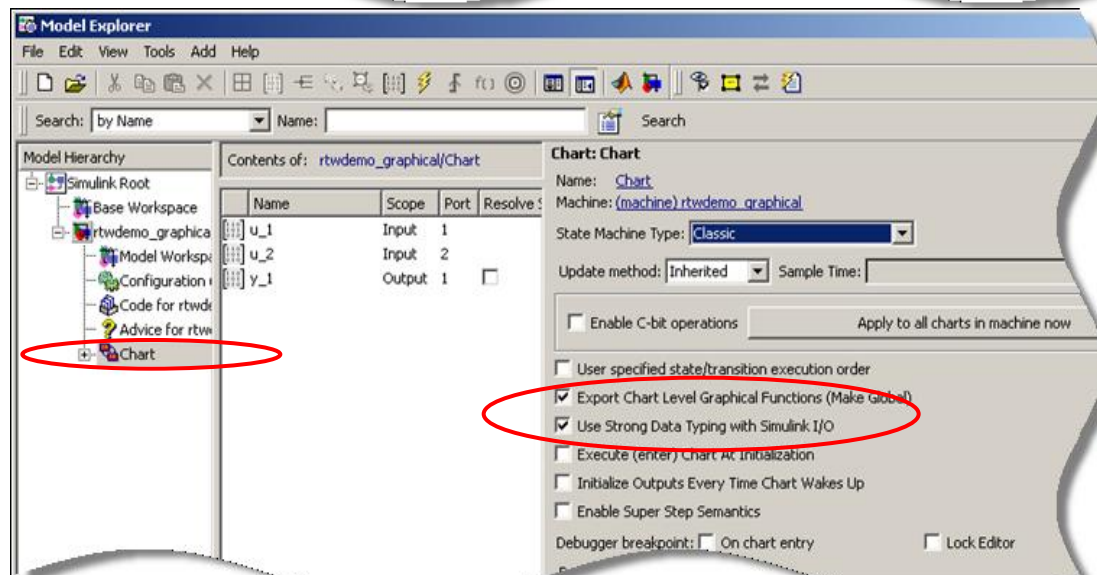
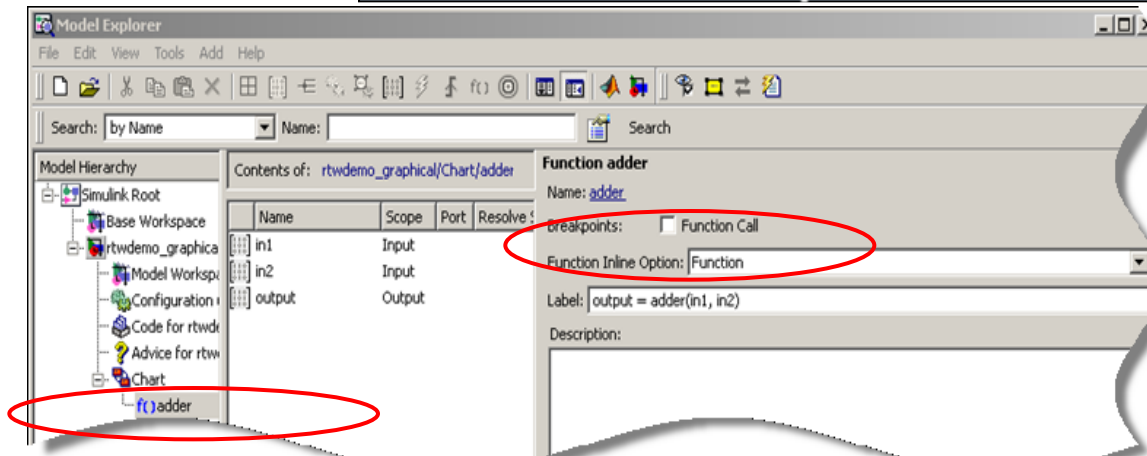
# C Code Pattern: Function Prototyping

Code Pattern	Modeling Methodology
<pre>double adder (double u_1, double u_2) {     return u_1 +u_2 ; }</pre> <p><b>Description:</b> Obtain functions in the generated code, that take input arguments and return an output. In most cases Simulink Subsystems do not generate function signatures which return values. However, pointers to the function outputs can be passed in as arguments. The function prototype can be controlled for the top-level of a model.</p>	<ol style="list-style-type: none"> <li>1. Use a Stateflow graphical function and export the function globally.</li> </ol>
	<ol style="list-style-type: none"> <li>2. Create a model and control the function prototype of the &lt;model&gt;_step function</li> </ol>



### Generated Code

```
real_T adder(real_T sf_in1, real_T sf_in2)
{
    return sf_in1 + sf_in2;
}
```



rtwdemo\_graphical.mdl

## functions

### C- Code Pattern

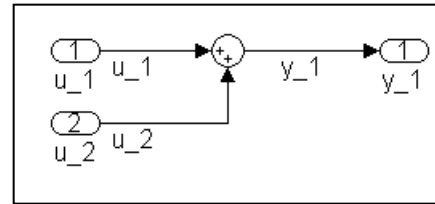
```
double A Badder(Cdouble u_1, Ddouble u_2)
{
    return u_1 + u_2;
}
```

### Generated Code

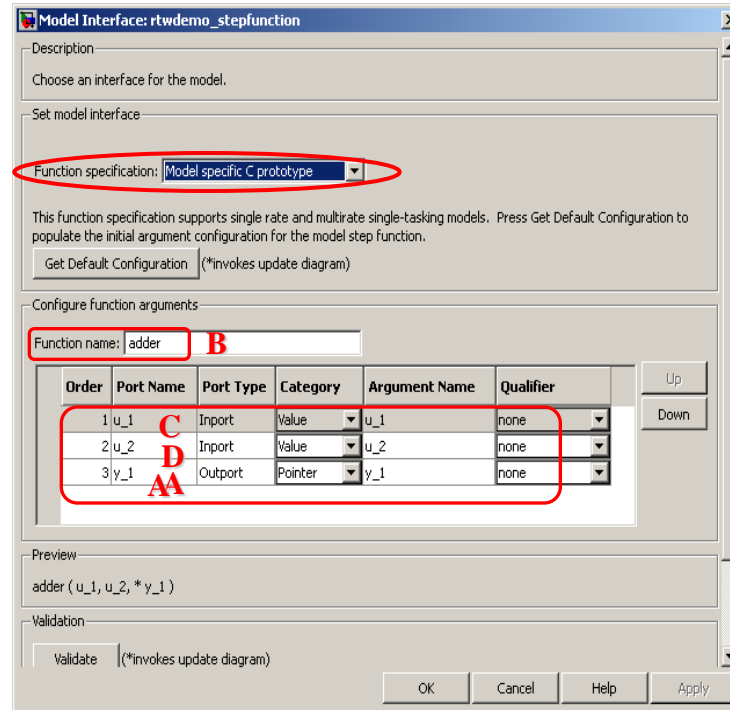
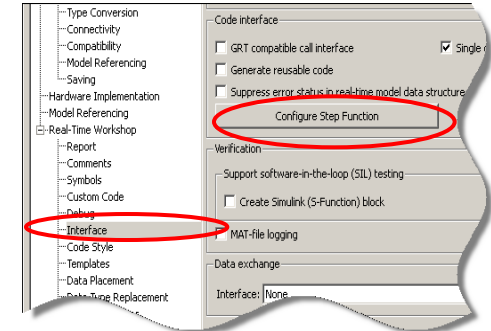
```
void Badder(Creal_T u_1, Dreal_T u_2, Areal_T *y_1)
{
    (*y_1) = u_1 + u_2;
}
```

rtwdemo\_stepfunction.mdl

## Top-level function prototype control



### Configuration wizard (ctrl + E)



# C Code Pattern: Calling external C functions

Code Pattern, Custom Function	Modeling Methodology
<pre data-bbox="212 435 826 739">/* filename: add.h */ #ifndef _ADD_H #define _ADD_H  extern double add(double, double);  #endif  /* EOF */</pre> <pre data-bbox="212 775 826 1079">/* filename: add.c */ #include "add.h" double add(double u_1, double u_2) {     double y_1;     y_1 = u_1 + u_2;     return (y_1); } /* EOF */</pre> <p data-bbox="115 1203 931 1229"><i>Description: Integrate custom/legacy functions in the generated code.</i></p>	<ol style="list-style-type: none"> <li>1. Use the Legacy Code Toolbox to create an S-function</li> </ol>
	<ol style="list-style-type: none"> <li>2. Use Stateflow Target to call external code.</li> </ol>
	<ol style="list-style-type: none"> <li>2. Use Embedded MATLAB Function to call external code.</li> </ol>

# Calling External C functions

## Creation

SL

SF

EML

```
/* filename: add.h */
#ifndef _ADD_H
#define _ADD_H

extern double add(double, double);

#endif
/* EOF */
```

```
/* filename: add.c */
#include "add.h"
double add(double u_1, double u_2)
{
    double y_1;
    y_1 = u_1 + u_2;
    return (y_1);
}
/* EOF */
```

```
% Initialize legacy code tool data structure
def = legacy_code('initialize') ;
%% Specify Source File
def.SourceFiles = {'add.c'};
%% Specify Header File
def.HeaderFiles = {'add.h'};
%% Specify the Name of the generated S-function
def.SFunctionName = 'Adder';
%% Create a c-mex file for S-function
legacy_code('sfcn_cmex_generate', def);
%% Define function signature and target the Output method
def.OutputFcnSpec = ['double y1 = add(double u1, double u2)'];
%% Compile/Mex and generate a block that can be used in simulation
legacy_code('generate_for_sim', def);
%% Create a TLC file for Code Generation
legacy_code('sfcn_tlc_generate', def);
%% Create a Masked S-function Block
legacy_code('slblock_generate', def);
```

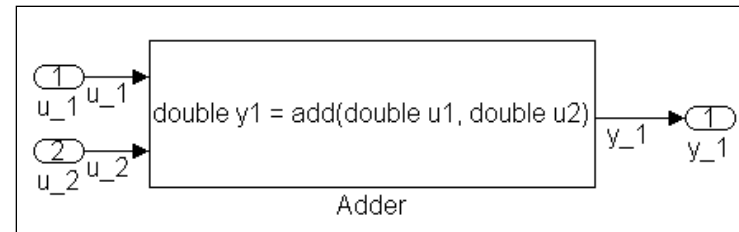
### Generated Code

&lt;model&gt;.h

#include "add.h"

&lt;model&gt;.c

y\_1 = add( u\_1, u\_2);



rtwdemo\_leg\_code\_model.mdl



# Calling External C functions

## Creation

SL SF EML

```
/* filename: add.h */
#ifndef _ADD_H
#define _ADD_H

extern double add(double, double);

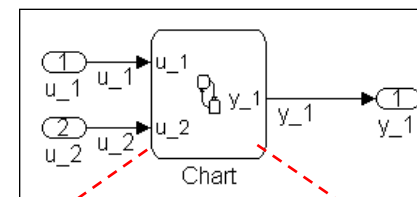
#endif

/* EOF */
```



```
/* filename: add.c */
#include "add.h"
double add(double u_1, double u_2)
{
    double y_1;
    y_1 = u_1 + u_2;
    return (y_1);
}

/* EOF */
```



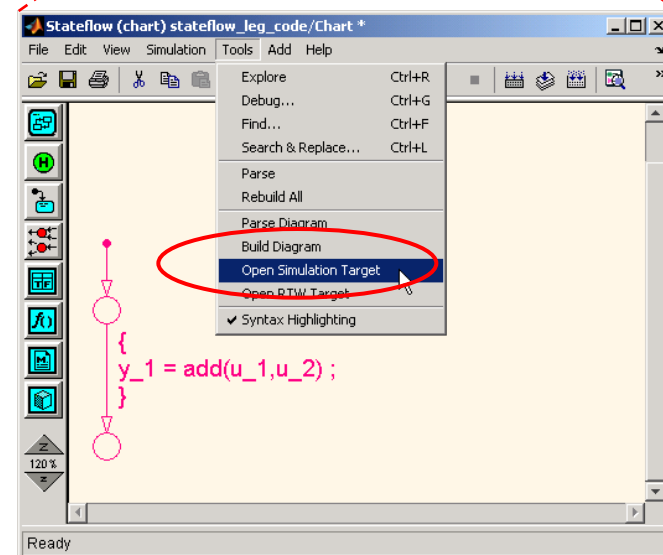
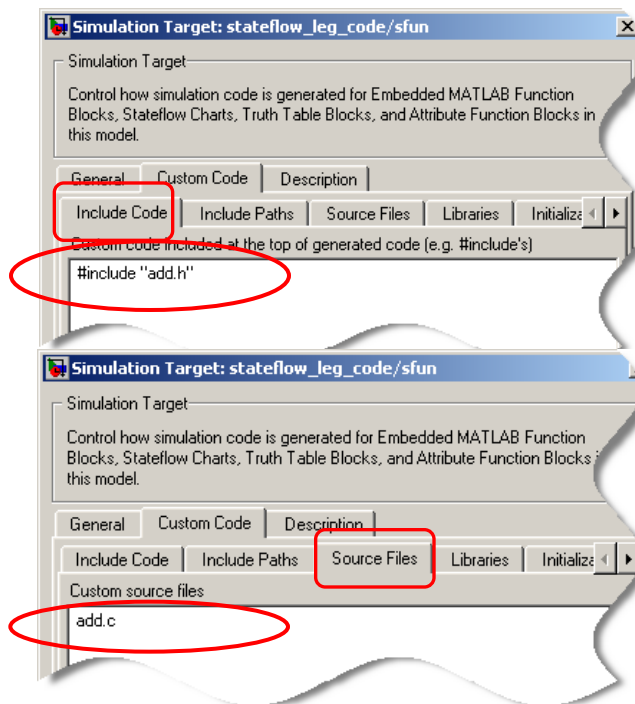
## Generated Code

```
<model>.h

#include "add.h"

<model>.c

y_1 = (real_T)add(u_1, u_2);
```



rtwdemo\_stateflow\_leg\_code.mdl

# Calling External C functions

## Creation

SL | SF | EML

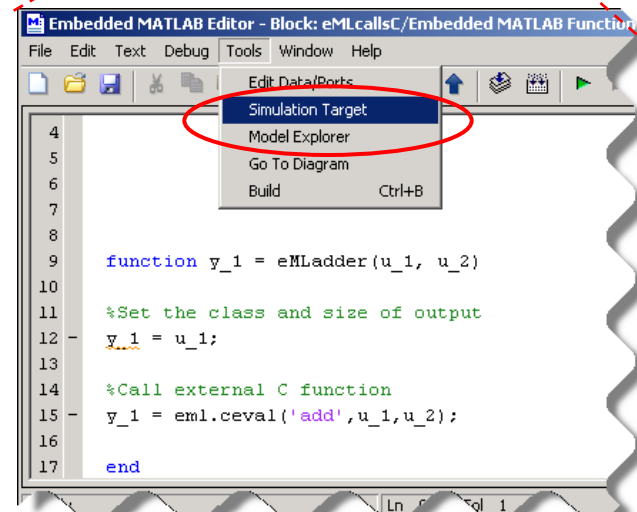
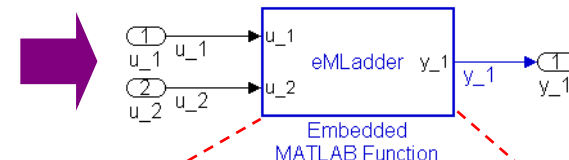
```
#ifndef _ADD_H
#define _ADD_H

#include "tmwtypes.h"
extern double add(double, double) ;

#endif

/* EOF */
```

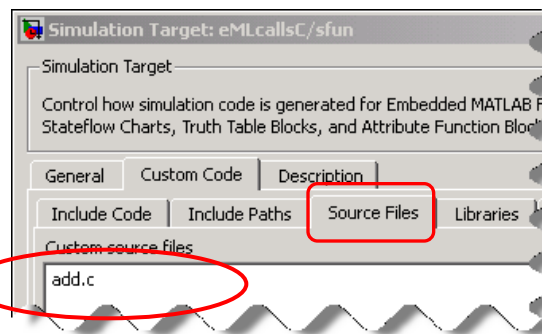
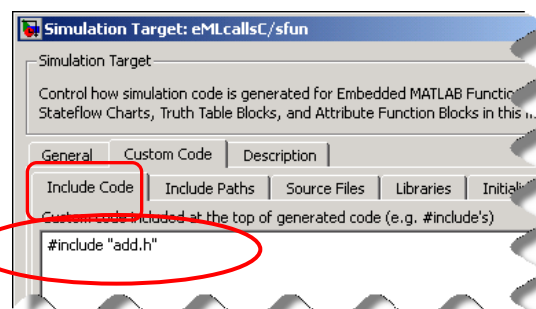
```
/* filename: add.c */
#include "add.h"
double add(double u_1, double u_2)
{
    double y_1;
    y_1 = u_1 + u_2;
    return (y_1);
}
/* EOF */
```



## Generated Code

```
{
    real_T eml_y_1;
    eml_y_1 = add(u_1, u_2);
    y_1 = eml_y_1;
}
```

rtwdemo\_eMLcallsC.mdl



# C Code Pattern: #define

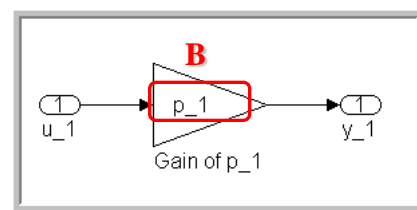
Code Pattern for Parameters	Modeling Methodology
<pre>#define p_1 9.8</pre> <p><i>Description: Use #define macros for constant parameters.</i></p>	1. Create a Data Object for the parameter and use the 'Define' CSC.
	2. Import the parameters from a custom header file with the ImportFromFile CSC.

## #define

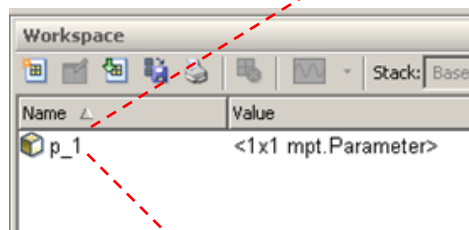
## Creation with Define CSC

### C- Code Pattern

**A** **B** **C**  
`#define p_1 9.8`



```
>> p_1 = mpt.Parameter;
```



**mpt.Parameter: default**

Value: **C** 9.8

Data type: auto

Dimensions: [1 1] Complexity: real

Minimum: -Inf Maximum: Inf

Units: m/s^2

Code generation options

Storage class: **A** Define (Custom)

Custom attributes

Header file:

Alias:

Description:

OK Cancel Help Apply

### Generated Code

<model>.h

**A** **B** **C**  
`#define p_1 9.8`

rtwdemo\_pound\_define.mdl

## #define

## Creation with ImportFromFile CSC

### C- Code Pattern

```
#define Ap_1 B9.8
```

### Generated Code

<model>\_private.h

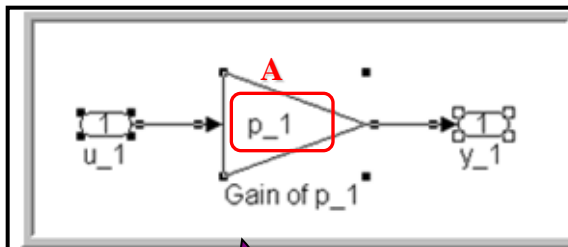
```
#include C"external_params.h"
```

Custom Header File  
external\_params.h

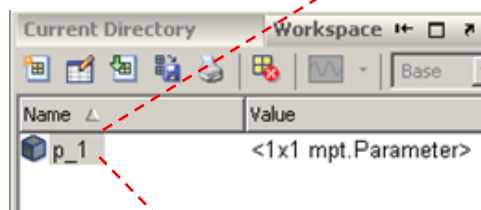
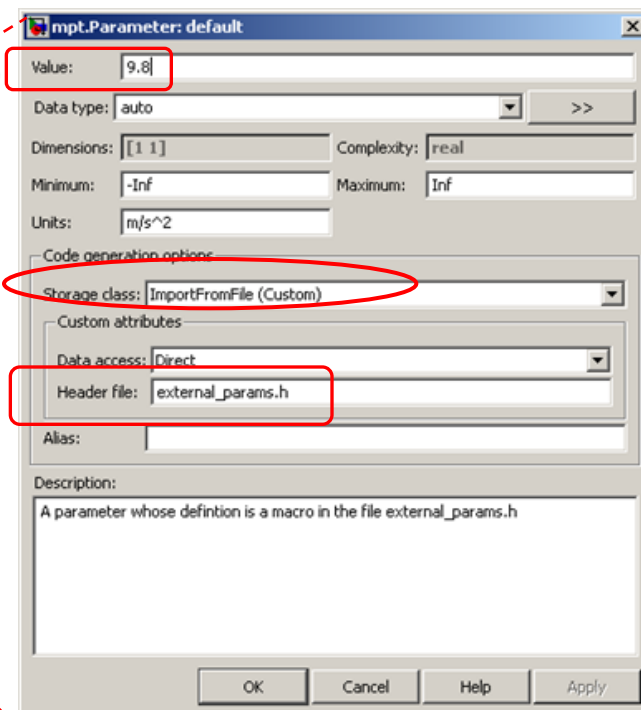
```
#ifndef __EXTERNAL_PARAMS__
#define __EXTERNAL_PARAMS__

#define Ap_1 B9.8
#define p_2 1.633

#endif
```



```
>> p_1 = mpt.Parameter
```

mpt.Parameter: default

Value: 9.8 <sup>B</sup>

Data type: auto

Dimensions: [1 1] Complexity: real

Minimum: -Inf Maximum: Inf

Units: m/s^2

Code generation options

Storage class: ImportFromFile (Custom)

Custom attributes

Data access: Direct

Header file: external\_params.h <sup>C</sup>

Alias:

Description:

A parameter whose defintion is a macro in the file external\_params.h

OK Cancel Help Apply

# C Code Pattern: typedef

Code Pattern	Modeling Methodology
<pre>typedef double float_64 ;</pre> <p><b>Description:</b> Obtain and use a typedef data type in the generated code.</p>	<p>Use Simulink AliasType data object.</p>

## typedef

## Creation with Data Object

### C- Code Pattern

```
typedef Adouble Bfloat_64;
```

### Generated Code

```
<model>_types.h
```

```
typedef Areal_T Bfloat_64;
```

NOTE: real\_T is the Real-Time Workshop Embedded Coder typedef for double

Step 1:

```
>> Bfloat_64 = Simulink.AliasType
```

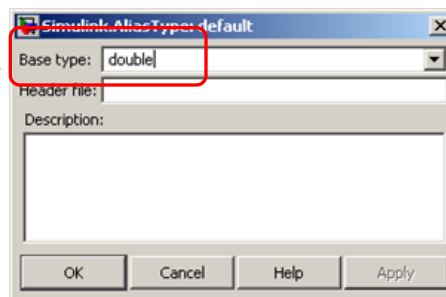
Step 2:

Create Simulink Data objects to signals/Parameters if necessary



Step 3:

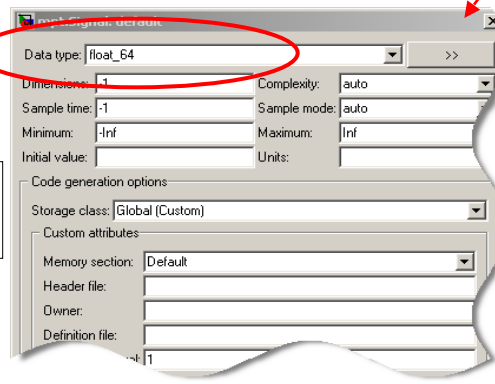
Specify Base Type



Workspace	
Name	Value
float_64	<1x1 Simulink.AliasType>
p_1	<1x1 mpt.Parameter>
u_1	<1x1 mpt.Signal>

Step 4:

Specify usage of alias data type



rtwdemo\_get\_type\_def.mdl

# C Code Pattern: Structures

Code Pattern, Parameters	Modeling Methodology
<pre>typedef struct{     double p_1;     double p_2;     double p_3; }my_struct_type;  my_struct_type my_struct={1.0,2.0,3.0};</pre> <p><b>Description:</b> Define a data-type structure and create an object to that data-type to initialize parameters.</p>	<p>Use Simulink Data-Objects with Struct CSC (Custom Storage Class)</p>



## Structure typedef for Parameters

### C- Code Pattern, Parameters

```
typedef struct{ A
    double p_1;
    double p_2;
    double p_3;
}my_struct_type;

B
my_struct_type my_struct={1.0,2.0,3.0};
```

### Generated Code, Parameters

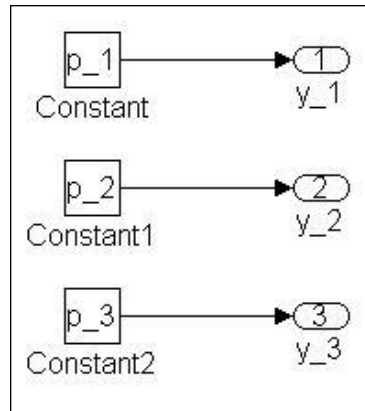
```
<model>_types.h
A typedef struct my_struct_tag {
    real_T p_1;
    real_T p_2;
    real_T p_3;
} my_struct_type;

<model>.c B
my_struct_type my_struct = {
    /* p_1 */
    1.0,

    /* p_2 */
    2.0,

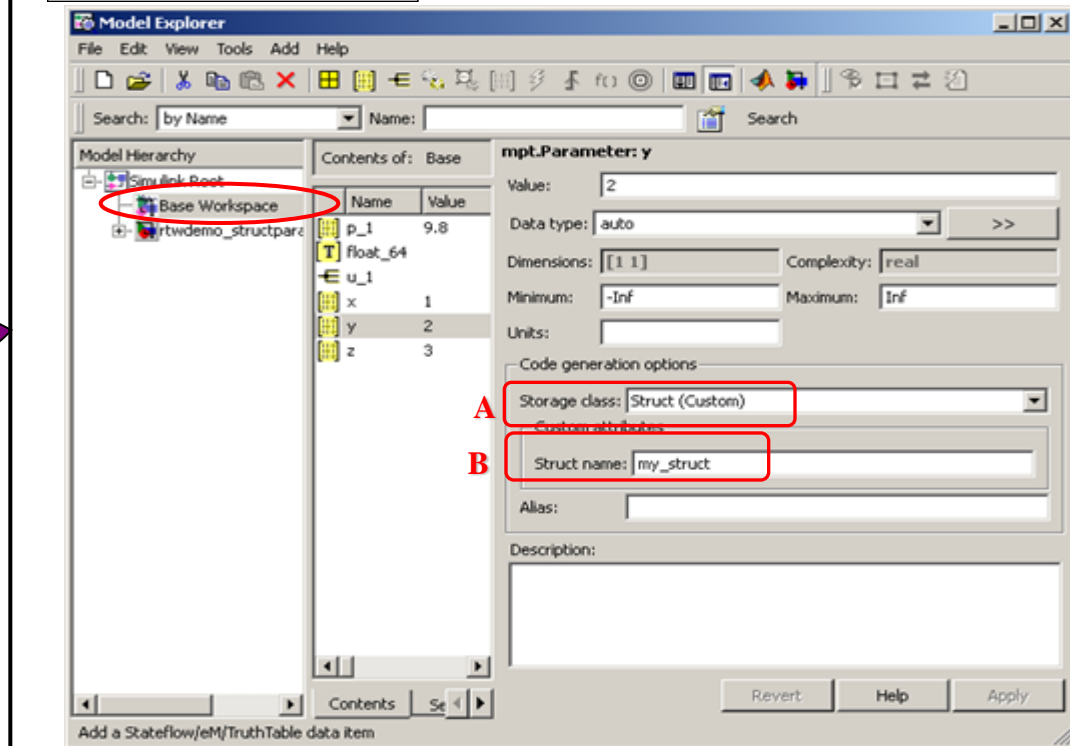
    /* p_3 */
    3.0
};
```

## Creation with Struct CSC



Create Data Objects for Parameters in the Workspace

```
>> p_1 = mpt.Parameter ;
>> p_2 = mpt.Parameter ;
>> p_3 = mpt.Parameter ;
```



rtwdemo\_structparam.mdl

# C Code Pattern: Structure typedef for Signals

Code Pattern, Signals	Modeling Methodology
<pre>typedef struct {     double u_1;     double u_2;     double u_3; }MySignals;</pre> <p><b>Description:</b> Define a structure containing signals.</p>	<ol style="list-style-type: none"> <li>1. Use Simulink Data-Objects with Struct CSC (Custom Storage Class)</li> </ol>
	<ol style="list-style-type: none"> <li>2. Use Simulink Non-Virtual Bus Objects.</li> </ol>

## Structure typedef for Signals

### C- Code Pattern, Signals

```
typedef struct {
    double u_1;
    double u_2;
    double u_3;
} MySignals;
```

### Generated Code, Parameters

<model>\_types.h

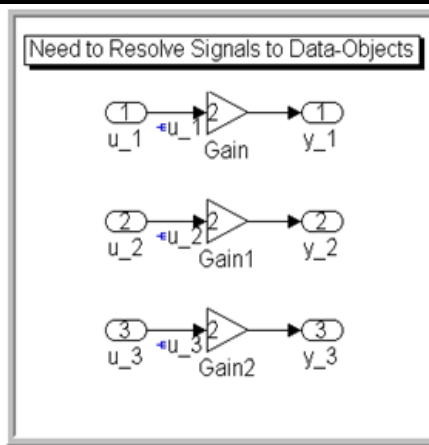
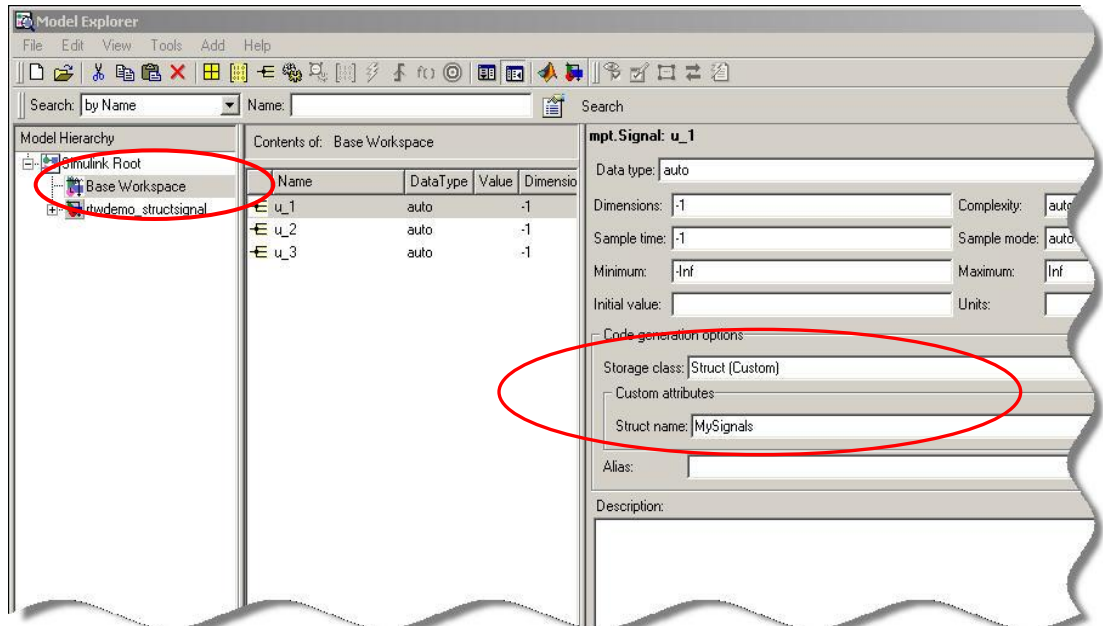
```
typedef struct MySignals_tag {
    real_T u_1;
    real_T u_2;
    real_T u_3;
} MySignals_type;
```

NOTE : real\_T is a Real-Time Workshop Embedded Coder Typedef for double.

## Creation with CSC

Create Simulink Data Objects

```
>> u_1 = mpt.Signal;
>> u_2 = mpt.Signal;
>> u_3 = mpt.Signal ;
```

Name	Data Type	Value	Dimension
u_1	auto	-1	-1
u_2	auto	-1	-1
u_3	auto	-1	-1

mpt.Signal: u\_1

Data type: auto

Dimensions: -1 Complexity: auto

Sample time: -1 Sample mode: auto

Minimum: -Inf Maximum: Inf

Initial value: Units:

Code generation options

Storage class: Struct (Custom)

Custom attributes

Struct name: MySignals

Alias:

Description:

## Structure typedef for Signals

### C- Code Pattern, Signals

```
typedef struct {
    double u_1;
    double u_2;
    double u_3;
} MySignals;
```

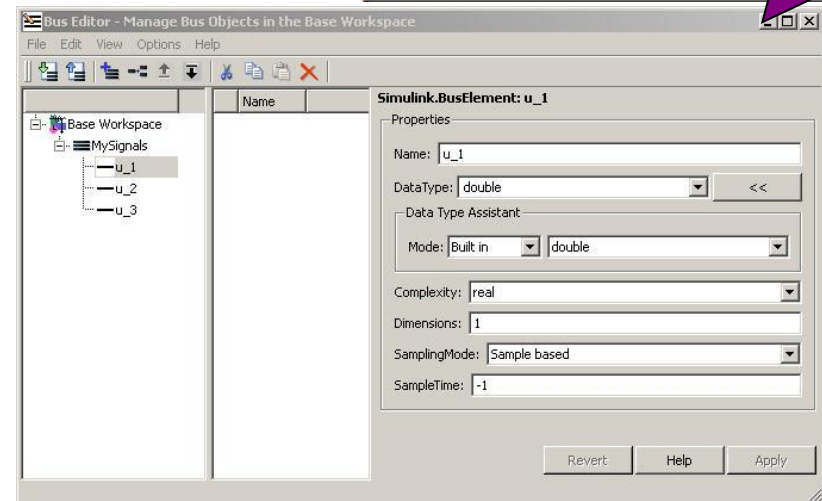
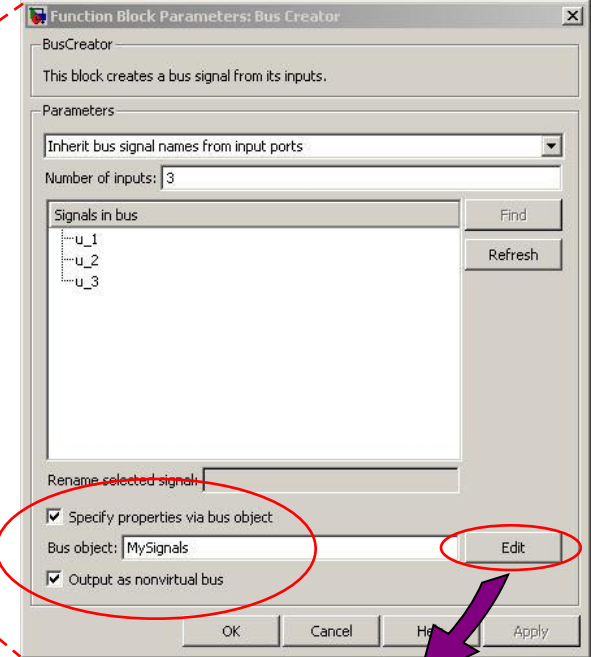
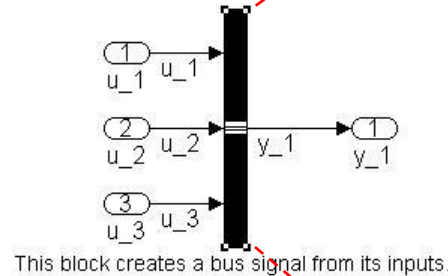
### Generated Code, Signals

<model>\_types.h

```
typedef struct {
    real_T u_1;
    real_T u_2;
    real_T u_3;
} MySignals;
```

rtwdemo\_structsignal2.mdl

## Creation with Bus Objects



# C Code Pattern: Nested Structures

Code Pattern, Signals	Modeling Methodology
<pre>typedef struct {     real_T u_1;     real_T u_2;     real_T u_3; }My_Signals_123;  typedef struct {     real_T u_4;     real_T u_5;     real_T u_6; }My_Signals_456;  typedef struct {     My_Signals_123 y_1;     My_Signals_456 y_2; } Nested_Signals;</pre> <p><i>Description: Define a nested structure.</i></p>	<p>Use Simulink Non-Virtual Bus Objects.</p>

## Structure typedef for Signals

### C- Code Pattern, Signals

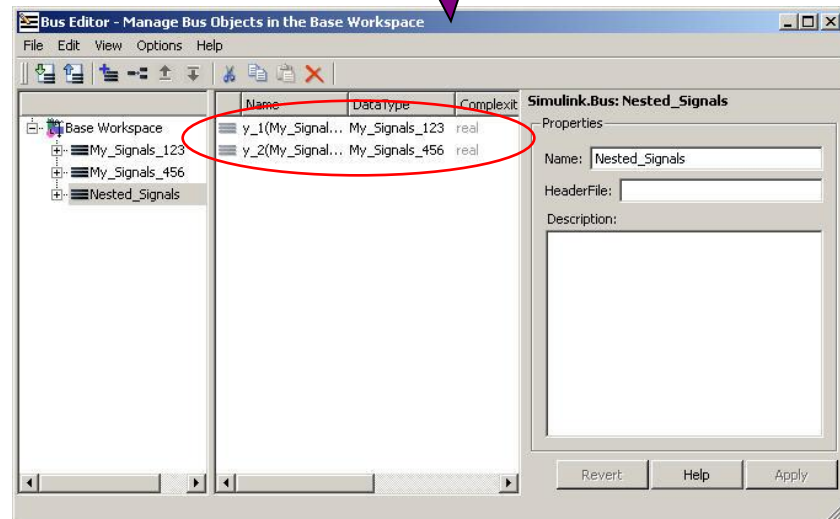
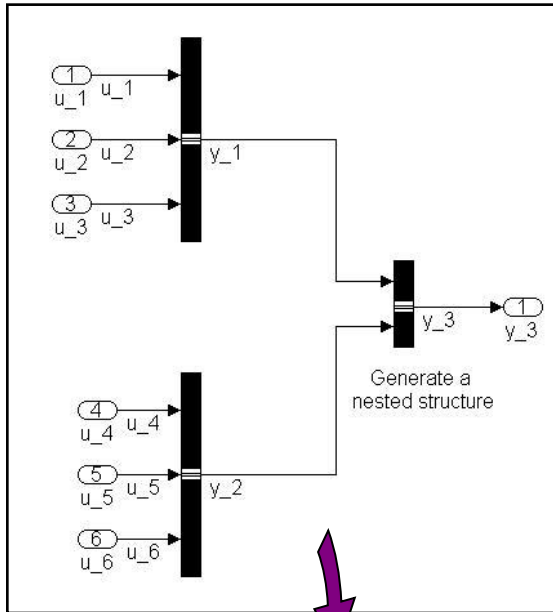
```
typedef struct {
    real_T u_1;
    real_T u_2;
    real_T u_3;
}My_Signals_123;
```

```
typedef struct {
    real_T u_4;
    real_T u_5;
    real_T u_6;
}My_Signals_456;
```

```
typedef struct {
    My_Signals_123 y_1;
    My_Signals_456 y_2;
} Nested_Signals;
```

rtwdemo\_nestedstructure.mdl

## Creation with Bus Objects



continued ...

### Generated Code, Signals

```
#ifndef _DEFINED_TYPEDEF_FOR_My_Signals_123_
#define _DEFINED_TYPEDEF_FOR_My_Signals_123_

typedef struct {
    real_T u_1;
    real_T u_2;
    real_T u_3;
} My_Signals_123;

#endif

#ifndef _DEFINED_TYPEDEF_FOR_My_Signals_456_
#define _DEFINED_TYPEDEF_FOR_My_Signals_456_

typedef struct {
    real_T u_4;
    real_T u_5;
    real_T u_6;
} My_Signals_456;

#endif

#ifndef _DEFINED_TYPEDEF_FOR_Nested_Signals_
#define _DEFINED_TYPEDEF_FOR_Nested_Signals_

typedef struct {
    My_Signals_123 y_1;
    My_Signals_456 y_2;
} Nested_Signals;

#endif
```

# C Code Pattern: Bit-Fields

Code Pattern	Modeling Methodology
<pre>typedef struct {     unsigned int p_1 : 1;     unsigned int p_2 : 1;     unsigned int p_3 : 1; }My_Struct_type;</pre> <p><b>Description:</b> Define a structure containing bit fields.</p>	<p>Use Simulink Data-Objects with Bitfield CSC (Custom Storage Class)</p>



## Bit Fields

## Creation with Bitfield CSC

### C- Code Pattern

```
typedef struct {
    unsigned int p_1 : 1;
    unsigned int p_2 : 1;
    unsigned int p_3 : 1;
} My_Struct_type;
```

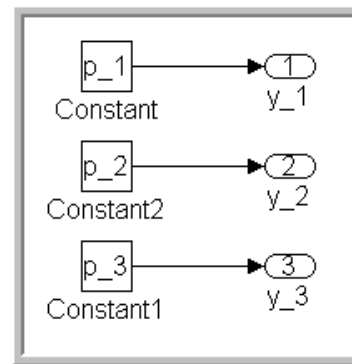
rtwdemo\_bitfield.mdl

### Generated Code

&lt;model&gt;\_types.h

```
typedef struct My_Struct_tag {
    uint_T p_1 : 1;
    uint_T p_2 : 1;
    uint_T p_3 : 1;
} My_Struct_type;
```

NOTE: unit\_T is the Real-Time Workshop Embedded Coder typedef for unsigned int



Create Data Objects for Parameters in the Workspace

```
>> p_1 = mpt.Parameter ;
>> p_2 = mpt.Parameter ;
>> p_3 = mpt.Parameter ;
```

Current Directory	
Name	Value
p_3	<1x1 mpt.Parameter>
p_2	<1x1 mpt.Parameter>
p_1	<1x1 mpt.Parameter>

mpt.Parameter: default

Value: 0

Data type: **boolean**

Dimensions: [1 1] Complexity: real

Minimum: -Inf Maximum: Inf

Units:

Code generation options

Storage class: **BitField (Custom)**

Custom attributes

Struct name: **My\_Struct**

Alias:

Description:  
x is a one-bit Bit-Field. Simulink treats it as a boolean.

OK Cancel Help Apply

# C Code Pattern: Arrays

Code Pattern, Signal Variables	Code Pattern, Parameter Constants
<pre>int u_1[5]; int y_1[5];  for (inx=0;inx&lt;5;inx++) { y_1[inx] = 5 * u_1[inx] ; }</pre> <p>Description:  <i>The aim is to obtain arrays such as the ones above in the generated code. u_1 and y_1 are signal arrays with integer data type. An example operation on arrays is also shown.</i></p>	<pre>int params[5]= {1,2,3,4,5} ;</pre> <p>Description:  <i>params is a constant array of parameters.</i></p>

## Arrays

## Creation : Signals

### C- Code Pattern, Signal

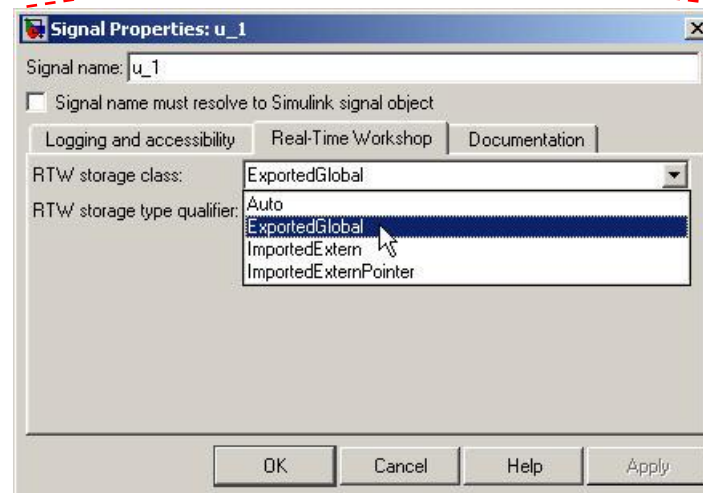
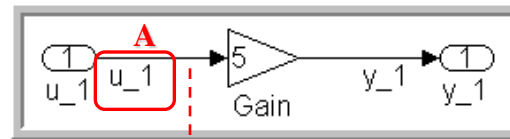
```
int Au_1B[5];
int y_1 [5];
```

```
for (inx=1; inx<5; inx++){
    y_1[inx] = 5 * u_1[inx];
}
```

### Generated Code, Signal

```
int16_T Au_1B[5];
int16_T y_1[5];
```

```
for (i = 0; i < 5; i++) {
    y_1[i] = (int16_T)(5 * u_1[i]);
}
```



## Arrays

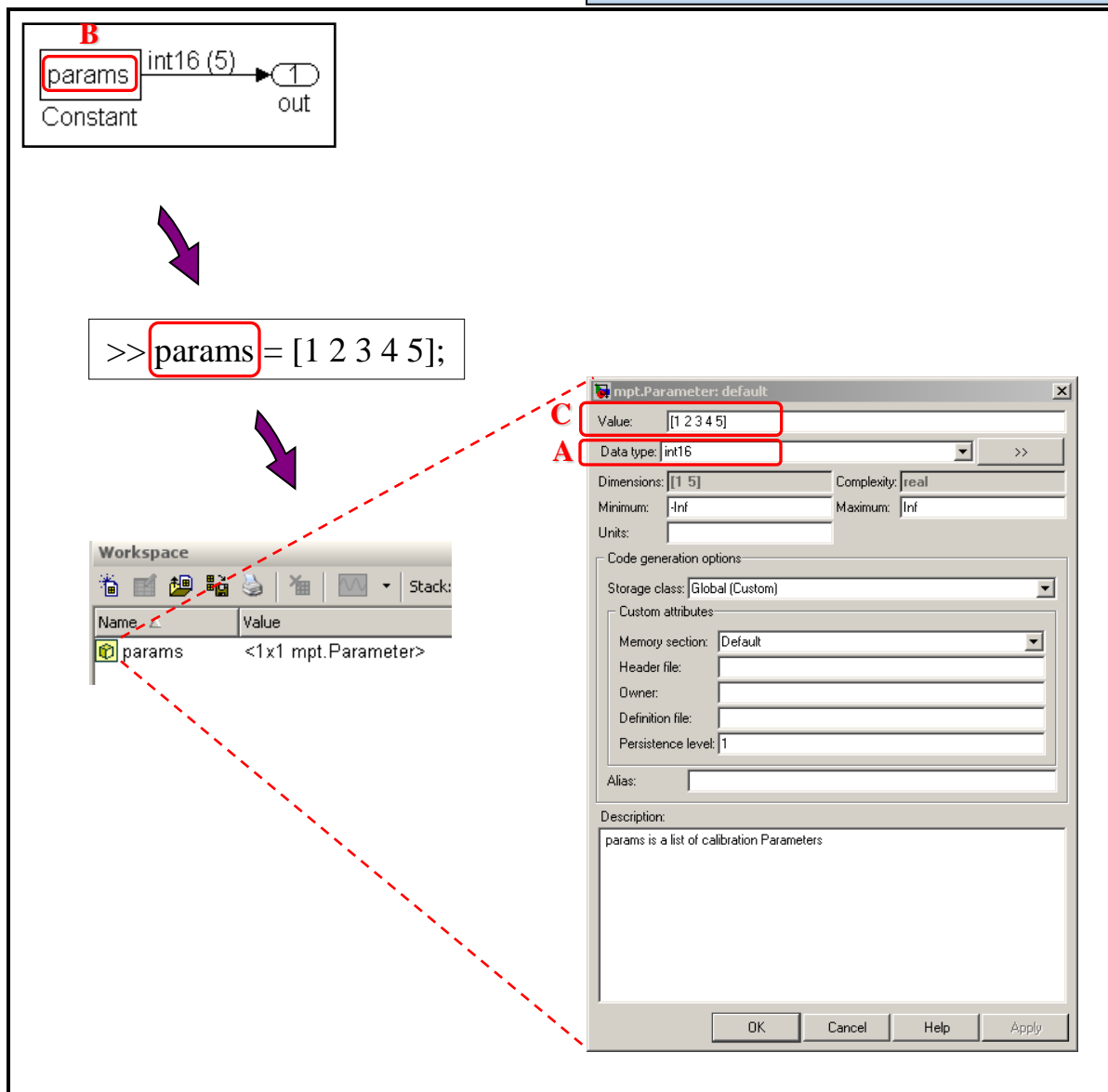
### C- Code Pattern, Parameter

```
A int B params C [5] = { 1,2,3,4,5 } ;
```

### Generated Code, Parameter

```
A int16_T B params C [5] = { 1, 2, 3, 4, 5 } ;
```

## Creation : Parameters



# C Code Pattern: Pointers

Code Pattern	Modeling Methodology
<pre>extern double *u_1 ;</pre> <p><i>Description: Import a pointer to a signal/parameter in the generated code.</i></p>	<ol style="list-style-type: none"> <li>1. Use the Imported Extern Pointer Storage Class for signals. Eliminates need for data objects.</li> </ol>
	<ol style="list-style-type: none"> <li>2. Create a data object for the signal/parameter and use the imported Extern Pointer Storage Class.</li> </ol>

## Pointers

## Creation with Imported Extern Storage Class

### C- Code Pattern

```
extern double *u_1 ;
```



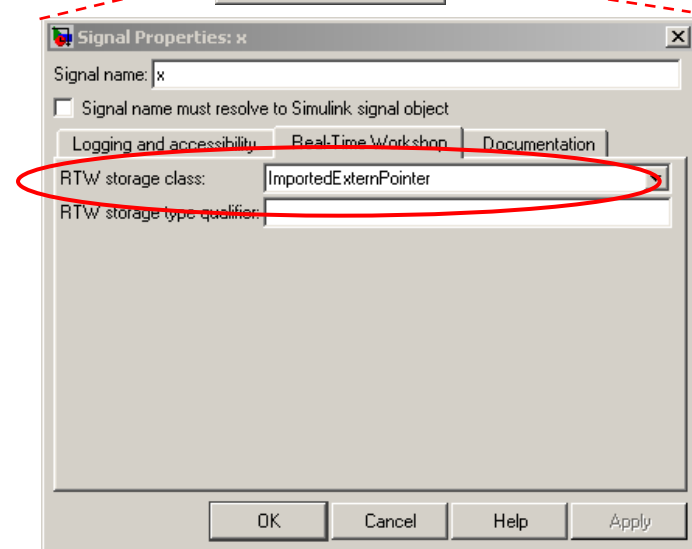
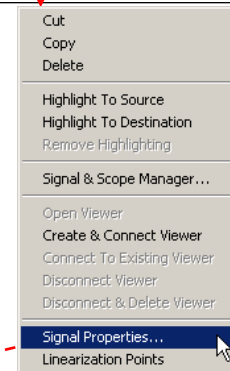
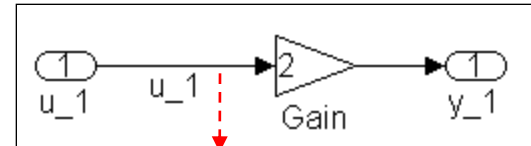
### Generated Code

```
<model>_private.h
```

```
extern real_T *u_1;
```



NOTE: real\_T is the Real-Time Workshop Embedded Coder typedef for double

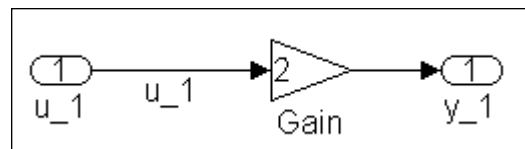


## Pointers

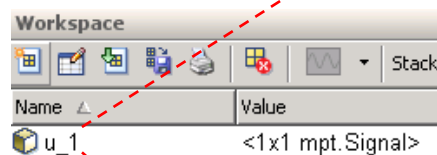
## Creation with Data Objects

### C- Code Pattern

<sup>A</sup>  
extern double \*u\_1 ;



>> u\_1 = mpt.Signal



<sup>A</sup>

mpt.Signal: default

Data type: auto

Dimensions: -1 Complexity: auto

Sample time: -1 Sample mode: auto

Minimum: -Inf Maximum: Inf

Initial value: Units:

Code generation options:

Storage class: ImportedExternPointer

Alias:

Description:

OK Cancel Help Apply

### Generated Code

<model>\_private.h

<sup>A</sup>  
extern real\_T \*u\_1;



NOTE: real\_T is the  
Real-Time Workshop Embedded Coder  
typedef for double