

# CS 35L

LAB 8,

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# Outline

**Multiprocessing**

**Parallelism**

**Multithreading**

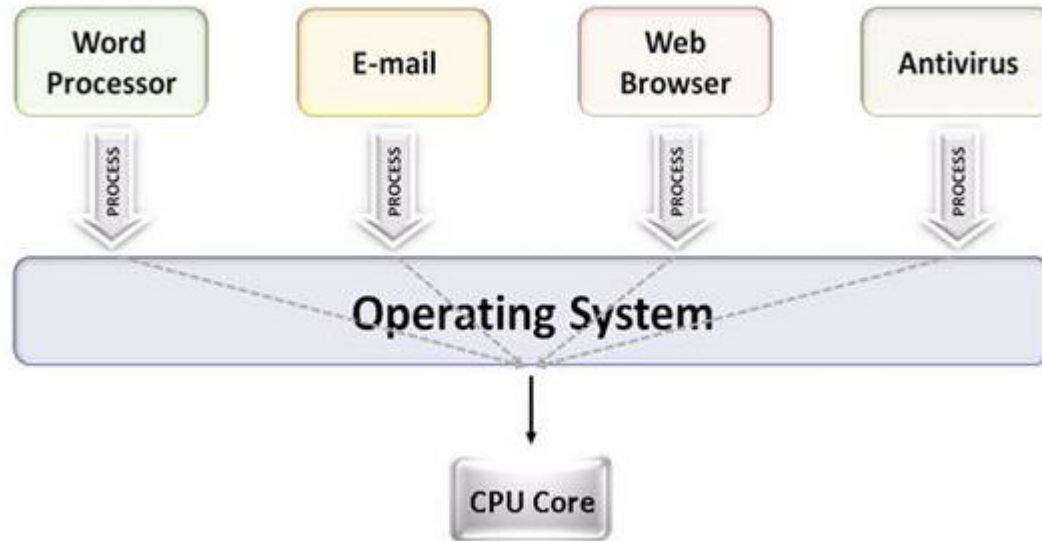


# Multiprocessing

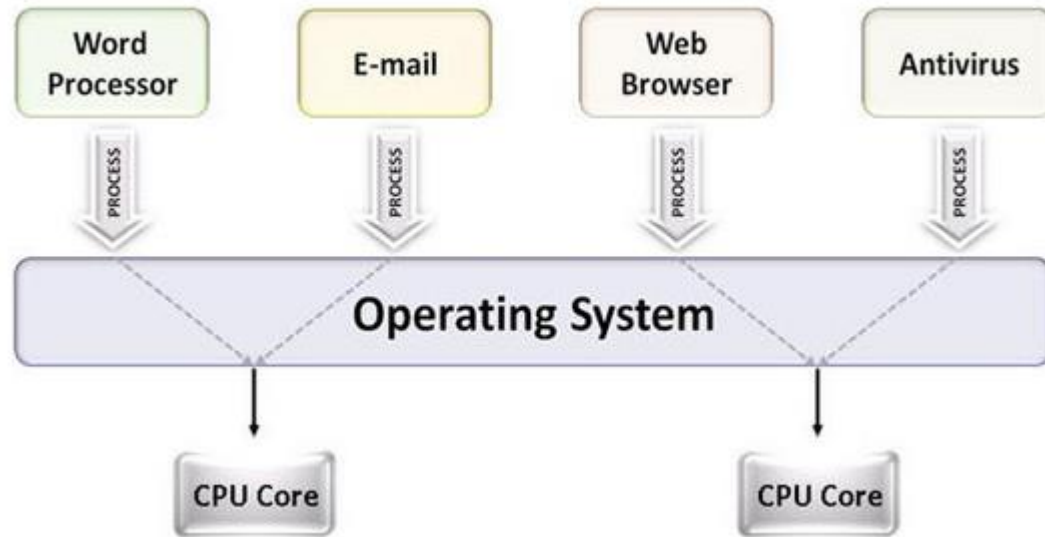
The use of multiple CPUs/cores to run multiple tasks simultaneously



# Uniprocessing



# Multiprocessing



# Parallelism

Executing several computations simultaneously to gain performance

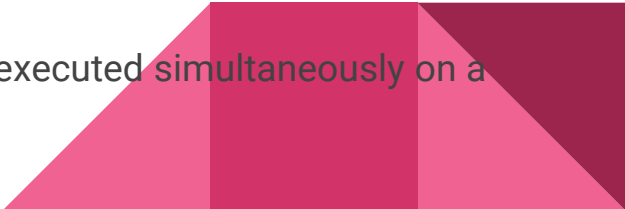
Different forms of parallelism

## Multitasking

Several processes are scheduled alternately or possibly simultaneously on a multiprocessing system

## Multithreading

Same job is broken logically into pieces (threads) which may be executed simultaneously on a multiprocessing system



# What is a thread?

A flow of instructions, path of execution within a process. The smallest unit of processing scheduled by OS. A process consists of at least one thread

Multiple threads can be run on:

A uniprocessor (time-sharing)

Processor switches between different threads

Parallelism is an illusion

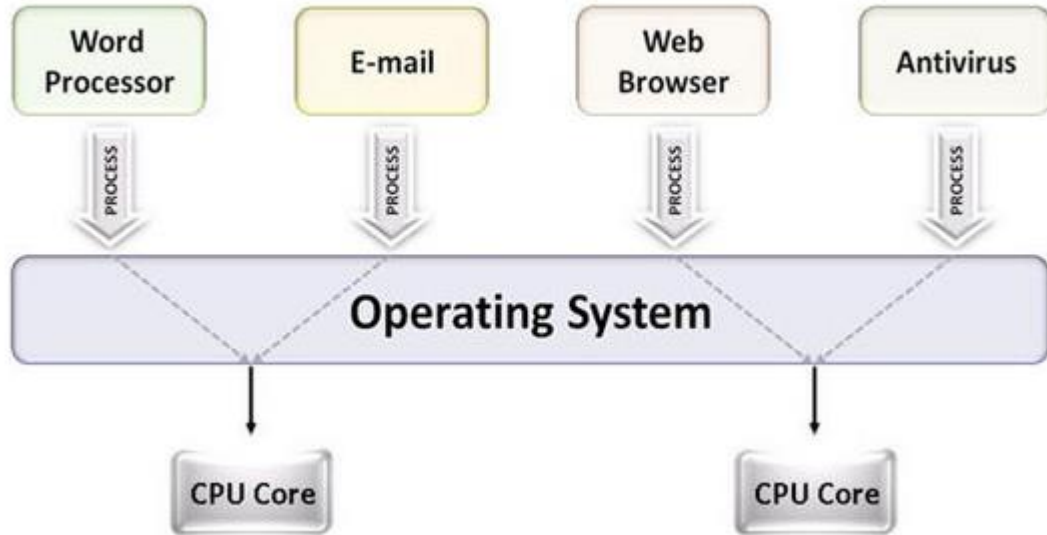
A multiprocessor

Multiple processors or cores run the threads at the same time

True parallelism

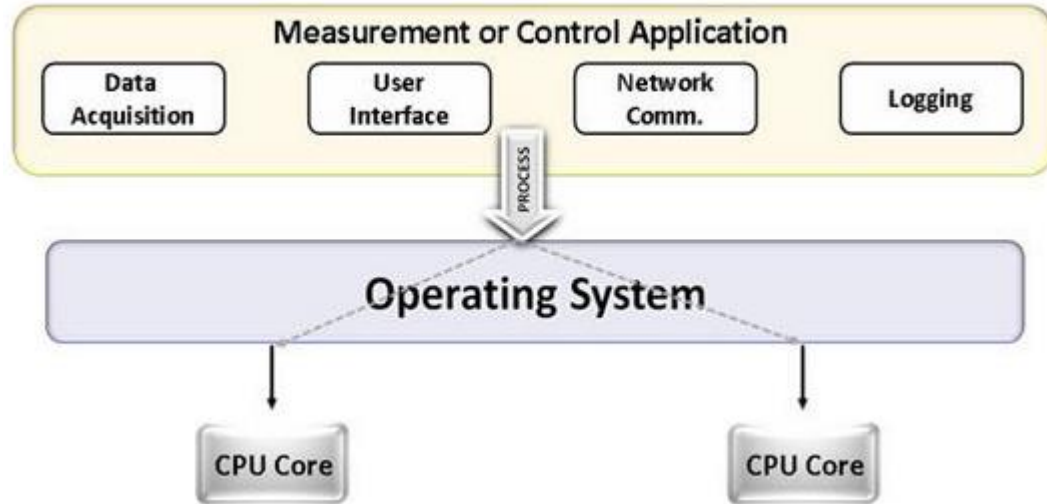


# Multitasking

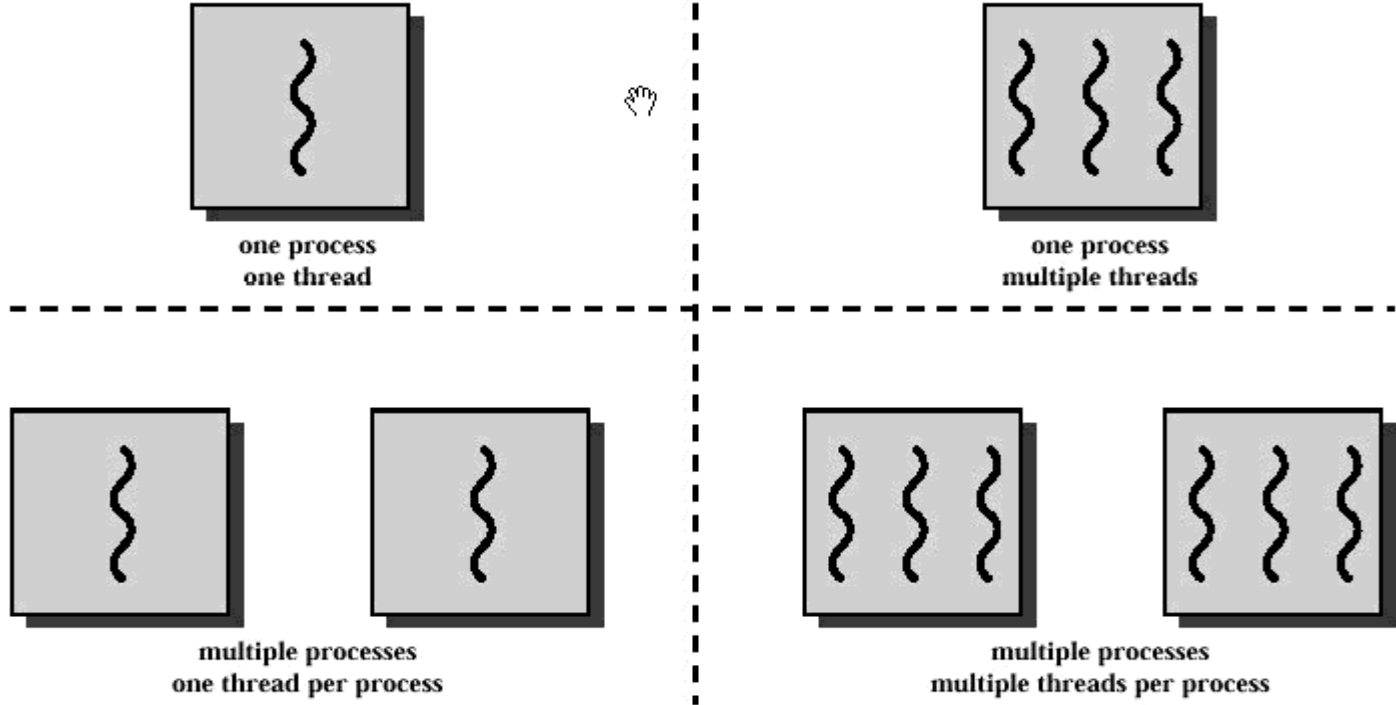




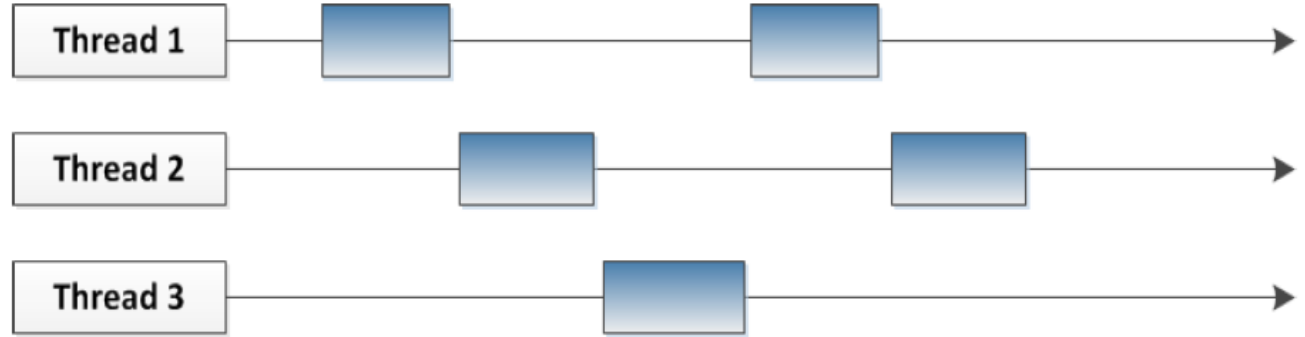
# Multithreading



# Multitasking and Multithreading



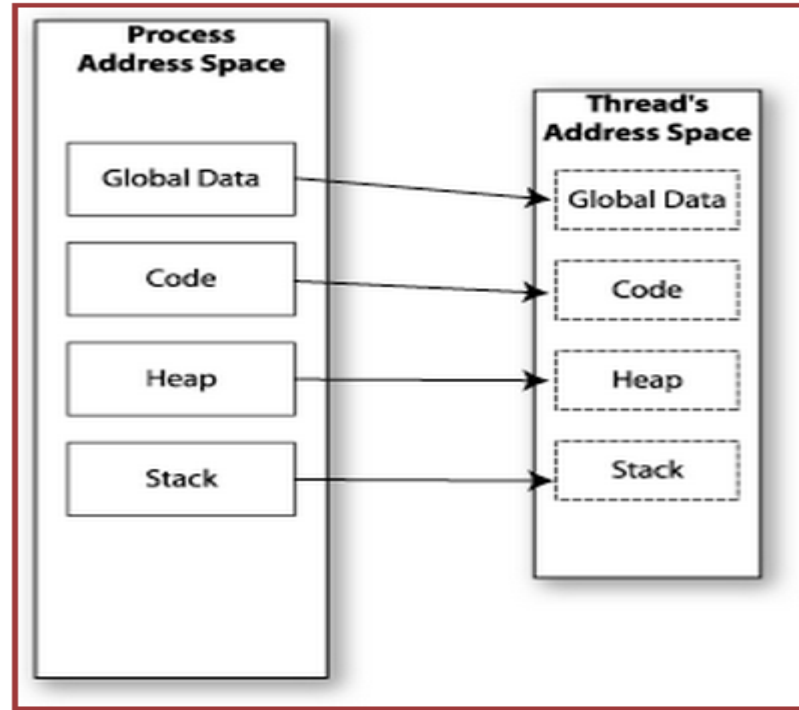
Multiple  
threads  
sharing a  
single CPU



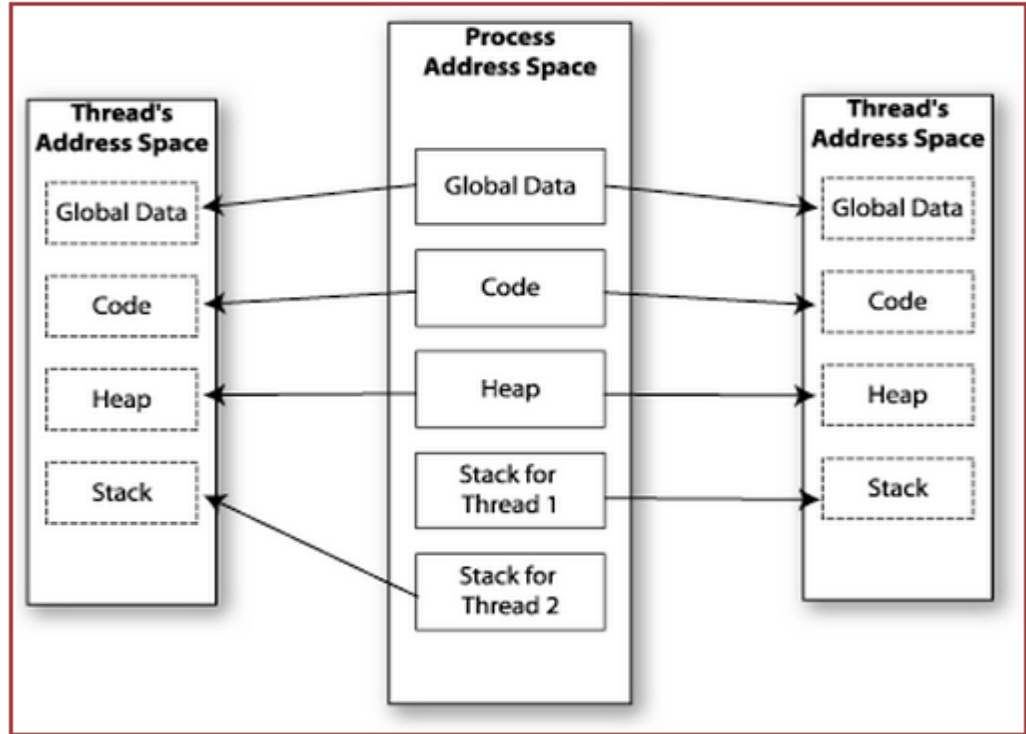
Multiple  
threads on  
multiple  
CPUs



# Memory Layout: Single-Threaded Program



# Memory Layout: Multithreaded Program



Multithreading

# Multithreading & Multitasking: Comparison

Threads share the same address space

Light-weight creation/destruction

Easy inter-thread communication

An error in one thread can bring down all threads in process

Multitasking

Processes are insulated from each other

Expensive creation/destruction

Expensive IPC

An error in one process cannot bring down another process



# Communication in Multitasking

```
tr -cs 'A-Za-z' '[\n*]' | sort -u | comm -23 - words
```

Process 1 (tr), Process 2 (sort), Process 3 (comm)

Each process has its own address space

How do these processes communicate?

Pipes/System Calls



# Communication in Multithreading

Threads share all of the process's memory except for their stacks

=> Data sharing requires no extra work (no system calls, pipes, etc.)





# Shared memory

Makes multithreaded programming

## Powerful

Can easily access data and share it among threads

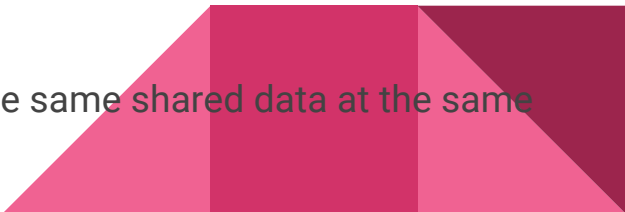
## More efficient

No need for system calls when sharing data

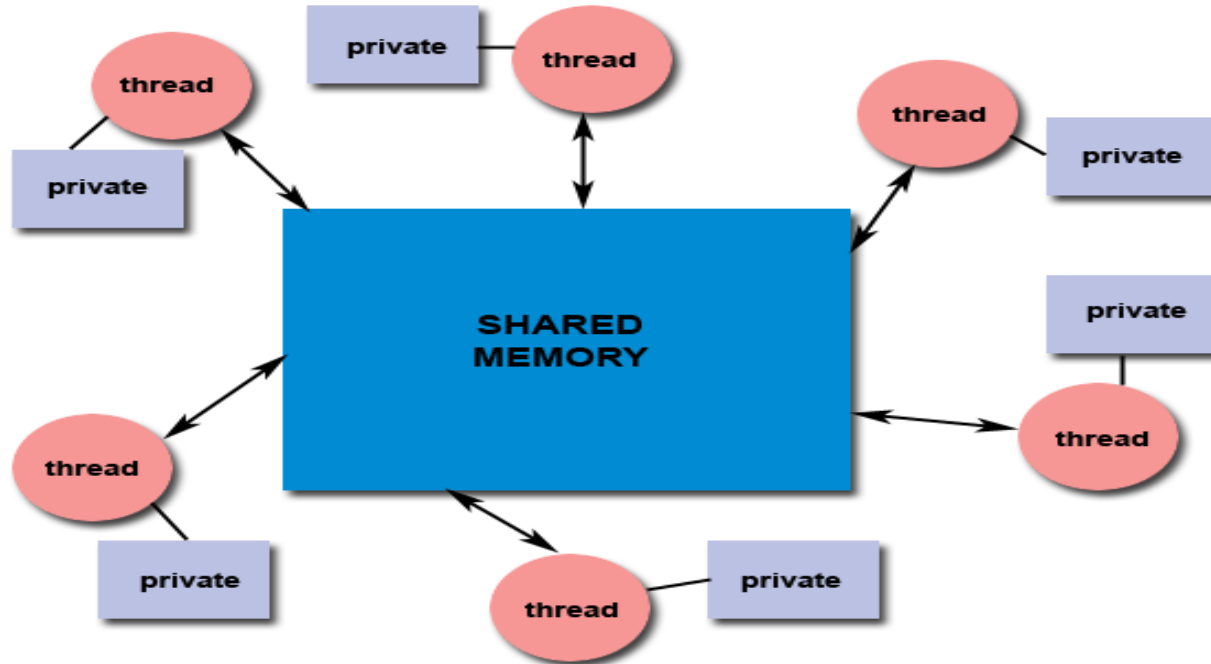
Thread creation and destruction less expensive than process creation and destruction

## Non-trivial

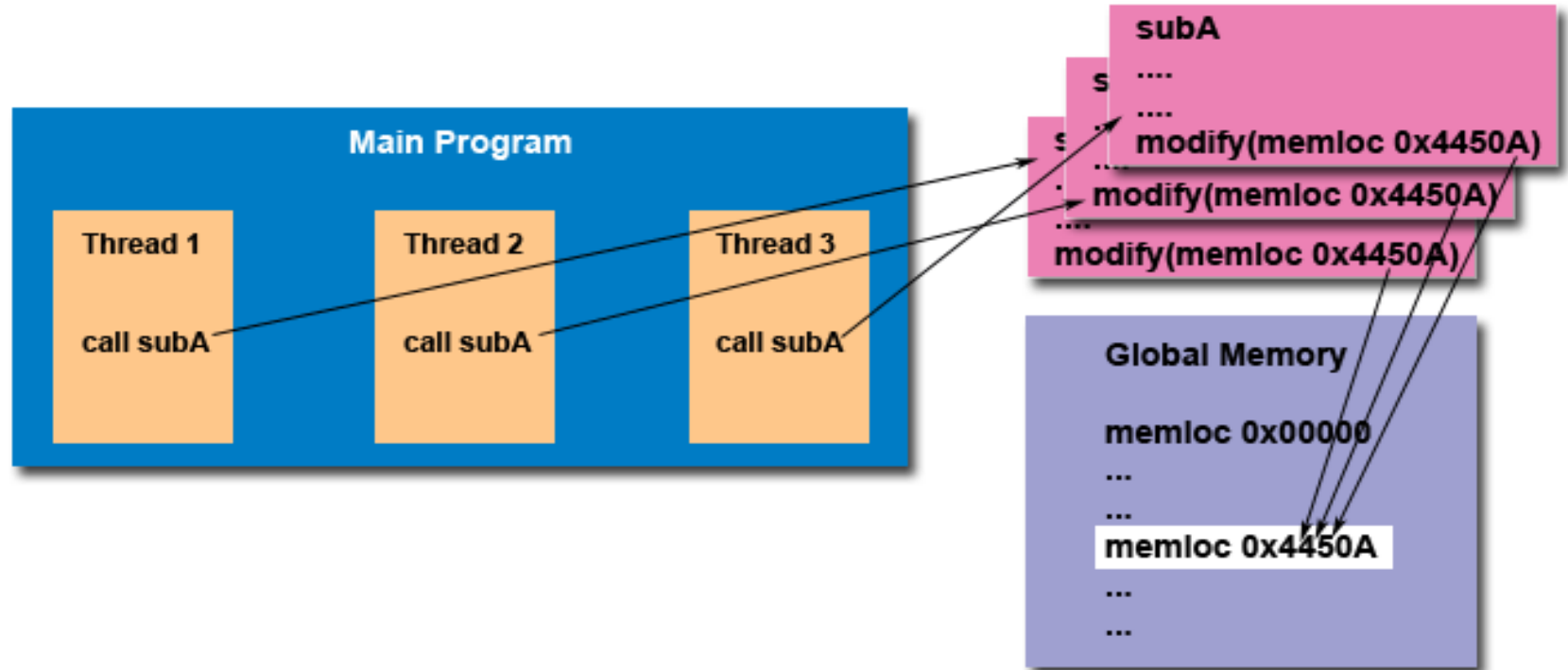
Have to prevent several threads from accessing and changing the same shared data at the same time (synchronization)



# Shared memory



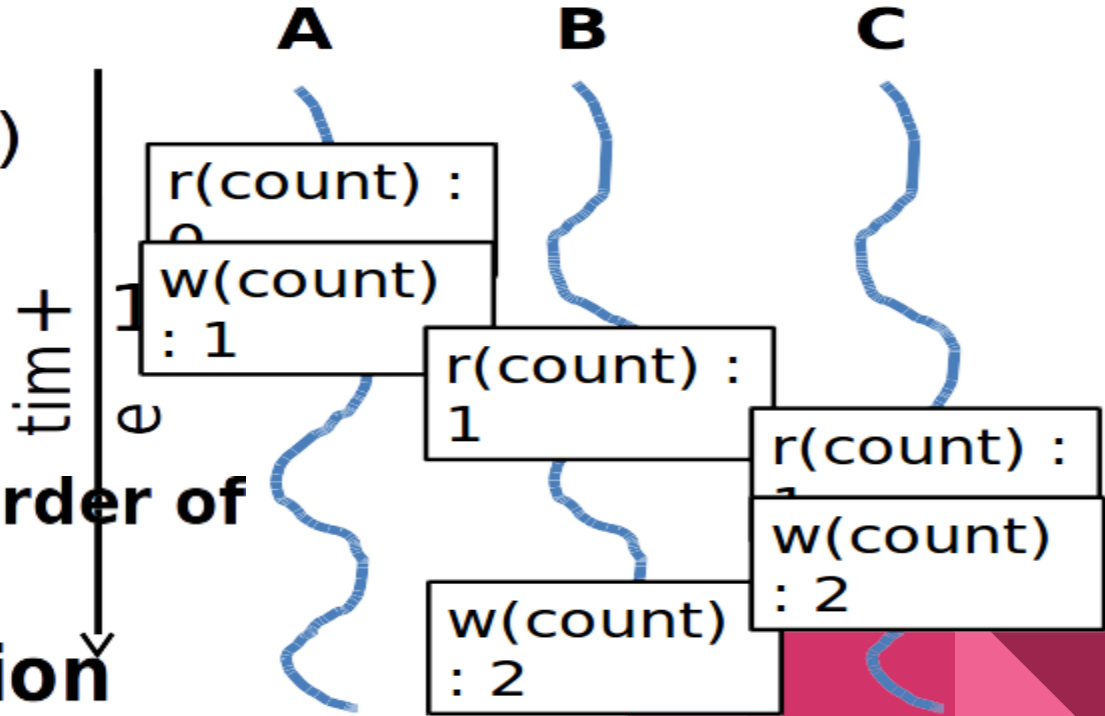
# Thread safety



# Race Condition

```
int count = 0;  
void increment()  
{  
    count = count + 1;  
}
```

**Result depends on order of execution**  
**=> Synchronization needed**



# Mutex

mutexes - Mutual exclusion lock: Block access to variables by other threads. This enforces exclusive access by a thread to a variable or set of variables.

Mutexes are used for serializing shared resources.

Anytime a global resource is accessed by more than one thread the resource should have a Mutex associated with it.

When a mutex lock is attempted against a mutex which is held by another thread, the thread is blocked until the mutex is unlocked.



# POSIX Threads

The POSIX thread libraries are a standards based thread API for C/C++.



# PThread Creation

```
int pthread_create(pthread_t * thread, const pthread_attr_t * attr,  
                  void * (*start_routine)(void *), void *arg);
```

## Arguments:

thread - returns the thread id. (unsigned long int defined in bits/pthreadtypes.h)

attr - Set to NULL if default thread attributes are used. void \* (\*start\_routine) - pointer to the function to be threaded. Function has a single argument: pointer to void.

\*arg - pointer to argument of function. To pass multiple arguments, send a pointer to a structure.

# Pthread exit


```
void pthread_exit(void *retval);
```

Arguments:

retval - Return value of thread.

This routine kills the thread.

Note: the return pointer \*retval, must not be of local scope otherwise it would cease to exist once the thread terminates.





# Pthread join

```
int pthread_join(pthread_t thread, void **value_ptr);
```


The *pthread\_join()* function suspends execution of the calling thread until the target *thread* terminates, unless the target *thread* has already terminated.



# Mutex

```
int pthread_mutex_lock(pthread_mutex_t *mutex);  
int pthread_mutex_unlock(pthread_mutex_t *mutex);
```

The mutex object referenced by *mutex* is locked by calling *pthread\_mutex\_lock()*. If the mutex is already locked, the calling thread blocks until the mutex becomes available. This operation returns with the mutex object referenced by *mutex* in the locked state with the calling thread as its owner.



# Lab

Evaluate the performance of multithreaded sort

Add /usr/local/cs/bin to PATH

```
$ export PATH=/usr/local/cs/bin:$PATH
```

Generate a file containing 10M random double-precision floating point numbers, one per line with no white space

/dev/urandom: pseudo-random number generator



# Lab

## od

Write the contents of its input files to standard output in a user-specified format

### Options

- t f: Double-precision floating point

- N <count>: Format no more than count bytes of input

## sed, tr

Remove address, delete spaces, add newlines between each float

# Lab

Use `time -p` to time the command `sort -g` on the data you generated

Send output to `/dev/null`

Run `sort` with the `--parallel` option and the `-g` option: compare by general numeric value

Use `time` command to record the real, user and system time when running `sort` with 1, 2, 4, and 8 threads

```
$ time -p sort -g file_name > /dev/null (1 thread)
```

```
$ time -p sort -g --parallel=[2, 4, or 8] file_name > /dev/null
```

Record the times and steps in `log.txt`

