# Assignment1

### **Training**

You can reproduce the experiment by run train.py.

The foundation of the script is PyTorch official Tutorial.

https://pytorch.org/tutorials/beginner/blitz/cifar10\_tutorial.html

I also refer to <a href="https://pytorch.org/docs/stable/">https://pytorch.org/docs/stable/</a> modules/torchvision/models/resnet.html to write my own network in

### **Data Augmentation:**

- RandomCrop
- RandomHorizontalFlip
- Normalize

Tricks come from

https://blog.csdn.net/weixin\_40123108/article/details/85246784

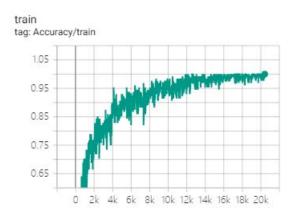
## **Optimizer**

Adam with initial learning rate 0.001, betas=(0.9, 0.999), eps=1e-08, weight\_decay=5e-4 Half the learning rate every 10 epochs 20k+ iterations in total

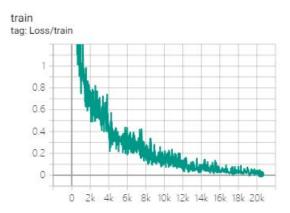
#### Metric

Cross\_entropy

# **Learning Progress**



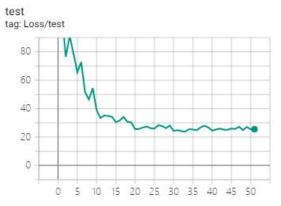
Training accuracy among mini-batch, final accuracy is 92.97% after 10k iterations



Training loss among 100 iterations, final loss is 9.8683e-3 after 20k iterations



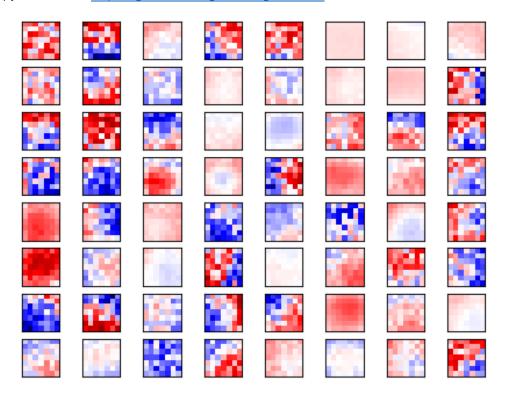
Testing accuracy among the whole test set, final accuracy is 91.2% after 20k iterations



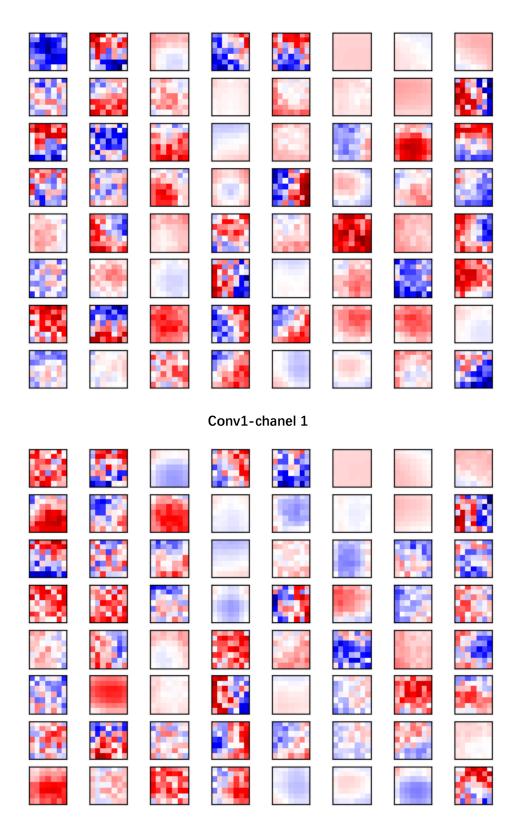
Testing loss among the whole test set, final loss is 25.49 after 20k iterations

## Filter visualization

 $\label{thm:com/grishasergei/conviz} \mbox{Utils.py come from $ \underline{ https://github.com/grishasergei/conviz} $ } \mbox{ } \mbox{$ \underline{ https://github.com/grishasergei/conviz} $ }$ 



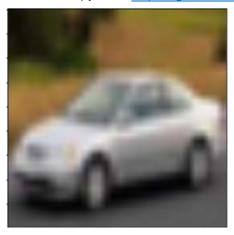
Conv1-chanel 0



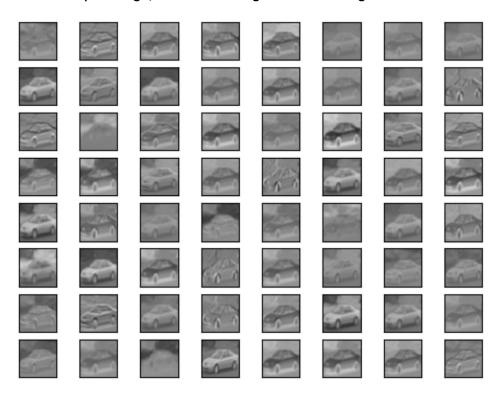
Conv1-chanel 2

# Feature mapping visualization

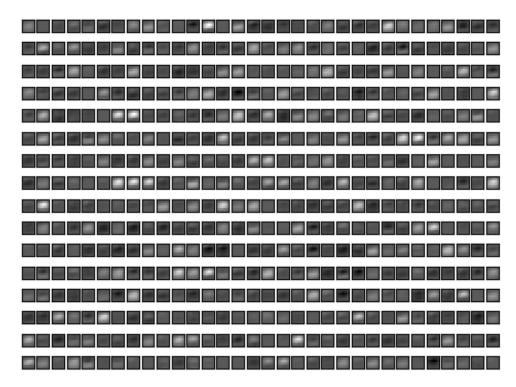
Visualized by a modified version of utils.py from <a href="https://github.com/grishasergei/conviz">https://github.com/grishasergei/conviz</a>



Input image, the 7876th image in cifar10 image dataset



Conv1\_output\_feature\_map



Conv5\_last\_layer\_output\_feature\_map

### Viusalization with deconvlution and max-unpool

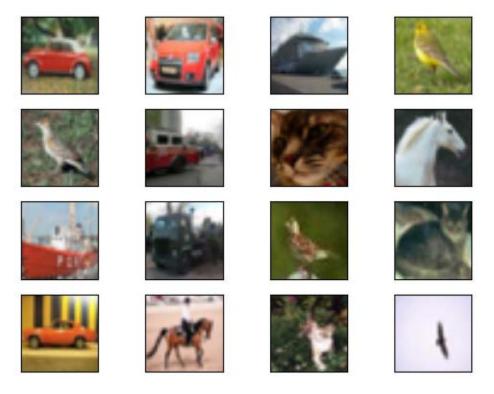
This strategy come from <a href="https://github.com/kvfrans/feature-visualization">https://github.com/kvfrans/feature-visualization</a>

```
plot_conv1_feature_map.py
plot_conv1_filters.py
plot_conv1_reconstructed_pattern.py
plot_conv5_feature_map.py
plot_conv5_reconstructed_pattern_shortcut.py
```

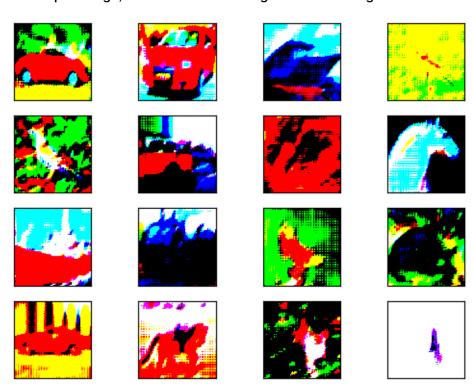
Code can be found in laplot conv5 reconstructed pattern trunk.py

The process is like backward propagation. Backward propagation propagate the gradients, while we propagate the feature map by sequentially apply the inverse operator corresponding to each operator from tail to head. Note that inverse operator defined here is not strict. I Inverse operator here just recover shape, e.g. deconvolution – convolution, maxpooling-maxunpooling.

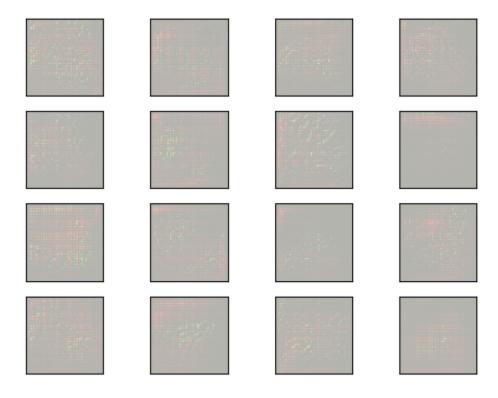
# Original image(corresponding image patches)



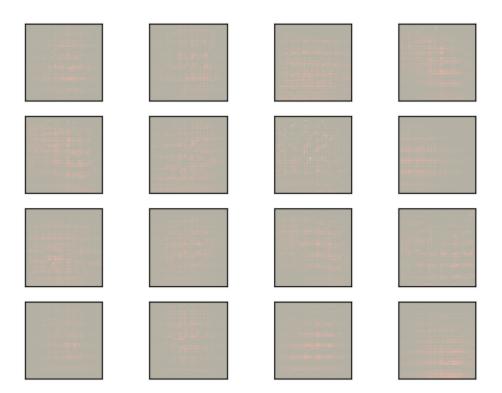
Input image, the 4531-4546th image in cifar10 image dataset



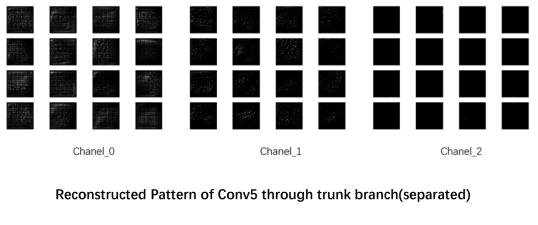
**Reconstructed Pattern of Conv1** 

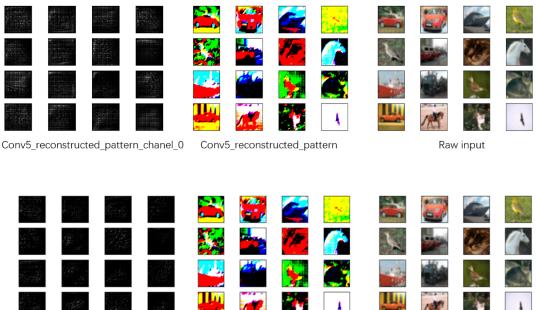


Reconstructed Pattern of Conv5 through shortcuts



Reconstructed Pattern of Conv5 through trunk branch





 ${\tt Conv5\_reconstructed\_pattern\_chanel\_1}$ 

Conv5\_reconstructed\_pattern

Raw input

### Viusalization with gradient based strategy

Idea and the base code come from <a href="https://github.com/utkuozbulak/pytorch-cnn-visualizations">https://github.com/utkuozbulak/pytorch-cnn-visualizations</a>. The basic idea is to find a pattern that cause a specified filter output the maximum activation map. This can be viewed as an unconstrained optimization problem. Thus we can use gradient decent to solve it.

I just focus on the first filter of the last layer in the block Conv5\_x. In order to get fine performance, I make two little changes. The first one to find an image in 10000 which cause specified filter output the maximum. I find the 7876th image activate the filter most.

```
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     model(temp_img.expand(1, -1, -1, -1))
max_index = 0
max_value = 0
max_activation_image = None
max_activation_input = None
for i in trange(10000):
   temp_img, label = testloader.dataset[i]
    img_for_plot = temp_img.clone()
   temp_img = norm(temp_img)
    temp_img = temp_img. to(device)
    input = temp_img. expand(1, -1, -1, -1)
    model(input)
    print(activations.features[0, 0].sum())
    v = activations.features[0, 0].sum()
    if i == 0:
        max_value = v
    else:
        if v > max_value:
            max_index = i
            max_value = v
            {\tt max\_activation\_image = img\_for\_plot.clone()}
           max_activation_input = input.clone()
print(max_index)
        tensor( 4.0024, device- cada.v , grad_in-\bumbackwardv//
       7876
```



Input image, the 7876th image in cifar10 image dataset

The second change is to maximize the activation as well as minimize the distance between the pattern we try to find and the input image. Finally, I find a nice pattern for the filter.



Reconstructed Pattern of Conv5-filter1 based on gradient

### Feedback

Time: 4 + 2 + 4 + 17 hours

Comments: Prof. Chen is nice. The lecture is becoming increasingly good.

Comments: hard for everyone

Suggestion: I am looking forward to learn more basic theory and knowledge on general

artificial intelligence.

#### Reference

https://pytorch.org/tutorials/beginner/blitz/cifar10\_tutorial.html

https://pytorch.org/docs/stable/ modules/torchvision/models/resnet.html

https://pytorch.org/docs/stable/index.html

https://github.com/utkuozbulak/pytorch-cnn-visualizations

https://github.com/kvfrans/feature-visualization

https://github.com/grishasergei/conviz