EECS 376: Foundations of Computer Science

Lecture 19 - Approximation Algorithms



What it means for an algorithm to be an α approximation

Minimization Problems: OPT \leq ALG \leq α • OPT, $\alpha \geq 1$ (smaller α is better)

Maximization Problems: OPT \geq ALG \geq α • OPT, $\alpha \leq 1$ (larger α is better)

ALG = value returned by our algorithm OPT = Optimal value

α is the approximation ratio

Two ingredients in approximation analysis

Minimization Problems:

- Upper bound on ALG
- Lower bound on OPT

Maximization Problems:

- Lower bound on ALG
- Upper bound on OPT

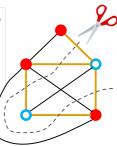
Next: an approximation algorithm for the problem of Maximum Cut...

Max Cut

Graph Cuts

defo

- * A cut of a graph is a partition of its vertices $(S, \overline{S})_{t}$
- * An edge **crosses** the cut (S, \overline{S}) if one of its endpoints is in S and the other is in \overline{S} .
- * The <u>size</u> of a cut (S, \overline{S}) is the number of edges crossing it.



Maximum Cut Problem

Max-Cut Problem: Given a graph, find a cut of maximum size.

o decision version is MP-complete (we won't prove)



Has applications in network/circuit design, physics, and more...

Approximate Maximum Cut

We will show a poly-time ½-approximation
(i.e. the cut returned by our algorithm is at least ½
the size of a max cut)



Technique: Local Search

Idea

- Start with an arbitrary cut.
- Pick a vertex v
- Switch the side of v if it increase the cut size (this is a local search).

Ouiz:

When switching the side of $\boldsymbol{\mathit{v}}$ will increase the cut size?

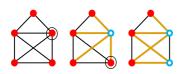
Ans:

#neighbors of v on the same side > #neighbors of v on the other side

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Algorithm

- Start with an arbitrary cut.
- ullet While there is a vertex v such that #neighbors of v on the same side > #neighbors of v on the other side
 - Switch the side of *v*
- Return the cut.



Analysis: Running Time

Why does the algorithm terminate?

B为 vertex有限

Why is it polynomial time?

000)

Analysis: Approximation Ratio

ALG: #edges in our cut OPT: #edges in an optimal cut

Want to show, $ALG \ge m/2$.

Lower bound on ALG

OPT ≤ m.

Upper bound on OPT

⇒ ALG ≥ ½ · OPT

- OPT ≤ m is clear.
 Why ALG ≥ m/2?

(actually OPT > =)

Analysis: Approximation Ratio

ALG: #edges in our cut OPT: #edges in an optimal cut

Want to show, ALG \geq m/2.

Lower bound on ALG

OPT ≤ m.

Upper bound on OPT

⇒ ALG ≥ ½ · OPT

- **OPT** ≤ m is clear.
- Why ALG ≥ m/2?

ALG = $\frac{1}{2}\Sigma_v(\#v'\text{s incident cut edges}) = \frac{1}{2}\Sigma_v\frac{\deg(v)}{2} \ge \frac{m}{2}$

Knapsack

Knapsack Problem

Given a backpack with weight capacity **W**, and a set of **n** items each with an integer value $v_i \le V$ and weight $w_i \le W$, what is the largest total value of a set of items that fit in the backpack (i.e. total weight of set \leq **W**)?







On the HW: Knapsack is NP-hard

Approximate Knapsack

We will show a poly-time 1/2-approximation i.e. the total value of the items chosen by our algorithm is at least $\ensuremath{\ensuremath{\%}}$ the optimal value.



~0.95 • OPT





Look at my algorithm! I'm relatively sure it works!



Relatively-Greedy Algorithm:

- Consider items in decreasing order by relative value (breaking ties arbitrarily) i.e. the ratio value/weight
- Greedily select item if it fits in remaining capacity.







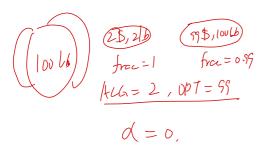


algorithm that solves the *fractional*



Your task: How bad is the approximation ratio of the Relatively-Greedy algorithm?

Construct an example to support your claim. (An example consists of: weight of backpack, and weight/value of each item)



Just take the one



Single-Greedy Algorithm: Take the one single item of largest value tha fits in the backpack. (Don't take any more items.)



Combined-Greedy Algorithm:

- Run Relatively-Greedy and Single-Greedy
- Take the best of the two solutions

One can show: Combined-Greedy is a ½-approximation!

Example of combined algorithms in practice: The Netflix Challenge (2009) "[The winning team] simply ran hundreds of algorithms from their 30-plus members and combined their results into a single set, using a variation of weighted averaging that favored the more accurate algorithms."

Metric Traveling Salesman Problem

Approximate Metric-TSP

Input

a complete graph with n vertices.

Edge weights form a metric, i.e., they obey the triangle inequality: for any $x, y, z \operatorname{dist}(x, z) \le \operatorname{dist}(x, y) + \operatorname{dist}(y, z)$

What is the minimum length cycle visiting each vertex once?



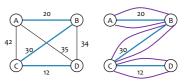
The decision version of Metric-TSP is NP-complete. We will show a poly-time 2-approximation. (returns a tour of length at most 2 times the optimal tour)

Algorithm

Step 1: Find an MST (in polynomial time)

Step 2: Walk around the perimeter of the MST to form "tree-tour"

tree-tour is not a legitimate TSP tour!



tree-tour = 2·MST

Algorithm

Step 1: Find an MST (in polynomial time)

Step 2: Walk around the perimeter of the MST to form "tree-tour"

tree-tour is not a legitimate TSP tour!

If you wanted to code it:

Find-Tour(u)

Let $v_1, ..., v_k$ be u's children

For i = 1, ..., k

 $T = T + (u, v_i)$

Find-Tour(v_i)

 $T = T + (v_i, u)$



tree-tour = 2·MST

Algorithm

Step 1: Find an MST (in polynomial time)

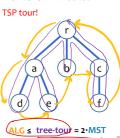
Step 2: Walk around the perimeter of the MST to form "tree-tour"

(tree-tour is not a legitimate TSP tour!

Repeatedly visit the next unvisited vertex in tree-tour

Why shortcut tree-tour ≤ tree-tour?

Triangle inequality!



Analysis

We have shown

ALG ≤ tree-tour = 2· MST

To get 2-approximation, ALG ≤ 2 · OPT, we will show

OPT ≥ MST

Why is this?

• An optimal cycle has weight at least that of some spanning tree

Can we do better than a 2-approximation?

Yes!

- * [Christofides 1976] 1.5-approximation
- * [Karlin-Klein-Oveis Gharan 2021] (1.5 10⁻³⁶)-approximation.
- [Karpinski-Lampis-Schmied 2013] No 1.008-approximation unless P = NP.

https://en.wikipedia.org/wiki/Christofides_algorithm

https://dl.acm.org/doi/10.1145/3406325.3451009

Wrap Up

Ways to deal with NP-Hardness

- 1. Approximation algorithms
- 2. Restrict to special classes of inputs
 - o $\,$ randomly-generated inputs, planar graphs, ...
 - o Fixed-parameterized algorithms
- 3. Heuristics: algorithms without provable guarantees that seem to work well in practice
 - o SAT solvers sometimes do well in practice
- 4. If your **input is small**, sometimes you can afford to run an exponential-time algorithm

Goodbye Complexity...

