

**MATH 217 - W24 - LINEAR ALGEBRA**  
**HOMEWORK 6, DUE Thursday, March 7 at 11:59pm**

Submit Part A and Part B as two *separate* assignments in Gradescope as a **pdf file**. At the time of submission, Gradescope will prompt you to match each problem to the page(s) on which it appears. **You must match problems to pages in Gradescope so we know what page each problem appears on.** Failure to do so may result in not having the problem graded.

**A few words about solution writing:**

- Unless you are explicitly told otherwise for a particular problem, **you are always expected to show your work and to give justification for your answers.**
- Your solutions will be judged on precision and completeness and not merely on “basically getting it right”.
- Cite every theorem or fact from the book that you are using (e.g. “By Theorem 1.10 ...”).

**Part A**

Solve the following problems from the book:

**Section 3.4:** 50, 70;

**Section 4.1:** 58;

**Section 4.2:** 46, 68.

**Part B**

**Problem 1.** Let  $V$  be a vector space, and let  $(\vec{v}_1, \dots, \vec{v}_n)$  be a list of vectors in  $V$ . Define the function  $T : \mathbb{R}^n \rightarrow V$  by

$$T \left( \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \right) = c_1 \vec{v}_1 + \dots + c_n \vec{v}_n \quad \text{for all } \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \in \mathbb{R}^n.$$

- Prove that  $T$  is a linear transformation.
- Prove that  $T$  is injective if and only if  $(\vec{v}_1, \dots, \vec{v}_n)$  is linearly independent.
- Prove that  $T$  is surjective if and only if  $(\vec{v}_1, \dots, \vec{v}_n)$  spans  $V$ .
- Prove that  $T$  is an isomorphism if and only if  $(\vec{v}_1, \dots, \vec{v}_n)$  is an ordered basis of  $V$ .

**Problem 2.** For a  $2 \times 2$  matrix  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ , define the **transpose** of  $A$  to be the matrix

$$A^T = \begin{bmatrix} a & c \\ b & d \end{bmatrix}.$$

Consider the linear transformation

$$T : \mathbb{R}^{2 \times 2} \rightarrow \mathbb{R}^{2 \times 2} \quad T(A) = \frac{1}{2}(A + A^T).$$

- Find the  $\mathcal{E}$ -matrix  $[T]_{\mathcal{E}}$  of  $T$ , where

$$\mathcal{E} = \left( \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right)$$

is the standard ordered basis of  $\mathbb{R}^{2 \times 2}$ .

- (b) Find the  $\mathfrak{C}$ -matrix of  $T$ , where  $\mathfrak{C}$  is the ordered basis

$$\mathfrak{C} = \left( \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right)$$

- (c) Compute the kernel of  $[T]_{\mathcal{E}}$ . This will be a subspace of the  $\mathcal{E}$ -coordinate space  $\mathbb{R}^4$  for  $\mathbb{R}^{2 \times 2}$ .  
 (d) Find a basis for the corresponding subspace of  $\mathbb{R}^{2 \times 2}$ —that is, for the image of  $\ker[T]_{\mathcal{E}}$  under the coordinate isomorphism  $L_{\mathcal{E}}^{-1} : \mathbb{R}^4 \rightarrow \mathbb{R}^{2 \times 2}$ .  
 (e) Compute the kernel of the  $\mathfrak{C}$ -matrix. This will be a subspace of the  $\mathfrak{C}$ -coordinate space  $\mathbb{R}^4$  for  $\mathbb{R}^{2 \times 2}$ .  
 (f) Compute the image of the subspace  $\ker[T]_{\mathfrak{C}}$  under the coordinate isomorphism  $L_{\mathfrak{C}}^{-1} : \mathbb{R}^4 \rightarrow \mathbb{R}^{2 \times 2}$ .  
 (g) Compare your answers in (d) and (f). How are they related to  $\ker T$ ?  
 (h) Find a basis for the image of  $T$  using **either**  $\mathcal{E}$ -coordinates or  $\mathfrak{C}$ -coordinates (which seems easier?) Don't forget to reinterpret vectors in the coordinate space as elements in  $\mathbb{R}^{2 \times 2}$ !

**Problem 3.** Let  $C^\infty(\mathbb{R})$  be the vector space of smooth functions from  $\mathbb{R}$  to  $\mathbb{R}$ . In other words, every vector  $f \in C^\infty(\mathbb{R})$  is a function  $f : \mathbb{R} \rightarrow \mathbb{R}$  that is differentiable  $k$ -times for all  $k \in \mathbb{N}$ . Let  $f_1, \dots, f_6$  be the six functions in  $C^\infty(\mathbb{R})$  defined by

$$f_1(x) = 1, \quad f_2(x) = \sin(2x), \quad f_3(x) = \cos(2x),$$

$$f_4(x) = \sin^2(x), \quad f_5(x) = \cos^2(x), \quad f_6(x) = \sin x \cos x.$$

Let  $V = \text{Span}(f_1, f_2, f_3, f_4, f_5, f_6)$ , and let  $\mathcal{B} = (f_1, f_2, f_4) = (1, \sin 2x, \sin^2 x)$ .

- (a) Prove that  $\mathcal{B}$  is an ordered basis of  $V$ . [*Hint*: For linear independence, write a relation and evaluate it at one or more carefully-chosen values of  $x$ . For spanning, remember (or look up) some trig identities.]  
 (b) For each  $i \in \{1, \dots, 6\}$ , find  $[f_i]_{\mathcal{B}}$ .  
 (c) Show that for all  $f \in V$ , the derivative of  $f$  is also in  $V$ .  
 (d) As a result of (c), we can define the linear transformation  $D : V \rightarrow V$  by  $D(f) = f'$  for all  $f \in V$ . Compute the  $\mathfrak{B}$ -matrix  $[D]_{\mathfrak{B}}$  of  $D$ .  
 (e) **Without using calculus**, compute  $[D]_{\mathfrak{B}}^{-1}$ .  
 (f) Using  $[D]_{\mathfrak{B}}^{-1}$ , but **without directly using calculus**, find an antiderivative of

$$3 \cos^2(x) + 4 \sin(x) \cos(x) + \sin(2x).$$

Note: In (e) and (f) you will **not** receive credit for computing integrals using “Calc 2” methods (e.g.,  $u$ -substitution or related techniques).

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Let  $A$  and  $B$  be sets. Recall from the handout *More Joy of Sets* that we define the *Cartesian product* of  $A$  and  $B$  to be the set

$$A \times B := \{(a, b) : a \in A \text{ and } b \in B\}.$$

If  $X$  and  $Y$  are vector spaces, then  $X \times Y$  is also a vector space, with addition and scalar multiplication given by

$$(\vec{x}, \vec{y}) + (\vec{x}', \vec{y}') = (\vec{x} + \vec{x}', \vec{y} + \vec{y}'), \quad c(\vec{x}, \vec{y}) = (c\vec{x}, c\vec{y})$$

for all  $(\vec{x}, \vec{y}), (\vec{x}', \vec{y}') \in X \times Y$  and  $c \in \mathbb{R}$ .

**Problem 4.** Let  $X$  and  $Y$  be finite-dimensional vector spaces.

- (a) Describe the zero vector of  $X \times Y$ . (*No justification necessary.*)
- (b) Let  $\{\vec{x}_1, \dots, \vec{x}_m\}$  be a basis of  $X$ , and let  $\{\vec{y}_1, \dots, \vec{y}_n\}$  be a basis of  $Y$ . Prove that

$$\{(\vec{x}_1, \vec{0}_Y), \dots, (\vec{x}_m, \vec{0}_Y), (\vec{0}_X, \vec{y}_1), \dots, (\vec{0}_X, \vec{y}_n)\}$$

is a basis of  $X \times Y$ .

- (c) Determine  $\dim(X \times Y)$  in terms of  $\dim(X)$  and  $\dim(Y)$ .

**Problem 5.** Let  $V$  be a vector space, and let  $X$  and  $Y$  be subspaces of  $V$ . Define the function  $T : X \times Y \rightarrow X + Y$  by

$$T(\vec{x}, \vec{y}) := \vec{x} + \vec{y} \quad \text{for all } (\vec{x}, \vec{y}) \in X \times Y.$$

- (a) Prove that  $T$  is a linear transformation and that  $T$  is surjective.
- (b) Prove that  $\ker(T)$  is isomorphic to  $X \cap Y$ .
- (c) Assuming that  $X$  and  $Y$  are finite-dimensional, prove that

$$\dim(X + Y) + \dim(X \cap Y) = \dim(X) + \dim(Y).$$

- (d) Let  $X$  and  $Y$  be 3-dimensional subspaces of  $\mathbb{R}^5$ . Is it possible that  $X \cap Y = \{\vec{0}\}$ ? Now instead assume that  $X$  and  $Y$  are 3-dimensional subspaces of  $\mathbb{R}^6$ . Is it possible that  $X \cap Y = \{\vec{0}\}$ ? Prove your answers.