

Worksheet 18: Orthogonal Transformations (§5.3)

Definition: A linear transformation $\mathbb{R}^n \xrightarrow{T} \mathbb{R}^n$ is **orthogonal** if it preserves dot products—that is, if $\vec{x} \cdot \vec{y} = T(\vec{x}) \cdot T(\vec{y})$ for all vectors \vec{x} and \vec{y} in \mathbb{R}^n .

Theorem A: Let $\mathbb{R}^n \xrightarrow{T} \mathbb{R}^n$ be a linear transformation. Then T is orthogonal if and only if it preserves the length of every vector—that is, $\|T(\vec{x})\| = \|\vec{x}\|$ for all $\vec{x} \in \mathbb{R}^n$.

Problem 1. Which of the following maps are orthogonal transformations? Short, geometric justifications are preferred, where possible.

- (a) The identity map $\mathbb{R}^3 \rightarrow \mathbb{R}^3$.
- (b) Rotation counterclockwise through θ in \mathbb{R}^2 .
- (c) The reflection $\mathbb{R}^3 \rightarrow \mathbb{R}^3$ over a plane (through the origin).
- (d) The projection $\mathbb{R}^3 \rightarrow \mathbb{R}^3$ onto a subspace V of dimension 2.
- (e) Dilation $\mathbb{R}^3 \rightarrow \mathbb{R}^3$ by a factor of 3.
- (f) Multiplication by $\begin{bmatrix} 3 & 1 \\ -2 & 5 \end{bmatrix}$.

Solution:

- (a) Yes, dot product is obviously the same before or after doing nothing.
- (b) Yes, rotation obviously preserves the LENGTH of every vector, so by the theorem, this means rotation is an orthogonal transformation.
- (c) Yes, reflection obviously preserves the LENGTH of every vector, so by the theorem, this means reflection is an orthogonal transformation.
- (d) No, projection will typically shorten the length of vectors.
- (e) No, dilation by three obviously takes each vector to a vector of length 3 times as long.
- (f) No. The vector \vec{e}_1 is sent to $\begin{bmatrix} 3 \\ -2 \end{bmatrix}$, which has length $\sqrt{13}$, not 1 like \vec{e}_1 .

Problem 2. Let $\mathbb{R}^n \xrightarrow{T} \mathbb{R}^n$ be an orthogonal transformation.

- (a) Prove that T is **injective**. [HINT: consider the kernel.]
- (b) Prove that T is an isomorphism. [HINT: Note that the source and target here have the same dimension.]
- (c) Prove that the matrix of T (in standard coordinates) has columns that are *orthonormal*.
- (d) Prove the composition of orthogonal transformations is orthogonal. [HINT: Use the Theorem!]

Solution:

- (a) Let $\vec{v} \in \ker T$. We want to show that $\vec{v} = 0$. We know that $T(\vec{v}) = 0$, so $\|T(\vec{v})\| = 0$. Since T is orthogonal, it preserves lengths (by the theorem), so also $\|\vec{v}\| = 0$. This means $\vec{v} = 0$ since no other vector has length 0. So the kernel of T is trivial and T is injective.
- (b) We already know T is injective, so we just need to check it is surjective. By rank-nullity, $n = \dim \ker T + \text{rank} T$. So by (1), we have $\text{rank} T = n$, so T is surjective. Thus T is a bijective linear transformation, that is, an isomorphism.
- (c) Let A be the standard matrix of T . The columns of A are $T(\vec{e}_1), \dots, T(\vec{e}_n)$ by our old friend the Key Theorem. We need to show these are orthonormal. Compute for each i : $T(\vec{e}_i) \cdot T(\vec{e}_i) = \vec{e}_i \cdot \vec{e}_i = 1$ (where we have used the fact that T preserves dot product). Also compute for each pair $i \neq j$: $T(\vec{e}_i) \cdot T(\vec{e}_j) = \vec{e}_i \cdot \vec{e}_j = 0$. This means that $T(\vec{e}_1), \dots, T(\vec{e}_n)$ are orthonormal.
- (d) Yes! Assume T and S are orthonormal transformations with source and target \mathbb{R}^n . To show that $S \circ T$ is orthogonal, we can show it preserves LENGTHS, by the theorem. Take any vector $\vec{x} \in \mathbb{R}^n$. Then $\|\vec{x}\| = \|T(\vec{x})\|$ since T is orthogonal (by the Theorem, or by the book definition). So also $\|T(\vec{x})\| = \|S(T(\vec{x}))\|$ since S is orthogonal. Putting these together we have $\|\vec{x}\| = \|S(T(\vec{x}))\|$. Since \vec{x} was arbitrary, we see that $S \circ T$ preserves every length. QED.

Definition: An $n \times n$ matrix A is **orthogonal** if $A^\top A = I_n$ —i.e., if its transpose is its inverse.

Problem 3. Which of the following matrices are orthogonal?

$$(i) \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \quad (ii) \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad (iii) \begin{bmatrix} 1 & -1 \\ 1 & 2 \end{bmatrix} \quad (iv) \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}.$$

Solution: Yes, yes, no, no.

Problem 4. Suppose that $A = [\vec{v}_1 \ \vec{v}_2 \ \vec{v}_3]$ is a 3×3 matrix with columns $\vec{v}_1, \vec{v}_2, \vec{v}_3 \in \mathbb{R}^3$.

- (a) Recalling that $A^\top = \begin{bmatrix} \vec{v}_1^\top \\ \vec{v}_2^\top \\ \vec{v}_3^\top \end{bmatrix}$, show that

$$A^\top A = \begin{bmatrix} \vec{v}_1 \cdot \vec{v}_1 & \vec{v}_1 \cdot \vec{v}_2 & \vec{v}_1 \cdot \vec{v}_3 \\ \vec{v}_2 \cdot \vec{v}_1 & \vec{v}_2 \cdot \vec{v}_2 & \vec{v}_2 \cdot \vec{v}_3 \\ \vec{v}_3 \cdot \vec{v}_1 & \vec{v}_3 \cdot \vec{v}_2 & \vec{v}_3 \cdot \vec{v}_3 \end{bmatrix}.$$

- (b) Does the argument work for any size square matrix?
- (c) Use (a)/(b) to prove a square matrix is orthogonal if and only if its columns are orthonormal.

(d) Is $B = \begin{bmatrix} 3/5 & 4/5 & 0 \\ -4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ orthogonal? Find B^{-1} . [Be clever! There are easy ways and hard ways!]

Solution:

(a) Multiply $A^T A = \begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vec{v}_3^T \end{bmatrix} [\vec{v}_1 \quad \vec{v}_2 \quad \vec{v}_3] = \begin{bmatrix} \vec{v}_1^T \vec{v}_1 & \vec{v}_1^T \vec{v}_2 & \vec{v}_1^T \vec{v}_3 \\ \vec{v}_2^T \vec{v}_1 & \vec{v}_2^T \vec{v}_2 & \vec{v}_2^T \vec{v}_3 \\ \vec{v}_3^T \vec{v}_1 & \vec{v}_3^T \vec{v}_2 & \vec{v}_3^T \vec{v}_3 \end{bmatrix}$, which produces the desired matrix since for any $n \times 1$ matrices (column vectors) \vec{w} and \vec{v} , the matrix product $\vec{w}^T \vec{v}$ is the same as the dot product $\vec{w} \cdot \vec{v}$.

(b) Yes! Let A have columns $\vec{v}_1, \dots, \vec{v}_n$. Then the ij -th entry of $A^T A$ is $\vec{v}_i^T \vec{v}_j = \vec{v}_i \cdot \vec{v}_j$. So the columns are orthonormal if and only if $A^T A$ is the identity matrix.

(c) For a square matrix $A = [\vec{v}_1 \quad \dots \quad \vec{v}_n]$, the ij -th entry of $A^T A$ is $\vec{v}_i \cdot \vec{v}_j$ by (b). So the columns are orthonormal if and only if $A^T A = I_n$.

(d) Yes—it's easy to check its columns are orthonormal. The inverse is the transpose, which is $\begin{bmatrix} 3/5 & -4/5 & 0 \\ 4/5 & 3/5 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

Problem 5. Show that if A and B are orthogonal $n \times n$ matrices, then the matrices A^T , A^{-1} , and AB are also orthogonal.

Solution: Since A is orthogonal, $A^{-1} = A^T$, so it's enough to show that A^T is orthogonal. We check: $(A^T)^T A^T = A A^T = I_n$ because a matrix always commutes with its inverse. For AB , we check: $(AB)^T (AB) = (B^T A^T)(AB)$, and now using $A^{-1} = A^T$, this collapses to $B^T B$, which is I_n , since B is orthogonal.

Theorem B: Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation with standard matrix A . Then T is orthogonal if and only if A is orthogonal.

Problem 6. Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation.

- (a) Prove Theorem B just above. [HINT: Use Problems 2 and 4.]
- (b) If \mathcal{B} is an arbitrary basis, is it still true that T is orthogonal if and if $[T]_{\mathcal{B}}$ is orthogonal? What about if \mathcal{B} is an *orthonormal basis*?

Solution: For (a), we need to show two things:

- 1). If T is orthogonal, then A is orthogonal. For this it suffices to show A has orthonormal columns. This was shown in 2c.
- 2). If A has orthonormal columns, T is orthogonal. By the Theorem on page 1, it suffices to show that for any $\vec{x} \in \mathbb{R}^n$, $\|T(\vec{x})\| = \|\vec{x}\|$. Since the length is always a non-negative number,

it suffices to show $\|T(\vec{x})\|^2 = \|\vec{x}\|^2$. That is, it suffices to show $T(\vec{x}) \cdot T(\vec{x}) = \vec{x} \cdot \vec{x}$. For, this we take an arbitrary \vec{x} and write it in the basis $\{\vec{e}_1, \dots, \vec{e}_n\}$. Note that

$$\vec{x} \cdot \vec{x} = (x_1\vec{e}_1 + \dots + x_n\vec{e}_n) \cdot (x_1\vec{e}_1 + \dots + x_n\vec{e}_n) = \sum_{ij} (x_i\vec{e}_i) \cdot (x_j\vec{e}_j) = x_1^2 + \dots + x_n^2.$$

Here the third equality is using some basic properties of dot product (like "foil"), and the third equality is using the fact that the \vec{e}_i are orthonormal so that $(x_i\vec{e}_i) \cdot (x_j\vec{e}_j) = 0$ if $i \neq j$. On the other hand, we also have

$$\begin{aligned} T(\vec{x}) \cdot T(\vec{x}) &= T(x_1\vec{e}_1 + \dots + x_n\vec{e}_n) \cdot T(x_1\vec{e}_1 + \dots + x_n\vec{e}_n) \\ &= \sum_{ij} (x_i T(\vec{e}_i)) \cdot (x_j T(\vec{e}_j)) \\ &= \sum_{ij} x_i x_j T(\vec{e}_i) \cdot T(\vec{e}_j) = x_1^2 + \dots + x_n^2 \end{aligned}$$

with the last equality coming from the fact that the $T(\vec{e}_i)$'s are the columns of A and hence orthonormal. QED.

For (b), the same proof works for any orthonormal basis—we really only used the fact that $\vec{e}_i \cdot \vec{e}_j$ is zero or one (if $i = j$), so that so is $T(\vec{e}_i) \cdot T(\vec{e}_j)$. Alternatively, we can deduce it from Theorem B as follows: Suppose $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is an orthogonal transformation, so the standard matrix $[T]_{\mathcal{E}}$ of T is orthogonal by Theorem B. Let $\mathcal{U} = (\vec{u}_1, \dots, \vec{u}_n)$ be an orthonormal basis of \mathbb{R}^n , and write $Q = [\vec{u}_1 \ \dots \ \vec{u}_n]$, so that Q is an orthogonal matrix and thus so is the matrix $Q^{-1} = Q^T$ by Problem 1. Then

$$[T]_{\mathcal{U}} = S_{\mathcal{E} \rightarrow \mathcal{U}} [T]_{\mathcal{E}} S_{\mathcal{U} \rightarrow \mathcal{E}} = Q^T [T]_{\mathcal{E}} Q$$

is also orthogonal, since products of orthogonal matrices are orthogonal (again by Problem 5).

For an arbitrary basis \mathcal{B} is false! For example, let T be rotation by 90° in \mathbb{R}^2 . let $\mathcal{B} = (\vec{e}_1, \vec{e}_1 + \vec{e}_2)$. The \mathcal{B} -matrix of T is $\begin{bmatrix} 1 & -2 \\ -1 & 1 \end{bmatrix}$, which is clearly not orthogonal as its columns do not have dot product zero. For an arbitrary basis, this fails.

Problem 7. Prove Theorem A from page 1. [HINT: For the harder direction, consider $T(\vec{x} + \vec{y})$.]

Solution: First assume that T is orthogonal. Take arbitrary $\vec{x} \in \mathbb{R}^n$. We want to show $\|\vec{x}\| = \|T(\vec{x})\|$. By definition $\|\vec{x}\| = (\vec{x} \cdot \vec{x})^{1/2}$ and $\|T(\vec{x})\| = (T(\vec{x}) \cdot T(\vec{x}))^{1/2}$. Since T is orthogonal, we know that $\vec{x} \cdot \vec{x} = T(\vec{x}) \cdot T(\vec{x})$, so the result follows.

For the converse, assume T preserves lengths. Take arbitrary $\vec{x}, \vec{y} \in \mathbb{R}^n$. We need to show that $T(\vec{x}) \cdot T(\vec{y}) = \vec{x} \cdot \vec{y}$. By assumption $\|T(\vec{x} + \vec{y})\| = \|(\vec{x} + \vec{y})\|$. This is the same as $T(\vec{x} + \vec{y}) \cdot T(\vec{x} + \vec{y}) = (\vec{x} + \vec{y}) \cdot (\vec{x} + \vec{y})$. By linearity, this is the same as $(T(\vec{x}) + T(\vec{y})) \cdot (T(\vec{x}) + T(\vec{y})) = (\vec{x} + \vec{y}) \cdot (\vec{x} + \vec{y})$. Expanding out using the rules of dot product, we get

$$T(\vec{x}) \cdot T(\vec{x}) + 2T(\vec{x}) \cdot T(\vec{y}) + T(\vec{y}) \cdot T(\vec{y}) = \vec{x} \cdot \vec{x} + 2\vec{x} \cdot \vec{y} + \vec{y} \cdot \vec{y}.$$

Now, we know that $T(\vec{x}) \cdot T(\vec{x}) = \|T(\vec{x})\|^2 = \|\vec{x}\|^2 = \vec{x} \cdot \vec{x}$ and similarly for \vec{y} , so this cancels down to

$$2T(\vec{x}) \cdot T(\vec{y}) = 2\vec{x} \cdot \vec{y}$$

and so $T(\vec{x}) \cdot T(\vec{y}) = \vec{x} \cdot \vec{y}$, as needed.

Problem 8. Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation, and let A be the standard matrix of T . Which of the following are equivalent?

- (a) T preserves length, i.e., $\|T(v)\| = \|v\|$ for all $v \in \mathbb{R}^n$.
- (b) T preserves distance, i.e., $\|T(v) - T(w)\| = \|v - w\|$ for all $v, w \in \mathbb{R}^n$.
- (c) T is an orthogonal transformation, i.e., T preserves the dot product.
- (d) T maps any orthonormal basis of \mathbb{R}^n to an orthonormal basis of \mathbb{R}^n .
- (e) T maps the standard basis of \mathbb{R}^n to an orthonormal basis of \mathbb{R}^n .
- (f) The columns of A form an orthonormal basis of \mathbb{R}^n .
- (g) $A^\top A = I_n$.
- (h) $AA^\top = I_n$.
- (i) A is an orthogonal matrix.
- (j) The rows of A form an orthonormal basis of \mathbb{R}^n .

Solution: These are all equivalent, and we've basically shown them above. Here are some direct proofs again.

(a) \Leftrightarrow (b): If T is linear and preserves lengths, then for all $v, w \in \mathbb{R}^n$, $\|T(v) - T(w)\| = \|T(v - w)\| = \|v - w\|$. Conversely, if T is linear and preserves distances, then for all $v \in \mathbb{R}^n$, $\|T(v)\| = \|T(v) - 0\| = \|T(v) - T(0)\| = \|v - 0\| = \|v\|$.

(a \wedge b) \Rightarrow (c): Let $v, w \in \mathbb{R}^n$. Expanding each side of $\|T(v - w)\| = \|v - w\|$ in terms of the dot product and using the facts that $\|T(v)\| = \|v\|$ and $\|T(w)\| = \|w\|$ to simplify, we find that $T(v) \cdot T(w) = v \cdot w$.

(c) \Rightarrow (d): Assuming (c), if $u_i \cdot u_j = \delta_{ij}$ for each i, j , then also $T(u_i) \cdot T(u_j) = \delta_{ij}$ for each i, j .

(d) \Rightarrow (e): Immediate, since the standard basis of \mathbb{R}^n is orthonormal.

(e) \Rightarrow (f): Follows from the fact that $A = [T(\vec{e}_1) \cdots T(\vec{e}_n)]$.

(f) \Leftrightarrow (g): If we write $A = [\vec{u}_1 \cdots \vec{u}_n]$, the (i, j) -entry of $A^\top A$ is $\vec{u}_i \cdot \vec{u}_j$.

(g) \Leftrightarrow (h): Follows from Theorem 2.4.8 in the text.

(h) \Leftrightarrow (i): Definition of orthogonal.

(h) \Leftrightarrow (j): If we write $A = \begin{bmatrix} - & \vec{u}_1^\top & - \\ & \vdots & \\ - & \vec{u}_n^\top & - \end{bmatrix}$, the (i, j) -entry of AA^\top is $\vec{u}_i \cdot \vec{u}_j$.

(g) \Rightarrow (c): If $A^\top A = I_n$, then $T(v) \cdot T(w) = Av \cdot Aw = v^\top A^\top Aw = v^\top w = v \cdot w$.

(c) \Rightarrow (a): If T preserves the dot product, then for all v , $\|T(v)\|^2 = T(v) \cdot T(v) = v \cdot v = \|v\|^2$.

Problem 9. Let $A \in \mathbb{R}^{n \times d}$ and $B \in \mathbb{R}^{d \times p}$. Prove that $(AB)^\top = B^\top A^\top$ using the ideas from Problem 4. [Note: You already proved this in the homework, most likely, a clumsier way!]

Solution: Let $\vec{\alpha}_i^\top$ denote the i -th row of A . So $A = \begin{bmatrix} \vec{\alpha}_1^\top \\ \vdots \\ \vec{\alpha}_n^\top \end{bmatrix} = [\vec{\alpha}_1 \cdots \vec{\alpha}_d]^\top$. Let $\vec{\beta}_j$ denote the j -th column of B , so that $B = [\vec{\beta}_1 \cdots \vec{\beta}_p]$. Then

$$AB = \begin{bmatrix} \vec{\alpha}_1^\top \\ \vdots \\ \vec{\alpha}_n^\top \end{bmatrix} [\vec{\beta}_1 \cdots \vec{\beta}_p] = [\vec{\alpha}_i^\top \vec{\beta}_j] = [\vec{\alpha}_i \cdot \vec{\beta}_j],$$

so the ij -entry of $(AB)^\top$ is $\vec{\alpha}_j \cdot \vec{\beta}_i$. And

$$B^\top A^\top = \begin{bmatrix} \vec{\beta}_1^\top \\ \vdots \\ \vec{\beta}_p^\top \end{bmatrix} [\vec{\alpha}_1 \quad \cdots \quad \vec{\alpha}_d] = [\vec{\beta}_i^\top \vec{\alpha}_j] = [\vec{\beta}_i \cdot \vec{\alpha}_j],$$

when is the same, since dot product is symmetric.