STATS / DATA SCI 315 Lecture 03

Regression
Loss functions and gradient descent

Training Dataset

- Need a dataset where we know the sale price, area, and age for each home
- This is called a training dataset or training set
- Put one sale info on each row
- Each row is called an example (or data point, data instance, sample)
- Each example has
 - A label (price)
 - Features (area, age)

Choosing weights and bias based on training data

- Choose the weights and the bias such that our model predictions best fit the true prices observed in the data
- Long form of our linear model:

price =
$$w_{\text{area}}$$
 · area + w_{age} · age + b

- If we had *d* features instead of just two:

$$\hat{y} = w_1 x_1 + ... + w_d x_d + b$$

- The "hat" on top of y denotes that it is an estimate

More compact notation

- Collect all features into a vector $\mathbf{x} \in \mathbb{R}^d$ and all weights into a vector $\mathbf{w} \in \mathbb{R}^d$
- Use dot product to express model compactly:

$$\hat{\mathbf{y}} = \mathbf{w}^{\mathsf{T}} \mathbf{x} + b$$

- Entire dataset of n examples is referred to as the design matrix $\mathbf{X} \subseteq \mathbb{R}^{n \times d}$
- X contains one row for every example and one column for every feature
- Prediction vector $\hat{\mathbf{y}} \in \mathbb{R}^n$ can be expressed via the matrix-vector product:

$$\hat{\mathbf{y}} = \mathbf{X}\mathbf{w} + b$$

Loss functions and gradient descent

Loss function

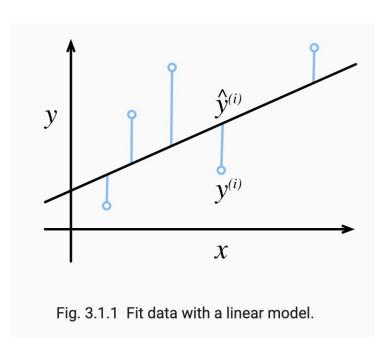
- We need a way to measure how good a prediction $\hat{y}^{(i)}$ is when the true label is $y^{(i)}$
- Most popular regression loss is the *squared error*:

$$l^{(i)}(\mathbf{w},b) = \frac{1}{2} (\hat{y}(i) - y(i))^2$$

- The ½ above is just for convenience
- Quality of model on entire dataset is assessed by:

$$L(\mathbf{w}, b) = \frac{1}{n} \sum_{i=1}^{n} l^{(i)}(\mathbf{w}, b) = \frac{1}{n} \sum_{i=1}^{n} \frac{1}{2} (\mathbf{w}^{\top} \mathbf{x}^{(i)} + b - y^{(i)})^{2}.$$

Visualizing the fit with 1-dimensional x



Minimizing the loss

- Bias can be absorbed into weights by using a "dummy" feature which is always 1:

$$\mathbf{w}^{\mathsf{T}}\mathbf{x} + b = (\mathbf{w}, b)^{\mathsf{T}}(\mathbf{x}, 1)$$

- Best choice for w is given by:

$$\mathbf{w}^* = \operatorname{argmin}_{\mathbf{w}} L(\mathbf{w}) = \operatorname{argmin}_{\mathbf{w}} \frac{1}{2} \|\mathbf{y} - \mathbf{X}\mathbf{w}\|^2$$

- Note that, in the last step, we removed *n* and used the Euclidean norm
- This optimization problem turns out to have a closed form solution

Taking derivatives

- How do we take the derivative of $L(\mathbf{w}) = \frac{1}{2} \|\mathbf{y} \mathbf{X}\mathbf{w}\|^2$ w.r.t. w?
- View L(w) as F(G(w)) and use chain rule:

$$L'(w) = G'(w) \times F'(G(w))$$

- G(u) = y-Xu and $F(u) = \frac{1}{2} ||u||^2$
- $G'(\mathbf{u}) = -\mathbf{X}^T$ and $F'(\mathbf{u}) = \mathbf{u}$
- Therefore, the derivative w.r.t. w is:

$$(-\mathbf{X}^{\mathsf{T}}) \times (\mathbf{y} - \mathbf{X}\mathbf{w}) = -\mathbf{X}^{\mathsf{T}}\mathbf{y} + \mathbf{X}^{\mathsf{T}}\mathbf{X}\mathbf{w}$$

Set gradient to zero

- Note that the derivative w.r.t. w has d components
- It is often called a gradient

$$\nabla L(\mathbf{w}) = -\mathbf{X}^{\mathsf{T}}\mathbf{y} + \mathbf{X}^{\mathsf{T}}\mathbf{X}\mathbf{w}$$

- Setting it to zero gives the closed-form solution

$$\mathbf{w}^* = (\mathbf{X}^{\mathsf{T}}\mathbf{X})^{-1}\mathbf{X}^{\mathsf{T}}\mathbf{y}$$

- We're assuming here that $\mathbf{X}^{\mathsf{T}}\mathbf{X}$ is invertible

Closed-form solutions are rare

- We got lucky in our simple setting (linear regression with squared loss)
- Usually we're not so lucky
- Even simple changes can destroy this property (like using absolute error)
- If we insisted on closed form solutions, almost *all* of DL will be excluded
- Key technique for incrementally lowering the loss function: gradient descent
- Iteratively reduces the loss by updating the parameters in the direction of the negative gradient

Gradient Descent

- For any objective function J(w), GD update takes the form:
 w ← w η ∇ J(w)
- The gradient gives you the direction of fastest local increase in J
- Since we're looking to minimize J, we move in the direction of *negative* gradient
- The step size (aka learning rate) η controls how much we move

Gradient Descent on the Loss

Takes the form:

$$\mathbf{w} \leftarrow \mathbf{w} - \mathbf{\eta} \nabla L(\mathbf{w})$$

- Here, the gradient has the form

$$\nabla L(\mathbf{w}) = 1/n \sum_{i} \frac{1}{2} \nabla (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} - y^{(i)})^2 = 1/n \sum_{i} \mathbf{x}^{(i)} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} - y^{(i)})$$

- So GD update becomes

$$\mathbf{w} \leftarrow \mathbf{w} - \mathbf{\eta}/n \sum_{i} \mathbf{x}^{(i)} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} - \mathbf{y}^{(i)})$$

- Requires one full pass through the entire data set

Minibatch Stochastic Gradient Descent

- In each iteration, we first randomly sample a minibatch **B** consisting of a fixed number of training examples
- Then we update $\mathbf{w} \leftarrow \mathbf{w} \mathbf{\eta}/|\mathbf{B}| \sum_{i \in \mathbf{B}} \mathbf{x}^{(i)} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} y^{(i)})$
- Note that the set **B** is random and changes from iteration to iteration
- η and |B| (the batch size) are hyperparameters: they're kept fixed during training
- However, an outer loop might optimize them by tracking performance on a *validation* set

Updates with bias kept separately

- Update w:

$$\mathbf{w} \leftarrow \mathbf{w} - \mathbf{\eta}/|\mathbf{B}| \sum_{i \in \mathbf{B}} \mathbf{x}^{(i)} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} + b - y^{(i)})$$

- Update bias:

$$b \leftarrow b - \eta/|\mathbf{B}| \sum_{i \in \mathbf{B}} (\mathbf{w}^{\mathsf{T}} \mathbf{x}^{(i)} + b - y^{(i)})$$

Making predictions with learned model

- Train for some predetermined number of iterations (or until some other stopping criteria are met)
- Record the estimated model parameters, denoted $\hat{\mathbf{w}}$, $\hat{\mathcal{D}}$
- Given a new house with area x_1 and age x_2 , we predict its price as $\hat{\mathbf{w}}^{\mathsf{T}}\mathbf{x}+\hat{b}$ where $\mathbf{x}=(x_1,x_2)$
- Estimating targets given features is commonly called *prediction*
- It's also (misleadingly) called *inference* in deep learning jargon