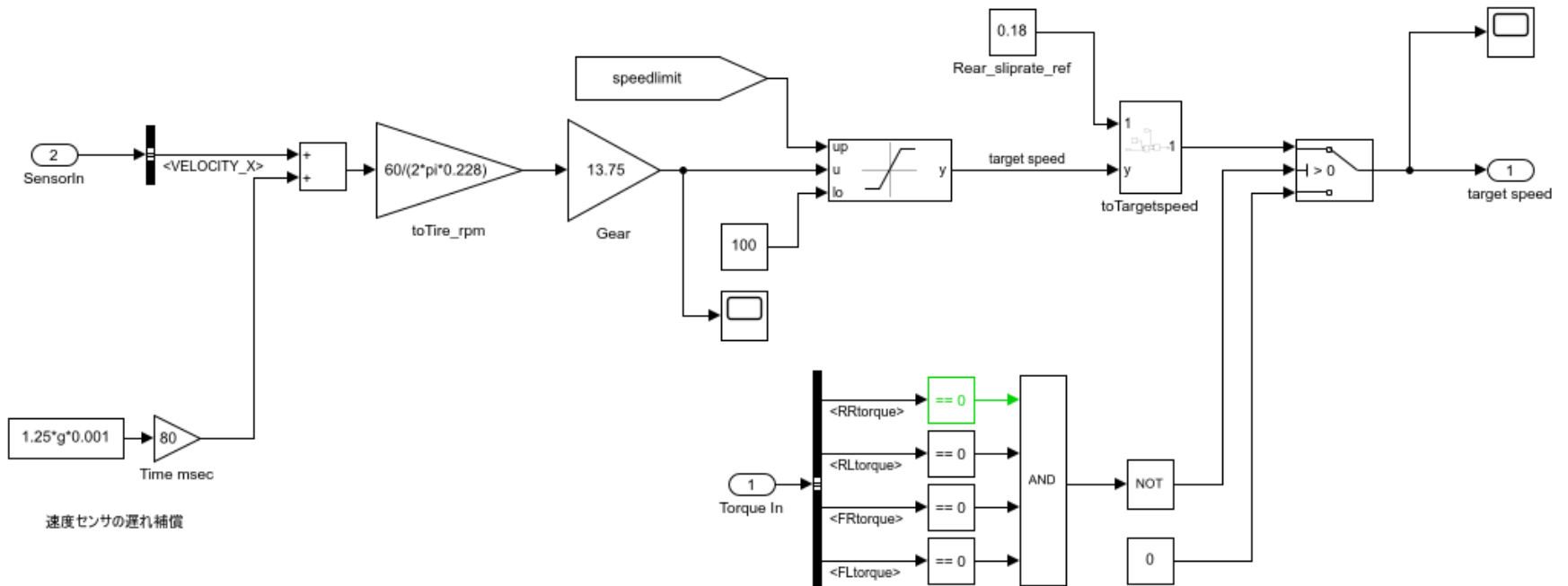


Robustness Check of Traction Control

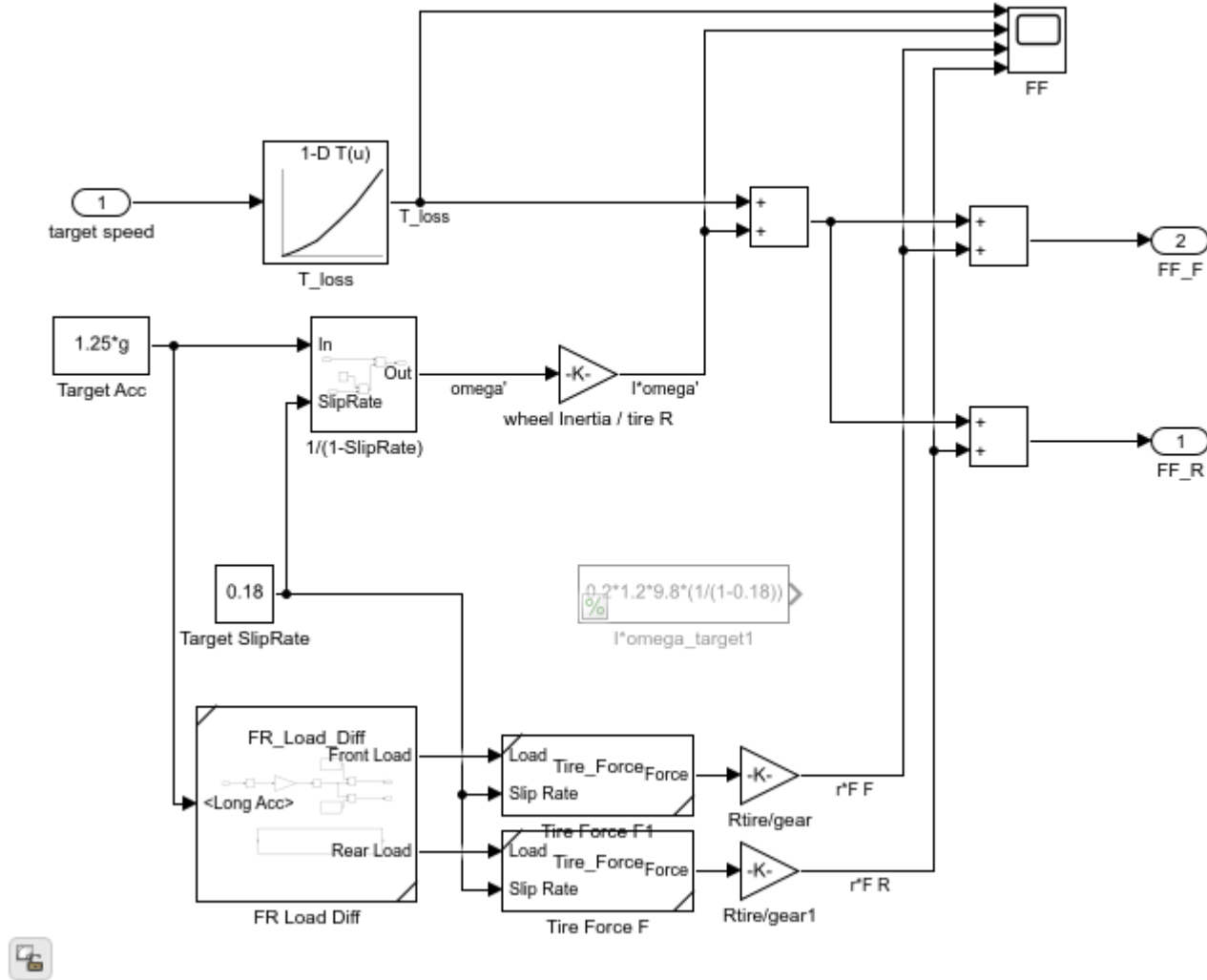
Tsuyoshi SOGA

2023/07/28

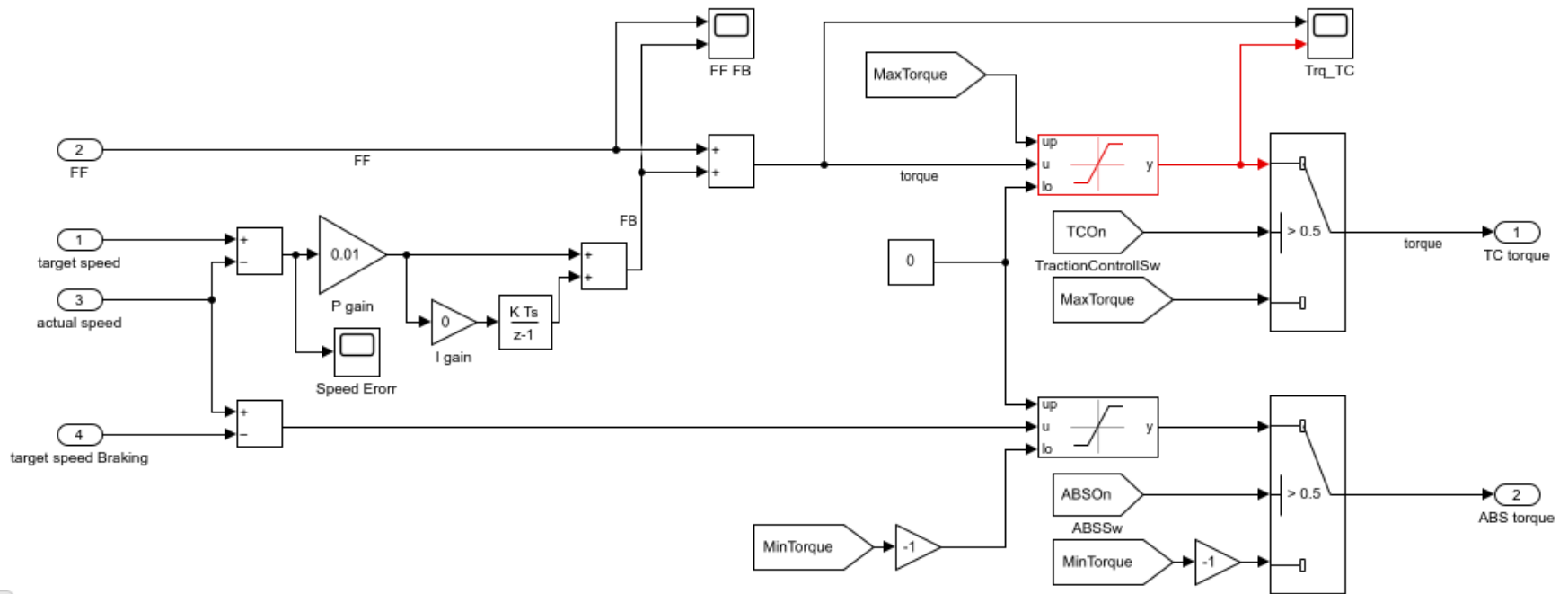
TargetSpeed_inAcc



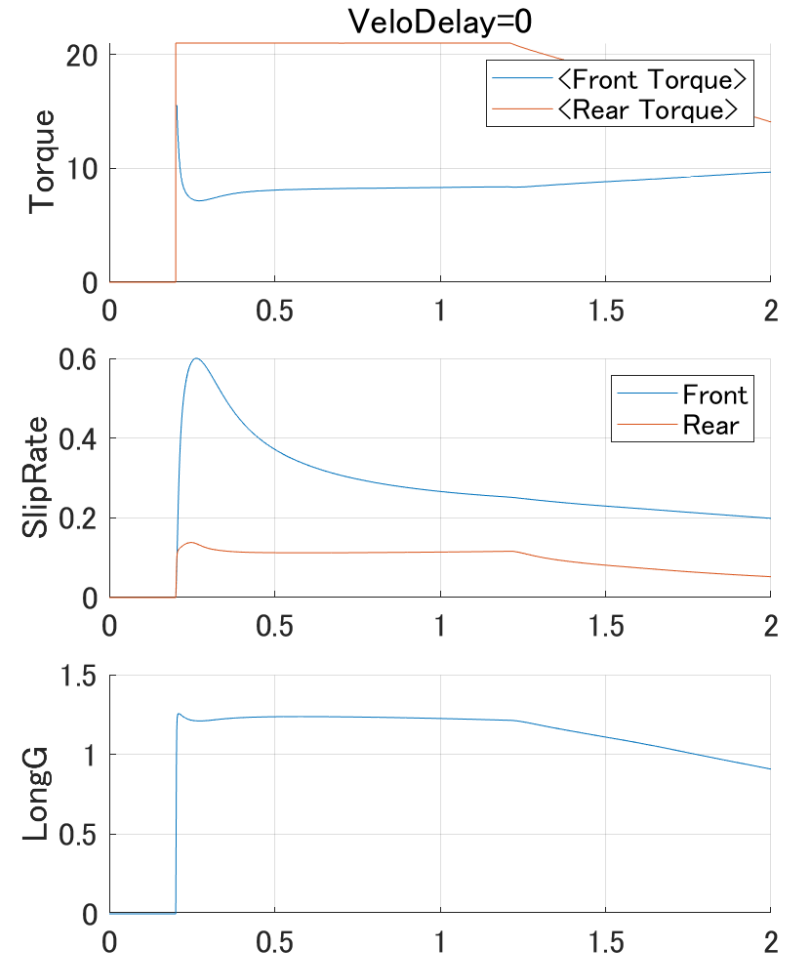
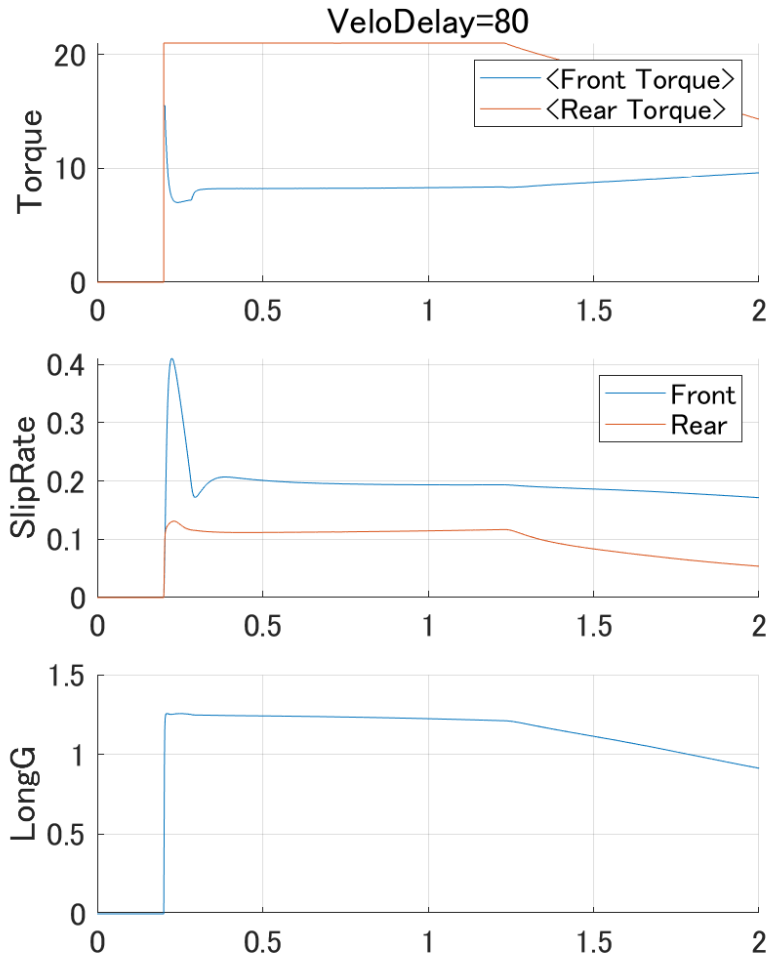
FeedForward



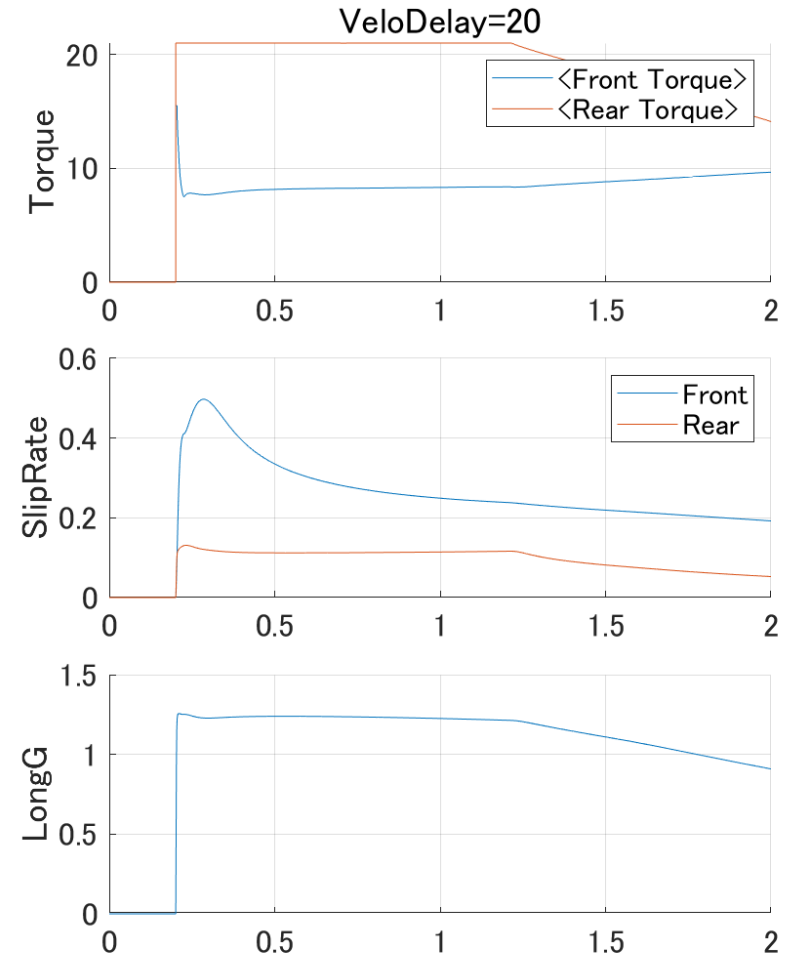
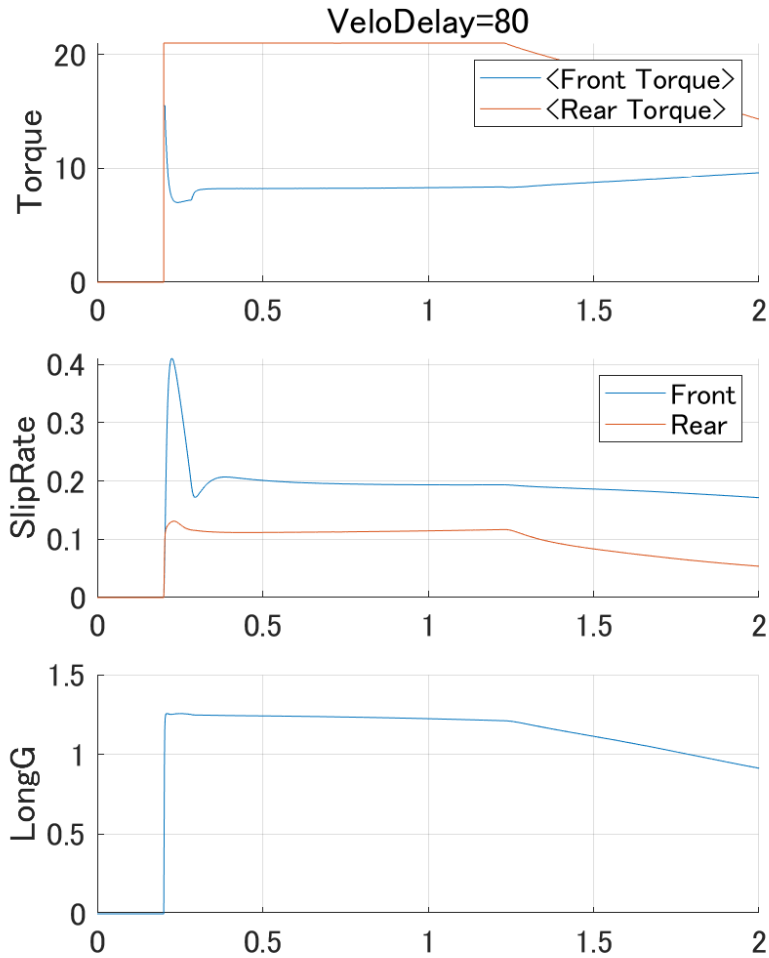
TractionControl



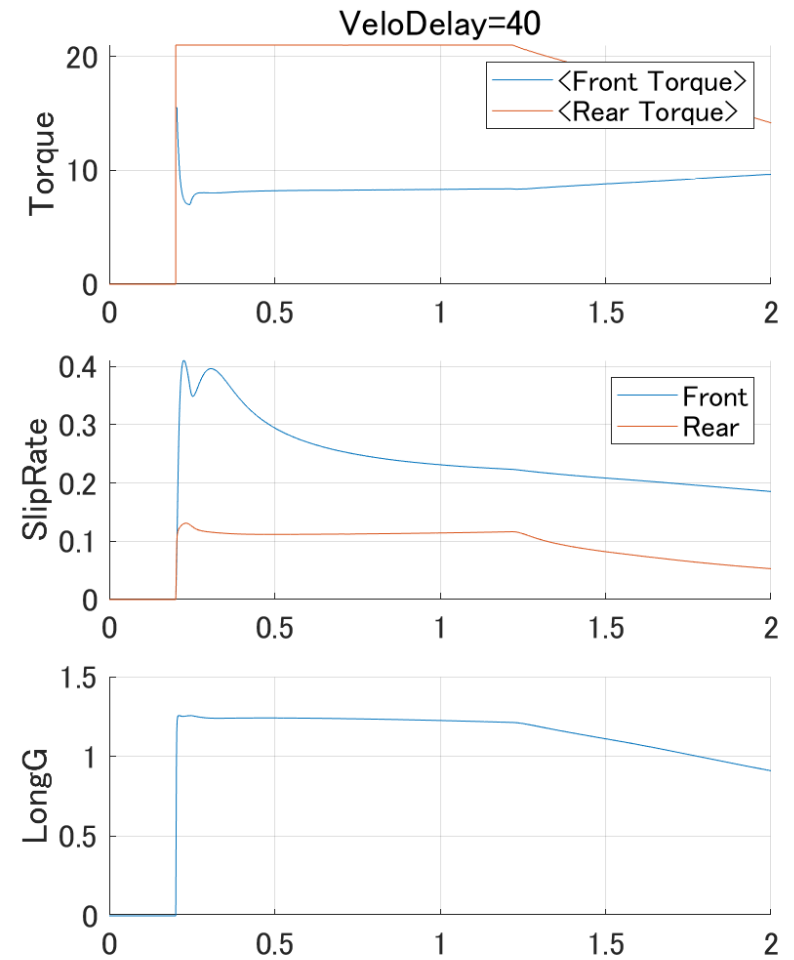
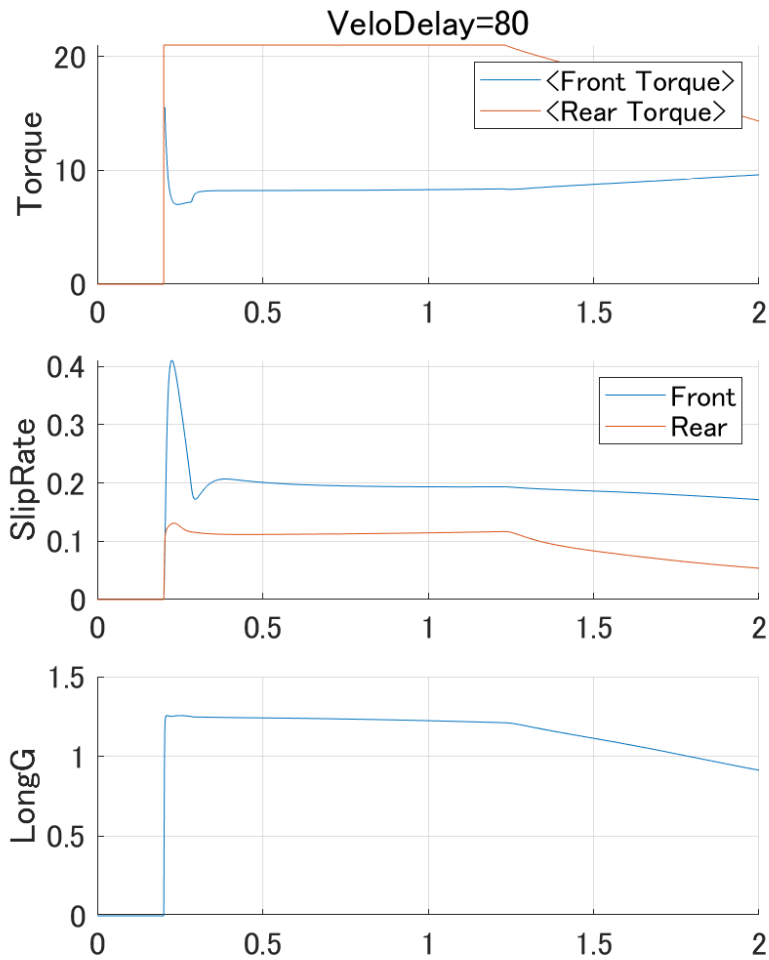
VeloDelay=0



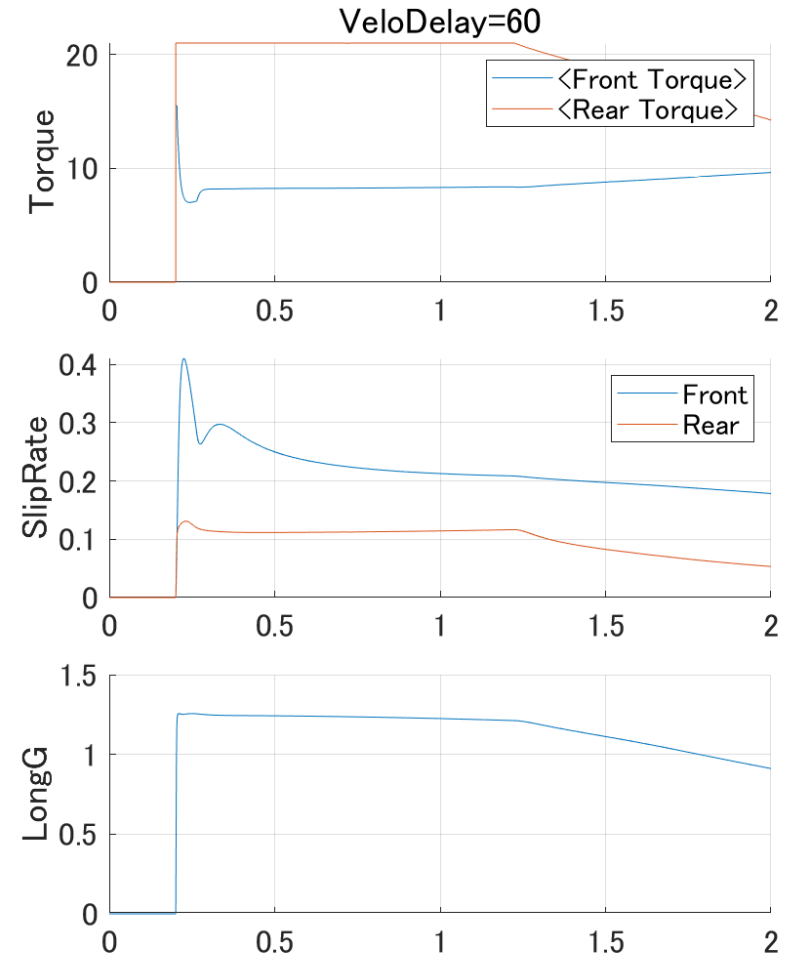
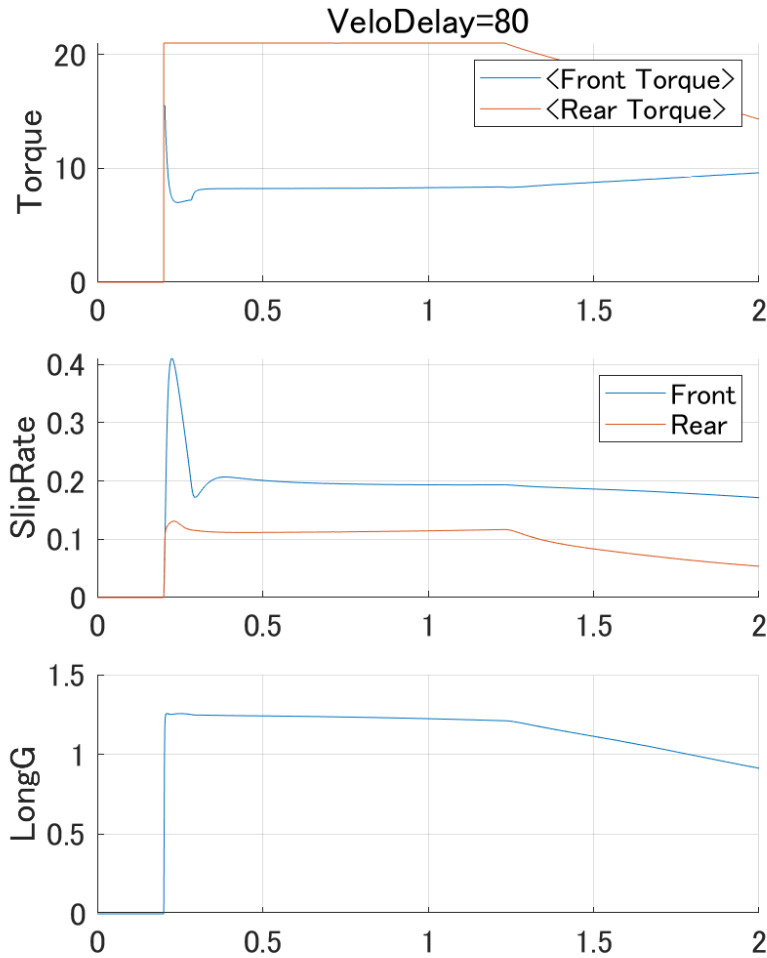
VeloDelay=20



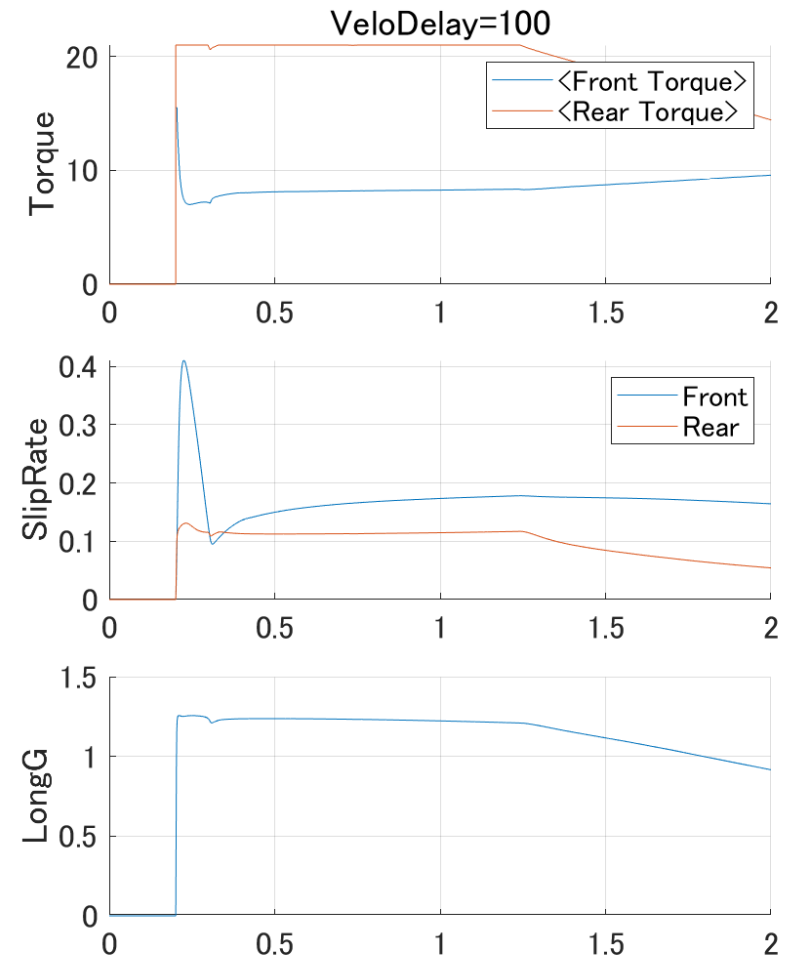
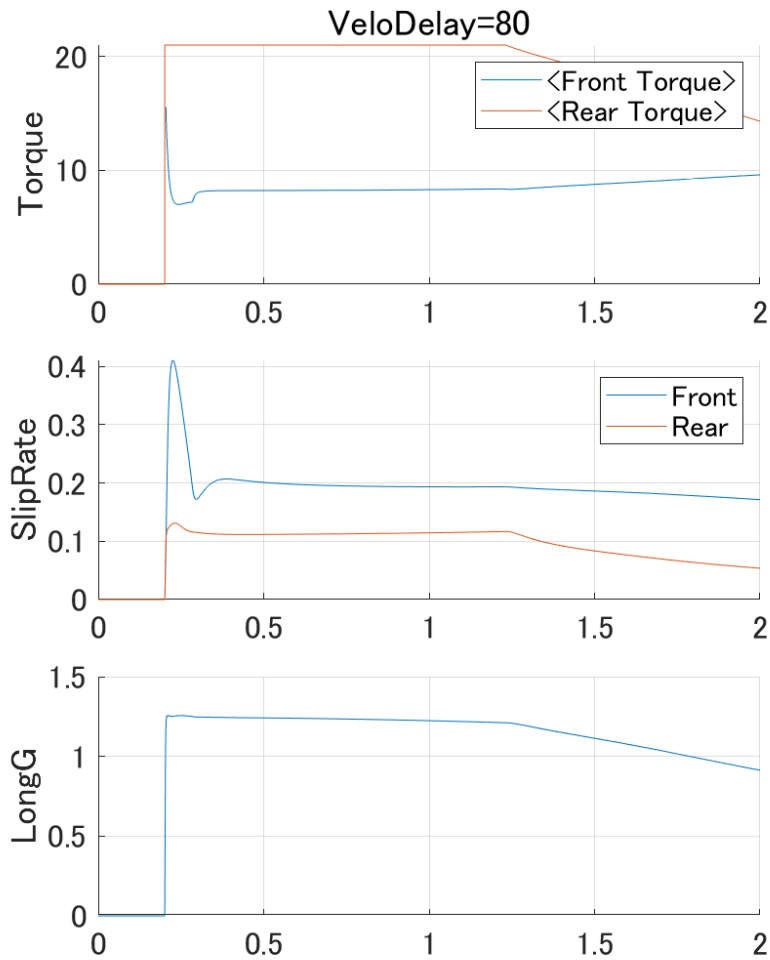
VeloDelay=40



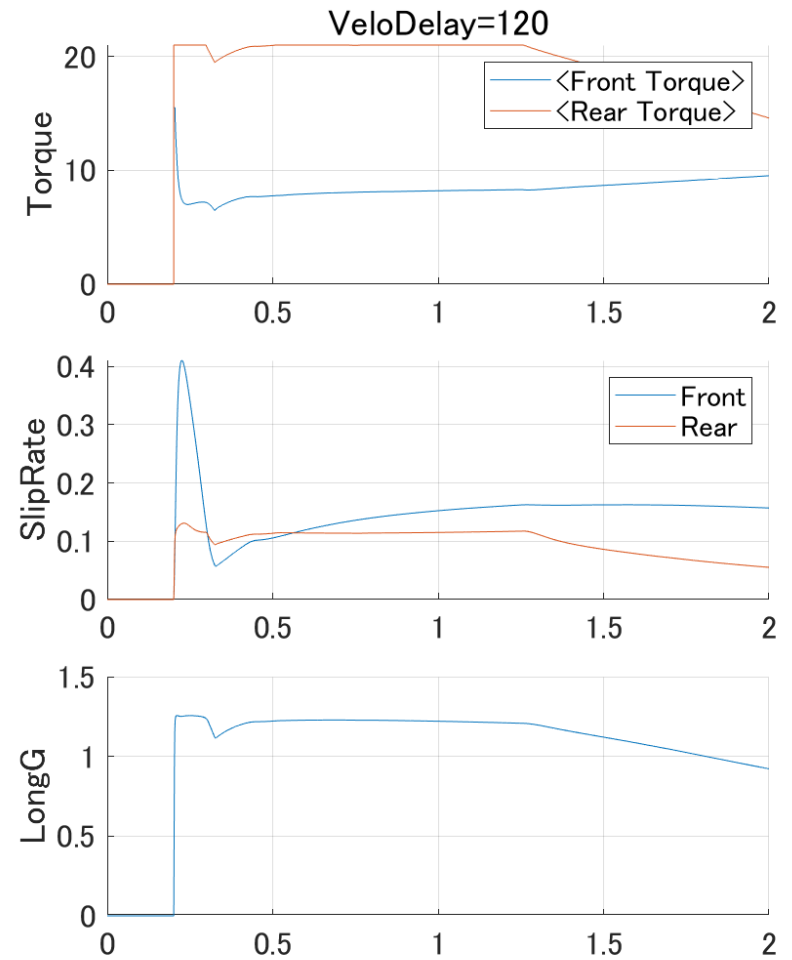
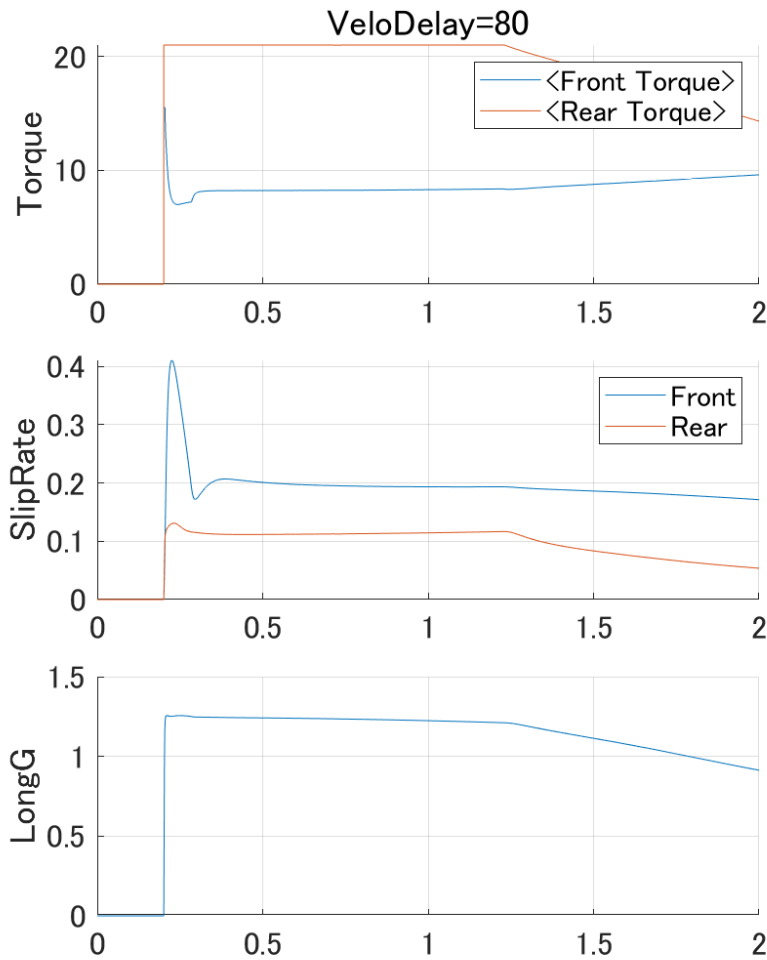
VeloDelay=60



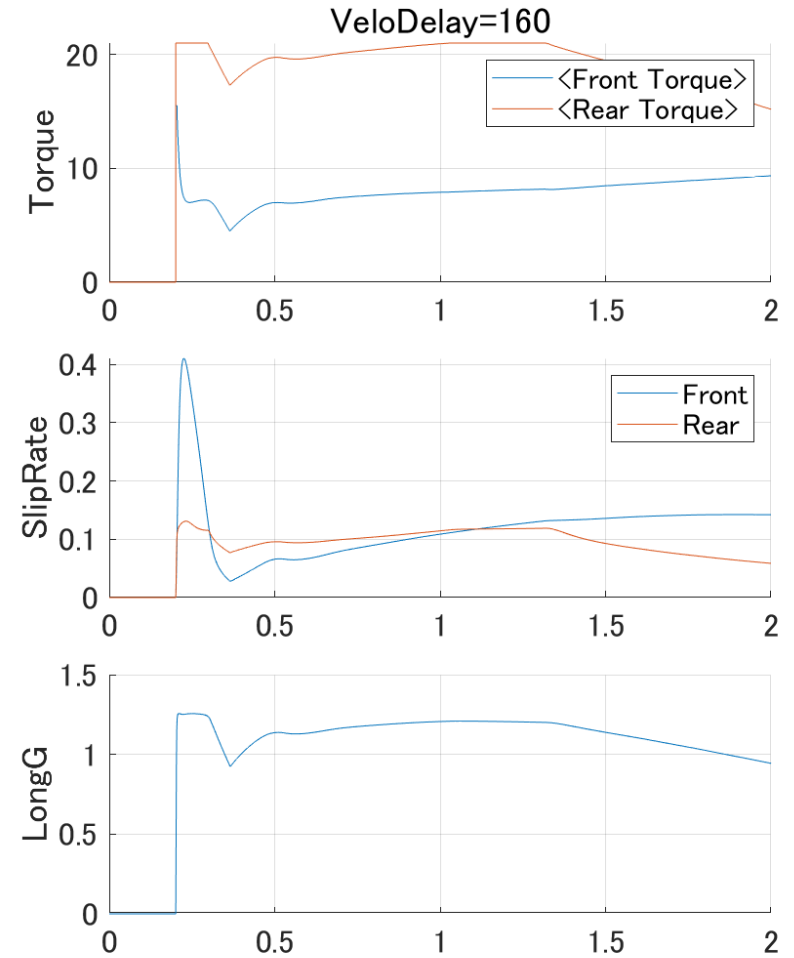
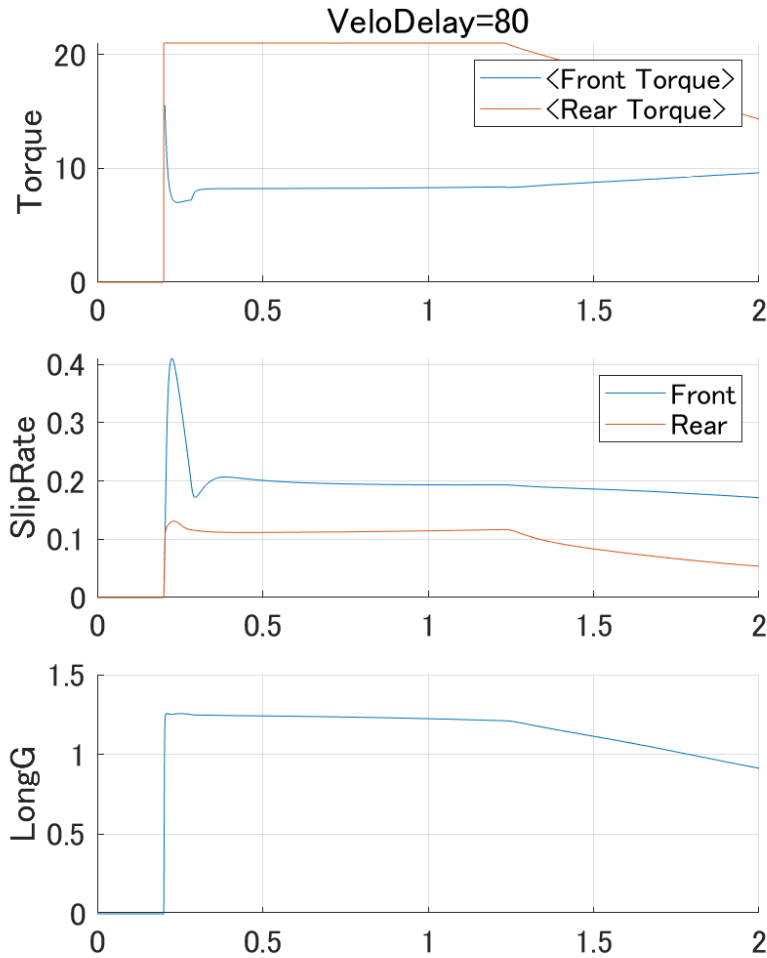
VeloDelay=100



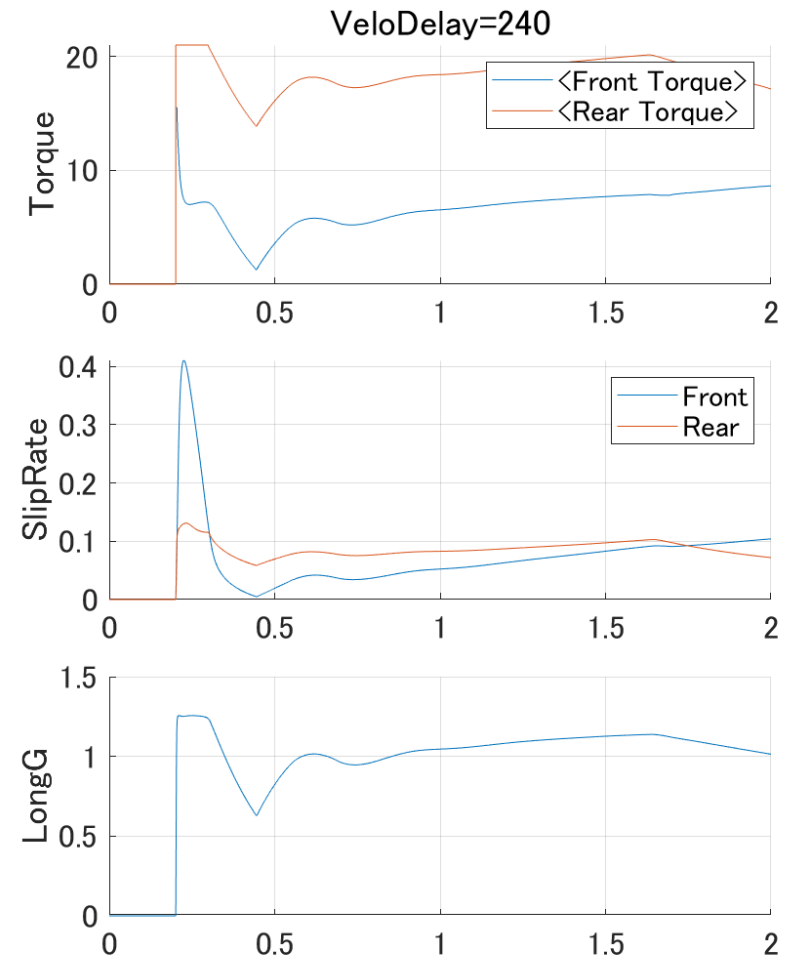
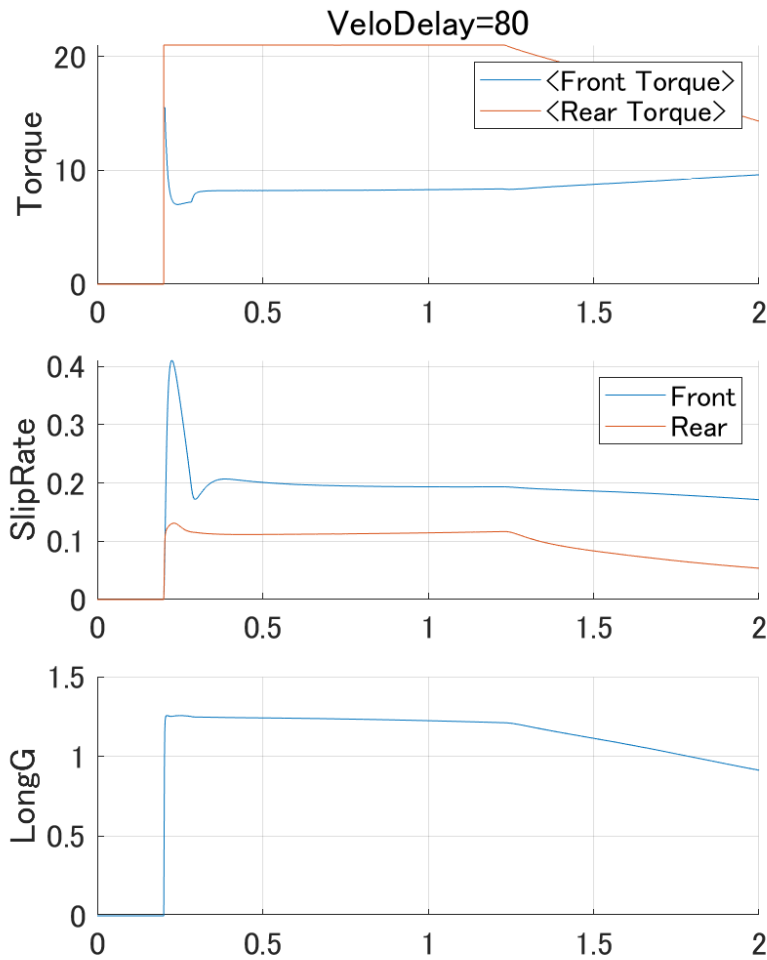
VeloDelay=120



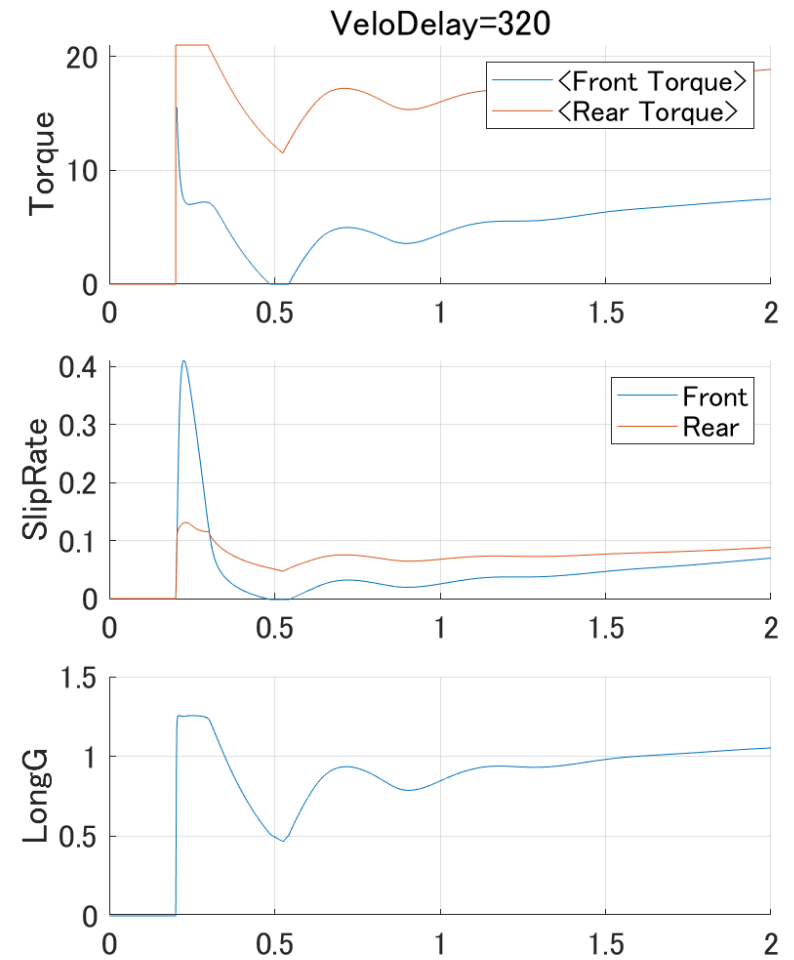
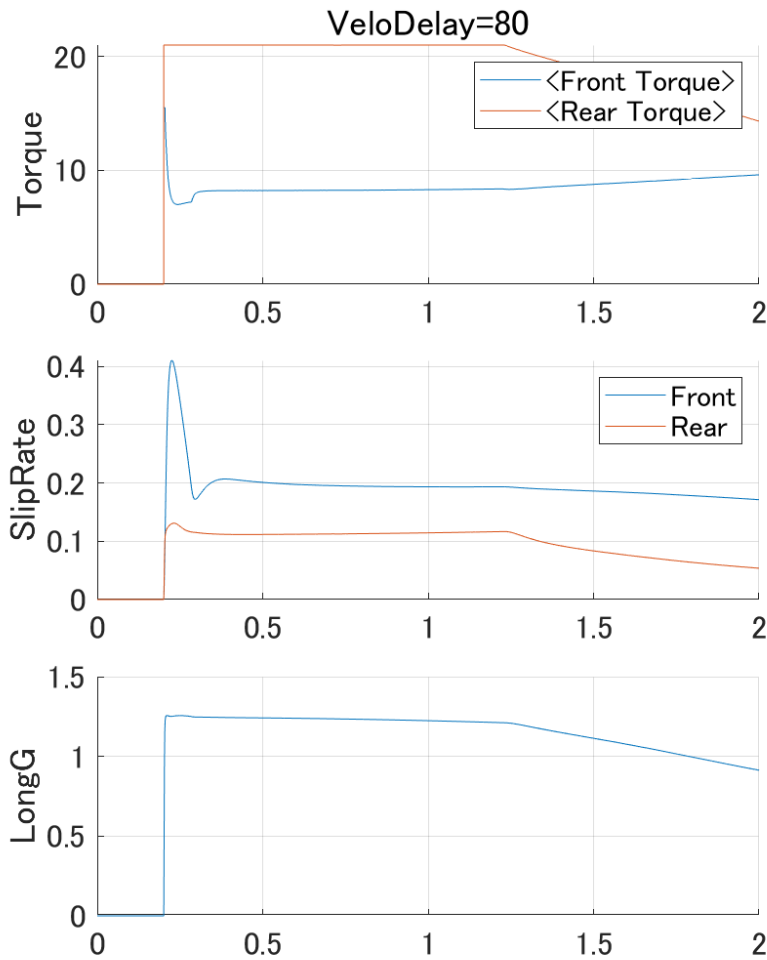
VeloDelay=160



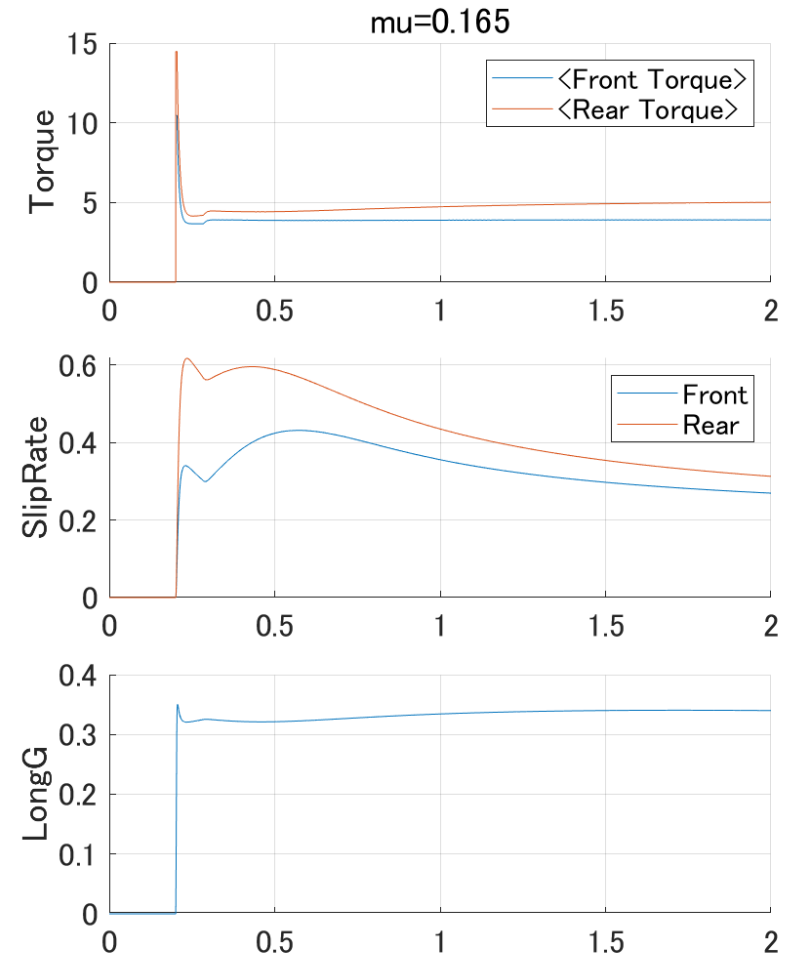
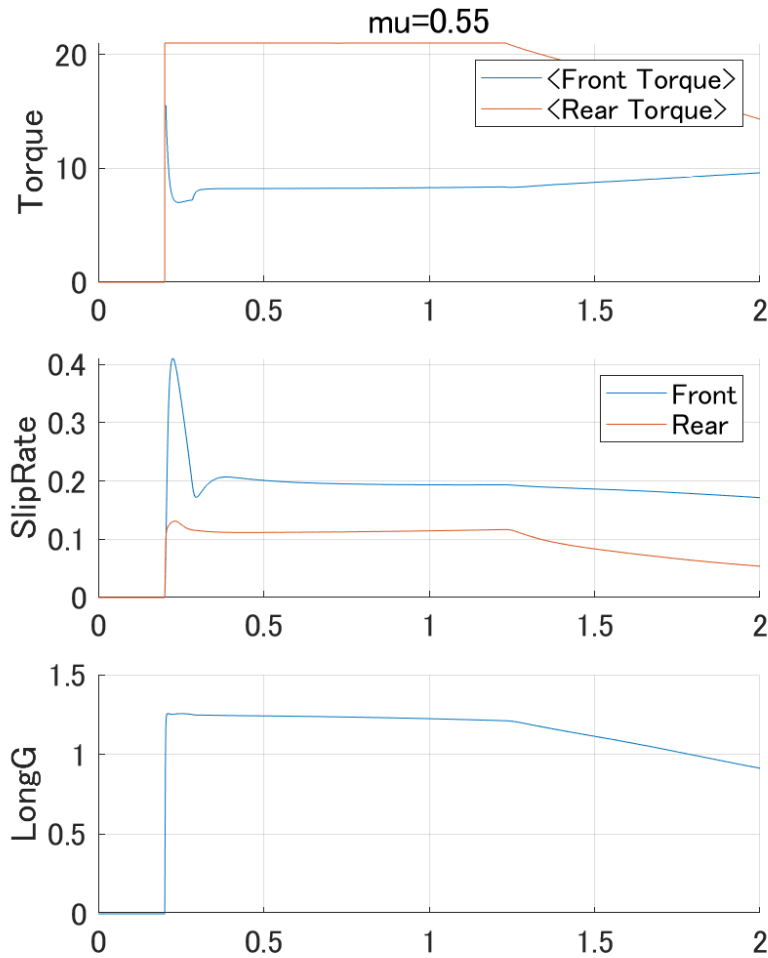
VeloDelay=240



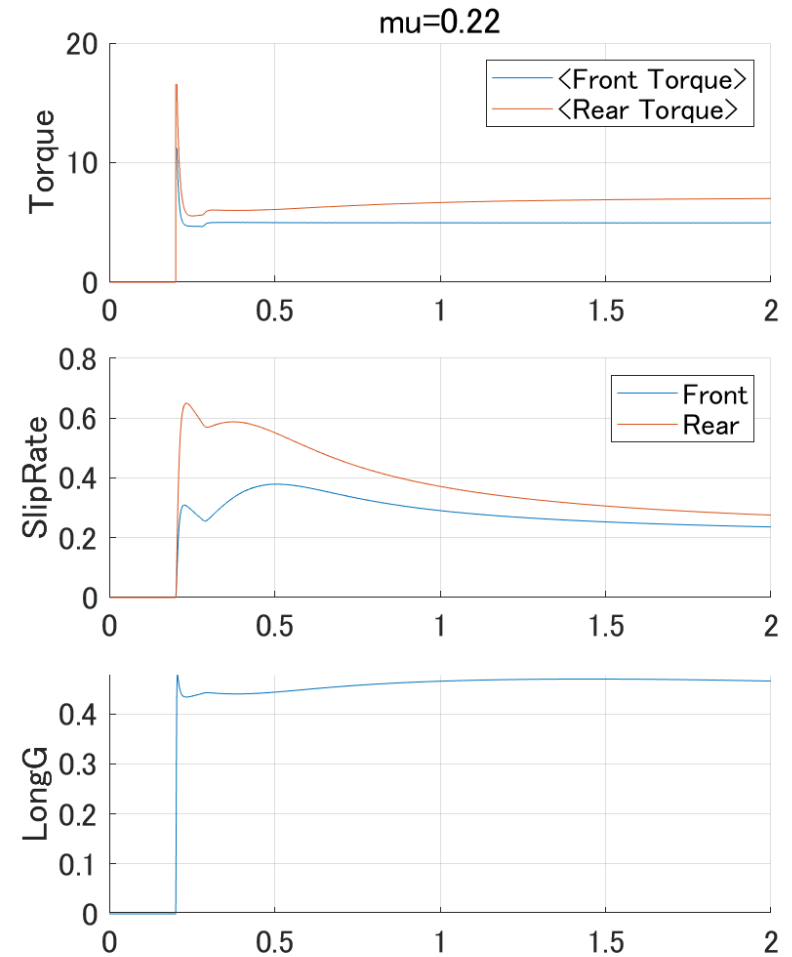
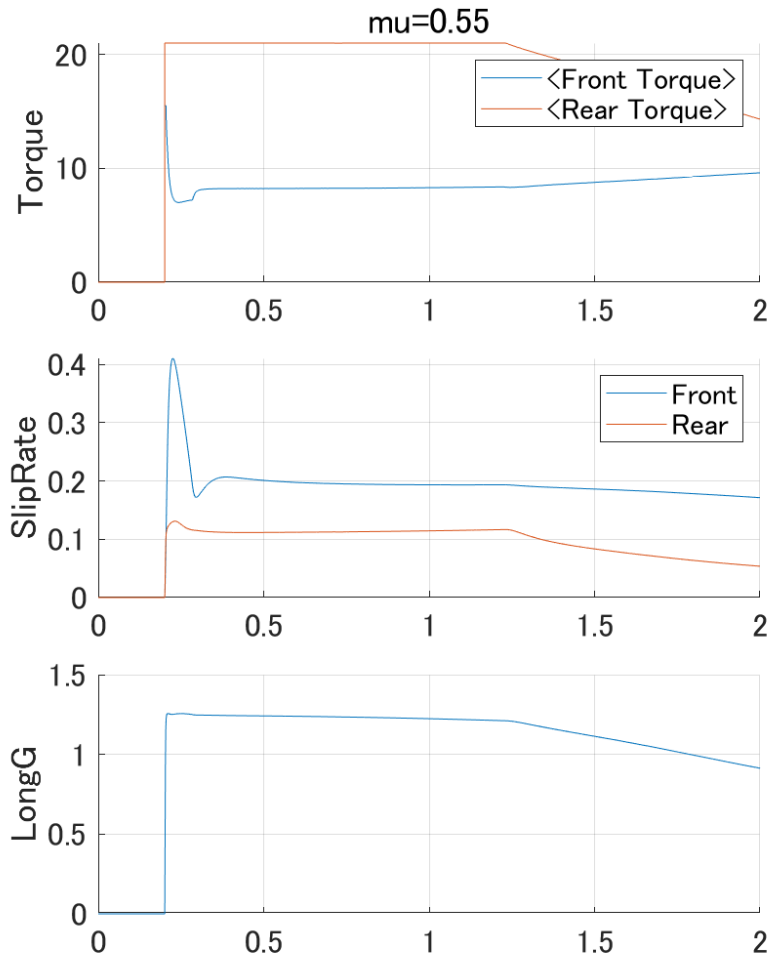
VeloDelay=320



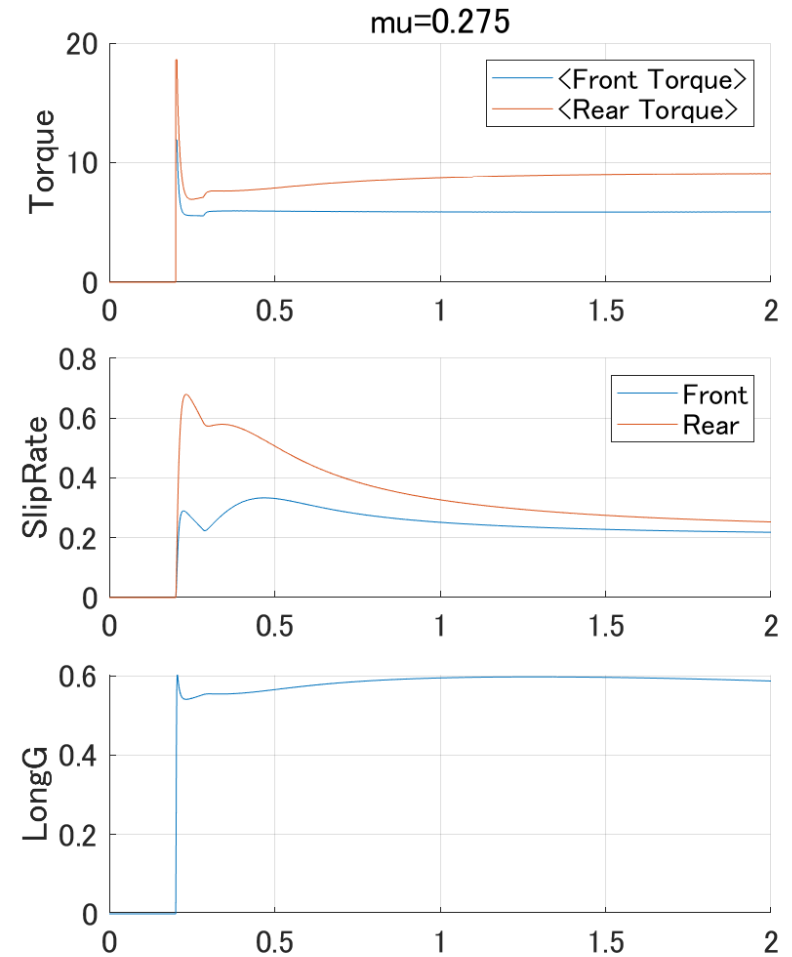
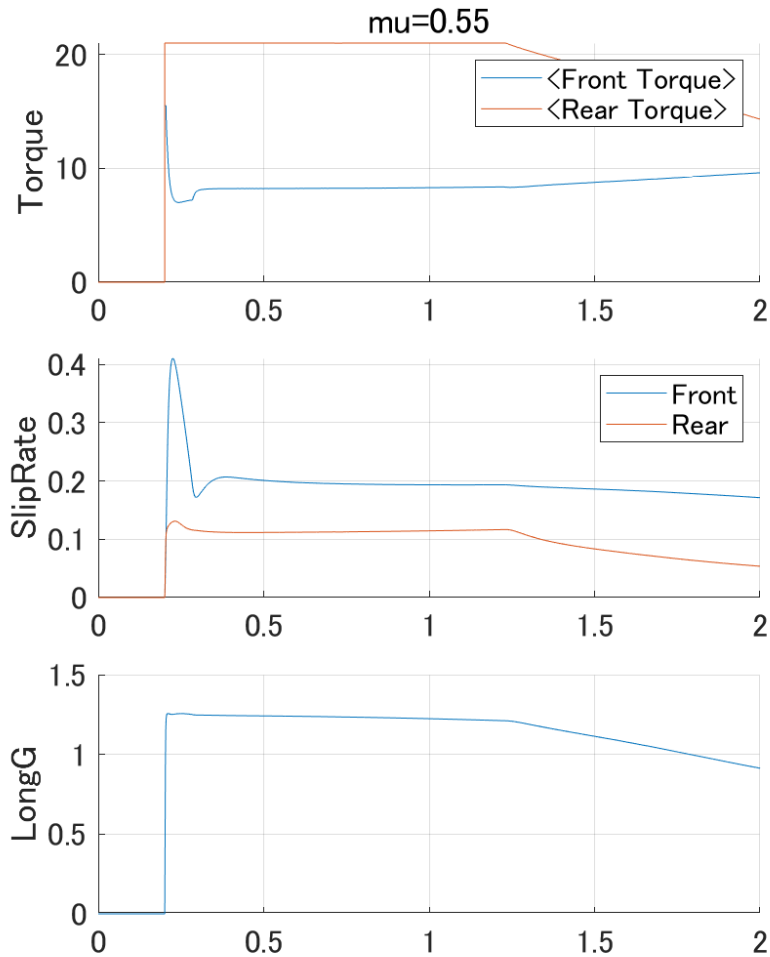
mu difference x0.3



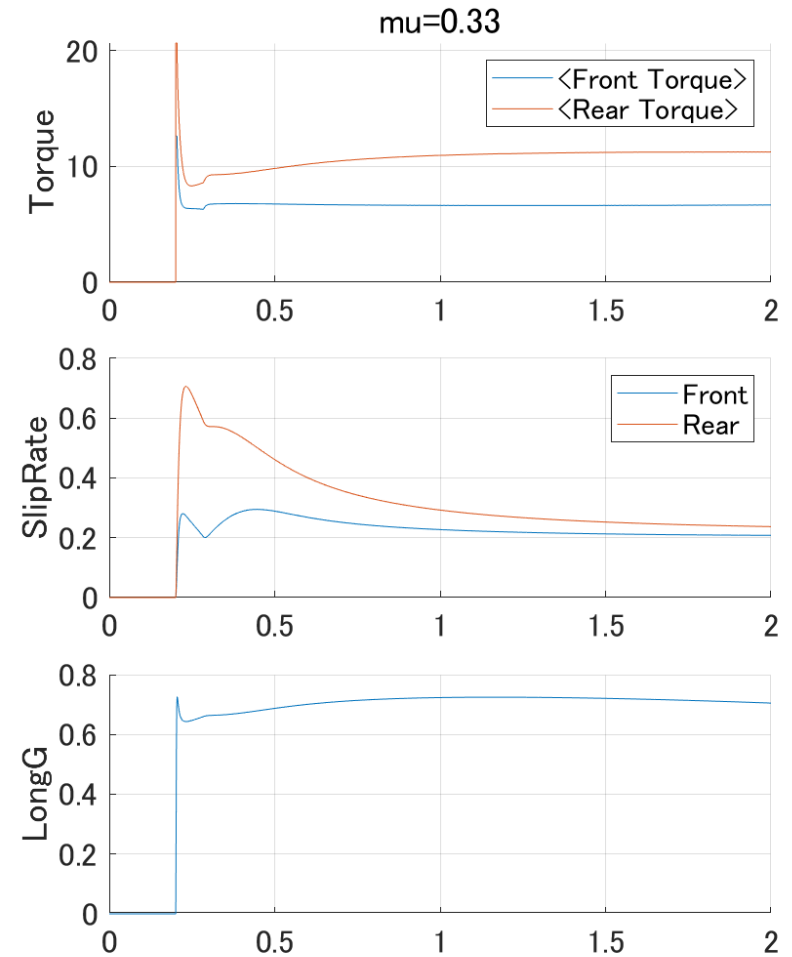
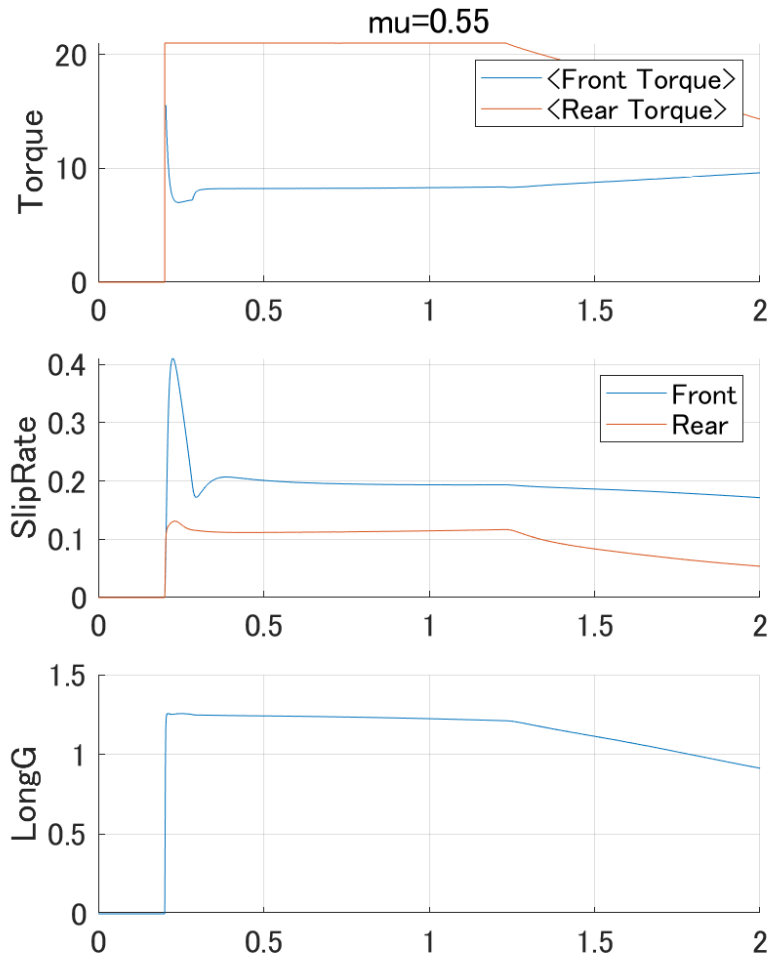
mu difference x0.4



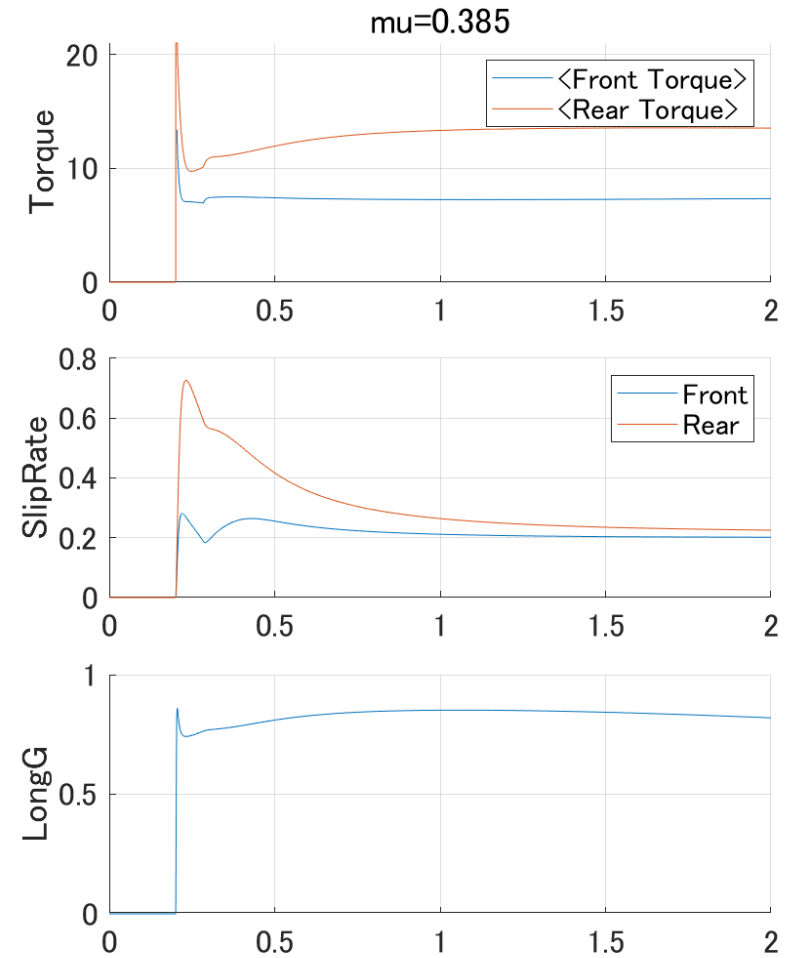
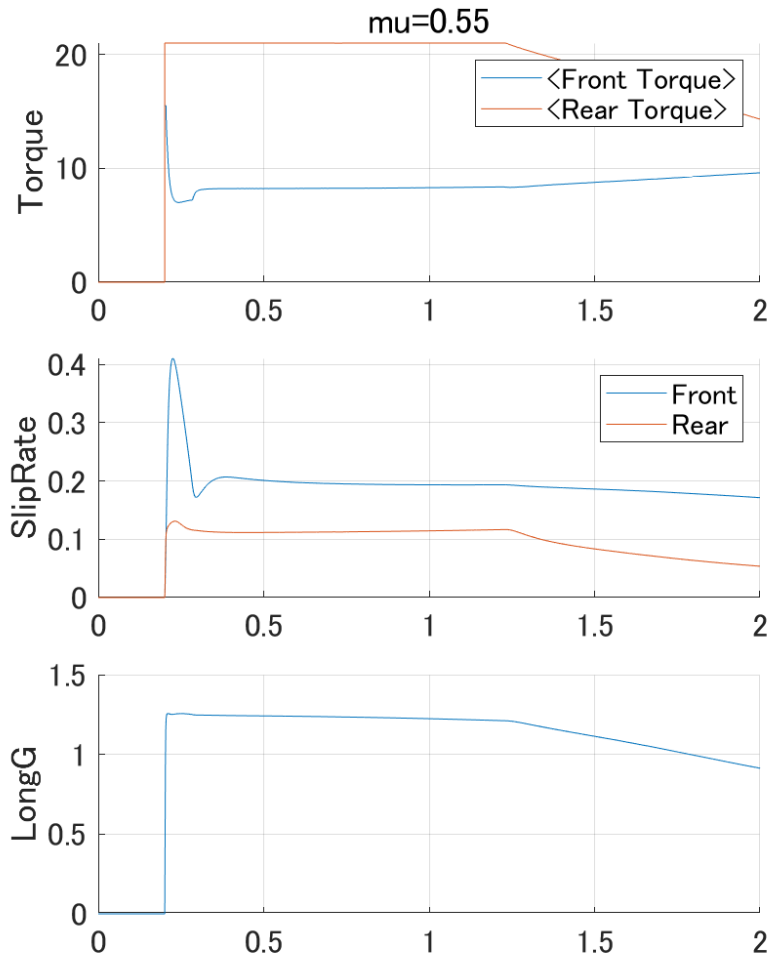
mu difference x0.5



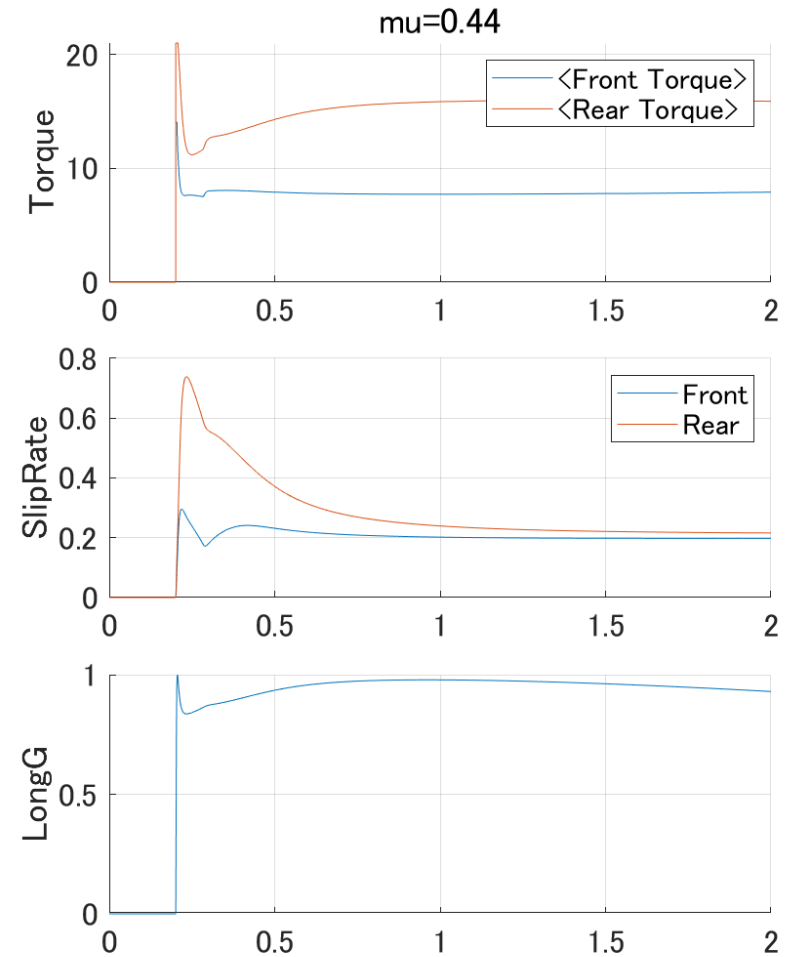
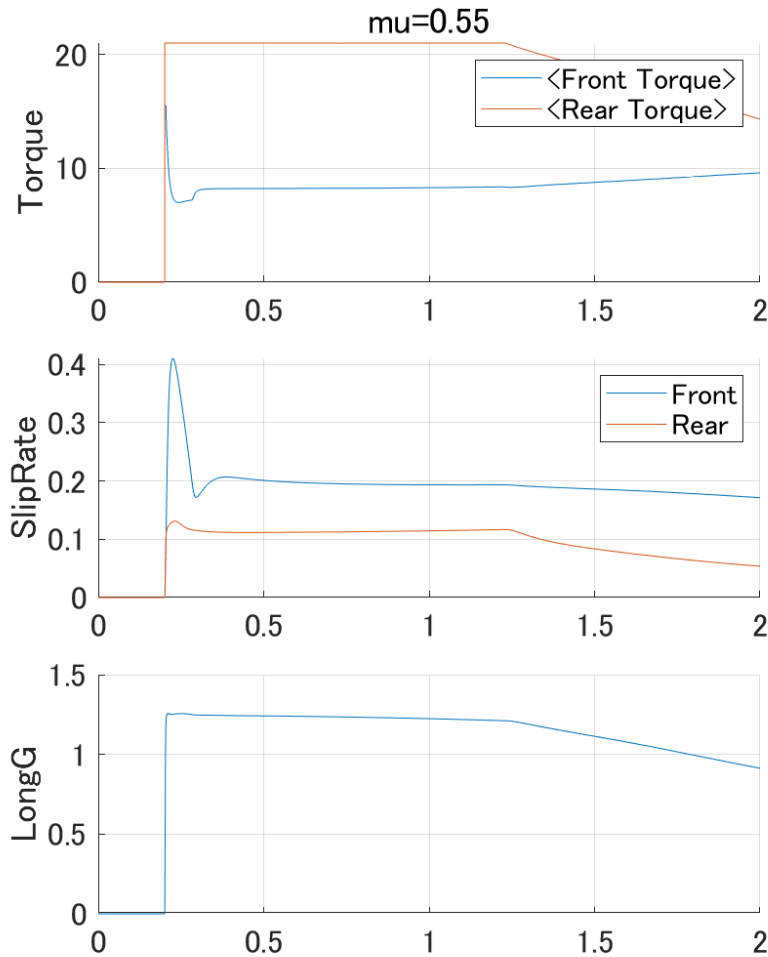
mu difference x0.6



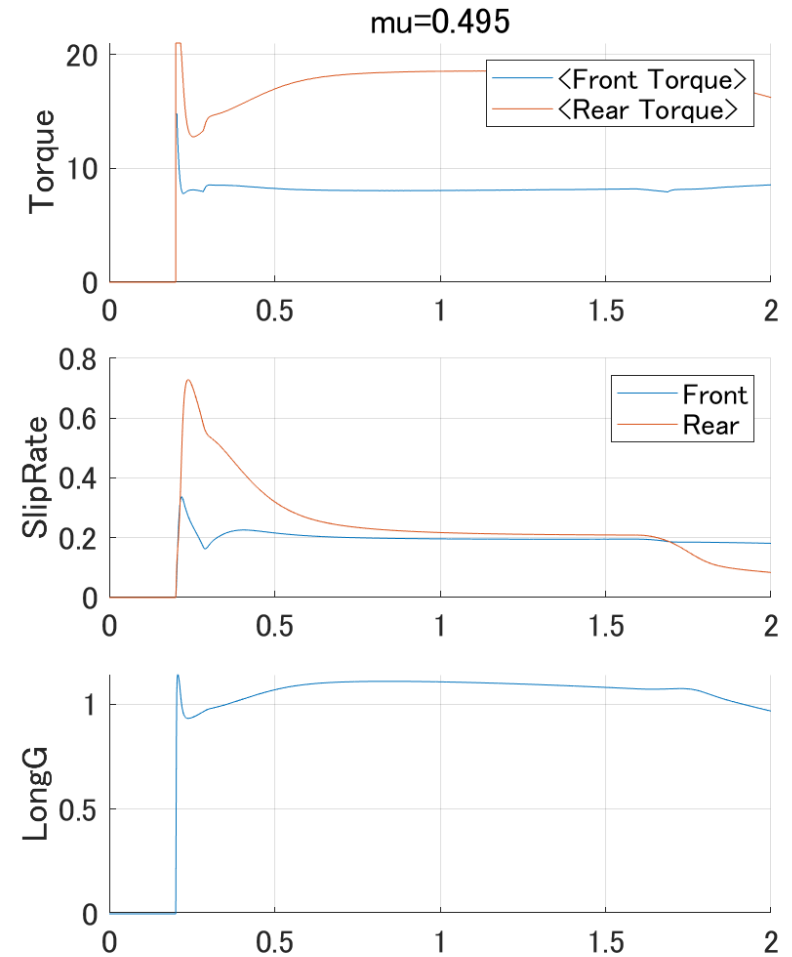
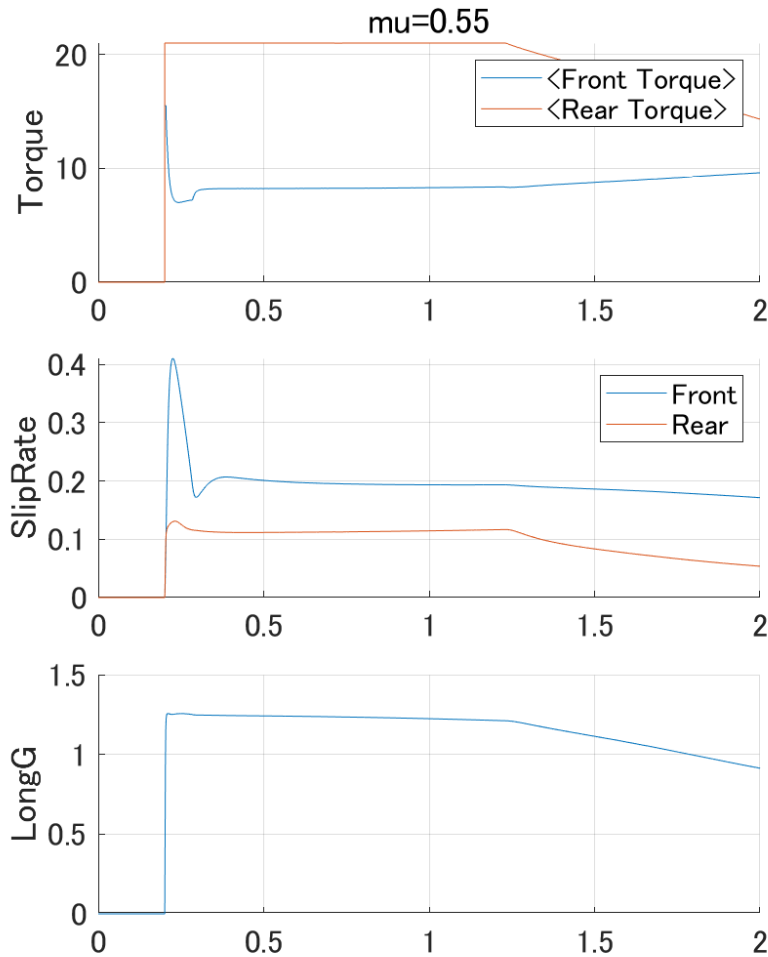
mu difference x0.7



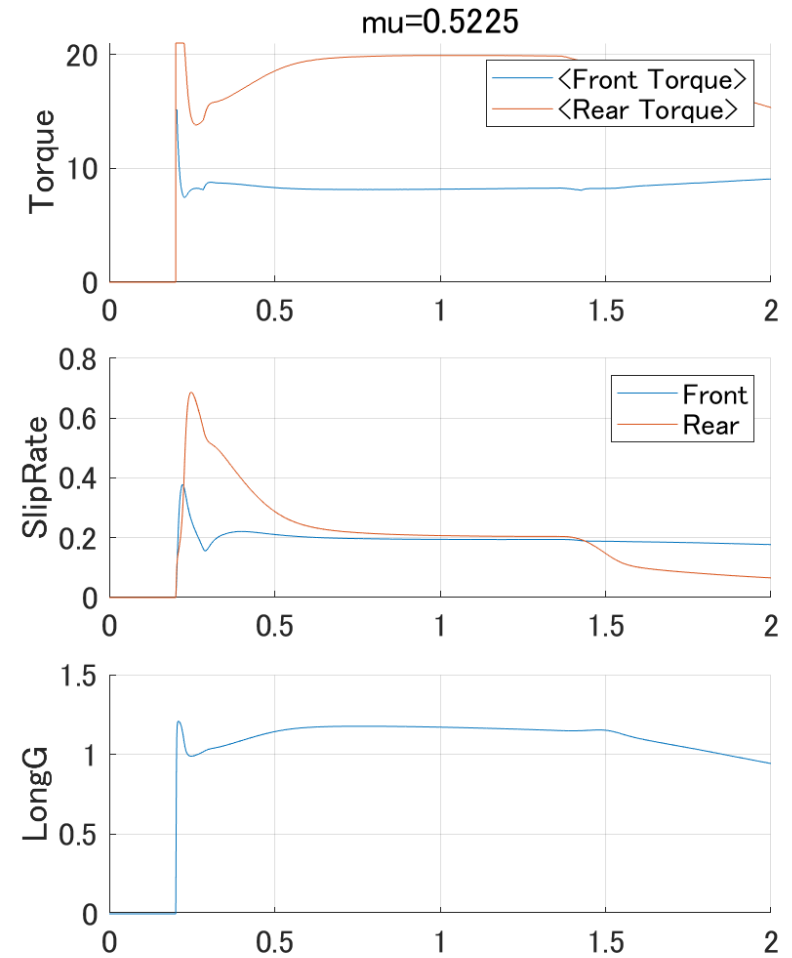
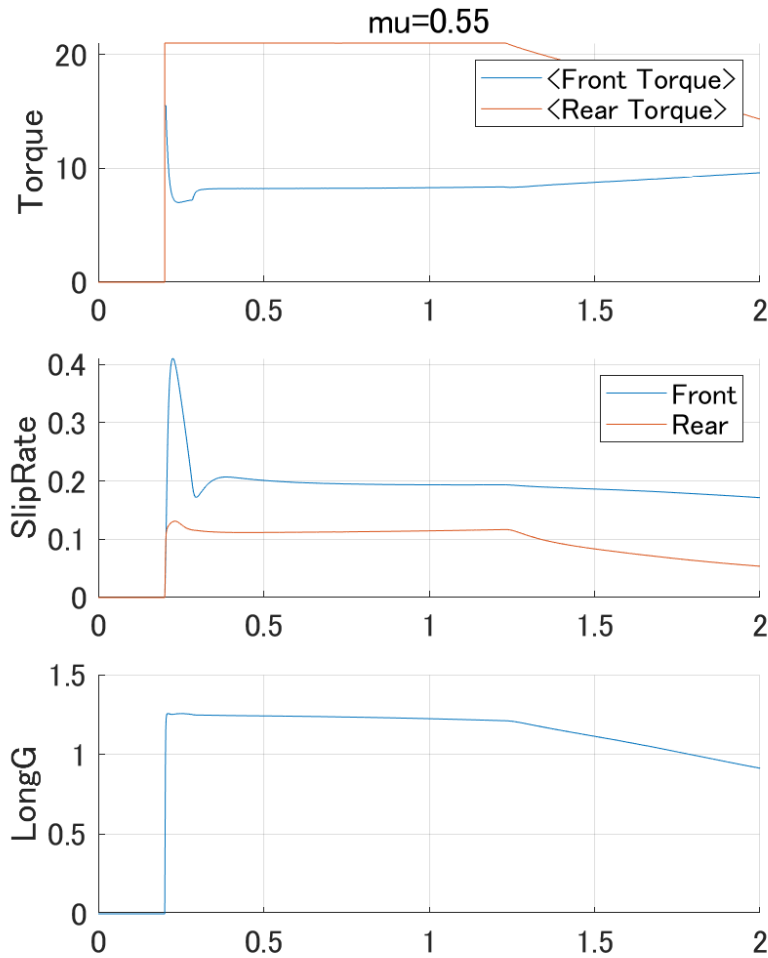
mu difference x0.8



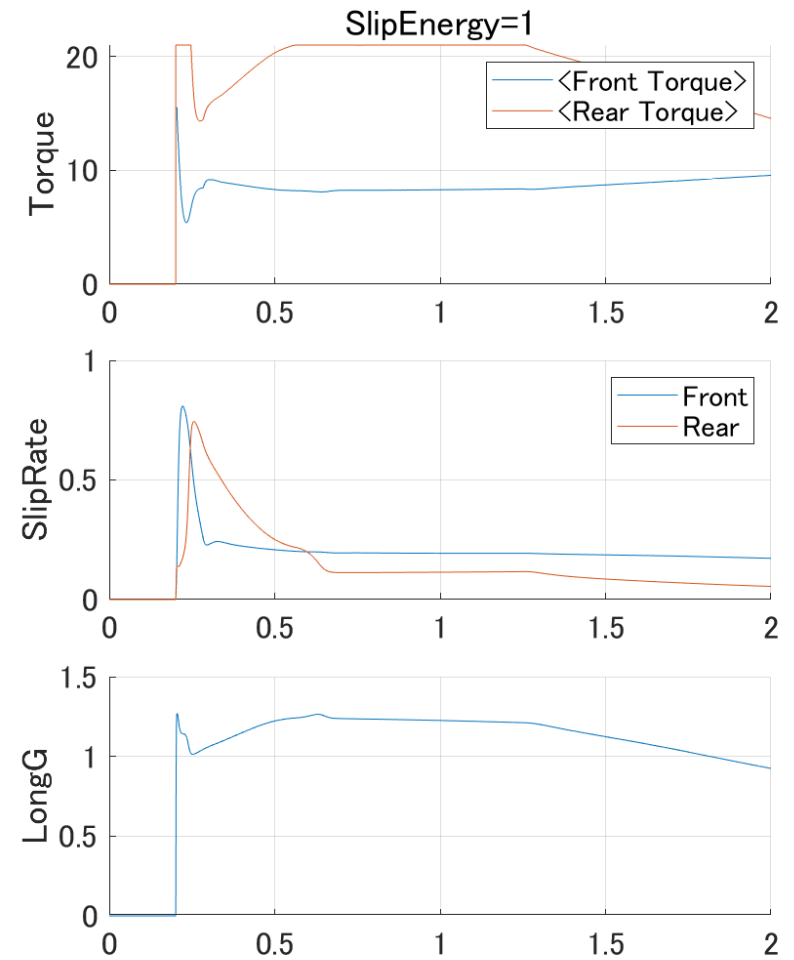
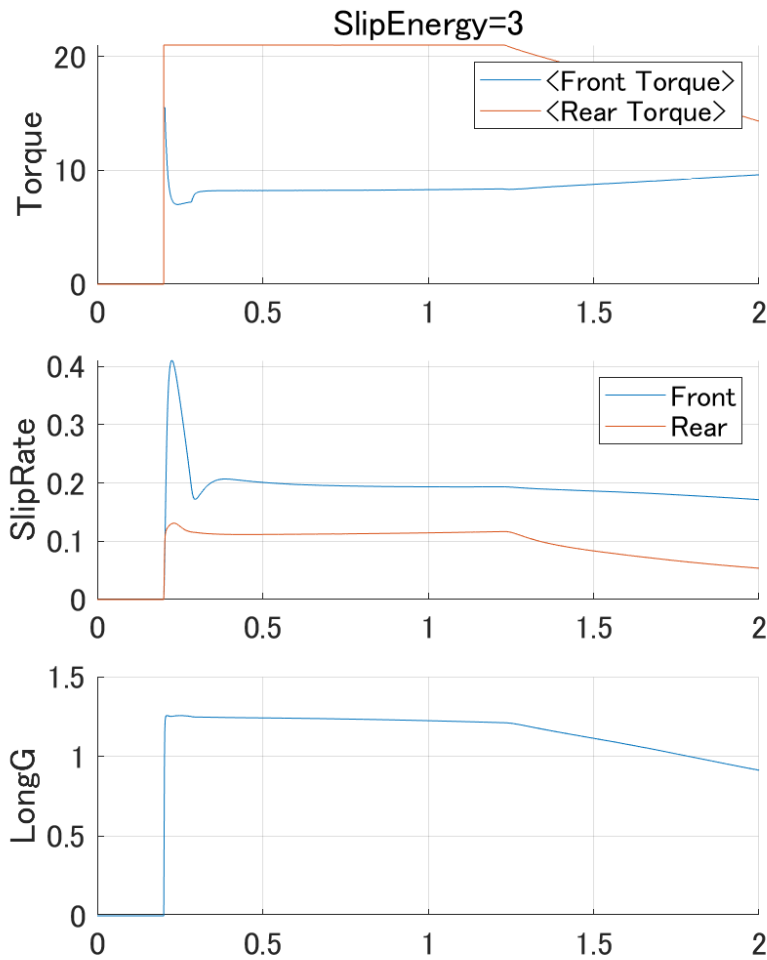
mu difference x0.9



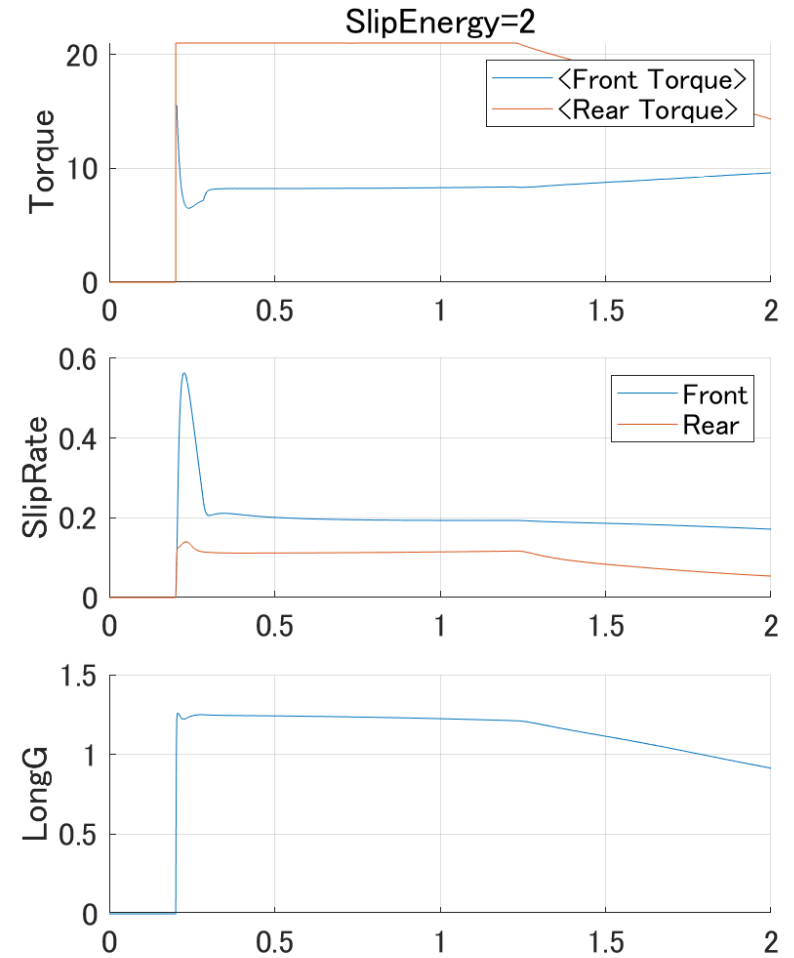
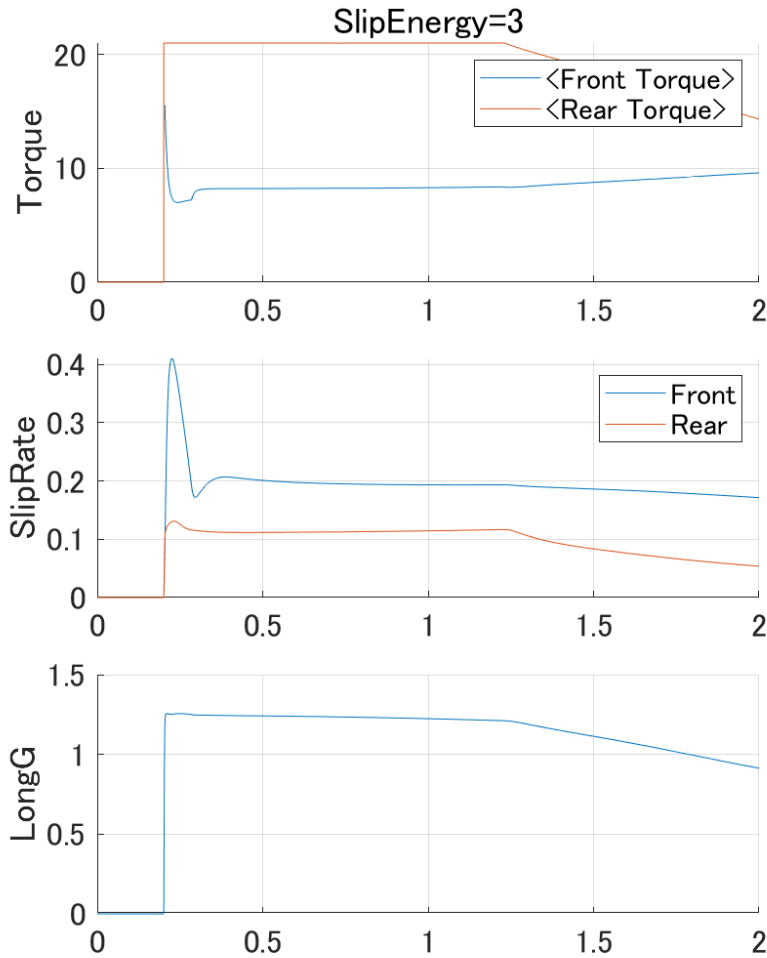
mu difference x0.95



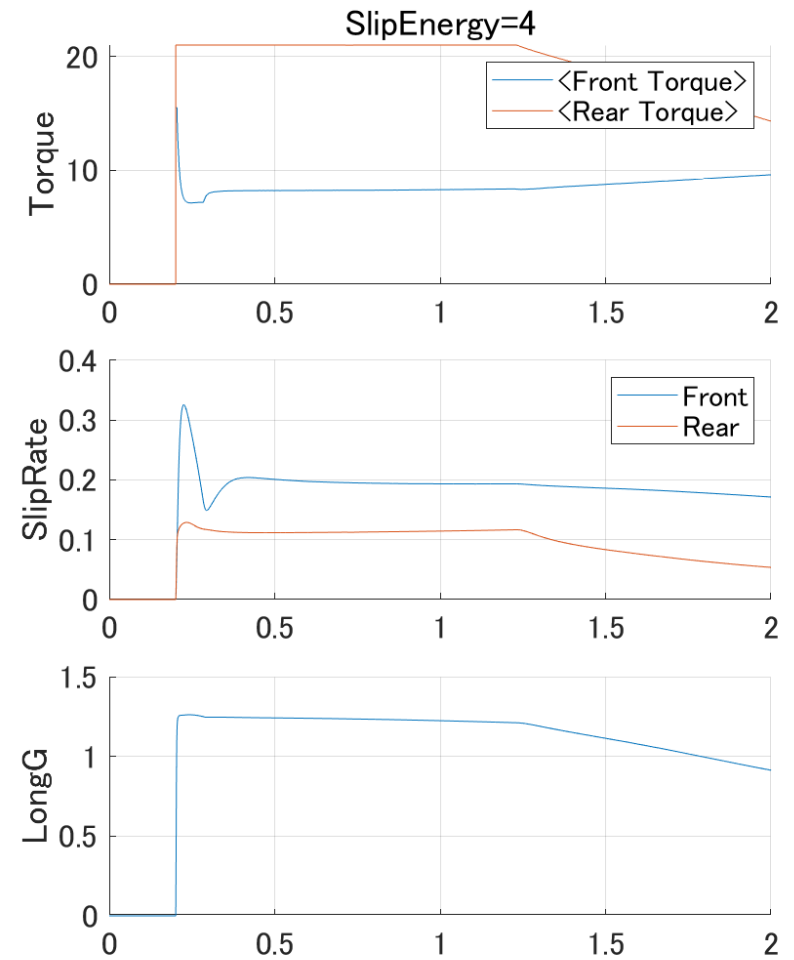
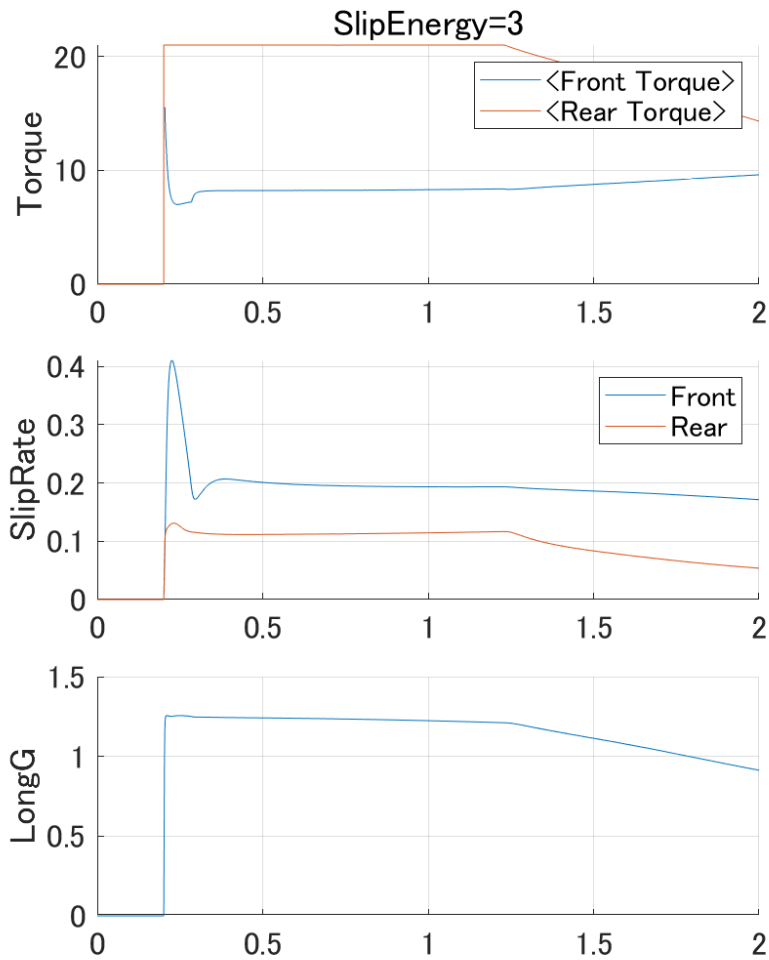
SlipEnergy difference



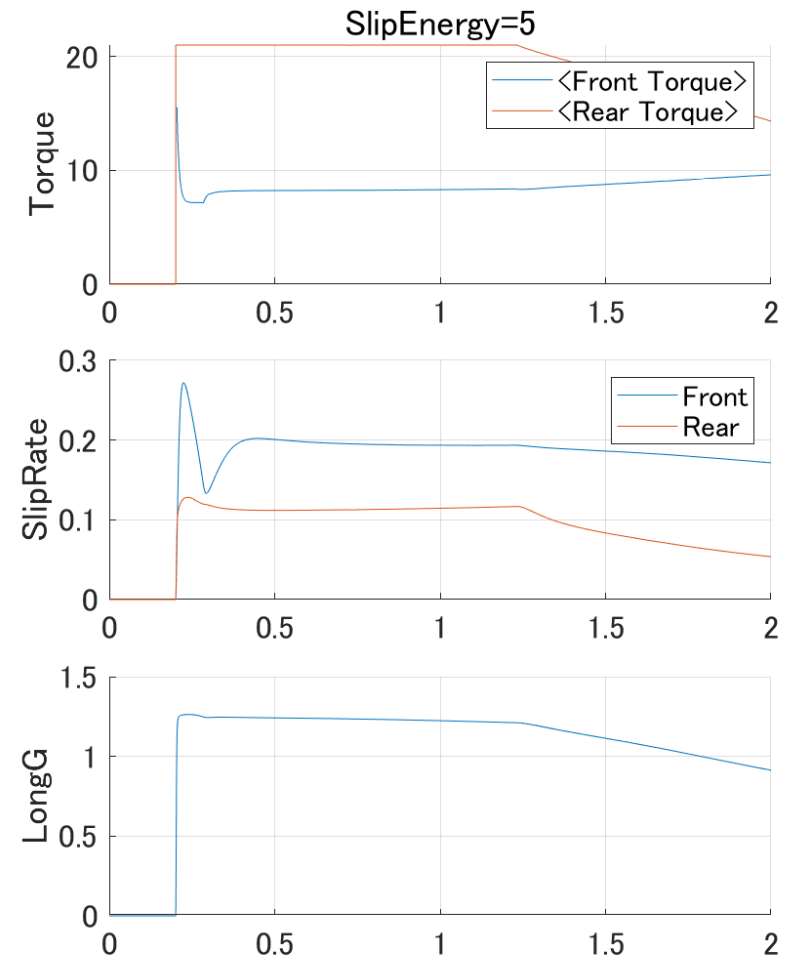
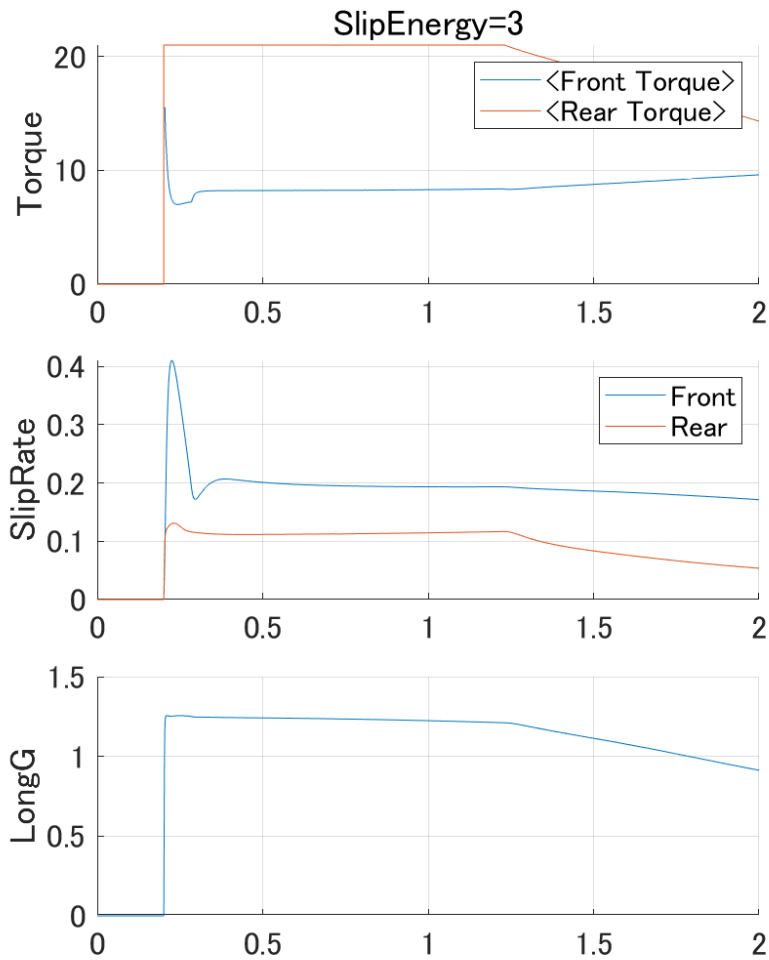
SlipEnergy difference



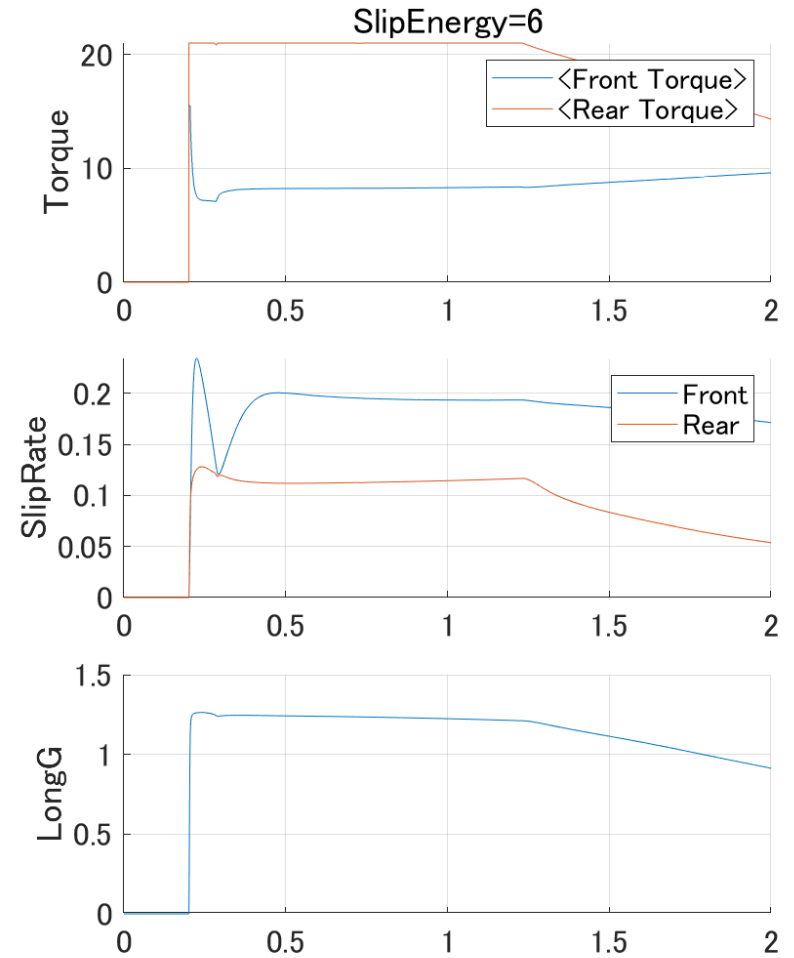
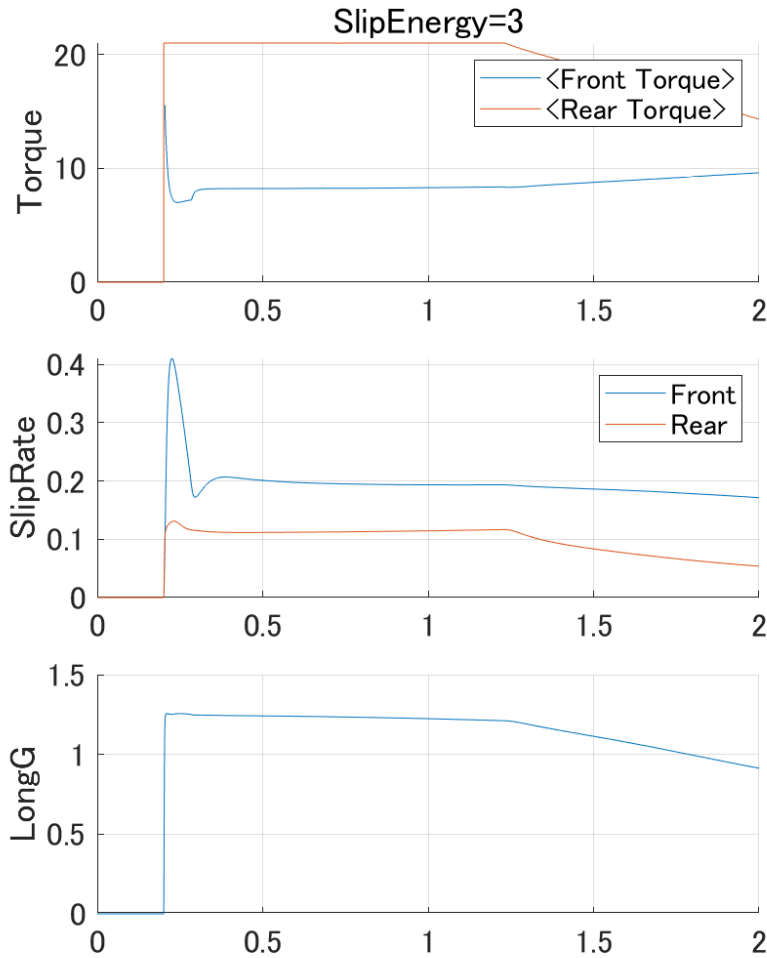
SlipEnergy difference



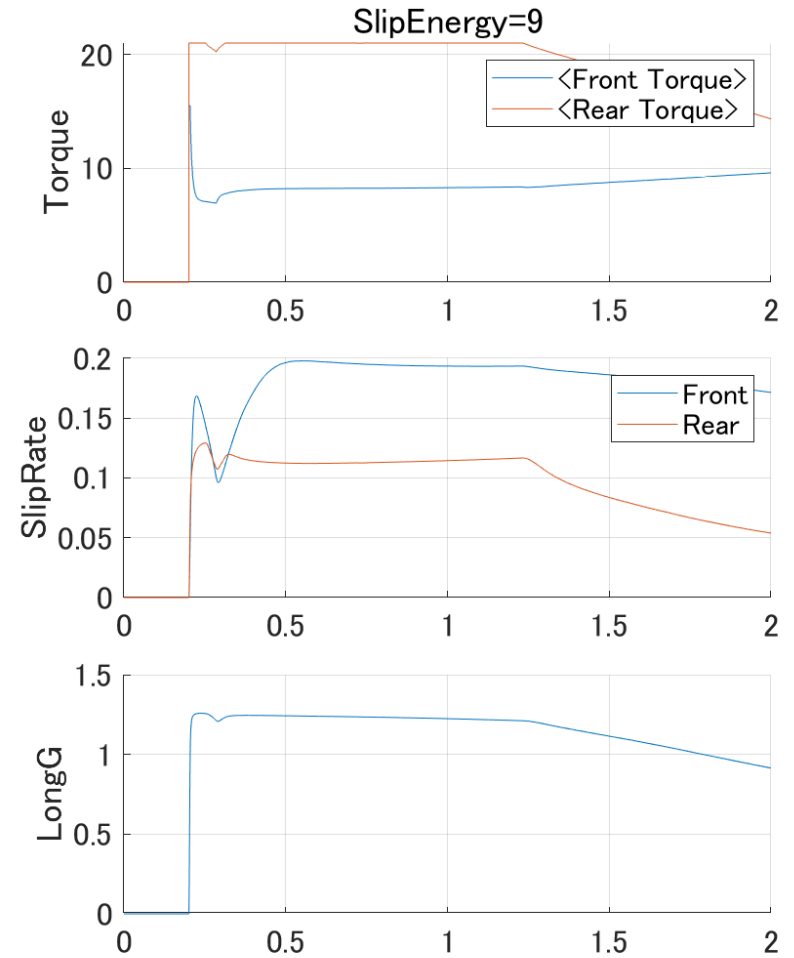
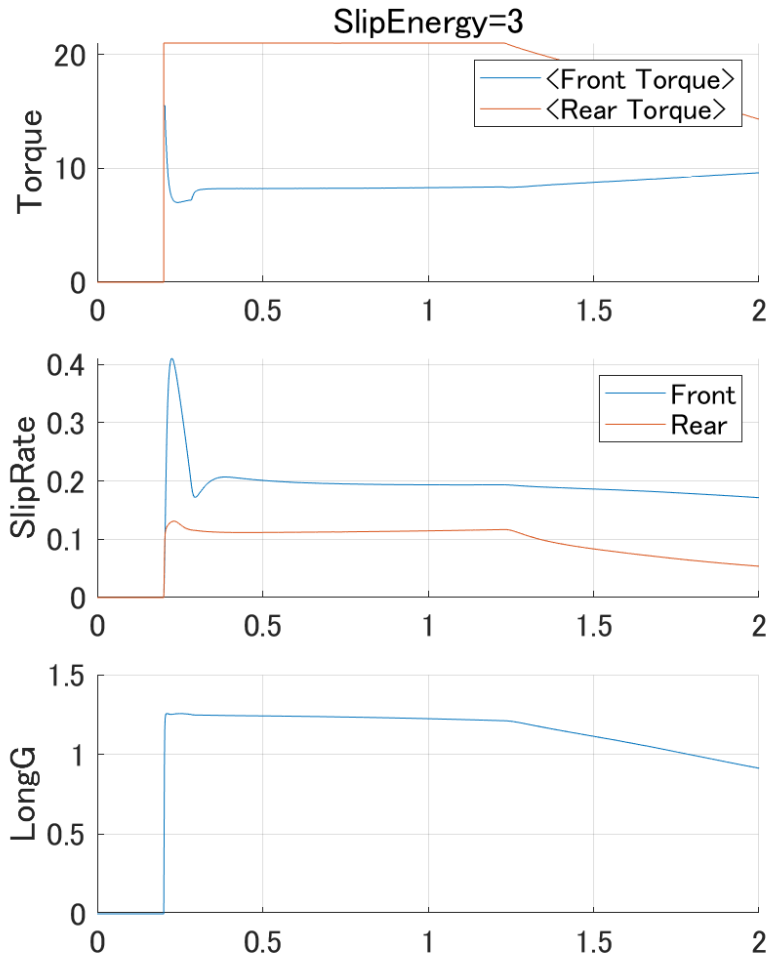
SlipEnergy difference



SlipEnergy difference



SlipEnergy difference



SlipEnergy difference

