$\mathcal{L}_{\lambda} = \begin{pmatrix} \chi_{i1} \\ \chi_{i2} \\ \vdots \\ \chi_{ip} \end{pmatrix} \qquad \chi = \begin{pmatrix} \chi_{1} \\ \chi_{2} \\ \vdots \\ \chi_{N} \end{pmatrix} \qquad \exists t = \begin{pmatrix} t_{1} \\ t_{2} \\ \vdots \\ t_{N} \end{pmatrix} \qquad \omega_{0} = \begin{pmatrix} \omega_{1} \\ \omega_{2} \\ \vdots \\ \omega_{b} \end{pmatrix}$ 

 $\nabla E(\omega) = -\sum_{k=1}^{N} \left\{ t_{k} \frac{\hat{t}_{k} (1-\hat{t}_{k}) \mathcal{H}_{k}}{\hat{t}_{k}} - (1-t_{k}) \frac{\hat{t}_{k} (1-\hat{t}_{k})}{(1-\hat{t}_{k})} \mathcal{H}_{k} \right\}$ 

 $= -\sum_{k=1}^{N} \{ t_{n} (1-\hat{t}_{n}) / t_{n} - (1-t_{n}) \hat{t}_{n} / t_{n} \}$ 

E(w) = - log L(w) = - \( \frac{2}{5} \) { th log th + (1-th) log(1-th) }

1.  $\nabla F(\omega) = \sum_{n=1}^{N} (\hat{t}_n - t_n) \chi_{t_n} = \chi^T (\hat{t} - t_n)$  E.f.  $\hat{t}$ 

= - \(\frac{N}{2}\) (tn-ta) 21 n

- XT (t. t) //

\_2. ω' = ω - η χ¹ (t-t)

3,

スティファサイズが大きすむるため、最適解を走るシス更新してしまうため、

更新回数が増加する、実行時間が大きくなる.

目的関数の差分がある1直にないさくなったらますなカラという外理を実行しないるか、

ステップサイス:が小さすをすと、最直解に到達するよりも先に、更新が遅くて打ちわら れてはっため、

勾配法とニュートン法では 初-2~3 計算の構造が異ななめ 更軒回数 によて 両者と

CC較了30~VII 難(以外、最終的日最終的日月的問款值 実行時間下來17 ニュートン法の方がめてくなっているので、ニュートン法の方が「事れていると意る

このデータセットにありては

ニュートン法は現時点での解付近にかいて目的関数が凸二次間数で近似以ると 頂定し、との 凸=次間数を最小に対点に解を更新していて、とのため、この仮定がある経度

正しければ、ステップサイズはつかりを必要としない

[5] ニュートン法は、ヘンアン行列の逆行列を計算なる必要があるため非常に次元数が 大きい間是見にかいては、その到真コストか、大きにかりすぎる場合かきえられるとのらな

場合は 最急降下法の方が適していると考えられる 一方で、ヘンアン行列の遂行列が 計算可能であればニュートン法はスラフ・サイズハラメ・タのちょニンかを必要とせかお

小さい実行時間で質の高い解をおめることができると考えられる

7. 5

$$E_{choss}(\omega) = \sum_{i=1}^{N} \left\{ -t_{i} \log_{i} \hat{t}_{i} - (1-t_{i}) \log_{i} (1-\hat{t}_{i}) \right\} -0$$

$$E_{cosistic}(\omega) = \sum_{i=1}^{N} \log_{i} (1+e-in^{2}N_{i}) - 0$$

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