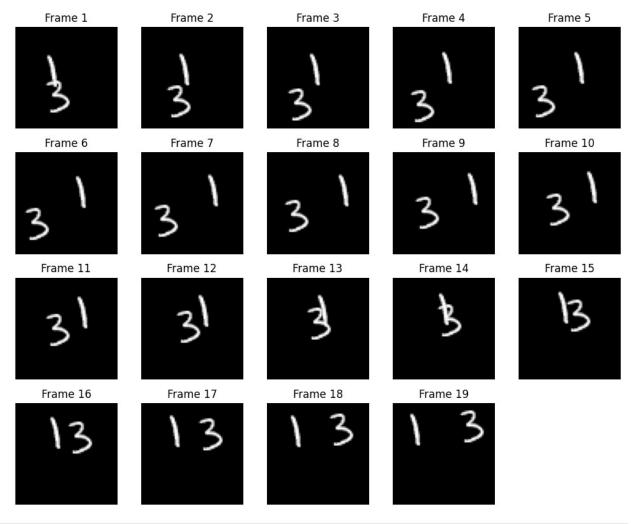
```
!pip install imageio
!pip install matplotlib
!pip install ipywidgets
!pip install tqdm
Requirement already satisfied: imageio in c:\users\sc23gd\.conda\envs\
pytorch\lib\site-packages (2.34.1)
Requirement already satisfied: numpy in c:\users\sc23gd\.conda\envs\
pytorch\lib\site-packages (from imageio) (1.24.3)
Requirement already satisfied: pillow>=8.3.2 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from imageio) (10.3.0)
Requirement already satisfied: matplotlib in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (3.9.0)
Requirement already satisfied: contourpy>=1.0.1 in c:\users\
sc23qd\.conda\envs\pytorch\lib\site-packages (from matplotlib) (1.2.1)
Requirement already satisfied: cycler>=0.10 in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from matplotlib) (0.12.1)
Requirement already satisfied: fonttools>=4.22.0 in c:\users\
sc23qd\.conda\envs\pytorch\lib\site-packages (from matplotlib)
(4.53.0)
Requirement already satisfied: kiwisolver>=1.3.1 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from matplotlib) (1.4.5)
Requirement already satisfied: numpy>=1.23 in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from matplotlib) (1.24.3)
Requirement already satisfied: packaging>=20.0 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from matplotlib) (24.1)
Requirement already satisfied: pillow>=8 in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from matplotlib) (10.3.0)
Requirement already satisfied: pyparsing>=2.3.1 in c:\users\
sc23qd\.conda\envs\pytorch\lib\site-packages (from matplotlib) (3.1.2)
Requirement already satisfied: python-dateutil>=2.7 in c:\users\
sc23qd\.conda\envs\pytorch\lib\site-packages (from matplotlib) (2.9.0)
Requirement already satisfied: six>=1.5 in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from python-dateutil>=2.7->matplotlib)
(1.16.0)
Requirement already satisfied: ipywidgets in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (8.1.3)
Requirement already satisfied: comm>=0.1.3 in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from ipywidgets) (0.2.2)
Requirement already satisfied: ipython>=6.1.0 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from ipywidgets)
Requirement already satisfied: traitlets>=4.3.1 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from ipywidgets)
(5.14.3)
Requirement already satisfied: widgetsnbextension~=4.0.11 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from ipywidgets)
(4.0.11)
Requirement already satisfied: jupyterlab-widgets~=3.0.11 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from ipywidgets)
```

```
(3.0.11)
Requirement already satisfied: decorator in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from ipython>=6.1.0->ipywidgets)
Requirement already satisfied: jedi>=0.16 in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from ipython>=6.1.0->ipywidgets)
(0.19.1)
Requirement already satisfied: matplotlib-inline in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from ipython>=6.1.0-
>ipywidgets) (0.1.7)
Requirement already satisfied: prompt-toolkit<3.1.0,>=3.0.41 in c:\
users\sc23gd\.conda\envs\pytorch\lib\site-packages (from
ipython >= 6.1.0 - ipywidgets) (3.0.47)
Requirement already satisfied: pygments>=2.4.0 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from ipython>=6.1.0-
>ipywidgets) (2.18.0)
Reguirement already satisfied: stack-data in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from ipython>=6.1.0->ipywidgets)
(0.6.2)
Requirement already satisfied: typing-extensions>=4.6 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from ipython>=6.1.0-
>ipywidgets) (4.11.0)
Requirement already satisfied: colorama in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from ipython>=6.1.0->ipywidgets)
(0.4.6)
Requirement already satisfied: parso<0.9.0,>=0.8.3 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from jedi>=0.16-
>ipython>=6.1.0->ipywidgets) (0.8.4)
Requirement already satisfied: wcwidth in c:\users\sc23gd\.conda\envs\
pytorch\lib\site-packages (from prompt-toolkit<3.1.0,>=3.0.41-
>ipython>=6.1.0->ipywidgets) (0.2.13)
Requirement already satisfied: executing>=1.2.0 in c:\users\
sc23gd\.conda\envs\pytorch\lib\site-packages (from stack-data-
>ipython>=6.1.0->ipywidgets) (2.0.1)
Requirement already satisfied: asttokens>=2.1.0 in c:\users\
sc23qd\.conda\envs\pytorch\lib\site-packages (from stack-data-
>ipython>=6.1.0->ipywidgets) (2.4.1)
Requirement already satisfied: pure-eval in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from stack-data->ipython>=6.1.0-
>ipywidgets) (0.2.2)
Requirement already satisfied: six>=1.12.0 in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from asttokens>=2.1.0->stack-data-
>ipython>=6.1.0->ipywidgets) (1.16.0)
Collecting tqdm
  Using cached tqdm-4.66.4-py3-none-any.whl.metadata (57 kB)
Requirement already satisfied: colorama in c:\users\sc23gd\.conda\
envs\pytorch\lib\site-packages (from tgdm) (0.4.6)
Downloading tqdm-4.66.4-py3-none-any.whl (78 kB)
   ----- 0.0/78.3 kB ? eta -:--:--
```

```
------ 30.7/78.3 kB 660.6 kB/s
eta 0:00:01
   ----- 78.3/78.3 kB 1.1 MB/s eta
0:00:00
Installing collected packages: tgdm
Successfully installed tqdm-4.66.4
import torch
import torch.nn as nn
import torch.optim as optim
import torch.distributed as dist
from torch.nn.parallel import DistributedDataParallel as DDP
from torch.utils.data import DataLoader, DistributedSampler,
TensorDataset
import numpy as np
import io
import imageio
import matplotlib.pyplot as plt
from IPython.display import Image, display
from ipywidgets import widgets, Layout, HBox
from torch.utils.data import TensorDataset, DataLoader
from torchvision.datasets.utils import download url
import random
from torch.utils.tensorboard import SummaryWriter
writer = SummaryWriter('runs/conv ae experiment')
# Downloading the Moving MNIST dataset
url =
"http://www.cs.toronto.edu/~nitish/unsupervised_video/mnist_test_seq.n
fpath = "moving mnist.npy"
download_url(url, root=".", filename=fpath)
dataset = np.load(fpath)
# Swapping the axes representing the number of frames and number of
data samples
dataset = np.swapaxes(dataset, 0, 1)
# We pick out 1000 of the 10000 total examples and use those
dataset = dataset[:5000, ...]
# Adding a channel dimension since the images are grayscale
dataset = np.expand dims(dataset, axis=-1)
# Splitting into train and validation sets using indexing to optimize
memory
indexes = np.arange(dataset.shape[0])
np.random.shuffle(indexes)
train index = indexes[: int(0.9 * dataset.shape[0])]
```

```
val_index = indexes[int(0.9 * dataset.shape[0]) :]
train dataset = dataset[train index]
val dataset = dataset[val index]
# Normalizing the data to the 0-1 range
train dataset = train dataset / 255
val dataset = val dataset / 255
1.1.1
#normalizing the data to have zero mean and unit variance
mean = train dataset.mean()
std = train dataset.std()
train dataset = (train dataset - mean) / std
val dataset = (val dataset - mean) / std
# We define a helper function to shift the frames, where
# 'x' is frame 0 to n - 1, and 'y' is frames 1 to n
def create shifted frames(data):
    x = data[:, 0 : data.shape[1] - 1, :, :]
    y = data[:, 1 : data.shape[1], :, :]
    return x, y
# Apply the processing function to the datasets
x train, y train = create shifted frames(train dataset)
x val, y val = create shifted frames(val dataset)
# Convert numpy arrays to PyTorch tensors
x train = torch.from numpy(x train).float()
y train = torch.from_numpy(y_train).float()
x val = torch.from numpy(x val).float()
y val = torch.from numpy(y val).float()
# Create TensorDataset and DataLoader
train dataset = TensorDataset(x train, y train)
val dataset = TensorDataset(x val, y val)
batch size = 64
train loader = DataLoader(train dataset, batch size=batch size,
shuffle=True, num workers=20)
val loader = DataLoader(val dataset, batch size=batch size,
shuffle=False, num workers=20)
# Inspect the dataset
print("Training Dataset Shapes: " + str(x train.shape) + ", " +
str(y train.shape))
print("Validation Dataset Shapes: " + str(x_val.shape) + ", " +
str(v val.shape))
```

```
Using downloaded and verified file: .\moving mnist.npy
Training Dataset Shapes: torch.Size([4500, 19, 64, 64, 1]),
torch.Size([4500, 19, 64, 64, 1])
Validation Dataset Shapes: torch.Size([500, 19, 64, 64, 1]),
torch.Size([500, 19, 64, 64, 1])
# Construct a figure on which we will visualize the images
fig, axes = plt.subplots(4, 5, figsize=(10, 8))
# Plot each of the sequential images for one random data example
data choice = np.random.choice(range(len(train dataset)), size=1)[0]
frames = train dataset.tensors[0][data choice]
for idx, ax in enumerate(axes.flat):
    if idx < frames.shape[0]:</pre>
        frame = frames[idx].squeeze().numpy()
        ax.imshow(frame, cmap="gray")
        ax.set title(f"Frame {idx + 1}")
        ax.axis("off")
    else:
        ax.axis("off")
# Print information and display the figure
print(f"Displaying frames for example {data choice}.")
plt.tight layout()
plt.show()
Displaying frames for example 1923.
```



```
# Define the Encoder module
class Encoder(nn.Module):
    def __init__(self, input_shape, latent_dim):
        super(Encoder, self).__init__()
        self.conv1 = nn.Conv3d(input shape[3], 128, kernel size=(3, 5,
5), padding=(1, 2, 2), stride=(1, 2, 2))
        self.bn1 = nn.BatchNorm3d(128)
        self.conv2 = nn.Conv3d(128, 256, kernel size=(3, 3, 3),
padding=(1, 1, 1), stride=(1, 2, 2))
        self.bn2 = nn.BatchNorm3d(256)
        self.conv3 = nn.Conv3d(256, 512, kernel_size=(3, 3, 3),
padding=(1, 1, 1), stride=(1, 2, 2))
        self.bn3 = nn.BatchNorm3d(512)
        self.flatten = nn.Flatten()
        self.densel = nn.Linear(512 * input shape[0] * input shape[1]
// 8 * input shape[2] // 8, latent dim)
    def forward(self, x):
        x = x.permute(0, 4, 1, 2, 3) # Rearrange dimensions to
```

```
(batch size, channels, frames, height, width)
        x = torch.relu(self.bn1(self.conv1(x)))
        x = torch.relu(self.bn2(self.conv2(x)))
        x = torch.relu(self.bn3(self.conv3(x)))
        x = self.flatten(x)
        z = self.densel(x)
        return z
# Define the Decoder module
class Decoder(nn.Module):
    def init (self, latent dim, output shape):
        super(Decoder, self). init ()
        self.densel = nn.Linear(latent dim, 512 * output shape[0] *
output shape[1] // 8 * output shape[2] // 8)
        self.unflatten = nn.Unflatten(dim=1, unflattened size=(512,
output_shape[0], output_shape[1] // 8, output_shape[2] // 8))
        self.deconv1 = nn.ConvTranspose3d(512, 256, kernel size=(3, 3,
3), padding=(1, 1, 1), stride=(1, 2, 2), output padding=(0, 1, 1))
        self.bn1 = nn.BatchNorm3d(256)
        self.deconv2 = nn.ConvTranspose3d(256, 128, kernel size=(3, 3,
3), padding=(1, 1, 1), stride=(1, 2, 2), output_padding=(0, 1, 1))
        self.bn2 = nn.BatchNorm3d(128)
        self.deconv3 = nn.ConvTranspose3d(128, output shape[3],
kernel size=(3, 3, 3), padding=(1, 1, 1), stride=(1, 2, 2),
output padding=(0, 1, 1)
    def forward(self, z):
        z = self.densel(z)
        z = self.unflatten(z)
        z = torch.relu(self.bn1(self.deconv1(z)))
        z = torch.relu(self.bn2(self.deconv2(z)))
        recon x = torch.sigmoid(self.deconv3(z))
        recon x = recon x.permute(0, 2, 3, 4, 1) # Rearrange
dimensions back to (batch size, frames, height, width, channels)
        return recon x
# Define the AE module
class AE(nn.Module):
    def init (self, input shape, latent dim):
        super(AE, self). init ()
        self.encoder = Encoder(input shape, latent dim)
        self.decoder = Decoder(latent dim, input shape)
    def forward(self, x):
        z = self.encoder(x)
        recon x = self.decoder(z)
        return recon x
# Set up device
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
```

```
# Define the model
input shape = x train.shape[1:]
latent dim = 10
model = AE(input_shape, latent dim).to(device)
for name, param in model.named parameters():
    if param.requires grad:
        print(name, param.data)
encoder.conv1.weight tensor([[[[[ 0.0285, -0.0742,  0.0167,  0.0849, -
0.0489],
           [-0.1114, -0.1008, -0.0854,
                                        0.0285,
                                                 0.0681],
                      0.0038, -0.0474, -0.0264,
           [ 0.0774,
                                                 0.0476],
           [ 0.0423,
                      0.0711, -0.0374,
                                        0.1122,
                                                 0.0588],
                                                 0.0972]],
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                      0.0509,
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           [0.0584, -0.0152, -0.0391, 0.1031,
                                                 0.0493],
                                        0.0199, -0.11141,
           [-0.0249, -0.0175,
                               0.1012,
           [-0.0355, 0.0188, -0.0347, 0.1017, 0.0299]],
          [[-0.0949, -0.0037, 0.0915, 0.1138, -0.0831],
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                                        0.0400,
           [-0.0608, -0.0180, -0.0949,
                                                 0.1048],
                               0.0547, -0.0753,
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           [-0.0951,
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           [ 0.0203,
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                                        0.1019, -0.0950,
           [-0.0306,
           [ 0.1148, -0.0186, 0.0077,
                                        0.0368, -0.0396],
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                                                0.1121]],
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        [[[-0.0096, -0.0318, -0.0222, -0.0912, -0.0651],
```

```
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                                          0.0774]],
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   [0.0030, 0.0114, -0.0825, 0.0608,
                                         0.1010]]],
. . . ,
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                       0.0593, -0.0659, -0.0799],
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                                0.0705,
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```

```
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```

```
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                    0.0690, -0.0386]]]]], device='cuda:0')
           [ 0.1407,
decoder.deconv3.bias tensor([0.0460], device='cuda:0')
```

```
from torch.cuda.amp import autocast, GradScaler
from torch.utils.tensorboard import SummaryWriter
from tqdm import tqdm
# Define the loss function for AE
def ae loss(x, recon x):
    recon_loss = nn.functional.mse_loss(recon_x, x, reduction='sum')
    return recon loss
# Train the AE model
def train(model, train dataloader, val dataloader, optimizer, epochs,
device):
    model.train()
    scaler = GradScaler() # Initialize GradScaler
    best loss = float('inf')
    for epoch in range(epochs):
        total loss = 0
        pbar = tqdm(train_dataloader, desc=f"Epoch
{epoch+1}/{epochs}")
        for batch in pbar:
            batch = batch[0].to(device)
            optimizer.zero grad()
            # Use autocast for mixed precision training
            with autocast():
                recon x = model(batch)
                loss = ae loss(batch, recon x)
            # Scale the loss and call backward() to create scaled
gradients
            scaler.scale(loss).backward()
            # Unscales the gradients of optimizer's assigned params
in-place and call step() to update params
            scaler.step(optimizer)
            # Updates the scale for next iteration
            scaler.update()
            total loss += loss.item()
            pbar.set postfix({'loss': total loss / (pbar.n + 1)})
        avg loss = total loss / len(train dataloader)
        writer.add scalar('Loss/train', avg loss, epoch) # Log the
average loss for this epoch
        # Validate and save the best model every 10 epochs
        if epoch % 10 == 0:
            model.eval()
            val loss = 0
            with torch.no grad():
                for batch in val dataloader:
                    batch = batch[0].to(device)
                    recon x = model(batch)
                    loss = ae loss(batch, recon x)
                    val loss += loss.item()
```

```
avg val loss = val loss / len(val dataloader)
           writer.add scalar('Loss/val', avg val loss, epoch) # Log
the average validation loss for this epoch
           if avg val loss < best loss:</pre>
               best loss = avg val loss
               torch.save(model.state dict(),
"movingmnist ae best.pth")
           model.train()
# Set up device
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
# Define the model
input shape = x train.shape[1:]
latent dim = 20
model = AE(input shape, latent dim).to(device)
# Define the optimizer
optimizer = optim.Adam(model.parameters(), lr=1e-6, weight decay=1e-6)
# Train the model
epochs = 100
train(model, train loader, val loader, optimizer, epochs, device)
writer.close()
Epoch 1/100: 100% | 100% | 71/71 [00:28<00:00, 2.47it/s,
loss=6.68e+6]
Epoch 2/100: 100% | 100% | 71/71 [00:27<00:00, 2.56it/s,
loss=6.34e+6]
Epoch 3/100: 100% | 100% | 71/71 [00:27<00:00, 2.58it/s,
loss=6.1e+6]
Epoch 4/100: 100% | 71/71 [00:27<00:00, 2.57it/s,
loss=5.91e+61
Epoch 5/100: 100% | 71/71 [00:27<00:00, 2.56it/s,
loss=5.77e+6]
Epoch 6/100: 100% | 100% | 71/71 [00:27<00:00, 2.63it/s,
loss=5.67e+61
Epoch 7/100: 100%
                   | 71/71 [00:27<00:00, 2.59it/s,
loss=5.6e+61
Epoch 8/100: 100% | 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=5.54e+6
Epoch 9/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=5.49e+6]
Epoch 10/100: 100%
                     | 71/71 [00:27<00:00, 2.57it/s,
loss=5.46e+6]
Epoch 11/100: 100% | | 71/71 [00:27<00:00, 2.56it/s,
loss=5.42e+6]
Epoch 12/100: 100% | 71/71 [00:27<00:00, 2.60it/s,
loss=5.4e+61
Epoch 13/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=5.38e+61
```

```
Epoch 14/100: 100% | 71/71 [00:27<00:00, 2.61it/s,
loss=5.35e+6]
Epoch 15/100: 100% | 71/71 [00:27<00:00,
                                            2.60it/s,
loss=5.34e+6
Epoch 16/100: 100% | 71/71 [00:27<00:00, 2.61it/s,
loss=5.32e+6]
Epoch 17/100: 100% | 100% | 71/71 [00:27<00:00, 2.58it/s,
loss=5.3e+6
Epoch 18/100: 100% | 71/71 [00:27<00:00, 2.58it/s,
loss=5.28e+6]
Epoch 19/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=5.27e+6]
Epoch 20/100: 100%
                     | 71/71 [00:27<00:00,
                                            2.60it/s,
loss=5.26e+61
Epoch 21/100: 100%
                   | 71/71 [00:27<00:00,
                                            2.58it/s,
loss=5.24e+6]
Epoch 22/100: 100% | 71/71 [00:27<00:00, 2.58it/s,
loss=5.23e+6]
Epoch 23/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=5.22e+6]
Epoch 24/100: 100%
                    | 71/71 [00:27<00:00, 2.57it/s,
loss=5.21e+6]
2.58it/s,
loss=5.2e+6
Epoch 26/100: 100%
                   | 71/71 [00:27<00:00, 2.58it/s,
loss=5.18e+61
Epoch 27/100: 100%
                        || 71/71 [00:27<00:00, 2.59it/s,
loss=5.18e+6]
Epoch 28/100: 100% | 71/71 [00:27<00:00, 2.58it/s,
loss=5.16e+6]
Epoch 29/100: 100%
                    | 71/71 [00:27<00:00,
                                            2.60it/s,
loss=5.15e+6]
Epoch 30/100: 100%
                   | 71/71 [00:27<00:00, 2.57it/s,
loss=5.14e+6]
Epoch 31/100: 100% | 71/71 [00:27<00:00, 2.58it/s,
loss=5.13e+6
Epoch 32/100: 100% | 71/71 [00:27<00:00, 2.54it/s,
loss=5.12e+6]
Epoch 33/100: 100%
                   | 71/71 [00:27<00:00, 2.59it/s,
loss=5.1e+6]
Epoch 34/100: 100%
                    | 71/71 [00:27<00:00,
                                            2.56it/s,
loss=5.09e+6]
Epoch 35/100: 100% | 71/71 [00:27<00:00, 2.56it/s,
loss=5.08e+6]
Epoch 36/100: 100% | 71/71 [00:27<00:00, 2.55it/s,
loss=5.07e+6]
Epoch 37/100: 100%
                   | 71/71 [00:28<00:00, 2.52it/s,
loss=5.05e+61
Epoch 38/100: 100% | 71/71 [00:27<00:00, 2.60it/s,
```

```
loss=5.03e+61
Epoch 39/100: 100% | 71/71 [00:27<00:00, 2.55it/s,
loss=5.03e+6
Epoch 40/100: 100% | 71/71 [00:27<00:00, 2.56it/s,
loss=5.02e+6
Epoch 41/100: 100%
                  | 71/71 [00:27<00:00, 2.56it/s,
loss=5e+6]
Epoch 42/100: 100%
                    | 71/71 [00:28<00:00,
                                            2.53it/s,
loss=4.98e+6]
Epoch 43/100: 100% | 71/71 [00:27<00:00, 2.55it/s,
loss=4.96e+6]
loss=4.95e+61
Epoch 45/100: 100% | 71/71 [00:27<00:00, 2.60it/s,
loss=4.93e+6]
Epoch 46/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=4.91e+6
Epoch 47/100: 100%
                   | 71/71 [00:27<00:00,
                                            2.56it/s,
loss=4.9e+6]
Epoch 48/100: 100%
                    | 71/71 [00:31<00:00, 2.26it/s,
loss=4.88e+6]
Epoch 49/100: 100%
                   | 71/71 [00:27<00:00, 2.61it/s,
loss=4.86e+6
Epoch 50/100: 100% | 71/71 [00:27<00:00, 2.61it/s,
loss=4.84e+6]
                    | 71/71 [00:27<00:00, 2.61it/s,
Epoch 51/100: 100%
loss=4.82e+6
Epoch 52/100: 100%
                   | 71/71 [00:27<00:00, 2.54it/s,
loss=4.8e+61
Epoch 53/100: 100% | 71/71 [00:28<00:00, 2.52it/s,
loss=4.78e+6]
Epoch 54/100: 100% | 71/71 [00:28<00:00, 2.46it/s,
loss=4.77e+6]
Epoch 55/100: 100%
                   | 71/71 [00:29<00:00, 2.41it/s,
loss=4.75e+6
Epoch 56/100: 100%
                    | 71/71 [00:28<00:00,
                                            2.51it/s,
loss=4.73e+6
Epoch 57/100: 100% | | 71/71 [00:27<00:00, 2.58it/s,
loss=4.71e+6
                        | 71/71 [00:27<00:00, 2.60it/s,
Epoch 58/100: 100%
loss=4.69e+61
Epoch 59/100: 100% | 71/71 [00:30<00:00, 2.36it/s,
loss=4.67e+6]
Epoch 60/100: 100% | 71/71 [00:28<00:00, 2.52it/s,
loss=4.66e+6]
Epoch 61/100: 100%|
                        | 71/71 [00:27<00:00,
                                            2.55it/s,
loss=4.64e+61
Epoch 62/100: 100% | 71/71 [00:26<00:00, 2.63it/s,
loss=4.62e+6
```

```
Epoch 63/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=4.61e+6]
Epoch 64/100: 100% | 71/71 [00:27<00:00,
                                            2.56it/s,
loss=4.59e+6
Epoch 65/100: 100% | 71/71 [00:27<00:00, 2.58it/s,
loss=4.58e+6]
                                           2.58it/s,
Epoch 66/100: 100%
                   | 71/71 [00:27<00:00,
loss=4.57e+6
Epoch 67/100: 100% | 71/71 [00:27<00:00,
                                           2.54it/s,
loss=4.55e+6
Epoch 68/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=4.54e+6
Epoch 69/100: 100%
                        | 71/71 [00:27<00:00,
                                            2.56it/s,
loss=4.53e+61
Epoch 70/100: 100%
                   | 71/71 [00:27<00:00,
                                           2.59it/s,
loss=4.52e+6
Epoch 71/100: 100% | 100% | 71/71 [00:27<00:00,
                                           2.57it/s,
loss=4.5e+6]
Epoch 72/100: 100% | 71/71 [00:27<00:00, 2.56it/s,
loss=4.49e+6]
Epoch 73/100: 100%
                    | 71/71 [00:27<00:00,
                                           2.56it/s,
loss=4.47e+6]
2.57it/s,
loss=4.46e+6]
                        | 71/71 [00:27<00:00, 2.56it/s,
Epoch 75/100: 100%
loss=4.45e+61
Epoch 76/100: 100%
                        | 71/71 [00:27<00:00,
                                           2.56it/s,
loss=4.45e+6]
Epoch 77/100: 100%
                  | 71/71 [00:27<00:00, 2.60it/s,
loss=4.43e+6
Epoch 78/100: 100%
                    | 71/71 [00:27<00:00,
                                           2.59it/s,
loss=4.42e+61
Epoch 79/100: 100%
                   | 71/71 [00:27<00:00,
                                           2.59it/s,
loss=4.42e+6]
Epoch 80/100: 100%
                  | 71/71 [00:27<00:00,
                                           2.58it/s,
loss=4.41e+6
2.58it/s,
loss=4.39e+6]
Epoch 82/100: 100%
                   | 71/71 [00:28<00:00,
                                           2.52it/s,
loss=4.39e+6]
Epoch 83/100: 100%
                    | 71/71 [00:27<00:00,
                                            2.60it/s,
loss=4.38e+6]
Epoch 84/100: 100% | 71/71 [00:28<00:00,
                                           2.52it/s,
loss=4.37e+61
Epoch 85/100: 100%
                        || 71/71 [00:27<00:00, 2.57it/s,
loss=4.36e+6]
Epoch 86/100: 100%
                   | 71/71 [00:27<00:00, 2.56it/s,
loss=4.36e+61
Epoch 87/100: 100% | 71/71 [00:27<00:00,
                                           2.60it/s,
```

```
loss=4.35e+61
Epoch 88/100: 100% | 71/71 [00:27<00:00, 2.61it/s,
loss=4.34e+6]
Epoch 89/100: 100% | 71/71 [00:27<00:00, 2.60it/s,
loss=4.33e+6
Epoch 90/100: 100% | 71/71 [00:27<00:00, 2.57it/s,
loss=4.33e+6
Epoch 91/100: 100%
                     | 71/71 [00:30<00:00, 2.36it/s,
loss=4.32e+6
Epoch 92/100: 100% | 71/71 [00:27<00:00, 2.60it/s,
loss=4.32e+61
Epoch 93/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=4.31e+61
Epoch 94/100: 100% | | 71/71 [00:27<00:00, 2.59it/s,
loss=4.3e+6
Epoch 95/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=4.3e+61
Epoch 96/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=4.29e+6]
Epoch 97/100: 100% | 71/71 [00:27<00:00, 2.59it/s,
loss=4.29e+6]
Epoch 98/100: 100% | 71/71 [00:27<00:00, 2.60it/s,
loss=4.28e+61
Epoch 99/100: 100% | 71/71 [00:27<00:00, 2.60it/s,
loss=4.28e+6
                    | 71/71 [00:27<00:00, 2.58it/s,
Epoch 100/100: 100%
loss=4.27e+61
# Visualize some example reconstructions
import matplotlib.pyplot as plt
model.eval()
with torch.no grad():
   for examples in val loader:
       examples = examples[0].to(device)
       *_, recon_examples = model(examples)
       break
examples = examples.cpu().numpy()
recon examples = recon examples.cpu().numpy()
fig, axes = plt.subplots(\frac{2}{10}, figsize=(\frac{20}{4}))
for i in range(10):
   axes[0, i].imshow(examples[i, 0], cmap='gray')
   axes[0, i].axis('off')
   axes[1, i].imshow(recon examples[i, 0], cmap='gray')
   axes[1, i].axis('off')
plt.show()
```

