

COVID 19 SEGMENTATION API

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TEAM NO: 14

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INTRODUCTION

- **COVID-19** is an **infectious disease caused by the SARS-CoV-2**
- **Common method detecting** COVID-19 - **RT-PCR** testing,
- **CT scan imaging** - **fast and cost-effective** alternative
- **Deep learning techniques** - **U-Net models**
- This **promising research field** - significant step towards rapid and reliable
COVID-19 detection

MOTIVATION

- Detecting COVID-19 from CT-scan image using CNN models is a highly relevant and timely project, given the ongoing global pandemic.
- Creating a reliable CNN model to detect COVID-19 from CT-scans can assist healthcare professionals in early diagnosis and treatment, utilizing a common diagnostic tool.
- Developing a CNN model for CT-scan-based COVID-19 detection can aid in patient triage and improve outcomes in the fight against the pandemic. Ultimately, this project has the potential to contribute to the fight against COVID-19 and improve patient outcomes.

PROBLEM STATEMENT

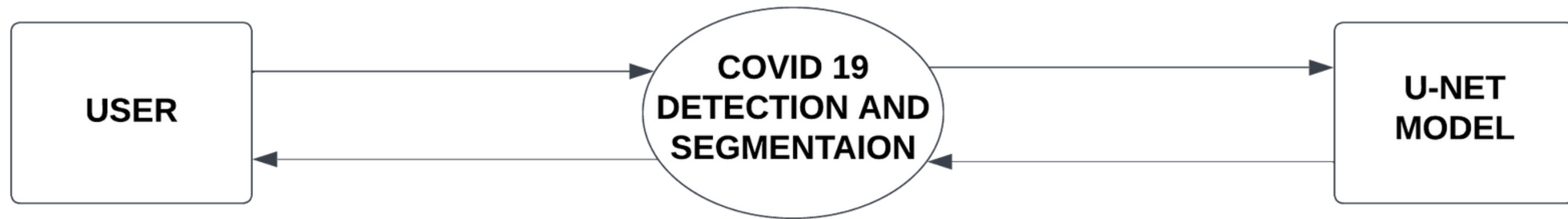
The accurate segmentation of COVID-19 infected regions in medical images is crucial for diagnosing and monitoring the disease. However, the manual segmentation process is time-consuming, subjective, and prone to human error. Therefore, there is a need to develop a reliable and efficient COVID-19 Segmentation API using the UNet deep learning model to automate the segmentation process and provide accurate and timely results.

OBJECTIVES

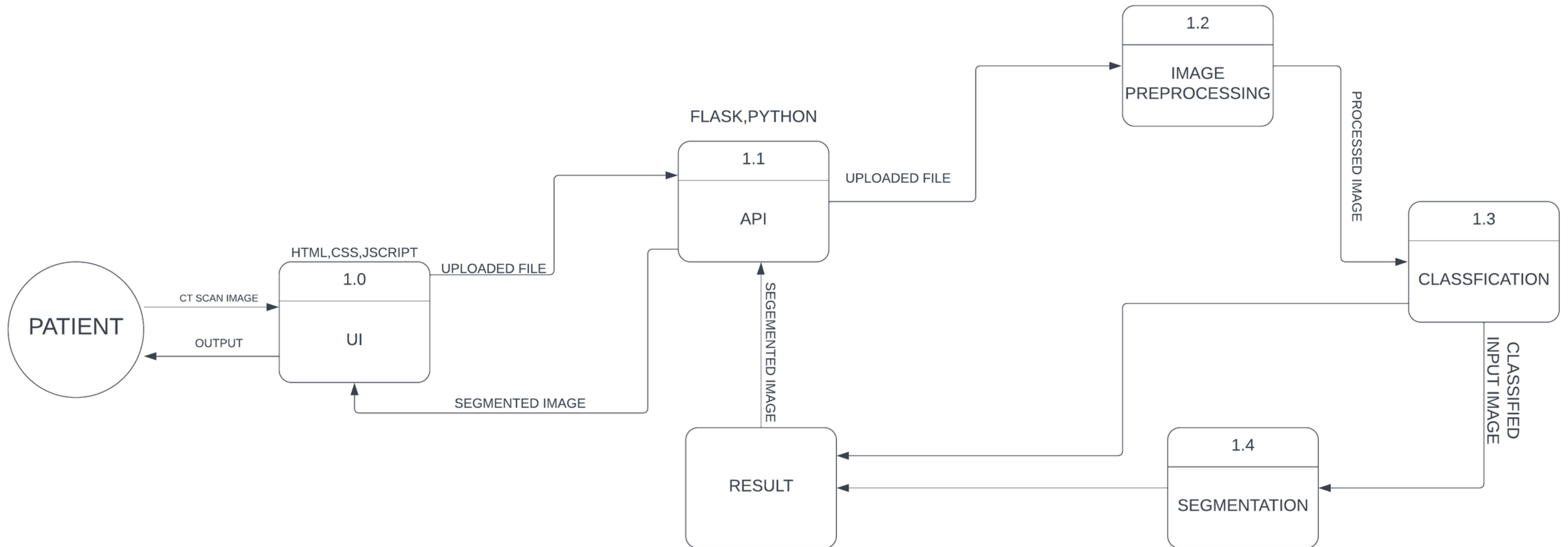
- Develop an API that allows users to perform automated segmentation of COVID-19 infected regions in medical images.
- Implement the UNet architecture, a deep learning model known for its effectiveness in image segmentation tasks, as the core algorithm for the API
- Optimize the model for efficient inference, ensuring that the API provides segmentation results in a timely manner
- Implement a user friendly interface.
- Provide comprehensive testing to validate the accuracy and reliability of the segmentation results across different types of COVID-19 lung images

DATA FLOW DIAGRAM

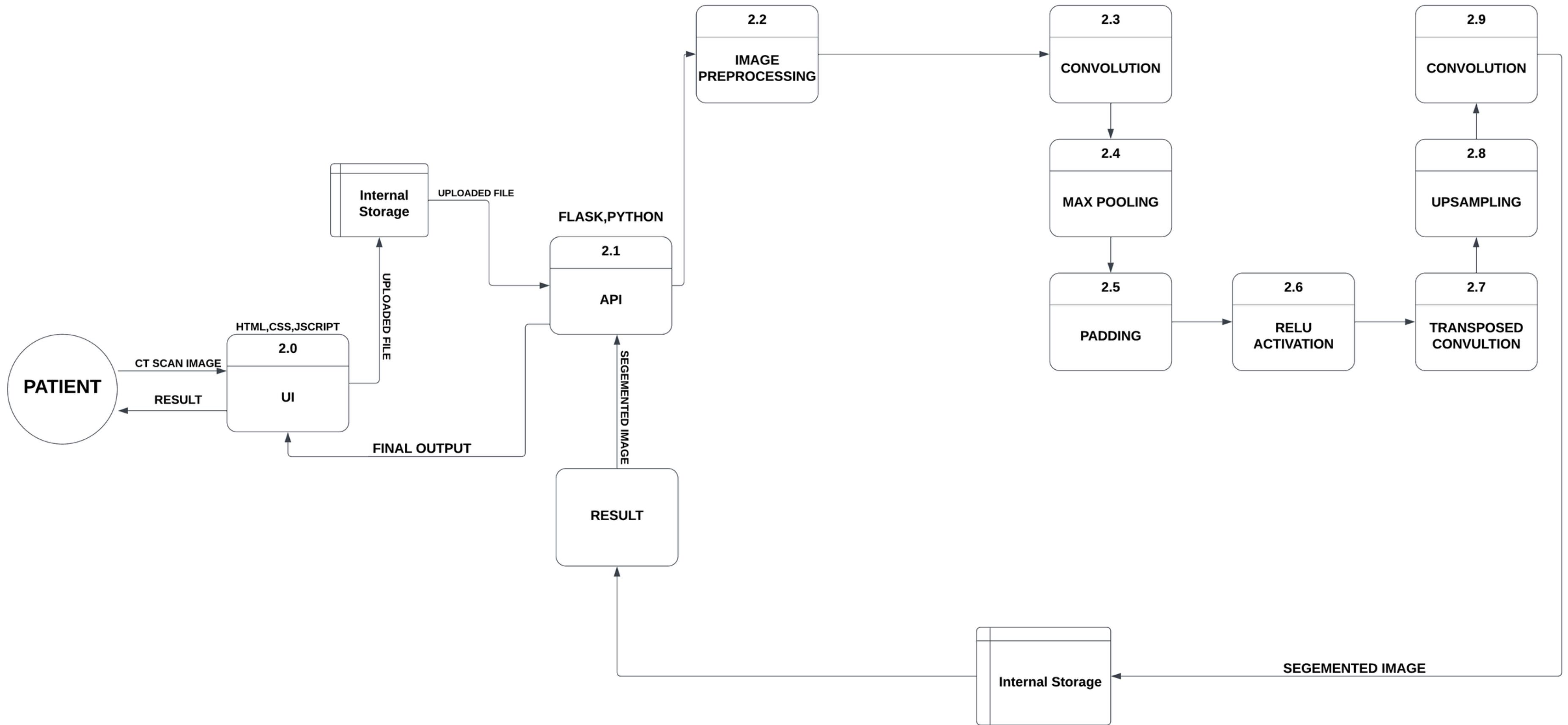
LEVEL 0

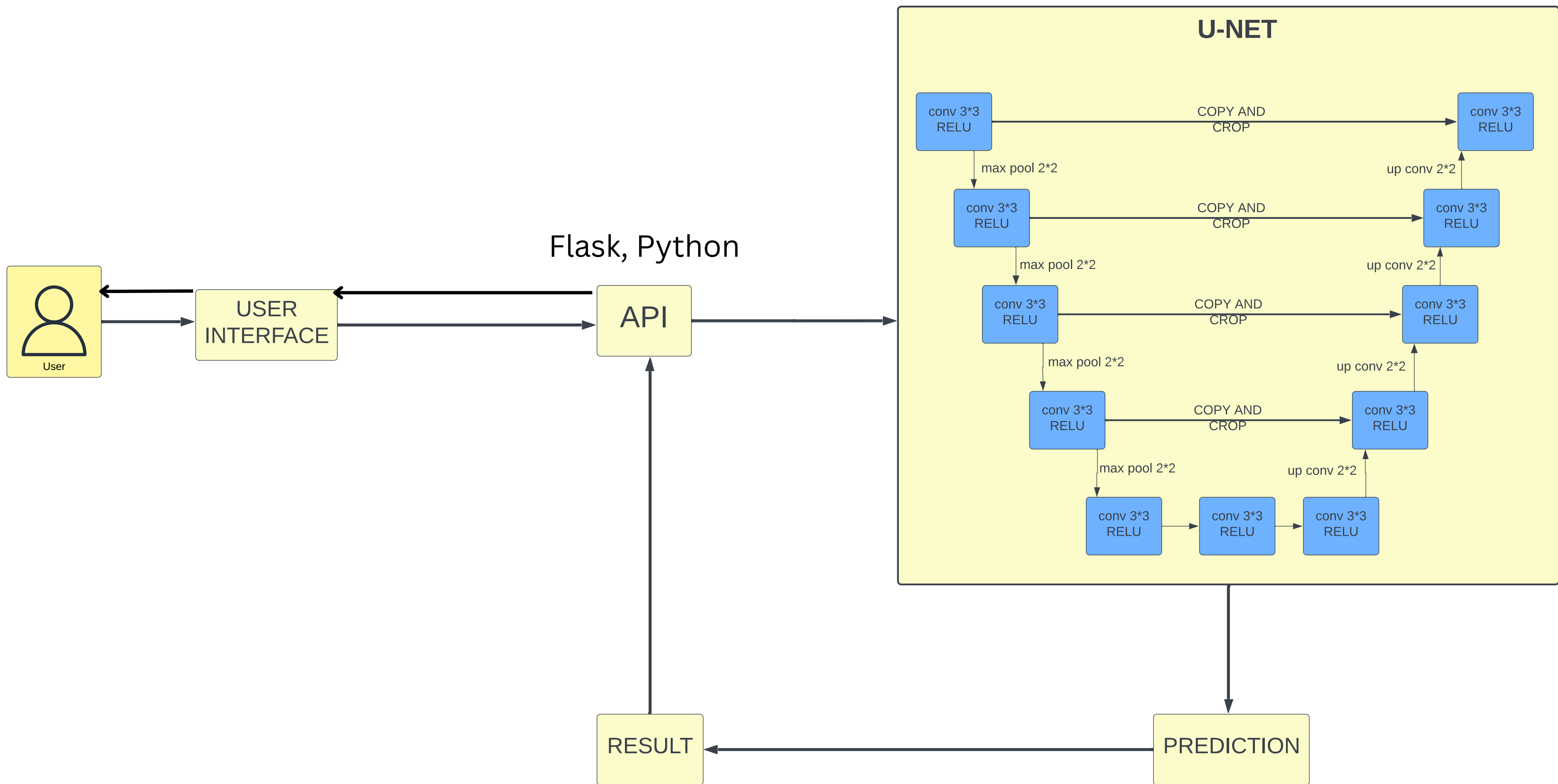


LEVEL 1

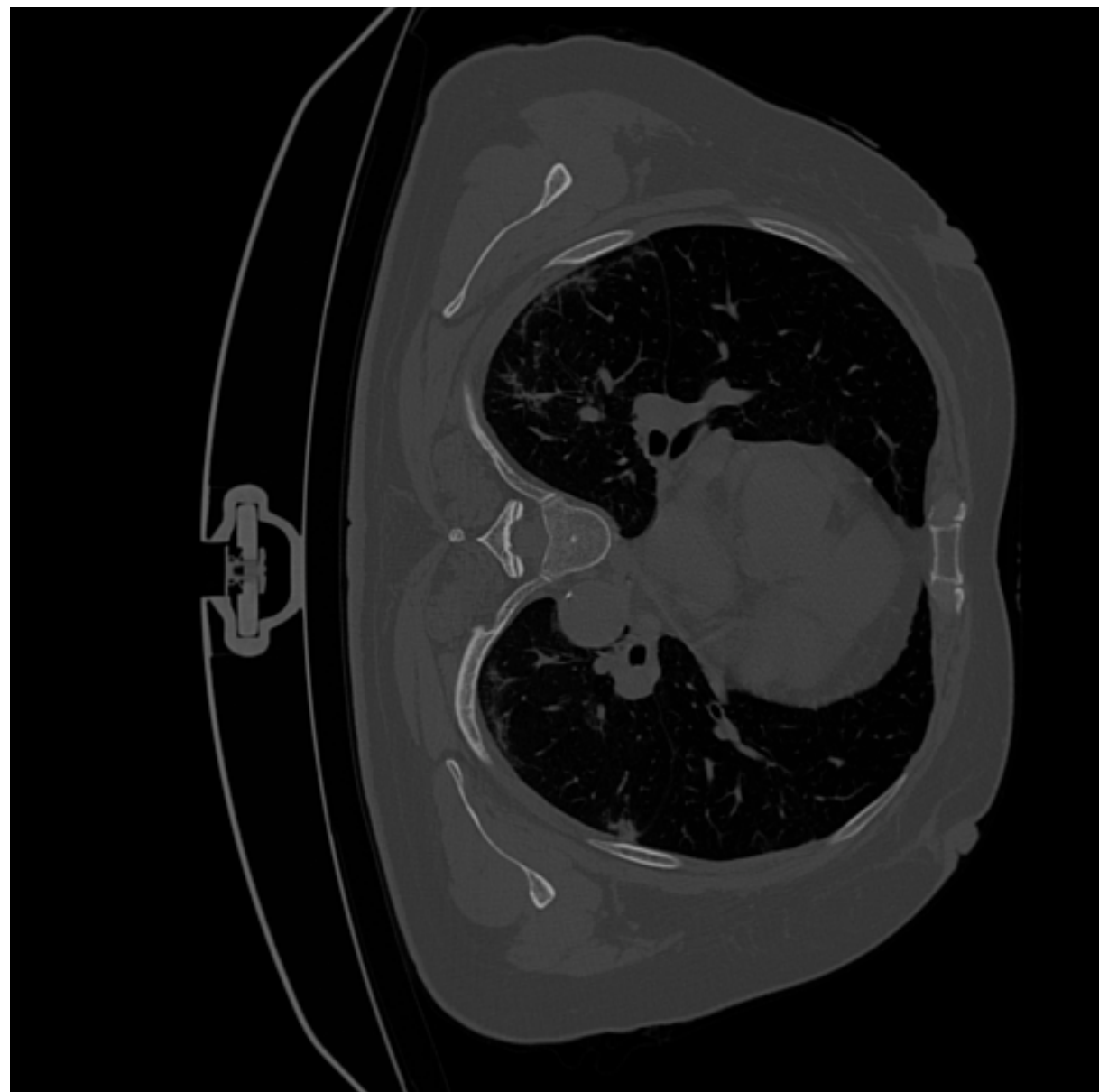


LEVEL 2

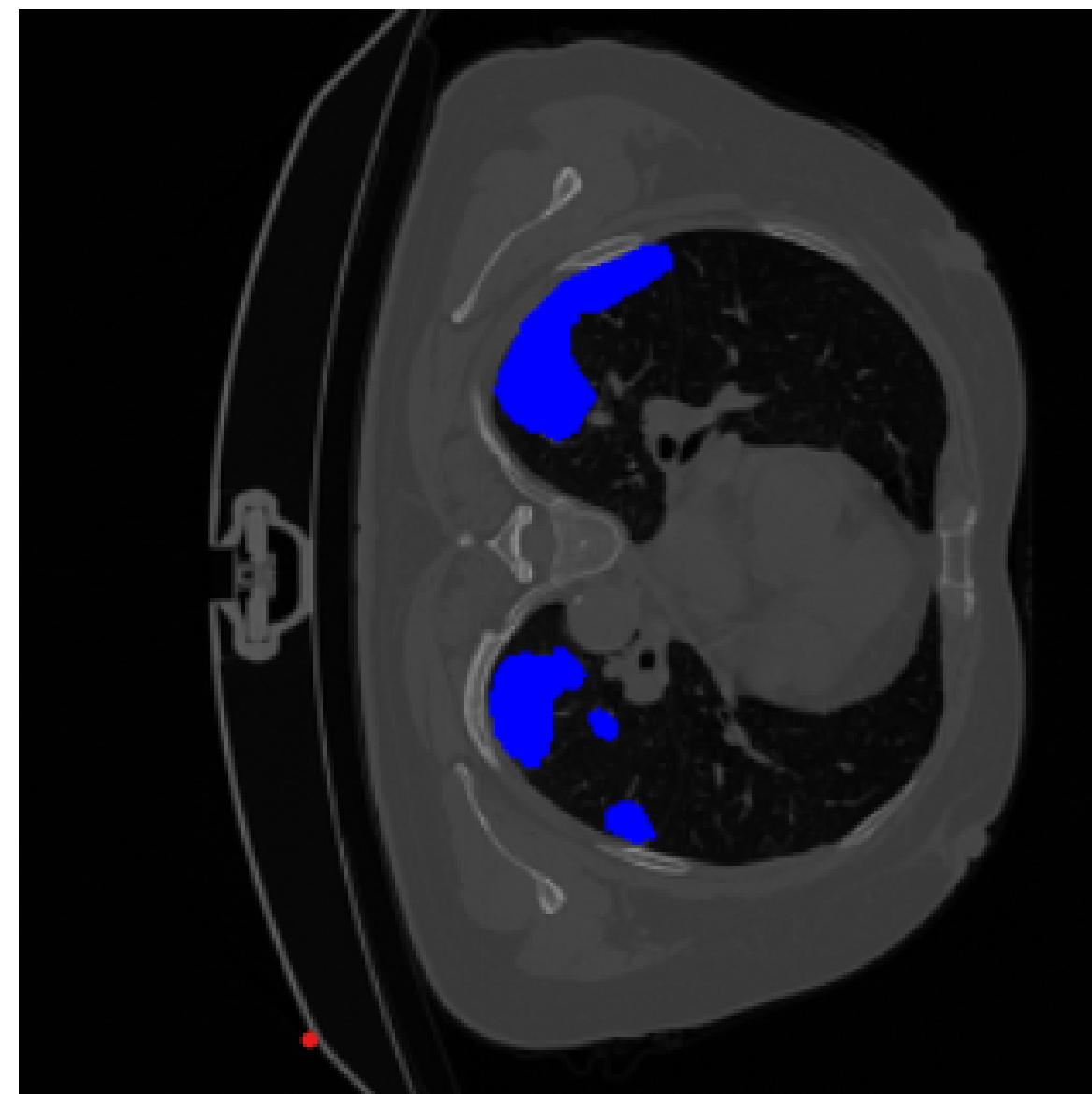




Input



Output



MODULE DETAILS

- 1.Design the user interface
- 2.Build API
- 3.Collection of the dataset
- 4.Implement UNET Model
- 5.Prediction

DESIGNING USER INTERFACE

- 1.Design an intuitive and user-friendly interface.
- 2.It consists of a simple UI that is connected through an API to the model.
- 3.An option to add the CT Scan will be provided.
- 4.The result is then fetched from the API and is displayed to the user.

BUILDING API

- The back-end API will receive the CT-scan image from the front-end and process it using UNET model.
- To build an API a web framework such as Flask (Python), Express (Node.js), or Ruby on Rails (Ruby) is required.
- When the API receives the image, it will need to preprocess the image to prepare it for input to the UNET model.

COLLECTION & TRAINING

- Public dataset from **Ma et al.** which consists of 700 annotated COVID-19 chest CT volumes.
- 3D volume set with annotated COVID-19 infection segmentation.
- It is used by the model to provide accurate and helpful responses to users.

IMPLEMENTING U-NET MODEL

- Segmentation :It provides fine-grained information about the image as well as the shapes and boundaries of the objects.
- Encoding layers : Extracting features from the input image using convolution,padding,maxpooling operations.
- Decoding Layers : precise localization using transposed convolutions

SEGMENTATION & RESULT

Receive a CT scanned image of a lung through an API to be Segmented by a Convolutional neural network.

SYSTEM REQUIREMENTS

Software Requirement

- Language : Python
- Supporting libraries like KERAS
- API framework : FLASK
- IDE : VS Code

Hardware Requirement

- Processor : Intel(R) Xeon w-2255 CPU(3.7Ghz)
- RAM : 64 GB
- GPU : RTX 3080 10 GB

COMPARISON WITH EXISTING SYSTEM

- Current Existing systems are
 - Reverse-Transcription Polymerase Chain Reaction (RT-PCR)
 - Rapid Antigen Test
 - Chest X-Ray/ CT Scan
- Compared to these systems the model will have:
 - Lower False Positives / False Negatives
 - Easily Available
 - Lesser Turnaround Time
 - Reduced Cost

WORKPLAN

Week 1–3: Planning and research

- Define project requirements and objectives
- Research on CNN U-NET
- Determine feasibility of project within the given timeline and resources

Week 4–5: Development Process

- Collect required training datas
- Training the U-NET model with the datas and tuning hyperparameters
- Developing API for the system
- Making user interface

Week 6–7: Testing and refinement

- Test the model with sample data and check for accuracy
- Gather feedback from users and identify areas for improvement.

IMPLEMENTATION

IMPORTS

```
import os
os.environ["TF_CPP_MIN_LOG_LEVEL"] = "2"
import numpy as np
import cv2
from glob import glob
from sklearn.model_selection import train_test_split
import tensorflow as tf
from tensorflow.keras.callbacks import ModelCheckpoint, CSVLogger, ReduceLROnPlateau
from tensorflow.keras.optimizers import Adam
from tensorflow.keras.metrics import Recall, Precision
from model import build_unet
from metrics import dice_loss, dice_coef, iou
```

All the necessary libraries & packages required to run the program are installed.

CONVOLUTION BLOCK

```
def conv_block(input, num_filters):  
    x = Conv2D(num_filters, 3, padding="same")(input)  
    x = BatchNormalization()(x)  
    x = Activation("relu")(x)  
  
    x = Conv2D(num_filters, 3, padding="same")(x)  
    x = BatchNormalization()(x)  
    x = Activation("relu")(x)  
  
    return x
```

- The convolution operation, when performed on an image, extracts features from it.
- The number of filters in the Conv2D block is defined with num_filters
- Normalization ensures that all the values are normalized between 0 and 1.
- The activation function chosen is the Relu function.
- A single convolution block contains two Conv2D layers, 2 Normalization layers followed by an activation function

ENCODER BLOCK & DECODER BLOCK

```
def encoder_block(input, num_filters):  
    x = conv_block(input, num_filters)  
    p = MaxPool2D((2, 2))(x)  
    return x, p  
  
def decoder_block(input, skip_features, num_filters):  
    x = Conv2DTranspose(num_filters, (2, 2), strides=2, padding="same")(input)  
    x = Concatenate()([x, skip_features])  
    x = conv_block(x, num_filters)  
    return x
```

The above block contains the code for U-Net Architecture. It has 2 parts:

- Encoder Block
 - Responsible for extracting patterns in the image, such as infected regions.
 - Uses convolutions and max-pooling layers.
 - Convolutions make patterns more obscure and reduce image size.
 - Max-pooling ensures important features are retained.
- Decoder Block
 - Opposite of Encoder Block
 - Localizes the extracted features

U-NET MODEL

```
def build_unet(input_shape):
    inputs = Input(input_shape)

    s1, p1 = encoder_block(inputs, 64)
    s2, p2 = encoder_block(p1, 128)
    s3, p3 = encoder_block(p2, 256)
    s4, p4 = encoder_block(p3, 512)

    b1 = conv_block(p4, 1024)

    d1 = decoder_block(b1, s4, 512)
    d2 = decoder_block(d1, s3, 256)
    d3 = decoder_block(d2, s2, 128)
    d4 = decoder_block(d3, s1, 64)

    outputs = Conv2D(1, 1, padding="same", activation="sigmoid")(d4)

    model = Model(inputs, outputs, name="U-Net")
    return model
```

The U-Net model consists of:

- 4 Encoder blocks
- Bottle neck layer
- 4 Decoder Blocks
- Activation Function : Sigmoid Function

MODEL SUMMARY

The summary of the model that we have constructed to perform segmentation of covid-19 infected CT scans.

Model: "U-Net"			
Layer (type)	Output Shape	Param #	Connected to
=====			
input_3 (InputLayer)	[(None, 512, 512, 3 0)]		[]
conv2d_16 (Conv2D)	(None, 512, 512, 64 1792)		['input_3[0][0]']
batch_normalization_14 (BatchN ormalization)	(None, 512, 512, 64 256)		['conv2d_16[0][0]']
activation_14 (Activation)	(None, 512, 512, 64 0)		['batch_normalization_14[0][0]']
max_pooling2d_6 (MaxPooling2D)	(None, 256, 256, 64 0)		['activation_14[0][0]']
conv2d_17 (Conv2D)	(None, 256, 256, 12 73856 8)		['max_pooling2d_6[0][0]']
batch_normalization_15 (BatchN ormalization)	(None, 256, 256, 12 512 8)		['conv2d_17[0][0]']
activation_15 (Activation)	(None, 256, 256, 12 0 8)		['batch_normalization_15[0][0]']
max_pooling2d_7 (MaxPooling2D)	(None, 128, 128, 12 0 8)		['activation_15[0][0]']


```

activation_18 (Activation)      (None, 128, 128, 25  0 6)      ['batch_normalization_18[0][0]']

conv2d_transpose_7 (Conv2DTran (None, 256, 256, 12 131200 8)      ['activation_18[0][0]']
spose)

concatenate_7 (Concatenate)     (None, 256, 256, 25  0 6)      ['conv2d_transpose_7[0][0]',
                                'activation_15[0][0]']

conv2d_21 (Conv2D)              (None, 256, 256, 12 295040 8)      ['concatenate_7[0][0]']

batch_normalization_19 (BatchN (None, 256, 256, 12 512 8)      ['conv2d_21[0][0]']
ormalization)

activation_19 (Activation)      (None, 256, 256, 12  0 8)      ['batch_normalization_19[0][0]']

conv2d_transpose_8 (Conv2DTran (None, 512, 512, 64 32832 )      ['activation_19[0][0]']
spose)

concatenate_8 (Concatenate)     (None, 512, 512, 12  0 8)      ['conv2d_transpose_8[0][0]',
                                'activation_14[0][0]']

conv2d_22 (Conv2D)              (None, 512, 512, 64 73792 )      ['concatenate_8[0][0]']

batch_normalization_20 (BatchN (None, 512, 512, 64 256 )      ['conv2d_22[0][0]']
ormalization)

activation_20 (Activation)      (None, 512, 512, 64  0 )      ['batch_normalization_20[0][0]']

conv2d_23 (Conv2D)              (None, 512, 512, 1) 65      ['activation_20[0][0]']

=====
Total params: 3,793,985
Trainable params: 3,791,169
Non-trainable params: 2,816

```

The input shape of the image is (512,512)
The output shape of the image is (512,512)

TRAINING & TESTING

```
""" Global parameters """
H = 512
W = 512

def create_dir(path):
    """ Create a directory. """
    if not os.path.exists(path):
        os.makedirs(path)

def load_data(path, split=0.1):
    images = sorted(glob(os.path.join(path, "images", "*.png")))
    masks = sorted(glob(os.path.join(path, "masks", "*.png")))

    split_size = int(len(images) * split)

    train_x, valid_x = train_test_split(images, test_size=split_size, random_state=42)
    train_y, valid_y = train_test_split(masks, test_size=split_size, random_state=42)

    train_x, test_x = train_test_split(train_x, test_size=split_size, random_state=42)
    train_y, test_y = train_test_split(train_y, test_size=split_size, random_state=42)

    return (train_x, train_y), (valid_x, valid_y), (test_x, test_y)
```

Total dataset : 700 images

Training Data : 400 images

Validation : 200 images

Testing : 100 images

MODEL DEFINITION

```
model = build_unet((H, W, 3))
metrics = [dice_coef, iou, Recall(), Precision()]
model.compile(loss=dice_loss, optimizer=Adam(lr), metrics=metrics)

callbacks = [
    ModelCheckpoint(model_path, verbose=1, save_best_only=True),
    ReduceLROnPlateau(monitor='val_loss', factor=0.1, patience=5, min_lr=1e-7, verbose=1),
    CSVLogger(csv_path)
]

model.fit(
    train_dataset,
    epochs=num_epochs,
    validation_data=valid_dataset,
    callbacks=callbacks
)
```

The model is build by :

- Defining it's structure
- Setting metrics
- Implementing callbacks when desired performance is achieved
- `model.fit()` is used to train the model with pre-defined epochs & datasets

METRICS

```
def iou(y_true, y_pred):
    def f(y_true, y_pred):
        intersection = (y_true * y_pred).sum()
        union = y_true.sum() + y_pred.sum() - intersection
        x = (intersection + 1e-15) / (union + 1e-15)
        x = x.astype(np.float32)
        return x
    return tf.numpy_function(f, [y_true, y_pred], tf.float32)

smooth = 1e-15
def dice_coef(y_true, y_pred):
    y_true = tf.keras.layers.Flatten()(y_true)
    y_pred = tf.keras.layers.Flatten()(y_pred)
    intersection = tf.reduce_sum(y_true * y_pred)
    return (2. * intersection + smooth) / (tf.reduce_sum(y_true) + tf.reduce_sum(y_pred) + smooth)

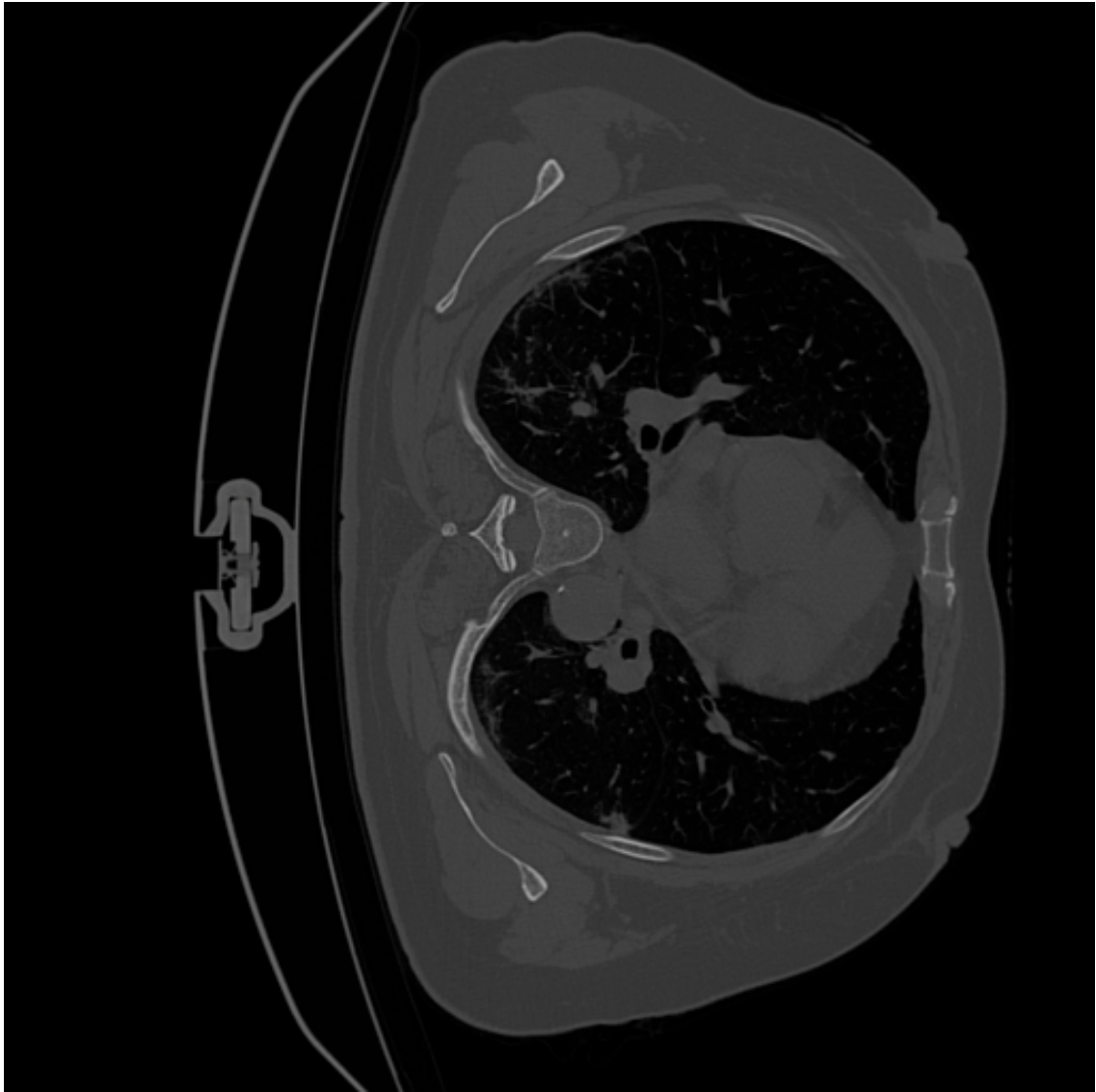
def dice_loss(y_true, y_pred):
    return 1.0 - dice_coef(y_true, y_pred)
```

The metrics that we have chosen to evaluate our model are:

- Dice coefficient : $(2 * \text{intersection}) / (\text{sum of sizes})$.
- Intersection over Union (IoU) : $\text{IoU} = \text{intersection} / \text{union}$
- Precision : $\text{Precision} = \text{True Positives} / (\text{True Positives} + \text{False Positives})$
- Recall : $\text{Recall} = \text{True Positives} / (\text{True Positives} + \text{False Negatives})$

SAMPLE TRAINING DATA

CT SCAN



MASK



SEGMENTATION

```
""" Predicting the mask """
for x, y in tqdm(zip(test_x, test_y), total=len(test_x)):
    """ Extracing the image name. """
    image_name = x.split("/")[-1]

    """ Reading the image """
    ori_x = cv2.imread(x, cv2.IMREAD_COLOR)
    ori_x = cv2.resize(ori_x, (W, H))
    x = ori_x/255.0
    x = x.astype(np.float32)
    x = np.expand_dims(x, axis=0)

    """ Reading the mask """
    ori_y = cv2.imread(y1, cv2.IMREAD_GRAYSCALE)
    # ori_y2 = cv2.imread(y2, cv2.IMREAD_GRAYSCALE)
    # ori_y = ori_y1 + ori_y2
    ori_y = cv2.resize(ori_y, (W, H))
    ori_y = np.expand_dims(ori_y, axis=-1)  ## (512, 512, 1)
    ori_y = np.concatenate([ori_y, ori_y, ori_y], axis=-1)  ## (512, 512, 3)

    """ Predicting the mask. """
    y_pred = model.predict(x)[0] > 0.5
    y_pred = y_pred.astype(np.int32)

    """ Saving the predicted mask along with the image and GT """
    save_image_path = f"results/{image_name}"
    y_pred = np.concatenate([y_pred, y_pred, y_pred], axis=-1)

    sep_line = np.ones((H, 10, 3)) * 255

    cat_image = np.concatenate([ori_x, sep_line, ori_y, sep_line, y_pred*255], axis=1)
    cv2.imwrite(save_image_path, cat_image)
```

API

```
@app.route('/')

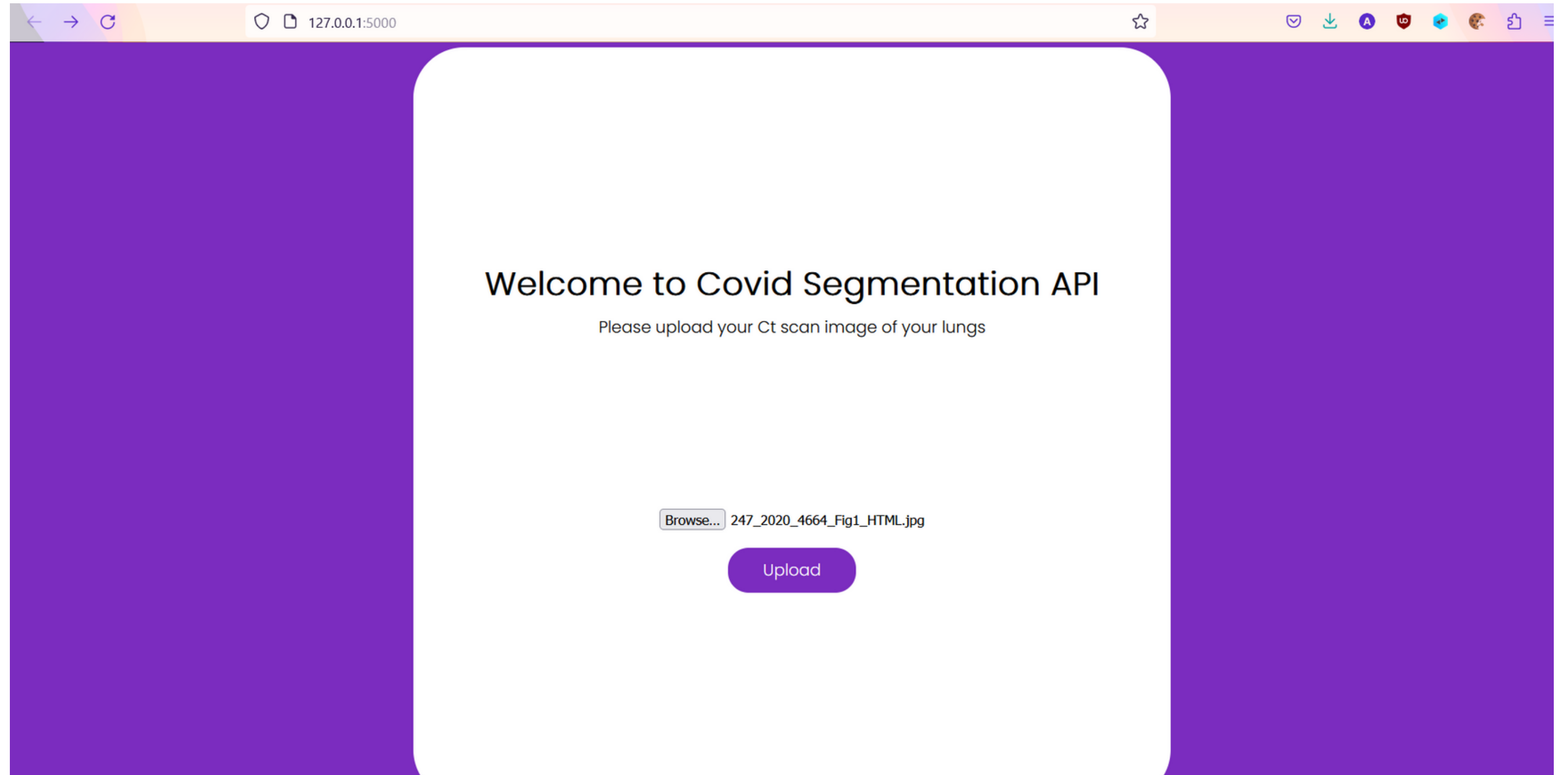
def index():
    return render_template('h.html')

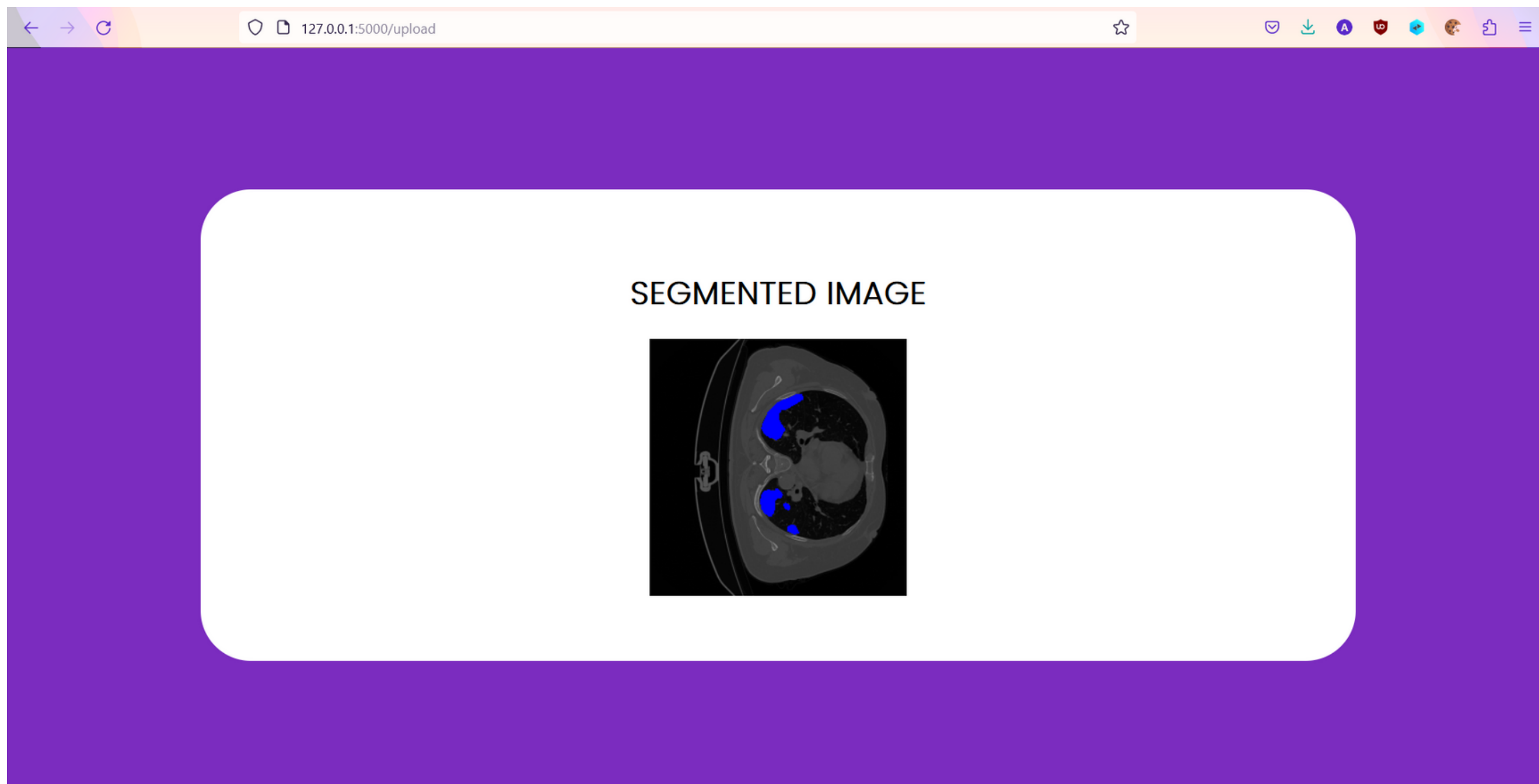
@app.route('/upload', methods=['GET', 'POST'])
def upload_file():
    if request.method == 'POST':
        uploaded_file = request.files['file']
        temp_file_path='D:\\downloads\\flsk\\static\\input.png'
        uploaded_file.save(temp_file_path)
        output= process_image(temp_file_path)

        return render_template('result.html',output='output.png')

app.run()
```

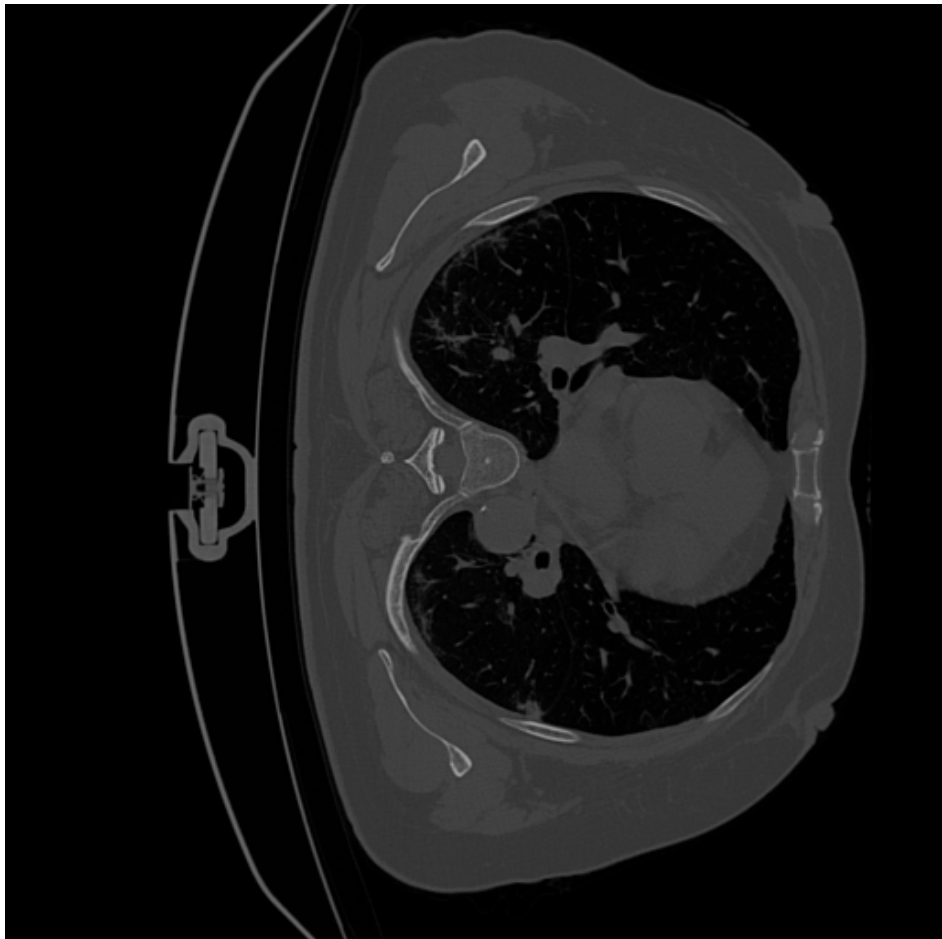
INTERFACE





Sample Test Data

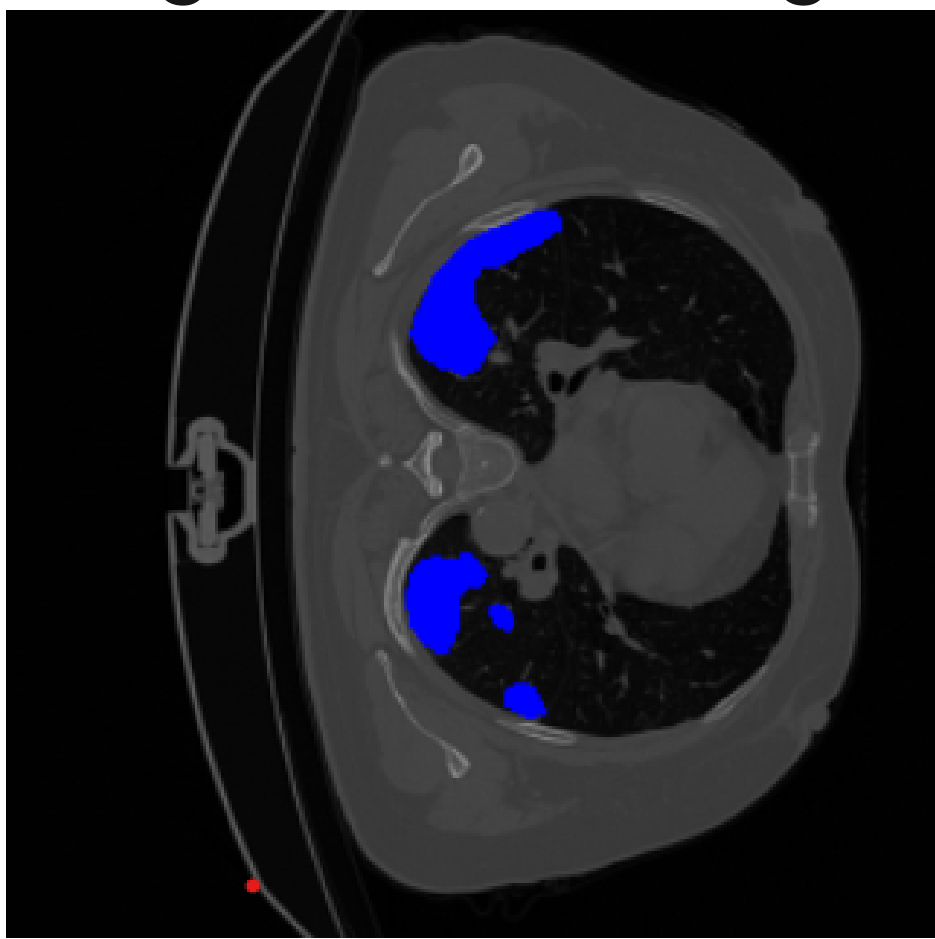
CT-Scan



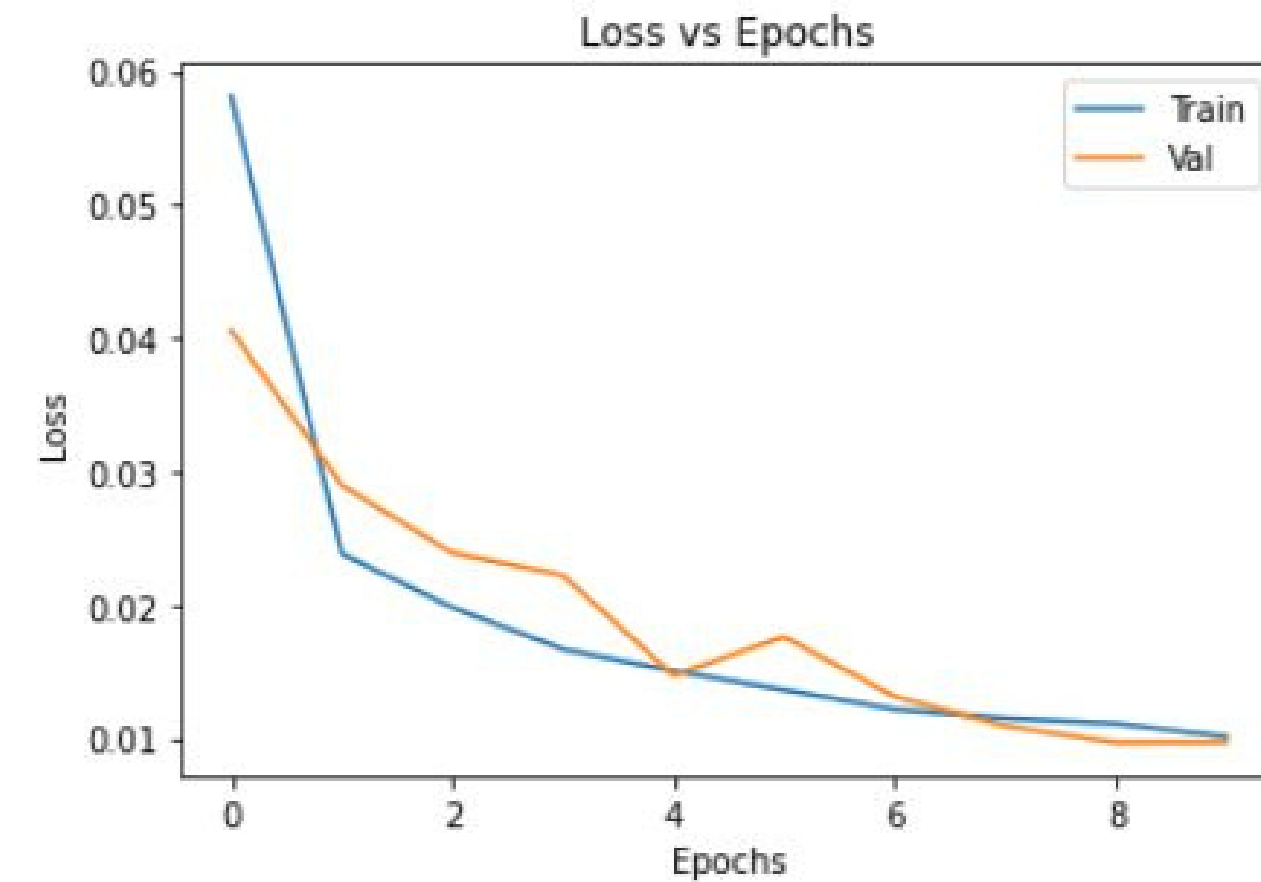
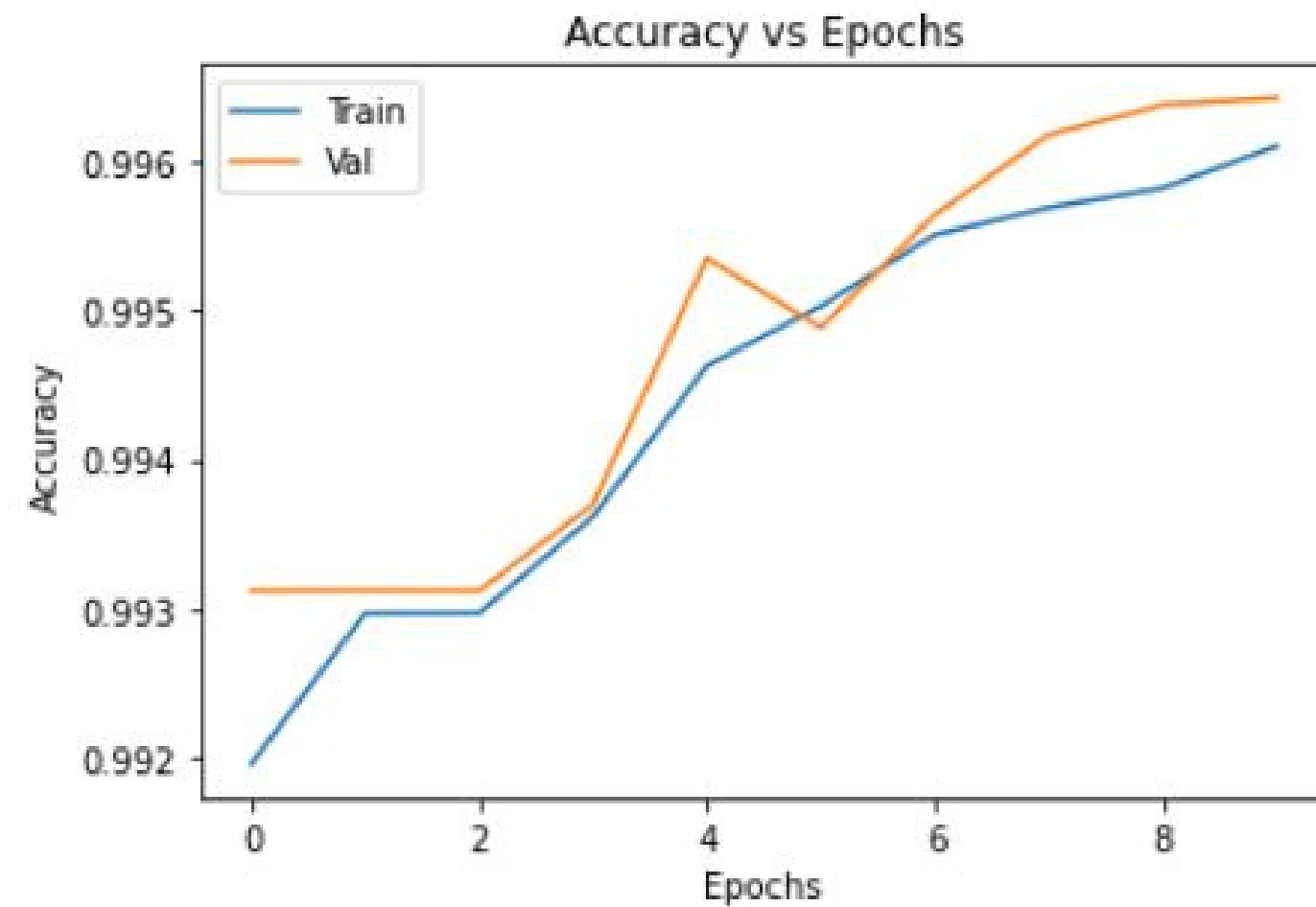
Mask



Segmented image



PERFORMANCE



- No overfitting is observed as the graphs align with each other and rise together.
- The training accuracy curve converges at 97% at 10 epochs.
- The validation accuracy reaches 95% at 10 epochs.

CONCLUSION

- The '**Covid-19 Segmentation API**' utilizes the U-net model to accurately segment COVID-19 infections.
- It provides a user-friendly interface for researchers and medical professionals to input COVID-19 images and obtain segmented results efficiently.
- It has the potential to be extended for segmenting other types of infections, making it valuable for medical research and diagnosis