

/xyz: 0.07 0.032 0.052 /xyz: 0.126 0 0 \

end_effector_joint

end_effector_link

rpy: 0 -0 0

rpy: 0 -0 0

camera_joint

camera_link

depth_camera_joint

depth_camera_bottom_screw_frame

depth_camera_link_joint

depth_camera_link

xyz: 0 -0.03 -0.02 rpy: 0 -0 0

xyz: 0.0106 0.0175 0.0125 rpy: 0 -0 0 xyz: 0.0817 0.021 0 \ xyz: 0.0817 -0.021 0

gripper_sub

gripper_link_sub

rpy: 0 -0 0

rpy: 0 -0 0

gripper

gripper_link