ECE 120 Midterm 3 Review

Topic Overview

- Finite State Machine

  - Analysis

  - FSM Design

  - Counter Design

- Memory

  - Flip Flops

  - RAM

  - Tri-State Buffer

Serialized Design:

Similar to Bit Slice Design, just change the way the output and input are delivered (store output to flip-flops), and you need 1 flip-flop per carry-bit.

FSM

FSM Knowledge

Three main components of FSM's:

- Next State Logic

- Current State

- Output Logic

How many bits are needed to represent N states in a standard FSM?

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How many bits are needed to represent N states in a standard FSM?

   Requires $\lceil log_2(N) \rceil$ bits to represent each state (ceiling / round up)

FSM (Lecture 19)

- Two types: Mealy and Moore
  - Moore: Outputs are based off of current state
  - Mealy: Outputs are based off of past state and current transition
  - Mealy uses less states, but possibly glitches
- Consist of five elements:
  - Finite number of states
  - Finite number of external inputs
  - Finite number of external outputs
  - Explicit number of state transitions
  - Explicit definition of what determines output values
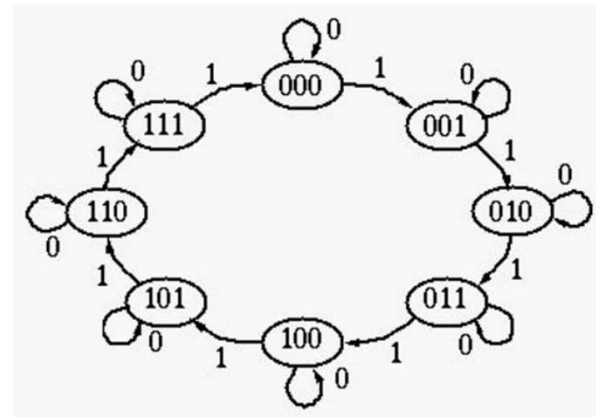
D Flip Flops

- Made from two D latches. Behavior of D latch
- D latch behavior
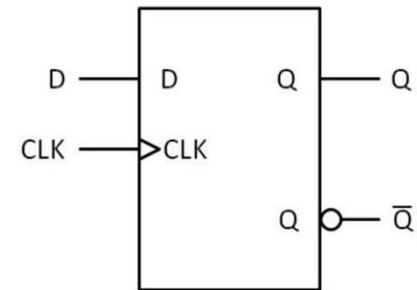
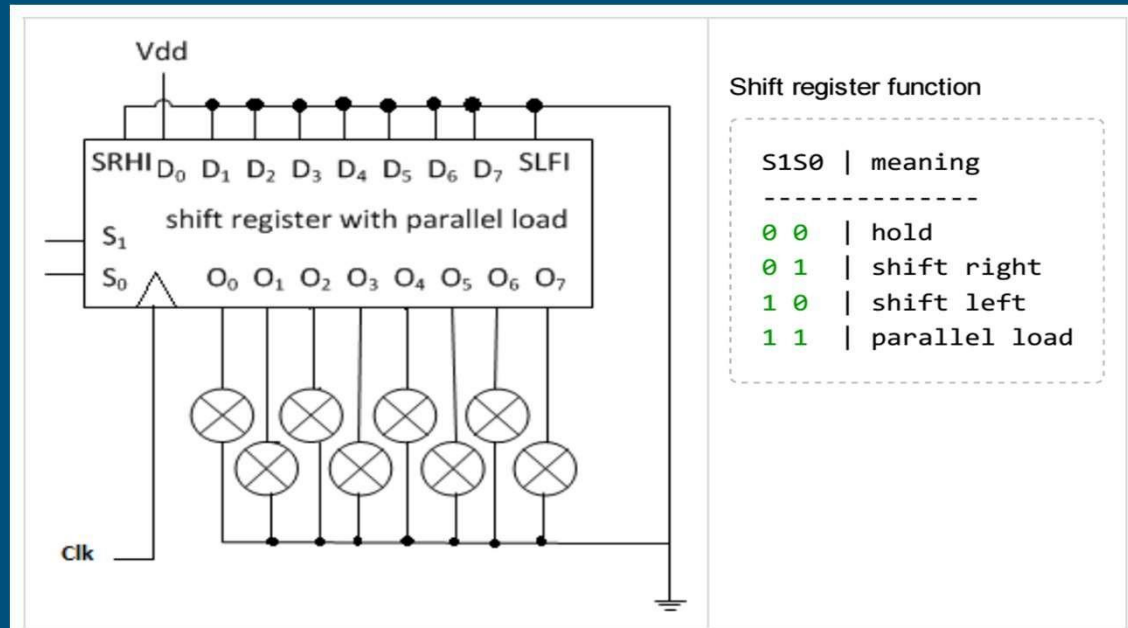| C	D	R	S	Q+	
1	0	1	0	0	Reset
1	1	0	1	1	Set
0	0	0	0	Q	No change
0	1	0	1	1	No Change

- D flip flop stores the input bit D

D	Q+
0	0
1	1

FSM Design


```
Shift register function

S1S0 | meaning
--------------
0 0  | hold
0 1  | shift right
1 0  | shift left
1 1  | parallel load
```

1. List all inputs to your FSM
2. LIst all outputs to your FSM
3. Draw the Moore FSM state diagram to control the shift register. Clearly mark state names, state outputs, and state transitions. Your design should use as few states as possible in order to receive full credit.

Optimized Boolean Expression

When you're trying to find the boolean expression for the outputs for an FSM or output logic,

Consider:
- Both POS and SOP form

- Try to see which of these expression minimizes the total number of gates/area

- Check HW and the solutions if you need to review this

  - HW 8 and 9!

Memory

Memory

Memory is an important concept in computing. Memory is the ability to store a value.

Memory has 3 basic parts to describe its structure:
Address: A unique identifier associated with each memory location. Addressability:

Number of bits in each location.

Address Space: The total number of uniquely identifiable memory locations. Notes:

1MB = 2^20, 1KB = 2^10
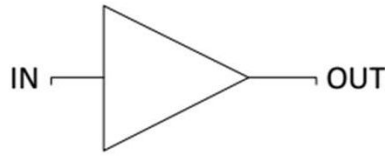
RAM

- Inputs:
    - **Addr** - Address to save data to
    - **Data** - Information to be saved
    - **CS** - "Enable bit", turns on RAM Chip
    - **R/W'** - Specifies whether or not you can write (R = 1, W = 0)
    - **Dout** - Output data
- Notes: 1M = 2^20 and 1K = 2^10

CS	R/W'	Operation
0	X	No operation
1	0	write
1	1	read
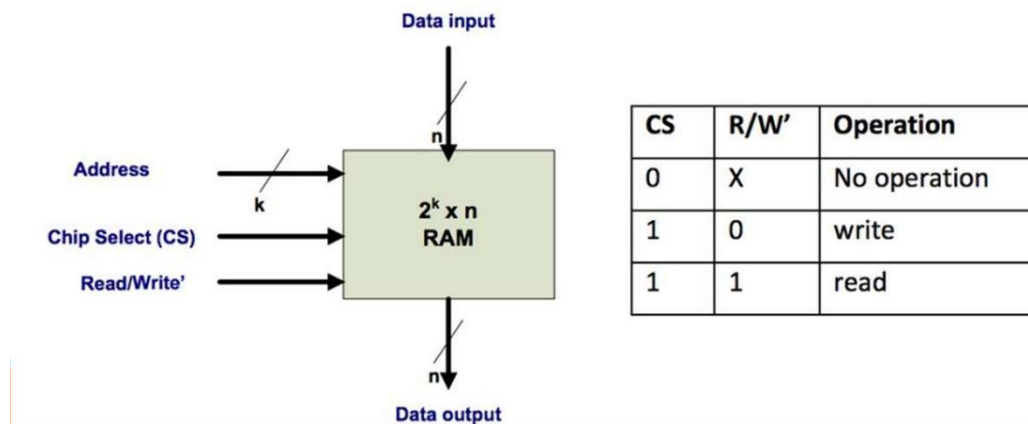
Tri-state buffer

- A *buffer* is a device that passes an input to its output

IN	OUT
0	0
1	1

- A *tri-state buffer* is a device with 3 output states: 0, 1, and 'Z' (high impendence)
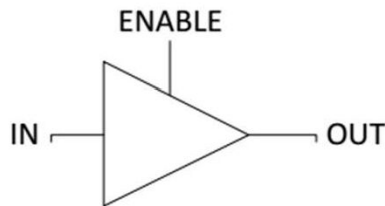
IN	E	OUT
0	1	0
1	1	1
X	0	Z

  o Z, or Hi-Z output means "Disconnected" - no output appears at all

ENABLE

  o We can build a tri-state buffer using just a few MOS FETs

Registers
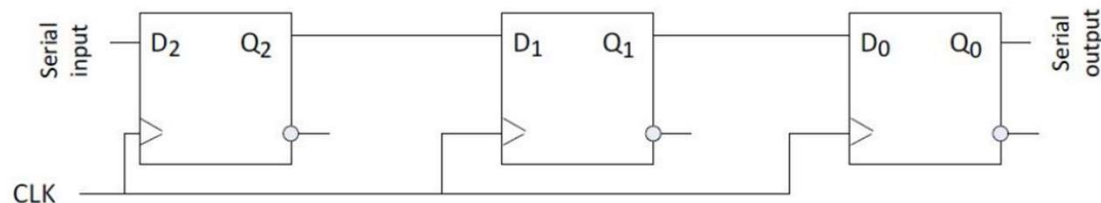
- Is group of flip flops to store information with inputs Common clock, load, clear
- Shift Registers
    - Data is entered one bit per clock cycle, data in flip flops are shifted in a direction
    - Left shift or right shift
    - Logical shift data is entered in the left or right flip flop
    - Circular shift the output is fed back as the input
    - Arithmetic left shift corresponds to multiply by 2. like logical but input is zero.
    - Arithmetic right shift corresponds to divide by 2
- Parallel Load registers
    - New bits for each flip flop is loaded all at the same time
    - Need load signal, data loaded when clock and load are both high

Using 1K x 8 RAM chips, implement a 32K x 16 RAM. Each 1K x 8 RAM chip has inputs **data**, **addr**, **CS**, and **r/w'** and an output gated by a tri-state buffer. Finish the implementation by drawing the missing connections and labeling all newly added wires. (You do not need to draw all the rows, they are shown as " ... ", but be sure the pattern is clear.) The RAM output wires and CS are already drawn for you.

$D_{out}[15:8]$ $D_{out}[7:0]$
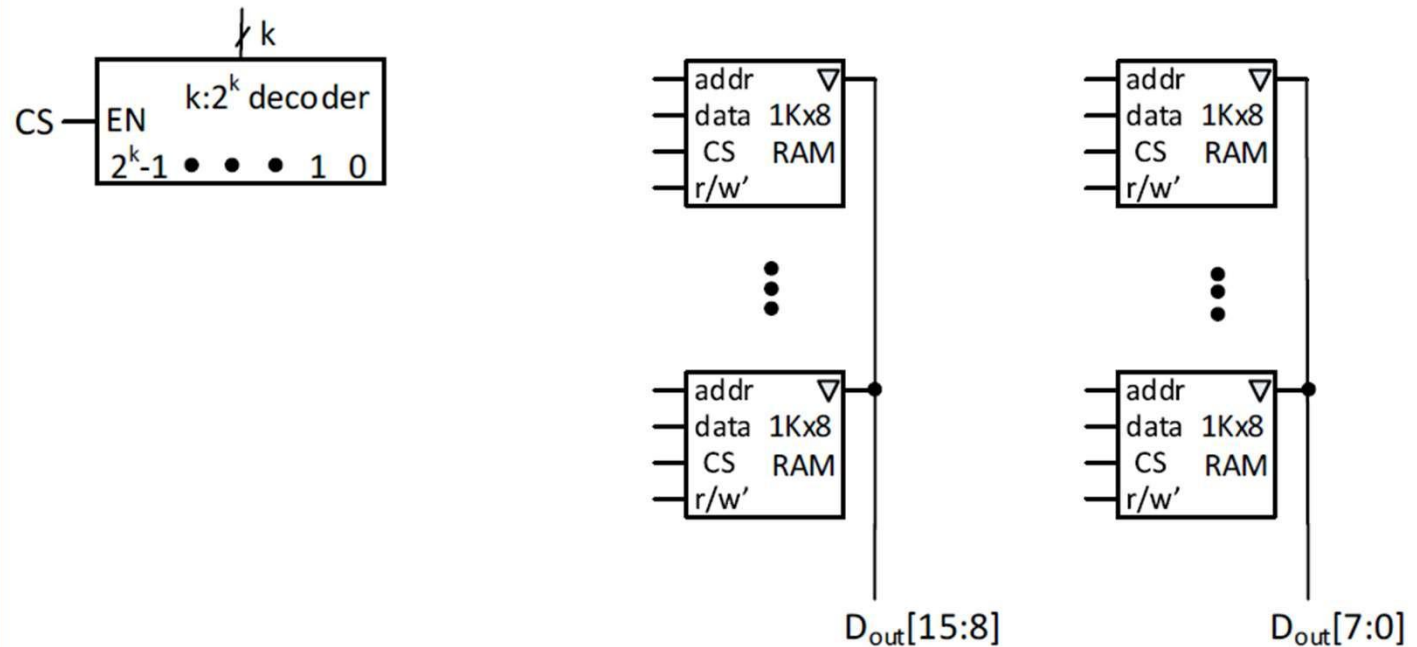
ECE 190: Problem 3 Memory

In this problem you will be working with 2x1-bit memory cells. Each cell stores 2 bits which can only be accessed one at a time. Which bit is accessed is determined by the address input to the memory cell. Given four 2x1-bit memory cells, build a 4x2-bit memory unit using only AND, OR, NOT gates and MUXes.

Individual Memory Cell
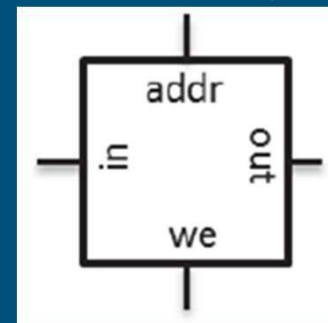
LC3

SPRING 2013 PROBLEM 7

Name all components of the Von Neumann architecture and briefly describe their function (101)

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    c. Input - means to enter data and program

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e. Control Unit - controls the order of instruction execution

SPRING 2013 PROBLEM 7

List all phases of the Von Neumann Instruction cycle (106)

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SPRING 2013 PROBLEM 7

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e. Execute - Instruction carried out   f. Store Result - Save into Memory

SPRING 2013 PROBLEM 7

Describe the purpose of the following registers in the Von Neumann Architecture:

a. PC - keeps track where the program is in memory (updated in fetch)

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    c.   MDR - acts like a buffer when we read/write from/to memory

SPRING 2013 PROBLEM 7

Describe the purpose of the following registers in the Von Neumann Architecture:

a. PC - keeps track where the program is in memory (updated in fetch)

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c. MDR - acts like a buffer when we read/write from/to memory

d. MAR - holds the address that you are accessing in memory

SPRING 2013 PROBLEM 7

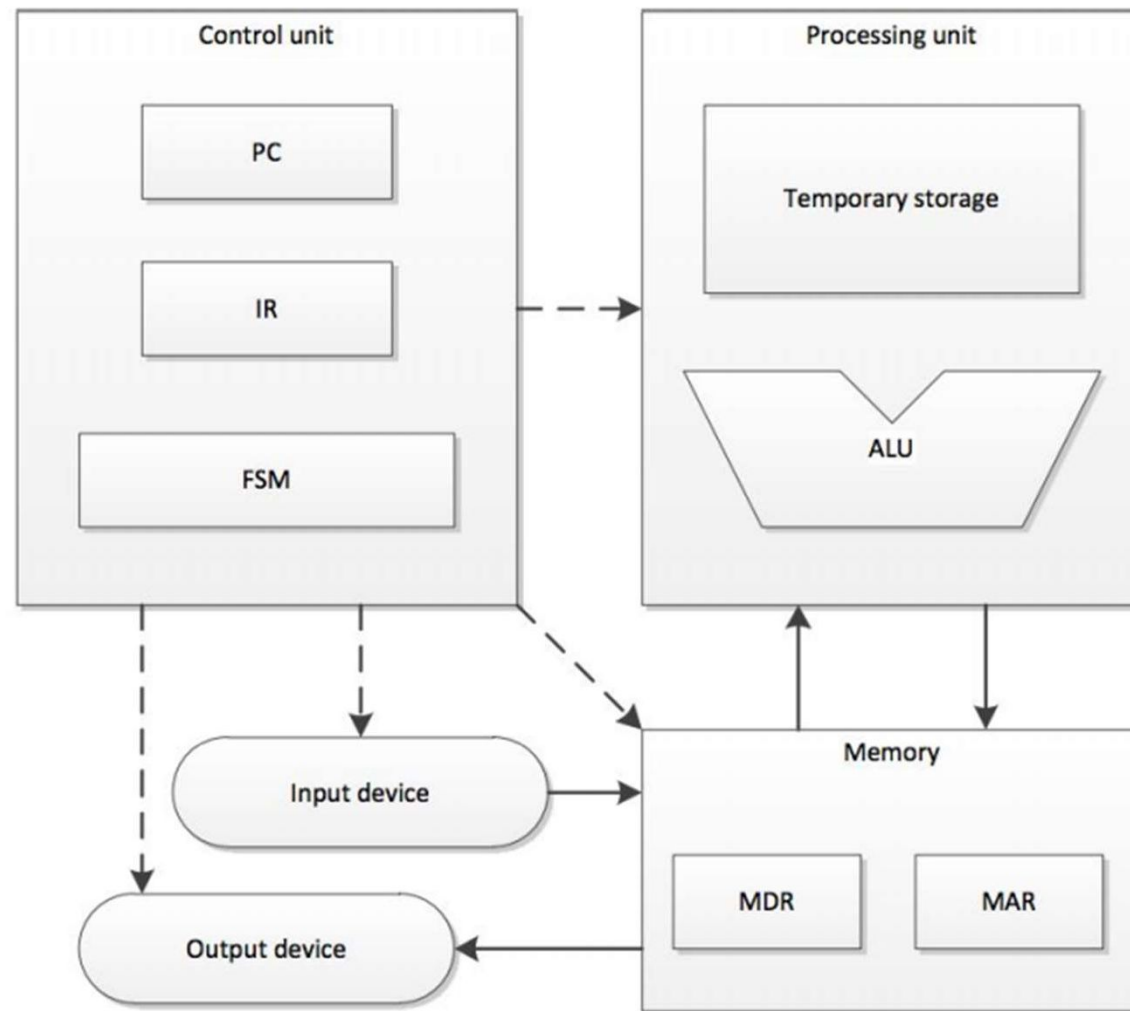Describe the purpose of the following registers in the Von Neumann Architecture:

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c. MDR - acts like a buffer when we read/write from/to memory

d. MAR - holds the address that you are accessing in memory

e. General-purpose register file - R0-R7

Von Neumann Architecture

SPRING 2016 PROBLEM 5

The following LC-3 program fragment, represented as four hexadecimal numbers, is stored in memory at the indicated locations and the following values are stored in registers:

Address	Instruction
x3FFF	xAFFE
x4000	x2001
x4001	x743F
x4002	x3002

Register	Value
R0	xF021
R1	xF023
R2	xF025
R3	xF027

Address	Instruction	Binary instruction	RTL (Be specific to this instruction)
x3FFF	xAFFE	1010 111 111111110	R7 ← M[M[PC − 2]] setcc
x4000	x2001		
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SPRING 2016 PROBLEM 5

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x4002	x3002	0011 000 000000010	

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x4000	x2001	0010 000 000000001	R0 ← M [PC+1] set cc
x4001	x743F	0111 010 000 111111	M [R0−1] ← R2
x4002	x3002	0011 000 000000010	M [PC +2] ← R0

2. (14 points) Assuming PC is initially set to x4000, trace the execution of the given program segment for **two** instruction cycles, filling in the table below. Write down the values stored in the PC, IR, MAR, MDR, R0, N, Z, and P registers **at the end of each instruction cycle**. Values for PC, IR, MAR, MDR, and R0 should be written in **hexadecimal**. Values for N, Z, and P should be written in **binary**.

PC	IR	MAR	MDR	R0	N	Z	P

Extra

Synchronization Problem

Draw a **datapath** (yes, only the datapath, not the FSM) of a circuit that adds two N-bit 2's complement binary numbers, A and B, stored in two N-bit right shift registers, R_A and R_B. Each shift register has serial output SO and serial input SI. Beginning with the least significant pair of bits in R_A and R_B, the circuit should add one pair at a time through a single fulladder (FA) circuit. The sum bit from the FA output should be stored back into shift register R_A.

Hint: You only need two N-bit shift registers, a single fulladder (FA) circuit, and a D flip-flop. Assume that the flip-flop starts in the 0 state.

Synchronization Solution

Data path for the serial adder