HKN ECE 210 Exam 3 Review Session

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Topics

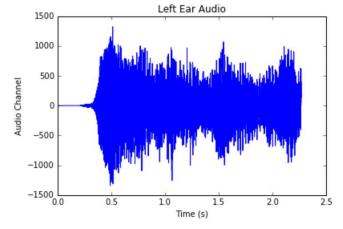
- Fourier Transform
- Signal Energy and Bandwidth
- LTI System Response with Fourier Transform
- Modulation, AM, Coherent Demodulation
- Impulse Response and Convolution
- Sampling and Analog Reconstruction
- LTIC and BIBO Stability

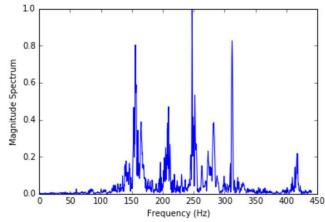
Fourier Transform

- The Fourier Transform of a signal shows the frequency content of that signal
 - In other words, we can see how much power is contained at each frequency for that signal
 - This is a big deal!
 - This is the <u>biggest deal!</u>

•
$$F(\omega) = \int_{-\infty}^{\infty} f(t)e^{-j\omega t}dt$$

•
$$f(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} F(\omega) e^{j\omega t} d\omega$$





Important Signals for Fourier Transform

$$rect\left(\frac{t}{T}\right) = \begin{cases} 1, for |t| < \frac{T}{2} \\ 0, for |t| > \frac{T}{2} \end{cases}$$

$$u(t) = \begin{cases} 0, for \ t < 0 \\ 1, for \ t > 0 \end{cases}$$

$$\Delta\left(\frac{t}{T}\right) = \begin{cases} 1 + \frac{2t}{T}, for \frac{-T}{2} < t < 0 \\ 1 - \frac{2t}{T}, for 0 < t < \frac{T}{2} \end{cases}$$

•
$$sinc(t) = \begin{cases} \frac{\sin(t)}{t}, for \ t \neq 0 \\ 1, for \ t = 0 \end{cases}$$

Fourier Transform Tips

- Convolution in the time domain is multiplication in the frequency domain
 - Conversely, multiplication in the time domain is convolution in the frequency domain
- Scaling your signal can force properties to appear; typically time delay
 - Ex: $e^{-2(t+1)}u(t-1) \to e^{-4}e^{-2(t-1)}u(t-1)$
- The properties really do matter! Take the time to acquaint yourself with them.
- Remember that the Fourier Transform is linear, so you can express a spectrum as the addition of two easier spectra
 - Ex: Staircase function
- Magnitude Spectrum is even symmetric, Angle Spectrum is odd symmetric for real valued signals

Signal Energy and Bandwidth

- Energy = $W = \int_{-\infty}^{\infty} |f(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |F(\omega)|^2 d\omega$
 - Energy signals can be either low-pass or band-pass signals
- Bandwidth for Low-pass Signals
 - 3dB BW
 - r% BW
 - $\frac{1}{2\pi} \int_{-\Omega}^{\Omega} |F(\omega)|^2 d\omega = rW$
- Bandwidth for Band-pass signals
 - r% BW
 - $\frac{1}{\pi} \int_{-\Omega}^{\Omega} |F(\omega)|^2 d\omega = rW$ notice that r% BW for Band-pass signals is twice that of low-pass signals!

LTI System Response using Fourier Transform

• Given the following LTI system:

$$f(t) \to H(\omega) \to y(t)$$

- $Y(\omega) = F(\omega)H(\omega)$
- Computationally speaking, and in future courses, we prefer to use Fourier Transforms instead of convolution to evaluate an LTI system
- Why?
 - So much faster, minimal error

Modulation, AM Radio, Coherent Demodulation

- Modulation Property
 - If $f(t) \leftrightarrow F(\omega)$, $f(t) \cos(\omega_o t) \leftrightarrow \frac{1}{2} [F(\omega \omega_o) + F(w + \omega_o)]$
- In general, for Amplitude Modulation in communications, we modulate with cosine in order to shift our frequency spectrum into different frequency bands
- Coherent Demodulation refers to the process of modulating a signal in order to make it band-pass, then modulating it back to the original low-pass baseband before low-pass filtering in order to recover the original signal
- Envelope detection is the process of Full-wave Rectification (absolute value), then low-pass filtering in order to extract the signal

Impulse Response and Convolution

- Convolution
 - $x(t) * y(t) = \int_{-\infty}^{\infty} x(\tau)y(t-\tau)d = \int_{-\infty}^{\infty} x(t-\tau)y(\tau)d$
 - We "flip and shift" one signal and evaluate the integral of the product of the two signals at any value of t (our delay for the shift)
- Representing LTI Systems
 - y(t) = x(t) * h(t), where h(t)i the **impulse response** of the system
- Impulse Response is the system output to a $\delta(t)$ input
- Graphical convolution helps to visualize the process of flipping and shifting

Helpful Properties for Convolution

- Derivative
 - $h(t) * f(t) = y(t) \to \frac{d}{dt}h(t) * f(t) = h(t) * \frac{d}{dt}f(t) = \frac{d}{dt}y(t)$
 - Use of Derivative property: Finding the impulse response from the unit-step response
 - If y(t) = u(t) * h(t), then $\frac{d}{dt}y(t) = \frac{d}{dt}u(t) * h(t) = \delta(t) * h(t) = h(t)$
- Start Point
 - If the two signals have start points at t_1 and t_2 , then the start point of their convolution will be at $t_1 + t_2$
- End Point
 - Similarly for the end points, if the two signals have end points at t_1 and t_2 , then the end point of their convolution will be at $t_1 + t_2$
- Width
 - From the above two properties, we can see that if the two signals have widths W_1 and W_2 , then the width of their convolution will be $W_1 + W_2$

The Impulse Function $\delta(t)$

- The impulse function is the limit of $\frac{1}{T}rect\left(\frac{t}{T}\right)as T \to 0$
 - Infinitesimal Width
 - Infinite Height
 - Of course, it integrates to 1. $(0 * \infty = 1)$
- Sifting
 - $\int_a^b \delta(t-t_o)f(t)d = f(t_o)$ if t_o lies in your limits of integrations; 0 else
- Sampling
 - $f(t)\delta(t-t_o) = f(t_o)\delta(t-t_o)$
- Unit-step derivative
 - $\frac{du}{dt} = \delta(t)$

Sampling and Analog Reconstruction

- If we have an original analog signal f(t)
- Our digital samples of the signal are obtained through sampling property as:
 - f[n] = f(nT) where T is our sampling period; this is Analog to Digital (A/D) conversion
- We must make sure to satisfy Nyquist Criterion:
 - $T < \frac{1}{2B} \text{ or } f_S > 2B$
 - To learn more about Nyquist Criterion take ECE 110!

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 - Jk take ECE 310

Sampling and Analog Reconstruction

- If we have an original analog signal $\bar{f}(t)$
- Our digital samples of the signal are obtained through sampling property as:
 - f[n] = f(nT) where T is our sampling period; this is Analog to Digital (A/D) conversion
 - This results in infinitely many copies of the original signal's Fourier Transform spaced by $\frac{2\pi}{T}$
- We must make sure to satisfy Nyquist Criterion:
 - $T < \frac{1}{2B} \text{ or } f_S > 2B$
 - To learn more about Nyquist Criterion take ECE 110!
 - Jk take ECE 310
- Following A/D conversion, we perform D/A conversion, then low-pass filter our signal in order to obtain our original signal according to the following relation
- $f(t) = \sum_{n} f_n sinc(\frac{\pi}{T}(t nT))$
- For a more complete explanation, take ECE 310!

LTIC

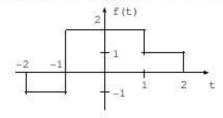
- LTIC stands for Linearity Time-Invariance and Causality (sometimes called LSIC, where SI means Shift-Invariance)
- Linearity
 - Satisfy Homogeneity and Additivity
 - Can be summarized by Superposition
 - If $x_1(t) \to y_1(t)$ and $x_2(t) \to y_2(t)$, then $ax_1(t) + bx_2(t) \to ay_1(t) + by_2(t)$
- Shift Invariance
 - If $x(t) \rightarrow y(t)$ then $x(t t_o) \rightarrow y(t t_o) \forall t_o$ and x(t)
- Causality
 - Output cannot depend on future input values

BIBO Stability

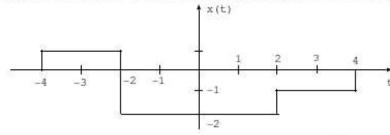
- A system is BIBO stable if for any bounded input, we obtain a bounded output
- Two ways to check BIBO stability
- By the definition:
 - If $|f(t)| \le \alpha < \infty$, then $|y(t)| \le \beta < \infty \ \forall \ t$
- By Absolute Integrability
 - $\int_{-\infty}^{\infty} |h(t)| d < \infty$

Problem 1 FA13

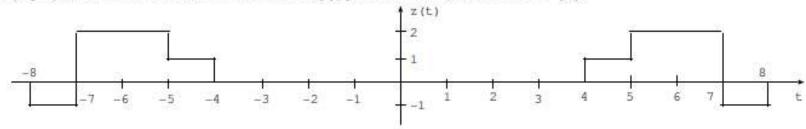
1. (10 pts) Let f(t), plotted below, have Fourier transform $F(\omega)$.



(a) (4 pts) Obtain the Fourier transform of x(t), plotted below, in terms of $F(\omega)$.

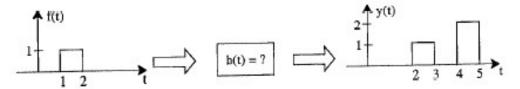


(b) (6 pts) Obtain the Fourier transform of z(t), plotted below, in terms of $F(\omega)$.

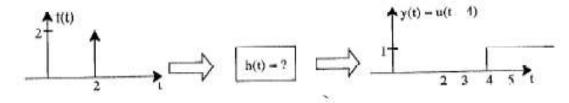


Problem 5 FA13

- 5. (8 pts) The two parts of this problem deal with impulse response, causality and BIBO stability.
 - (a) (4 pts) The figure below depicts a LTI system. Input signal f(t) produces the corresponding output y(t).



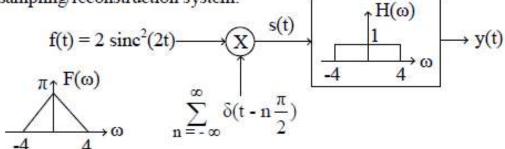
(b) (4 pts) The figure below depicts a LTI system. Input signal f(t) produces the corresponding output y(t).



- a)i. Determine h(t)
 - ii. Is the system causal?
- iii. Is the system BIBO stable?
- b)i. Determine h(t)
- ii. Is the system causal?
- iii. Is the system BIBO stable?

Problem 2 SP16

) Consider this sampling/reconstruction system.



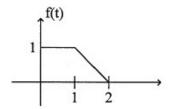
- i) Circle the correct answer and explain it below.
 - f(t) is: UNDERSAMPLED / OVERSAMPLED / SAMPLED AT NYQUIST RATE

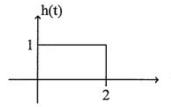
Explanation:

- ii) Sketch $S(\omega)$ and $Y(\omega)$ on the axes below.
- iii) Determine y(t)

Problem 2 SP16

(a) For h(t) and f(t) shown below, compute the specified values for y(t) = f(t) * h(t)





$$y(4.5) =$$

(b) Let $h(t) = e^{-2t}u(t)$ and f(t) = u(t-4). Find y(t) = f(t) * h(t) for all values of t.

Problem 3 SP14

(a) An impulse response is given by

$$\mathbf{h}(\mathbf{t}) = \mathbf{rect}\left(\frac{\mathbf{t} - 1}{2}\right) \mathbf{e}^{-\mathbf{t}}$$

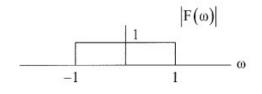
- i) Find the Fourier transform of h(t).
- ii) If the input is $f(t) = 2rect\left(\frac{t}{2}\right)$, find the output y(t) = f(t) * h(t).
- iii) If the input is $f(t) = \frac{1}{a} rect(at)$, find the output y(t) = f(t) * h(t), when $a \to o$.

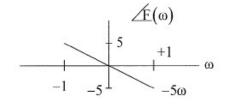
Problem 1 FA15

a) Find the Fourier transform $F(\omega)$ and the energy of the following signal f(t).

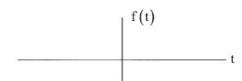
$$f(t) = [u(t-1)-u(t-3)]e^{-t}$$

b) Fourier transform of a signal f(t) is given as





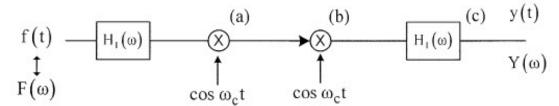
i) Find the inverse Fourier transform f(t). Simplify your answer. Sketch f(t), label axis carefully.



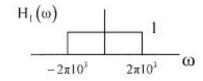
ii) Find the 90% energy bandwidth of f(t).

Problem 2 FA15

Consider the following system



where f(t) = rect($\frac{t}{\tau}$), $\tau = 10^{-3}$ sec, $\omega_c = 2\pi 10^6$ rad/sec and



a) What is $F(\omega)$? Label axis carefully.

$$F(\omega) =$$
 _____(5 points)

b) Draw the signal spectrum at points, (a), (b) and (c). Label axis carefully.

Problem 1 SP16

- Consider a real-valued function f(t) with bandwidth Ω and let $\omega_c > \Omega$. Obtain the bandwidth of the following functions All answers may be left in terms of Ω and ω_c .
- (a) $g_1(t) = f(t) \sin(\omega_c t)$
- (b) $g_2(t) = f(t) + \sin(\omega_c t)$
- (c) $g_3(t) = f(t) \sin^2(\omega_c t)$
- (d) $g_4(t) = f^2(t) \sin(\omega_c t)$
- (e) $g_5(t) = f(t) * \sin(\omega_c t)$

Problem 2 SP16

(a) Let $y_1(t) = 2tu(t)$. Obtain and simplify $\frac{d}{dt}y_1(t)$.

$$\frac{d}{dt}y_1(t) = \underline{\hspace{1cm}}$$

(b) Let $f_2(t) = e^{-2t}u(t)$. Obtain and simplify $y_2(t) = \int_{-5}^5 f_2(\tau)\delta(4+\tau)d\tau$.

$$y_2(t) =$$

(c) Let $f_3(t)=u(t-1)$ and $y_3(t)=f_3(t)*h_3(t)=rect\left(\frac{t}{2}-3\right)$. Obtain and simplify $h_3(t)$.