

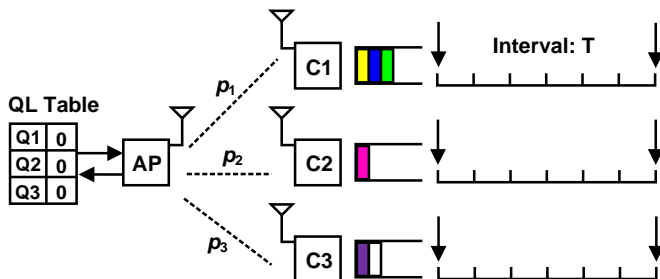
# Scheduling for Uplink Transmissions with Point Coordination Function

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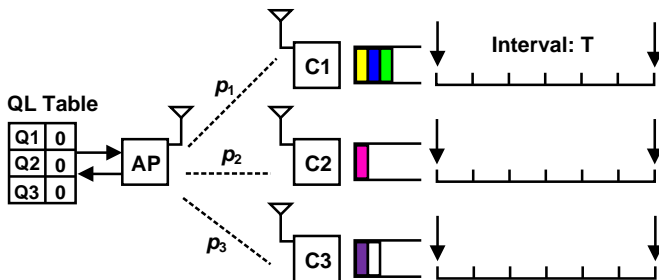
# Uplink Transmissions

- One AP and  $N$  clients
- 1 slot = 10ms; 1 interval =  $T$  slots
- Packets generated in the beginning of each interval
- Number of packets follows  $\text{Unif}\{N_{\min}, N_{\max}\}$
- Real-time and non-real-time traffic



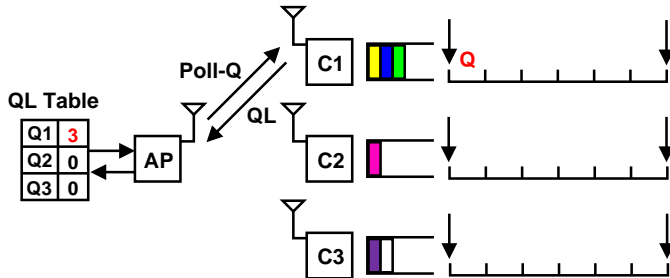
## Baseline Policy - A Toy Example

- $N = 3$  and  $T = 6$
- $p_1 = p_2 = p_3 = 0.5$
- Real-time traffic
- $X_n(k)$  = queue length at the start of the  $k$ -th interval



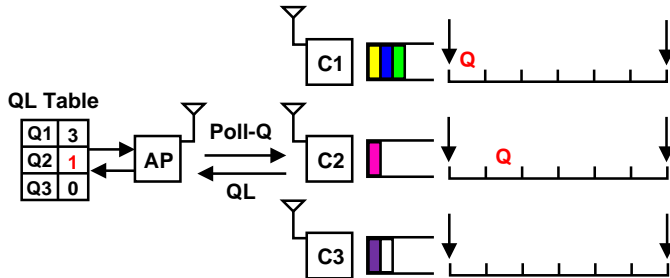
# Baseline Policy - A Toy Example

- Phase 1: AP polls  $X_n$  in a round-robin manner



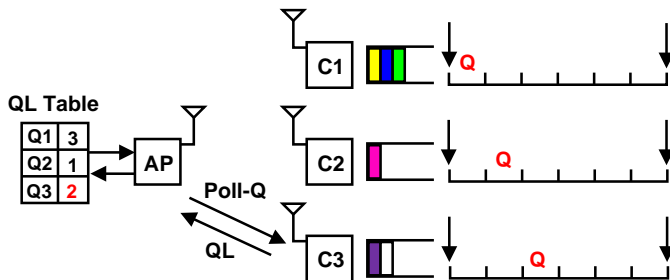
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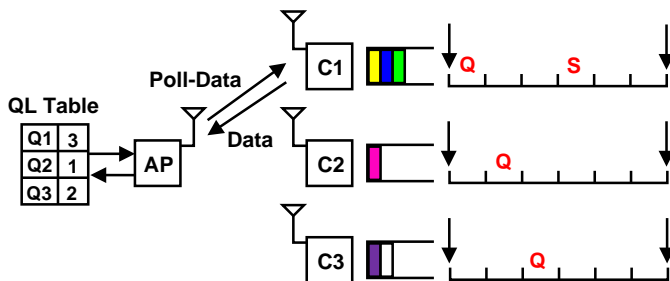
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- Phase 1: AP polls  $X_n$  in a round-robin manner



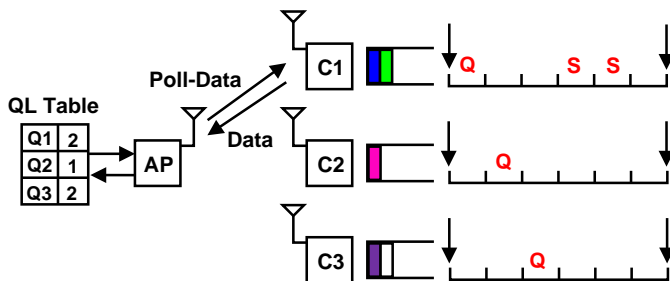
# Baseline Policy - A Toy Example

- Phase 2: AP schedules a client based on Max-Weight policy
- Max-Weight: select the client that maximizes  $p_n X_n$



# Baseline Policy - A Toy Example

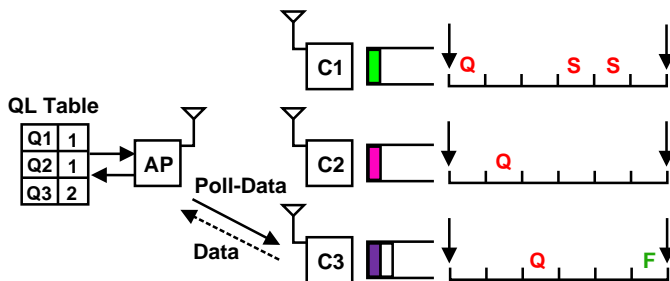
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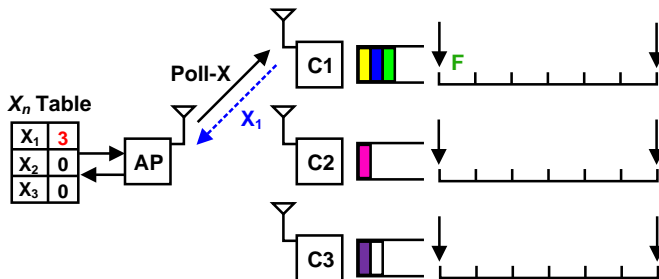
# Baseline Policy - A Toy Example

- Phase 2: AP schedules a client based on Max-Weight policy
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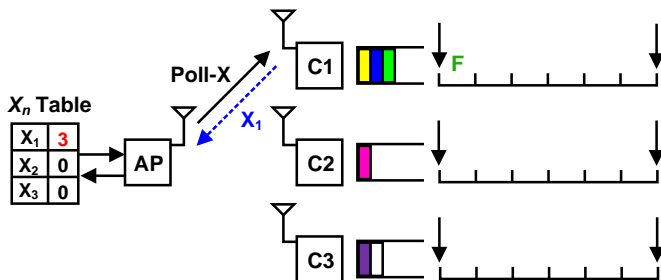
# Discussion 1

- What if Poll-X or  $X_1$  is not delivered?



# Discussion 1

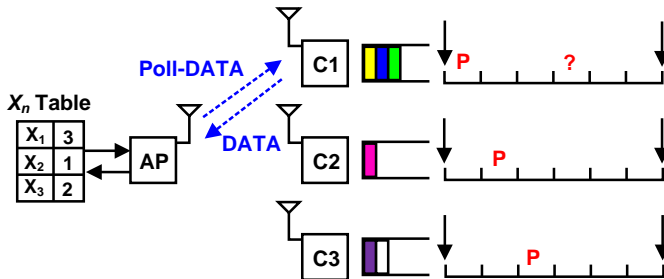
- What if Poll-X or  $X_1$  is not delivered?



- Re-transmit Poll-X until the AP receives  $X_n$
- Option: just set  $X_n = 0$

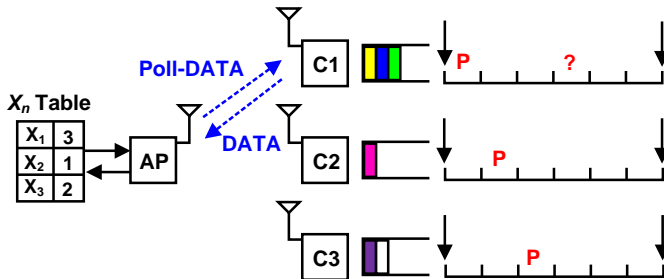
## Discussion 2

- How does a client know the DATA packet is delivered?
- Do we need an application-layer "ACK" for AP?



## Discussion 2

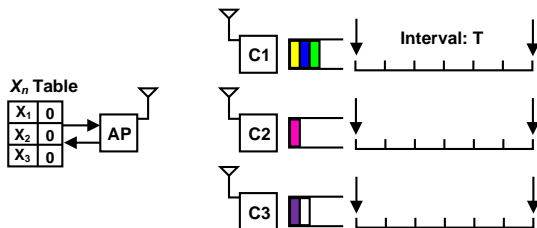
- How does a client know the DATA packet is delivered?
- Do we need an application-layer "ACK" for AP?



- Put "expected packet ID" in Poll-DATA packets

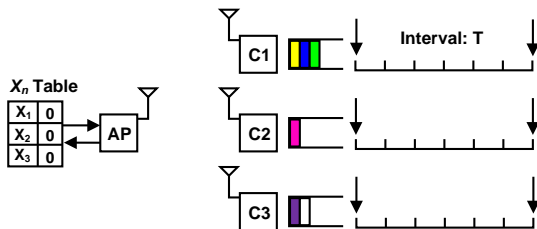
## Discussion 3

- For non-real-time traffic, what does " $X_n$ " mean?
- There is no application-layer ACK from AP



## Discussion 3

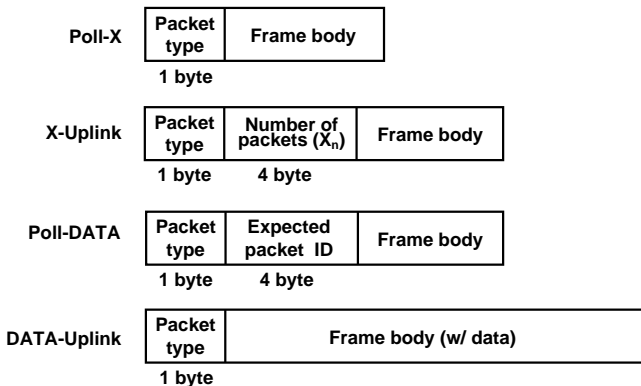
- For non-real-time traffic, what does " $X_n$ " mean?
- There is no application-layer ACK from AP



- $X_n :=$  total number of packets generated by client  $n$
- $Y_n :=$  total delivery of data packets from client  $n$  (maintained by AP)
- Max-Weight: choose  $n$  that maximizes  $p_n(X_n - Y_n)$

## NS-2 Implementation: Packet Types

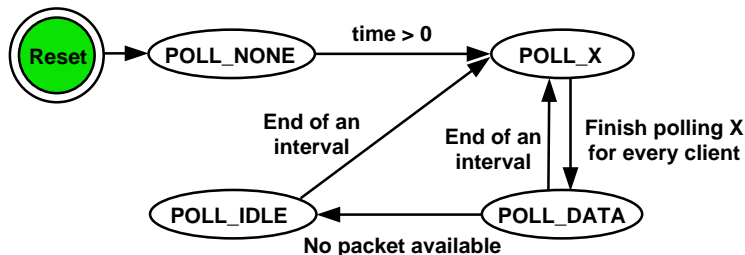
- AP: Poll-X and Poll-DATA
- Client: X-Uplink and DATA-Uplink





# NS-2 Implementation: State Machine

- AP is controlled by the state machine as follows.



# Pros and Cons

## Pros:

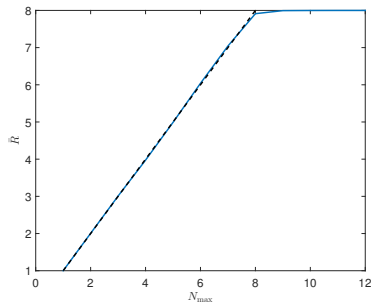
- Simple polling scheme
- AP is work-conserving in phase 2

## Cons:

- Overhead due to polling
- Channel utilization for data packets is low
- Not practical when  $N$  is large

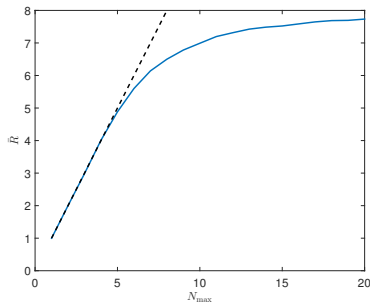
# Simulation Results

- $N = 2$  and  $T = 10$
- Reliable channel:  $p_1 = p_2 = 1$  (symmetric)
- $N_{\max}$  ranges from 1 to 12
- Non-real-time traffic



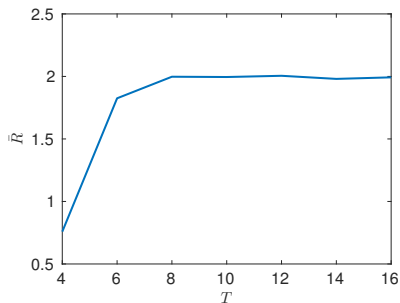
# Simulation Results

- $N = 2$  and  $T = 10$
- Reliable channel:  $p_1 = p_2 = 1$  (symmetric)
- $N_{\max}$  ranges from 1 to 20
- Real-time traffic



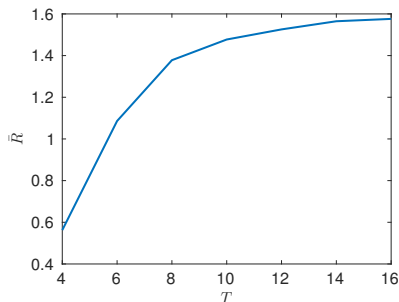
# Simulation Results

- $N = 2$
- Unreliable channel:  $p_1 = p_2 \approx 0.57$  (distance 1000 m)
- $T$  ranges from 4 to 16
- Non-real-time traffic



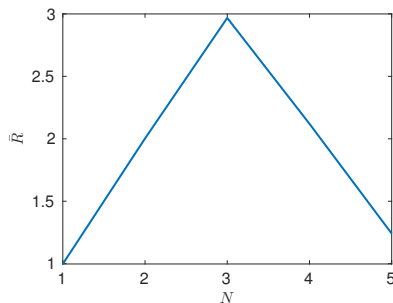
# Simulation Results

- $N = 2$
- Unreliable channel:  $p_1 = p_2 \approx 0.57$  (distance 1000 m)
- $T$  ranges from 4 to 16
- Real-time traffic



# Simulation Results

- Fix  $T = 10$
- Unreliable channel:  $p_1 = p_2 \approx 0.57$  (distance 1000 m)
- $N$  ranges from 1 to 5
- Non-real-time traffic



# Simulation Results

- Fix  $T = 10$
- Unreliable channel:  $p_1 = p_2 \approx 0.57$  (distance 1000 m)
- $N$  ranges from 1 to 5
- Real-time traffic

