FTDI Chip Commands

Introduction

The following list is of FTDI-specific commands sent via the ioctl system call to the USB driver. The usb_control_msg routine of libusb wraps these commands into the correct ioctl format. The 7 parameters of the usb_control_msg are:

```
struct usb_device
                                    The particular USB device to talk with
1-byte request type
                                    Read (0xC0), Write(0x40), or read and write
1-byte command
                                    Defined by FTDI firmware
                                    Defined by FTDI firmware
2-byte Value
2-byte Index
                                    Defined by FTDI firmware
                                    Defined by FTDI firmware
pointer to data structure
2-byte size of data structure
                                    sizeof(data structure)
Timeout
                                    read or write Timeout (5000 milliseconds is typical)
```

These are the command messages issued by libftdi routines:

```
reset:
                   usb_control_msg(ftdi->usb_dev, 0x40, 0x00,
                                                                           Index,
                                                                                            NULL, 0, Timeout)
purge RX buffer:
                  usb_control_msg(ftdi->usb_dev, 0x40, 0x00,
                                                                           Index,
                                                                                            NULL, 0, Timeout)
                  usb_control_msg(ftdi->usb_dev, 0x40, 0x00,
purge TX buffer:
                                                                           Index,
                                                                                            NULL, 0, Timeout)
setflowctrl:
                   usb_control_msg(ftdi->usb_dev, 0x40, 0x01,
                                                               Value,
                                                                           Index,
                                                                                            NULL, 0, Timeout)
                        Value encodes cc parameters, etc. (See ftdi_sio.c in Linux Kernel for details.)
                        Index encodes the following flow control options:
                                Disable flow control on Channel A
                         0x01
                                Disable flow control on Channel B
                         0x10
                                Set RTS/CTS flow control on Channel A
                          0x11
                                Set RTS/CTS flow control on Channel B
                                Set DTR/DSR flow control on Channel A
                         0x21
                                Set DTR/DSR flow control on Channel B
                          0x40
                                Set XON/XOFF flow control on Channel A
                                Set XON/XOFF flow control on Channel B
set DTR:
                   usb_control_msg(ftdi->usb_dev, 0x40, 0x02,
                                                                                            NULL, 0, Timeout)
                                                               Value, Interface,
                        Value is 0x10 to set DTR Low, 0x11 to set DTR High
                        Interface is 0 for Channel A, 1 for Channel B
set RTS:
                   usb_control_msg(ftdi->usb_dev, 0x40, 0x02, Value, Interface,
                                                                                            NULL, 0, Timeout)
                        Value is 0x20 to set RTS Low, 0x21 to set RTS High
                        Interface is 0 for Channel A, 1 for Channel B
set baudrate:
                   usb_control_msg(ftdi->usb_dev, 0x40, 0x03,
                                                               Value,
                                                                                            NULL, 0, Timeout)
                                                                           Index,
                        Value and Index combined encode the divisor and output channel.
                               (See ftdi_convert_baudrate for details.)
set line property: usb_control_msg(ftdi->usb_dev, 0x40, 0x04,
                                                               Value, Interface,
                                                                                            NULL, 0, Timeout)
                        Value encodes the number of data bits, stop bits and parity.
                                     Number of data bits
                         Bits 8-10: Parity: NONE=0x00, ODD=0x01, EVEN=0x02, MARK=0x03, SPACE=0x04
                          Bits 11-12: Stop bits: STOP_BIT_1=0x00, STOP_BIT_15=0x01, STOP_BIT_2=0x02
                        Interface is 0 for Channel A, 1 for Channel B
get modem status: usb_control_msg(ftdi->usb_dev, 0xC0, 0xO5, Value, Interface, (char *)&Value, 0, Timeout)
                        Value is returned with the following bits set:
                          Bit 4:
                                      CTS state
                         Bit 5:
                                     DSR state
                         Bit 6:
                                     RI state
                                     RLSD state
                        Interface is 0 for Channel A, 1 for Channel B
                   usb_control_msg(ftdi->usb_dev, 0x40, 0x06,
set event char:
                                                               Value, Interface,
                                                                                           NULL, 0, Timeout)
                        Value encodes the event character and whether it is to be used:
                          Bits 0-7: Event character
                          Bit 8:
                                     Event character enabled=1, disabled=0
```

Interface is 0 for Channel A, 1 for Channel B set error char: usb_control_msg(ftdi->usb_dev, 0x40, 0x07, Value, Interface, NULL, 0, Timeout) Value encodes the error character and whether it is to be used: Bits 0-7: Error character Bit 8: Error character enabled=1, disabled=0 set latency time: usb_control_msg(ftdi->usb_dev, 0x40, 0x09, Value, Interface, NULL, 0, Timeout) Value has the latency time with Value between 1 and 255 milliseconds.) Interface is 0 for Channel A, 1 for Channel B get latency time: usb_control_msg(ftdi->usb_dev, 0xC0, 0x0A, 0, Interface, (char *)&Value, 1, Timeout) The current latency time will be placed in Value. Interface is 0 for Channel A, 1 for Channel B enable bitbang: usb_control_msg(ftdi->usb_dev, 0x40, 0x0B, Value, Index, NULL, 0, Timeout) Value encodes the bitmask and bitbang mode (1=normal, 2=SPI bitbang mode). Index encodes channel (1 = Channel A, 2 = Channel B) disable bitbang: usb_control_msg(ftdi->usb_dev, 0x40, 0x0B, Index, NULL, 0, Timeout) Index encodes channel (1 = Channel A, 2 = Channel B) set bitmode: usb_control_msg(ftdi->usb_dev, 0x40, 0x0B, Value, NULL, 0, Timeout) Value encodes the bitmask in bits 0-7 and MPSSE bitmode in bits 8-12. The bitmode bits are: 0x00 Reset I/O Bit Mode 0x01 Asynchronous Bit Bang Mode 0x02 Multi-Protocol Synchronous Serial Engine Mode 0x04 Synchronous Bit Bang Mode 0x08 MCU Host Bus Emulation Mode 0x10 Fast Opto-Isolated Serial Interface Mode Index encodes channel (1 = Channel A, 2 = Channel B) read pins: usb_control_msg(ftdi->usb_dev, 0xC0, 0x0C, Index, (char *)&Value, 1, Timeout) Index encodes channel (1 = Channel A, 2 = Channel B) The bits of Value will contain the pin settings. read eeprom: usb control msg(ftdi->usb dev, 0xC0, 0x90, i, eeprom+(i*2), 2, Timeout)

Called for each byte pair read from EEPROM. Results put in the 128-byte eeprom string.

NULL, 0, Timeout) write eeprom: usb_control_msg(ftdi->usb_dev, 0x40, 0x91, Value, i,

Called for each byte pair to be written to EEPROM address i. Value contains the pair of bytes starting at EEPROM address i.

usb_control_msg(ftdi->usb_dev, 0x40, 0x92, NULL, 0, Timeout) erase eeprom:

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Contact Craig Van Degrift if you have problems or questions with this web site.