## Computational Methods and Modelling

## Antonio Attili & Edward McCarthy

antonio.attili@ed.ac.uk ed.mccarthy@ed.ac.uk

School of Engineering University of Edinburgh United Kingdom

Solution tutorial 8 Solution of a system of differential equations



## Python code for the solution

► The complete code is available on Learn in the file solve\_ivp\_system\_Lorenz.py.

```
Lorenz
# importing modules
                                                             return [f 1 , f 2, f 3]
import numpy as np
import matplotlib.pvplot as plt
                                                          # initial conditions
import math
                                                         \mathbf{v} \cap = 0
from scipy, integrate import solve ivp
                                                         v0 1 = 5
# -----
                                                         v0 2 = 5
# functions that returns du/dx
                                                         v0 3 = 5
# i.e. the equation we want to solve:
                                                          # total solution interval
def model(x,v):
                                                         t final = 30
   sigma = 10.0
                                                          # step size
   beta = 8.0/3.0
                                                          # not needed here. The solver solve_ivp
                                                          # will take care of finding the appropriate step
   rho = 28.0
   #rho = 10.0
   v_1 = v[0]
                                                          # Apply solve_ivp method
                                                         t_eval = np.linspace(0, t_final, num=5000)
   v_2 = v[1]
   y_3 = y[2]
                                                         y = solve_ivp(model, [0 , t_final] ,
   f_1 = sigma * (v_2-v_1)
                                                                 [y0_1 , y0_2, y0_3],t_eval=t_eval)
   f_2 = rho * v_1 - v_2 - v_1 * v_3
   f_3 = -beta * v_3 + v_1 * v_2
```

- ► The output y of y = solve\_ivp(...) is a data structure that contains several variables including
  - y.t containing the time instants at which the solution has been stored
  - y.y containing a 2D array with the solution. The first index of the array indicates the component of the solution (y<sub>1</sub> y<sub>2</sub> y<sub>3</sub>), while the second index is the time instant. So y.y[0,:] is the full solution for the first variable y<sub>1</sub>.

## Python code for the solution

 The plots can easily done with the code below (also included on Learn in the file solve\_ivp\_system\_Lorenz.py)

```
Lorenz
                                                            plt.ylabel('y_2')
# plot results
plt.figure(1)
plt.plot(y.t,y.y[0,:], 'b-',y.t,y.y[1,:]
        , 'r-', v.t, v. v[2,:], 'g-')
                                                            # plot results
plt.xlabel('t')
                                                            plt.figure(3)
plt.ylabel('y_1(t), y_2(t), y_3(t)')
                                                           plt.plot(y.y[0,:],y.y[2,:],'-')
                                                            plt.xlabel('v 1')
                                                            plt.vlabel('v 3')
# plot results
plt.figure(2)
plt.plot(y.y[0,:],y.y[1,:],'-')
                                                            plt.show()
plt.xlabel('y_1')
```

Plots of the solution for  $\sigma=10;\ \beta=8/3;\ \rho=28$  (top) and  $\sigma=10;\ \beta=8/3;\ \rho=10$  (bottom).











