

ED - 2 MIDTERM EXAM
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Problem: 7

a. The Lagrangian density of the field is given by:

$$\mathcal{L} = -\frac{1}{16\pi} F_{\mu\nu} F^{\mu\nu} - \frac{1}{c} J_\alpha A^\alpha$$

$$-\frac{1}{16\pi} g_{\mu\nu} g_{\rho\sigma} (\partial^\mu A^\sigma - \partial^\sigma A^\mu) (\partial^\rho A^\nu - \partial^\nu A^\rho) - \frac{1}{c} J_\alpha A^\alpha$$

$$(\because F_{\mu\nu} = \partial_\mu A_\nu - \partial_\nu A_\mu)$$

Now varying the \mathcal{L} w.r.t A^ν i.e the field quantity gives:

$$\frac{\partial \mathcal{L}}{\partial (\partial^\beta A^\alpha)} = -\frac{1}{16\pi} g_{\mu\nu} g_{\rho\sigma} \left\{ \begin{array}{l} \delta_\beta^\mu \delta_\alpha^\sigma F^{\lambda\nu} - \\ \delta_\beta^\sigma \delta_\alpha^\mu F^{\lambda\nu} \\ + \delta_\beta^\lambda \delta_\alpha^\nu F^{\mu\sigma} - \delta_\beta^\nu \delta_\alpha^\lambda F^{\mu\sigma} \end{array} \right\}$$



As $g_{\mu\nu} = g_{\nu\mu}$; and $F^{\alpha\beta} = -F^{\beta\alpha}$ we get:

$$\frac{\partial \mathcal{L}}{\partial (2^\beta A^\alpha)} = -\frac{1}{16\pi} \left\{ g_{\alpha\beta} g_{\gamma\delta} F^{\gamma\delta} - g_{\alpha\gamma} g_{\beta\delta} F^{\gamma\delta} \right\}$$

$$= -\frac{1}{16\pi} \left\{ g_{\alpha\beta} g_{\gamma\delta} F^{\gamma\delta} - g_{\alpha\gamma} g_{\beta\delta} F^{\gamma\delta} + g_{\beta\mu} g_{\gamma\sigma} F^{\mu\sigma} - g_{\alpha\mu} g_{\beta\sigma} F^{\mu\sigma} \right\}$$

$$= -\frac{1}{16\pi} \left\{ F_{\beta\alpha} - F_{\alpha\beta} + F_{\beta\alpha} - F_{\alpha\beta} \right\}$$

$$\left(\because F_{\alpha\beta} = g_{\alpha\gamma} g_{\beta\delta} F^{\gamma\delta} \right)$$

$$= -\frac{1}{4\pi} F_{\alpha\beta}.$$

i.e. the field eq be: $\partial_\beta^\beta \left\{ \frac{\partial \mathcal{L}}{\partial (2^\beta A^\alpha)} \right\} = \frac{\partial \mathcal{L}}{\partial A^\alpha}$

i.e. $\boxed{\frac{1}{4\pi} \partial_\beta^\beta (F_{\alpha\beta}) = -\frac{1}{c} J_\alpha} \rightarrow \text{Ans.}$

i.e. $\boxed{\frac{1}{4\pi} 2^\beta (F_{\beta\alpha}) = \frac{J_\alpha}{c}}$

For $\alpha = 0$ this gives:

$$\frac{1}{4\pi} \partial^{\beta} (\partial_{\alpha} F_{\beta}) = -\frac{1}{c} J_0$$

$$\text{i.e. } \frac{1}{4\pi} \left(2^0 \vec{F}_{00} + 2^1 \vec{F}_{01} \right) = -\frac{1}{c} \partial_{\alpha} \cdot \vec{P}_C$$

$$\begin{aligned} \text{i.e. } & 2^0 \left\{ (2_0 A_1 - 2_1 A_0) \right\} + \cancel{2^0 A_2} + 2^2 (2_0 A_2 - 2_2 A_0) \\ & + 2^3 (2_0 A_3 - 2_3 A_0) = -4\pi \int \end{aligned}$$

$$\text{i.e. } 2_0 \left\{ 2^i A_i \right\} - 2^i 2_0 A_0 = -4\pi \int$$

$$\text{i.e. } + \vec{\nabla} \cdot \left(\frac{\partial \vec{A}}{\partial t} \right) + \nabla^2 \phi = -4\pi \int$$

$$\boxed{\text{i.e. } \vec{\nabla} \cdot \left(-\nabla \phi - \frac{\partial \vec{A}}{\partial t} \right) = 4\pi \int} \dots (1)$$

for $\alpha = 1$:

$$\frac{1}{4\pi} \left(2^0 \vec{F}_{10} + 2^1 \vec{F}_{11} + 2^2 \vec{F}_{12} + 2^3 \vec{F}_{13} \right) = -\frac{J_1}{c}.$$

$$\begin{aligned} \text{i.e. } & \frac{1}{4\pi} \left\{ 2^0 (2_1 A_0 - 2_0 A_1) + 2^2 (2_1 A_2 - 2_2 A_1) \right. \\ & \left. + 2^3 (2_1 A_3 - 2_3 A_1) \right\} = -\frac{J_1}{c} \end{aligned}$$

$$\text{i.e. } \partial^2 (\nabla \times \vec{A})_3 - \partial^3 (\nabla \times \vec{A})_2 = -\frac{\partial}{\partial t} \left(-\vec{\nabla} \phi - \frac{\partial \vec{A}}{\partial t} \right)_1 \\ = -\frac{4\pi j_1}{c}$$

$$\text{i.e. } -\left\{ \nabla \times (\nabla \times \vec{A}) \right\}_1 + \frac{\partial}{\partial t} \left(-\vec{\nabla} \phi - \frac{\partial \vec{A}}{\partial t} \right)_1 = -\frac{4\pi j_1}{c}$$

$$\text{i.e. } (\nabla \times (\nabla \times \vec{A}))_1 = \frac{4\pi j_1}{c} + \frac{\partial}{\partial t} \left(-\vec{\nabla} \phi - \frac{\partial \vec{A}}{\partial t} \right)_1$$

i.e for $\alpha = 2, 3$ we get combining in vector forms

$$\boxed{\nabla \times (\nabla \times \vec{A}) = \frac{4\pi \vec{j}}{c} + \frac{\partial}{\partial t} \left\{ -\vec{\nabla} \phi - \frac{\partial \vec{A}}{\partial t} \right\}} \rightarrow (2)$$

Thus we get the source dependent Maxwell's eq from the Lagrangian.

Here if we do two substitutions

$$\text{i.e. } \nabla \times \vec{A} = \vec{B} \\ \text{And } -\vec{\nabla} \phi - \frac{\partial \vec{A}}{\partial t} = \vec{E} \quad \left. \begin{array}{l} \text{i.e Assume} \\ \text{true } \vec{E}, \vec{B} \text{ to be} \\ \text{two new fields,} \end{array} \right\}$$

then we get:

$$\boxed{\nabla \cdot \vec{E} = \frac{4\pi \rho}{c} \quad \nabla \times \vec{B} = \frac{4\pi \vec{j}}{c} + \frac{\partial \vec{E}}{\partial t}} \quad \left. \begin{array}{l} \text{i.e our familiar} \\ \text{form in terms of} \\ \vec{E}, \vec{B} \end{array} \right\}$$

if instead of they give written $F^{\alpha\beta}$ in terms
of \vec{E}, \vec{B} totally i.e. written ~~not~~ $\mathcal{L}(E, B)$
then we got true eqn's exactly. (I've done
that ~~in~~ in Assignment)

Now the Homogeneous Maxwell's eqn's are not
any new eqn's and they are assumed to be true
here. When we consider

$$\vec{B} = \nabla \times \vec{A} \Rightarrow \nabla \cdot \vec{B} = \nabla \cdot (\nabla \times \vec{A}) = 0$$

$$\text{And } \vec{E} = -\nabla\phi - \frac{\partial \vec{A}}{\partial t} \Rightarrow \nabla \times \vec{E} = -\frac{\partial(\nabla \times \vec{A})}{\partial t} = -\frac{\partial \vec{B}}{\partial t}$$

AM

b. $\mathcal{L} = -\frac{1}{16\pi} F_{\alpha\beta} F^{\alpha\beta} - \frac{1}{c} A_\alpha J^\alpha$

Stays EOM invariant under Gauge transform

$$A^\mu \rightarrow A^\mu + \partial^\mu \lambda \quad (\lambda = \text{Gauge parameter})$$

Now, $\mathcal{L} - \mathcal{L}'$

$$= -\frac{1}{16\pi} F_{\alpha\beta} F^{\alpha\beta} - \cancel{\frac{1}{c} A_\alpha J^\alpha} + \frac{1}{8\pi} \cancel{\partial_\alpha A_\beta} \partial^\alpha A^\beta \\ + \cancel{\frac{1}{c} A_\beta J^\beta}$$

$$= -\frac{1}{8\pi} \left(\frac{1}{2} F_{\alpha\beta} F^{\alpha\beta} - \partial_\alpha A_\beta \partial^\alpha A^\beta \right)$$

$$= -\frac{1}{8\pi} \left(\frac{1}{2} (\partial_\alpha A_\beta - \partial_\beta A_\alpha) (\partial^\alpha A^\beta - \partial^\beta A^\alpha) - \partial_\alpha A_\beta \partial^\alpha A^\beta \right)$$

$$= -\frac{1}{8\pi} \left(\frac{1}{2} (\cancel{\partial_\alpha A_\beta \partial^\alpha A^\beta} - \cancel{\partial_\beta A_\alpha \partial^\alpha A^\beta} - \cancel{\partial_\alpha A_\beta \partial^\beta A^\alpha} + \cancel{\partial_\beta A_\alpha \partial^\beta A^\alpha}) - \cancel{\partial_\alpha A_\beta \partial^\alpha A^\beta} \right)$$

$$= -\frac{1}{8\pi} \times (-\cancel{\partial_\alpha A_\beta \partial^\beta A^\alpha})$$

$$\frac{\cancel{\partial_\alpha A_\beta \partial^\beta A^\alpha}}{8\pi} = \frac{1}{8\pi} \partial_\alpha (A_\beta \partial^\beta A^\alpha)$$

$$= \frac{1}{8\pi} \partial_\alpha ((A \cdot \partial) A^\alpha) \quad \left(A \cdot \partial = 4 \text{ dim inner product} \right)$$

$$\text{i.e } \Delta L = \frac{1}{8\pi} \partial_\alpha J^\alpha$$

$$(J^\alpha = (A \cdot \partial) A^\alpha)$$

i.e L differs by a 4-divergence

proves

C. ~~The added 4 divergence does not change the E.O.M.~~

$$\Delta S = \int d^4x (\Delta L)$$

$$= \int \partial_\alpha (\partial_\alpha J^\alpha) d^4x$$

$$= \oint_{\text{4 surface}} \vec{J} \cdot \vec{dS}$$

provided that \vec{J} vanishes on boundary

$$\Delta S = 0$$

i.e the variation of S' is same as giving same E.O.M. \rightarrow proves

Problem: 8

$$\text{Given } M \rightarrow m_1 + m_2$$

In the rest frame of decaying particle the 4 momentum be:

$$P = M \gamma(c, \vec{v})$$

but $\gamma = 1$; $\vec{v} = 0$ & let $c = 1$ i.e.

$$P = M(1, \vec{0})$$

If $(E_1, E_2); (\vec{p}_1, \vec{p}_2)$ be the energy & momentum of produced particle then the 4-momentum

i.e.: $P_1^{\mu} = (E_1, \vec{p}_1)$; $P_2^{\mu} = (E_2, \vec{p}_2)$

Now: $P = p_1 + p_2$.

i.e. $p_2^2 = (P - p_1)^2 = P^2 + p_1^2 - 2P \cdot p_1$

but $p^2 = M^2$; $p_1^2 = m_1^2$; $p_2^2 = m_2^2$; $P \cdot p_1 = M E_1$

i.e. $m_2^2 = M^2 + m_1^2 - 2M E_1$

i.e. $E_1 = \frac{(M^2 + m_1^2 - m_2^2)}{2M}$ → boxed

b. When the ~~decay~~ decay is continuous i.e. M goes to $m (\rightarrow \infty)$ particles:

$$P = p_1 + p_2 + \dots$$

Ans from momentum conservation $\sum \vec{p}_i = 0$.

$$\text{Now, } T_1 = E_1 - m_1$$

$$= \frac{M^2 + m_1^2 - m_2^2}{2M} - m_1 \quad (\text{for 2 particles})$$

$$= \frac{M^2 - 2m_1 M + m_1^2 - m_2^2}{2M}$$

$$= \frac{(M - m_1)^2 - m_2^2}{2M}$$

$$= \frac{(M - m_1 + m_2)(M - m_1 - m_2)}{2M}$$

$$= \frac{\Delta M (2M - 2m_1 - M + m_1 + m_2)}{2M}$$

$(\Delta M = M - m_1 - m_2)$
= change of total mass to energy

$$= \Delta M \left(1 - \frac{m_1}{M} - \frac{\cancel{M}}{2M} \right)$$

Here I've assumed m_2 to be sum of all other masses. So for ith particle in general:

$$T_i = \cancel{m_i} GM \left(1 - \frac{m_i}{M} - \frac{GM}{2M} \right) \rightarrow \underline{\text{proved}}$$

problem:

Without loss of generality; let the Lorentz Boost be given along x direction with velocities v_1, v_2 . Consider the L.T matrix (only x-t part is important here).

$$M_1 = \begin{pmatrix} \gamma_1 & -\gamma_1 \beta_1 \\ -\gamma_1 \beta_1 & \gamma_1 \end{pmatrix} \quad \begin{pmatrix} \text{I've not written} \\ \text{other terms of} \\ \text{these don't affect} \\ \text{here} \end{pmatrix}$$

$$M_2 = \begin{pmatrix} \gamma_2 & -\gamma_2 \beta_2 \\ -\gamma_2 \beta_2 & \gamma_2 \end{pmatrix}$$

Now if the rapidity is ϕ then $e^\phi = \gamma(1+\beta)$

$$\text{i.e. } e^{-\phi} = \frac{1}{\gamma(1+\beta)} = \cancel{\gamma} \frac{\gamma(1-\beta)}{\gamma^2(1-\beta^2)} = \gamma(1-\beta)$$

$$\text{i.e. } \gamma = \frac{e^{\phi} + e^{-\phi}}{2} = \cosh \phi \quad \left. \begin{array}{l} \beta = \tanh \phi \\ = \tanh(\ln \gamma + \beta) \end{array} \right\}$$

$$\gamma \beta = \frac{e^{\phi} - e^{-\phi}}{2} = \sinh \phi$$

\therefore The L^T matrix be written as,

$$M_{L^T} = \begin{pmatrix} \cosh \phi & -\sinh \phi \\ -\sinh \phi & \cosh \phi \end{pmatrix}$$

i.e here the co-ordinate transformation is:

$$M = M_2 M_1 = \begin{pmatrix} \cosh \phi_2 & -\sinh \phi_2 \\ -\sinh \phi_2 & \cosh \phi_2 \end{pmatrix} \begin{pmatrix} \cosh \phi_1 & -\sinh \phi_1 \\ -\sinh \phi_1 & \cosh \phi_1 \end{pmatrix}$$

$$= \begin{pmatrix} \cosh \phi_2 \cosh \phi_1 & -(\cosh \phi_2 \sinh \phi_1 + \sinh \phi_2 \cosh \phi_1) \\ + \sinh \phi_2 \sinh \phi_1 & \cosh \phi_2 \cosh \phi_1 + \sinh \phi_2 \sinh \phi_1 \end{pmatrix}$$

Symm

i.e the effective γ be:

$$= \begin{pmatrix} \cosh(\phi_1 + \phi_2) & -\sinh(\phi_1 + \phi_2) \\ \sinh(\phi_1 + \phi_2) & \cosh(\phi_1 + \phi_2) \end{pmatrix} S_{\text{gamma}}$$

but $(\phi_1 + \phi_2)$ is the whole rapidity.

$$\begin{aligned} i.e. \quad \gamma &= \cosh(\phi_1 + \phi_2) \\ \gamma \beta &= \sinh(\phi_1 + \phi_2) \end{aligned} \quad \left. \right\}$$

$$\begin{aligned} i.e. \quad \beta &= \tanh(\phi_1 + \phi_2) = \tanh \left\{ \ln \gamma_1(1+\beta_1) + \ln \gamma_2(1+\beta_2) \right\} \\ &= \tanh \ln \frac{\gamma_1 \gamma_2 (1+\beta_1)(1+\beta_2)}{\cancel{\gamma_1 \gamma_2 (1+\beta_1)(1+\beta_2)}} = \tanh \left(\ln \frac{\gamma_1 \gamma_2 (1+\beta_1)}{(1+\beta_2)} \right) \end{aligned}$$

... (1)

↑

$$\text{i.e } \beta = 1 + \frac{v_1}{c} + \frac{v_2}{c} + \frac{v_1 v_2}{c^2}$$

?

$$\begin{aligned} \text{i.e } \gamma_B &= \gamma_1 \gamma_2 + \gamma_1 \gamma_2 \beta_1 \beta_2 \\ \gamma_B &= \gamma_1 \gamma_2 \beta_2 + \gamma_1 \gamma_2 \beta_1 \end{aligned} \quad \left. \right\}$$

$$\text{i.e } \beta = \frac{\gamma_1 \gamma_2 (\beta_1 + \beta_2)}{(1 + \beta_1 \beta_2) \gamma_1 \gamma_2}$$

$$\text{i.e } \frac{v_{\text{eff}}}{c} = \frac{\frac{v_1}{c} + \frac{v_2}{c}}{1 + \frac{v_1 v_2}{c^2}}$$

$$\boxed{\text{i.e } v_{\text{eff}} = \frac{v_1 + v_2}{1 + \frac{v_1 v_2}{c^2}}}$$

i.e the addition is a new S.T with

velocity $\boxed{v_{\text{eff}} = \frac{v_1 + v_2}{1 + \frac{v_1 v_2}{c^2}}} \rightarrow A$

Or from the rapidity: (or from eq(1)):

$$\text{or } e^{\phi_1} \cdot e^{\phi_2} = e^{\phi_1 + \phi_2} = e^{\phi}$$

$$\text{i.e. } \gamma_1(1+\beta_1) \gamma_2(1+\beta_2) = \gamma(1+\beta)$$

$$\gamma_1^2 (1+\beta_1)^2 + \gamma_2^2 (1+\beta_2)^2 = \gamma^2 (1+\beta)^2.$$

$$\text{i.e. } \frac{1}{\left(1 - \frac{v_1^2}{c^2}\right)} \cdot \frac{1}{\left(1 - \frac{v_2^2}{c^2}\right)} \left(1 + \frac{v_1}{c}\right)^2 \left(1 + \frac{v_2}{c}\right)^2 \\ = \frac{1}{\left(1 - \frac{v^2}{c^2}\right)} \left(1 + \frac{v}{c}\right)^2.$$

$$\text{i.e. } \frac{1 + \frac{v_1}{c}}{1 - \frac{v_1}{c}} \cdot \frac{1 + \frac{v_2}{c}}{1 - \frac{v_2}{c}} = \frac{1 + \frac{v}{c}}{1 - \frac{v}{c}}$$

$$\text{i.e. } \frac{(c+v_1)(c+v_2)}{(c-v_1)(c-v_2)} = \frac{c+v}{c-v}$$

$$\text{i.e. } \frac{(c+v)-(c-v)}{(c+v)+(c-v)} = \frac{(c+v_1)(c+v_2)-(c-v_1)(c-v_2)}{(c+v_1)(c+v_2)+(c-v_1)(c-v_2)}$$

$$\text{i.e. } \frac{v}{c} = \frac{2c(v_1+v_2)}{2(c^2+v_1v_2)}$$

i.e

$$V = V_{eff} = \frac{V_1 + V_2}{1 + \frac{V_1 V_2}{C^2}}$$

proves

= This is effective velocity of the two successive L.T in same direction

$$2. \quad \vec{E} \cdot (\vec{\nabla} \times \vec{B}) = \frac{4\pi}{c} (\vec{E} \cdot \vec{j}) + \frac{1}{c} \vec{E} \cdot \frac{\partial \vec{E}}{\partial t}.$$

Using product rule:

$$\vec{B} \cdot (\vec{\nabla} \times \vec{E}) - \vec{\nabla} \cdot (\vec{E} \times \vec{B}) = \frac{4\pi}{c} (\vec{E} \cdot \vec{j}) + \frac{1}{c} \cdot \frac{1}{2} \frac{\partial (\vec{E}^2)}{\partial t}$$

$$\text{i.e. } -\vec{B} \cdot \frac{\partial \vec{B}}{\partial t} - \vec{\nabla} \cdot (\vec{E} \times \vec{B}) = 0 \quad (\because \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t})$$

$$\text{i.e. } \vec{\nabla} \cdot (\vec{E} \times \vec{B}) = -\frac{4\pi}{c} (\vec{E} \cdot \vec{j}) - \frac{1}{2c} \frac{\partial}{\partial t} (E^2 + B^2)$$

$$\begin{aligned} \text{Now, } \vec{E} \cdot \vec{j} &= \oint \vec{E} \cdot \vec{v} = \oint (\vec{E} + \vec{v} \times \vec{B}) \cdot \vec{v} \\ &= \oint \vec{F}_p \cdot \vec{v} = \vec{F}_p \cdot \vec{v} \\ &= \frac{dw}{dt} \quad \left(w \text{ if the work done on charges in unit vol} \right) \end{aligned}$$

$\frac{1}{2} \frac{E^2 + B^2}{2}$ is the energy density of the E.M field

i.e

$$\Rightarrow \frac{4\pi}{c} \frac{dW}{dt} = - \frac{1}{4\pi} \left(\frac{E^2 + B^2}{2c} \right) - \cancel{\nabla \cdot (\vec{E} \times \vec{B})}$$

i.e $\int \frac{dW}{dt} d\tau = - \frac{1}{4\pi} \int \frac{1}{4\pi} \left(\frac{E^2 + B^2}{2} \right) d\tau$

$$= - \frac{c}{4\pi} \int \nabla \cdot (\vec{E} \times \vec{B}) d\tau$$

i.e $\frac{dW}{dt} = - \frac{1}{4\pi} \int \frac{1}{4\pi} \left(\frac{E^2 + B^2}{2} \right) d\tau - \frac{c}{4\pi} \oint_S (\vec{E} \times \vec{B}) \cdot d\vec{s}$

i.e the loss of energy by the charge
(work done by charge) is transmitted either to
the field ($E^2 + B^2$ term) or carried out by
the field by $\vec{E} \times \vec{B}$ along the direction of $(\vec{E} \times \vec{B})$

i.e

$$\text{Work done on charge} = \frac{\text{rate}}{\text{decrease of energy stored}} \text{ in } \vec{E}, \vec{B} \text{ field}$$



- energy going out through
surface by \vec{E}, \vec{B} in direction
 $(\vec{B} \hat{a}\vec{B})$

4.a. from thermal energy distribution law we get:

$$U(v) = \frac{2 h v^3}{c^3 (e^{\frac{hv}{kT}} - 1)}$$

Now for a moving frame γ (i.e v) changes due to two reasons.

- i) Spacetime transformation (i.e γ)
 - ii) Doppler Shift.
- } i) by Spacetime contraction (i.e γ) the contraction is:

$$\gamma_f' \rightarrow \frac{\gamma_i}{\gamma}$$

- ii) by Doppler Shift it further reduces to

$$\gamma_f \rightarrow \frac{\gamma_f'}{1 + \frac{v}{c} \hat{C} \cdot \hat{m}}$$

$$\text{i.e } \gamma_f \rightarrow \frac{\gamma_f'}{1 + \frac{v}{c} \cos \theta}$$

$$\text{i.e combining both giving: } \gamma_f = \frac{\gamma_i}{\gamma(1 + \frac{v \cos \theta}{c})}$$

i.e $v_{\text{observed}} = \sqrt{\frac{(1 - v^2/c^2)^{1/2} v_{\text{true}}}{(1 + \frac{v \cos \theta}{c})^{1/2}}} \quad (\because v \sim \lambda)$
 give first written wrong. hence the inverse is added later

$$\therefore U(v_{\text{observed}}) = \frac{2}{C^3} \cdot \frac{h v_{\text{obs}}}{e^{\frac{h v_{\text{obs}}}{k T'}} - 1}$$

$$= \frac{2}{C^3} \cdot h \left(\frac{\sqrt{1 - v^2/c^2}}{1 + \frac{v}{c} \cos \theta} \right)^{-3} v_{\text{true}}^3$$

$$= \frac{2}{C^3} \cdot \frac{h \left(\frac{1 + \frac{v}{c} \cos \theta}{\sqrt{1 - v^2/c^2}} \right)^3 v_{\text{true}}^3}{e^{\frac{h v_{\text{true}}}{k T'}} \left(\frac{1 + \frac{v \cos \theta}{c}}{\sqrt{1 - v^2/c^2}} \right)^{-3} - 1}$$

but for small velocity $\left(\frac{1 + \frac{v}{c} \cos \theta}{\sqrt{1 - v^2/c^2}} \right)^3 \approx 1 + O\left(\left(\frac{v}{c}\right)^3\right)$

i.e $U(v_{\text{obs}}) = \frac{2}{C^3} \cdot \frac{h v_{\text{true}}^3}{e^{\frac{h v}{k T'}} \left(\frac{1 + v \cos \theta/c}{\sqrt{1 - v^2/c^2}} \right)^{-3} - 1}$

i.e. equivalently we ~~can~~ can say that temperature transforming like:

$$T' = T \frac{\sqrt{1-\gamma/c^2}}{\left(1 + \frac{N \cos \theta}{c}\right)} \rightarrow \underline{\text{Ans}}$$

b: $I_n = CV_n$

i.e. $I_{\max} = C V_n (\max)$; $I_{\min} = C V_n (\min)$.

from part (A) we get:

I will be maximum for $\theta = \pi/2$ minimum for $\theta = 0$

$$\text{i.e. } I_{\max} = \frac{2}{C} \frac{h^2 v_{\text{cmr}}^3}{e^{\frac{h^2 v_{\text{cmr}}}{kT}} \sqrt{\frac{1+\gamma/c}{1-\gamma/c}}} - 1$$

$$I_{\min} = \frac{2}{C} \frac{h^2 v_{\text{cmr}}^3}{e^{\frac{h^2 v_{\text{cmr}}}{kT}} \sqrt{\frac{1+\gamma/c}{1-\gamma/c}}} - 1$$

(v, T given here).

Now, $I_{\text{Anisotropy}} = 10^3$

$$\frac{I_{\max} - I_{\min}}{I_{\max} + I_{\min}}$$

$$\text{i.e. } \frac{\frac{1}{e^{\frac{hv}{kT}} \sqrt{\frac{1-v/c}{1+v/c}} - 1} - \frac{1}{e^{\frac{hv}{kT}} \sqrt{\frac{1+v/c}{1-v/c}} - 1}}{1} = 10^{-3}$$

$$\frac{1}{e^{(\gamma) \sqrt{\frac{1-v/c}{1+v/c}} - 1}} + \frac{1}{e^{(\gamma) \sqrt{\frac{1+v/c}{1-v/c}} - 1}}$$

$$e^{(\gamma) \sqrt{\frac{1+v/c}{1-v/c}}} - e^{(\gamma) \sqrt{\frac{1-v/c}{1+v/c}}}$$

$$\text{i.e. } \frac{e^{(\gamma) \sqrt{\frac{1+v/c}{1-v/c}}} + e^{(\gamma) \sqrt{\frac{1-v/c}{1+v/c}}} - 2}{e^{(\gamma) \sqrt{\frac{1+v/c}{1-v/c}}} + e^{(\gamma) \sqrt{\frac{1-v/c}{1+v/c}}} - 2} = 10^{-3}$$

i.e. taking Taylor expansion upto $O(v/c)$:

$$\frac{\sqrt{\frac{1+\beta}{1-\beta}} - \sqrt{\frac{1-\beta}{1+\beta}}}{\sqrt{\frac{1+\beta}{1-\beta}} + \sqrt{\frac{1-\beta}{1+\beta}}} = 10^{-3}$$

$$\text{i.e } \sqrt{\frac{1+\beta}{1-\beta}} / \sqrt{\frac{1-\beta}{1+\beta}} = \frac{1+10^3}{-1+10^3}$$

$$\text{i.e } \frac{1+\beta}{1-\beta} = \frac{1001}{999}$$

$$\text{i.e } \beta \approx \frac{1001 + 999}{1001 - 999} \approx \frac{2 \times 1000}{2}$$

$$\text{i.e } \beta \approx \frac{1}{1000}$$

$$\text{i.e } V \approx \frac{c}{1000} \approx 3 \times 10^5 \text{ m/s.}$$

i.e The approximate value of earth's velocity w.r.t QMB is 3×10^5 m/s.

Problem 3.

Let $dN = \text{no. of points in phase space}$.

$dV = \text{volume element in phase Space}$.

Now for L.T along x direction.

$$\begin{array}{l|l} x' = x - vt & p'_x = p_x - \cancel{\beta} p^0 \\ y' = y & p'_y = p_y \\ z' = z & p'_z = p_z \end{array}$$

~~steady $f = \frac{dN}{dV}$ will be conserved under L.T iff $\frac{\partial f}{\partial x} = \frac{\partial}{\partial x} \left(\prod_i \frac{\partial p_i}{\partial x_i} \right) = \text{invariant}$~~
~~(as N is unaffected under L.T.)~~

The phase Space volume forming like:

$$dV \rightarrow dV' = J(x_i p_i \rightarrow x'_i p'_i) \cdot dV.$$

but $J = \det \left| \frac{\partial x'_i}{\partial x_j} \right|_{i,j} \quad (x_i \in \text{Space + momentum})$

i.e the transformation matrix Y_{ij}

$$= \begin{pmatrix} \frac{\partial \mathbf{x}_1'}{\partial \mathbf{x}_1} & \frac{\partial \mathbf{x}_1'}{\partial \mathbf{x}_2} & \dots & \frac{\partial \mathbf{x}_1'}{\partial \mathbf{x}_n} \\ \vdots & \vdots & & \vdots \\ \frac{\partial \mathbf{x}_n'}{\partial \mathbf{x}_1} & \frac{\partial \mathbf{x}_n'}{\partial \mathbf{x}_2} & \dots & \frac{\partial \mathbf{x}_n'}{\partial \mathbf{x}_n} \end{pmatrix}$$

i.e. $J = \det \left| \frac{\partial \mathbf{x}_i}{\partial \mathbf{x}_j} \right|_{A_{i,j}} = \gamma^2$.

i.e. $dN \rightarrow \gamma^2 dN = dN'$

Now, ~~$dN = \prod dm_{x_i} dm_{p_i}$~~

$dm_{x_i} = m_0$ of particle between x_i & x_{i+1}
 $dm_{p_i} = m_0$ of momentum in p_i & $p_i + dp_i$

i.e. ~~dm'_i~~ also have the same transformation like \mathbf{x}_i & \mathbf{p}_i

i.e $\frac{\partial m_{\text{ini}}}{\partial m_{\text{fin}}}$ is similar to ~~$\frac{\partial m_{\text{ini}}}{\partial m_{\text{fin}}}$~~ $\frac{\partial n}{\partial v'}$

(This is because L.T. does not affect dN by changing no. of particle; but affect by changing definition of measurement of m, dV etc.)

i.e $dN' = \gamma^2 dN$ (similarly)

$$\therefore f' = \frac{dN'}{dV'} = \frac{\gamma^2(dN)}{\gamma^2(dV)} = \cancel{\frac{dN}{dV}} = f$$

i.e phase space density is conserved
 \longrightarrow bores

b' $V(v) = \frac{2\pi v^3}{C^3 \left(e^{\frac{hv}{kT}} - 1 \right)}$

$$\text{Ans, } I(v) = \frac{2\pi}{C^3} \frac{v^3}{e^{\frac{hv}{kT}} - 1} \cdot \frac{dE}{dT}.$$

5.a The definition of $\delta(\vec{x}-\vec{x}')$ is given by integral

Eq:

$$\int_{\text{all Space}} \delta(\vec{x}-\vec{x}') f(\vec{x}') d^3x' = f(\vec{x})$$

i.e for $f(\vec{x}') = 1$: $\int \delta(\vec{x}-\vec{x}') d^3x' = 1$.

In some coordinate system

$$dxdydz \rightarrow |\mathcal{J}| du dv dw.$$

where $|\mathcal{J}|$ is the Jacobian & related to the metric tensor g as: $|\mathcal{J}| = \sqrt{\det(g)}$

i.e $dxdydz \rightarrow \sqrt{\det(g)} du dv dw.$

i.e $\int_{\text{all Space}} f(\vec{x}') \delta^3(\vec{x}'-\vec{x}) d^3x' = f(\vec{x})$

$$\int_{\text{all Space}} f(\vec{v}, \cancel{\vec{v}'}) \delta^3(\vec{v}-\vec{v}') \sqrt{\det(g)} d^3\vec{v}'$$
$$= \tilde{f}(\vec{v})$$

i.e. but for $f(\vec{r}) = 1$ for all space

$$f(\vec{r}) = 1 \quad " "$$

i.e. $\int_{\text{all Space.}} \delta(\vec{r} - \vec{r}') \sqrt{\det(\mathbf{g})} d^3 \vec{r}' = 1$ $\rightarrow \underline{\text{Ans}}$

b. for cylindrical system:

$$x = r \cos \varphi : y = r \sin \varphi ; z = z$$

$$\therefore |\mathbf{J}|^2 = \begin{vmatrix} \cos \varphi & r \sin \varphi & 0 \\ \sin \varphi & r \cos \varphi & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

i.e. $\det(\mathbf{g}) = r$.

$$\therefore \delta(\vec{r} - \vec{r}') = \frac{1}{r} \delta(r - r') \delta(\varphi - \varphi') \delta(z - z')$$

$$\rightarrow \underline{\text{Ans}}$$

Problem: 6

Let $\vec{E} = E \hat{x}$

& $\vec{v}(t=0) \parallel \hat{y}$.

Now, $\vec{F} = q \vec{E} \hat{x}$

i.e. $\frac{dp_x}{dt} = qE ; \frac{dp_y}{dt} = 0 ; \frac{dp_z}{dt} = 0$

clearly $p_x = p_x(t=0) = 0 \quad | \quad p_x = qEt$
 $p_y = p_y(t=0) = p_0 \quad |$

Now $E = \sqrt{p_x^2 c^2 + m^2 c^4}$
 $= \sqrt{c^2 q^2 E^2 t^2 + m^2 c^4 + p_0^2 c^2}$

but $E(0) = \sqrt{m^2 c^2 + p_0^2 c^2}$

i.e. $E = \sqrt{E(0)^2 + q^2 E^2 c^2 t^2}$

$\therefore v_m = \frac{p_x c}{E} = \frac{c^2 q E t}{\sqrt{E(0)^2 + q^2 E^2 c^2 t^2}}$

$$N_1 = \cancel{p_0} \frac{c^2}{E} = \frac{p_0 c^2}{\sqrt{E(0) + q^2 c^2 E^2 t^2}}$$

$$N_2 = 0$$

$$\frac{d\vec{r}}{dt} = \frac{c^2 q E t}{\sqrt{E(0) + q^2 c^2 E^2 t^2}}$$

$$\begin{aligned} \text{i.e } \vec{r} &= \int \frac{c^2 q E t}{\sqrt{E(0) + q^2 c^2 E^2 t^2}} dt \\ &= \frac{1}{q E} \sqrt{E(0) + q^2 c^2 E^2 t^2} + \vec{r}_0. \end{aligned}$$

$$\frac{d\vec{j}}{dt} = \frac{p_0 c^2}{\sqrt{E(0) + q^2 c^2 E^2 t^2}}$$

$$\text{i.e } \vec{j} = \int \frac{p_0 c^2 dt}{\sqrt{(\dots)}}$$

$$\text{i.e } \vec{j} = \frac{p_0 c^2}{q E} \sin \left(\frac{q c E t}{E(0)} \right) + \vec{j}_0.$$

(integrals done in mathematica)

$$\text{i.e } \frac{dz}{dt} = 0 \quad \text{i.e } z = z_0.$$

$$v = \frac{1}{\sqrt{E(0) + q^2 c^2 E^2 t^2}} \left(c^2 q E t, p_0 c^2, 0 \right)$$