

Jupyter Notebook Tutorial

1. INTRODUCTION

This tutorial explains the basic data reduction process for the SOAR Adaptive-Module Optical Spectrograph (SAMOS). The accompanying jupyter notebook is aptly named ‘jupyter_SAMOS’.

2. STARTING UP

As of now, the pipeline uses PyRAF for spectral line identification, which requires Python2. The environment file `EnvSAMOS.yml` is located in the main working directory. The user may copy the environment to their own computer by executing ‘`conda env create --file EnvSAMOS.yml`’ in their terminal.

3. INTRODUCTION

This manual is written for the reorganization-pyraf branch of the pipeline. For the original manual, see the master branch. This branch requires a separate environment than the other branches. The pipeline needs to use `pyraf` (which only supports `python2.7`) at this stage of development. The environment file `SAMOS_specs.txt` provides the correct environment for this branch of the code.

The main content of the directories the user should have in his or her working directory for the current version of the pipeline is shown below:

- `SAMOS-working-dir/`:

- * `cleaner.sh`
 - * `Docs/`
 - * `Readme.md`
 - * `LDSS3/`

- * helper_files/
- * linelists/
- * py_mods/
- SAMOS-working-dir/py_mods/:
 - * CreateFuelStructure.py
 - * CreateInput.py
 - * CreateSlitStructure.py
 - * FlatNorm.py
 - * InitializeSAMOS.py
 - * NormDivFlats.py
 - * OutlineSlits.py
 - * Overscan.py
 - * OverscanAndTrim.py
 - * SAMOSHelpers.py
 - * SlitCutout.py
 - * SlitID.py
 - * __init__.py
- SAMOS-working-dir/helper_files:
 - * LMask1.SMF
 - * LMask2.SMF
 - * LMask1_ycoords_c1.txt
 - * LMask2_ycoords_c1.txt
 - * LMask2_ycoords_red_c1.txt

This document reviews the purpose and describes how to use these programs to reduce the test data from LDSS3. Eventually, it will be used to reduce multi-object spectroscopy data taken with the SOAR Adaptive-Module Optical Spectrograph (SAMOS). For information on the instrument, see (Roberto et al. 2016). In order to avoid reinventing the wheel, this pipeline is heavily based on the [Flame DRP](#) written by Belli, Contursi, and Davies (2017). Flame is written in IDL, while the SAMOS pipeline will ultimately be written in Python3, but this version uses Python2.

4. INITIALIZATION

The pipeline is made to run in an ipython session. Upon starting a new session, import the initialization script with ‘`from InitializeSAMOS import initialize_SAMOS`’. This module is responsible for reading the headers from the sample data in **LDSS3/2017-11-30/**, and organizing the information into data structures for use by the rest of the code.

The initialization script takes in two arguments, the name of the directory with the test data (date on which data was retrieved) and the mask for which the user wants to use. The initialization then returns the main data structure of the pipeline, defined by the variable name ‘*fuel*’. The call for this step should look like:

```
In [1]: from InitializeSAMOS import initialize_SAMOS
In [2]: fuel = initialize_SAMOS(datadir,mask)
```

After running and reading over the terminal output, you should have a new directory named **LMask1** and a new file named **LMask1.db**. This step also now keeps track of the field image. The FITS headers for the test LDSS3 data do not contain the slit positions, so having the image of the actual slit mask is necessary at this time. The slit mask information is contained in the files LMask1.SMF and LMask2.SMF. The explanation for these files can be found on the Carnegie Observatories website, [here](#).

5. OVERSCANANDTRIM

Next, we have to determine the overscan and trim the edges of the fits data. This code reads the database file and creates arrays which separate the data into flats, comparison lamps, and science data.

The main part of `OverscanAndTrim` is the calling of the module `Overscan.py`. This module parses the fits data array into regions of bias and target data by reading the fits headers BIASSEC and DATASEC respectively. There is a function in `Overscan.py` called `FieldTrim(...)` that trims the field mask to the correct size. Then, I looked in DS9 for the top edges of each of the slits and made a text file of the positions which will be used in the step `OutlineSlits`. The function responsible for trimming and bias subtraction of the other FITS files is `Overscan(...)`.

The bias is due to a combination of the camera noise from the readout process and electric “pre-charge” on a CCD chip by the electronics. The BIASSEC header gives the region of overscan, which contains information for this bias. An array of this overscan region is made by grabbing the rows and columns from the data array (`d = f[0].data.astype('f') → overscan = d[biassec_rows, biassec_columns]`). The function then takes the median (or mean) of the overscan regions along the rows (`axis=1`), and subtracts these values from each data value in their respective data rows. The main procedure is shown in the figure below.

$$\begin{pmatrix} \text{cropped} & \text{and} \\ \text{bias} & \text{subtracted} \\ \text{data} & \text{matrix} \end{pmatrix} = \begin{pmatrix} d_{11} & d_{12} & d_{13} & \dots & d_{1m} \\ d_{21} & d_{22} & \dots & \dots & d_{2m} \\ \dots & \dots & \dots & \dots & \dots \\ d_{n1} & \dots & \dots & \dots & d_{nm} \end{pmatrix} - \begin{pmatrix} [b_1] \\ [b_2] \\ [b_3] \\ [...] \\ [b_n] \end{pmatrix}$$

This is the most up to date version of the documentation for the SAMOS pipeline thus far. Currently, there is no main script to run all the processes at once, so the user will have to run them step by step. To summarize, the user input for data reduction up to and including slit identification is,

```
> ./WhichFITSFiles 2017-11-30 LMask*
> ./OverscanAndTrim LMask*.db
> ./NormDivFlats LMask*.db
> ./OutlineSlits LMask*.db
```

(1)